



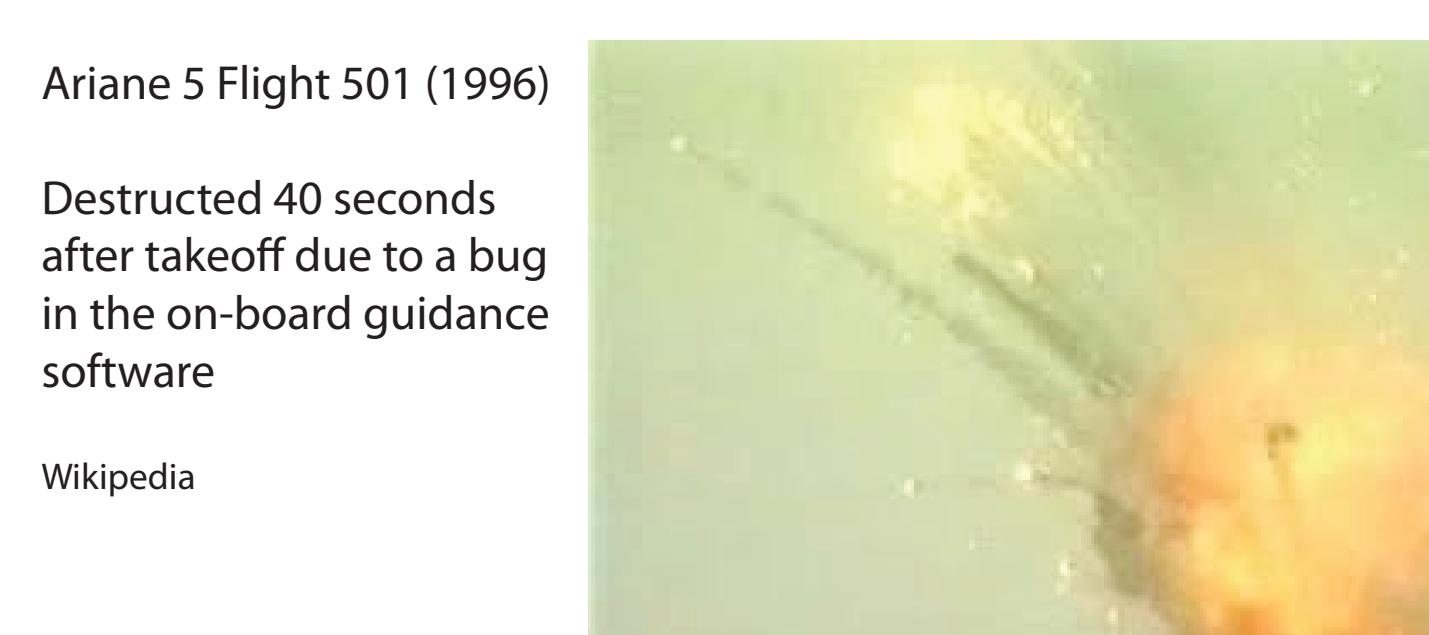
Hartford Coliseum Collapse (1978)  
CAD software used to design the Coliseum contained a bug that lead to incorrect design decisions  
[www.devtopics.com/20-famous-software-disasters](http://www.devtopics.com/20-famous-software-disasters)

# Refinements to techniques for verifying shape analysis invariants in Coq

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Destructed 40 seconds after takeoff due to a bug in the on-board guidance software  
[Wikipedia](http://en.wikipedia.org/wiki/Ariane_5_Flight_501)

## Summary

Formal Methods for Imperative Languages Such as C

Objective: Develop a Framework in Coq capable of reasoning about realistic programs and the complex data structures they manipulate

## Research Contributions

Extension of Coq separation logic reasoning to larger programs with more complex data structures.

Creation of a library of useful predicates, functions and tactics

- Deep model allows greater control over the design of tactics

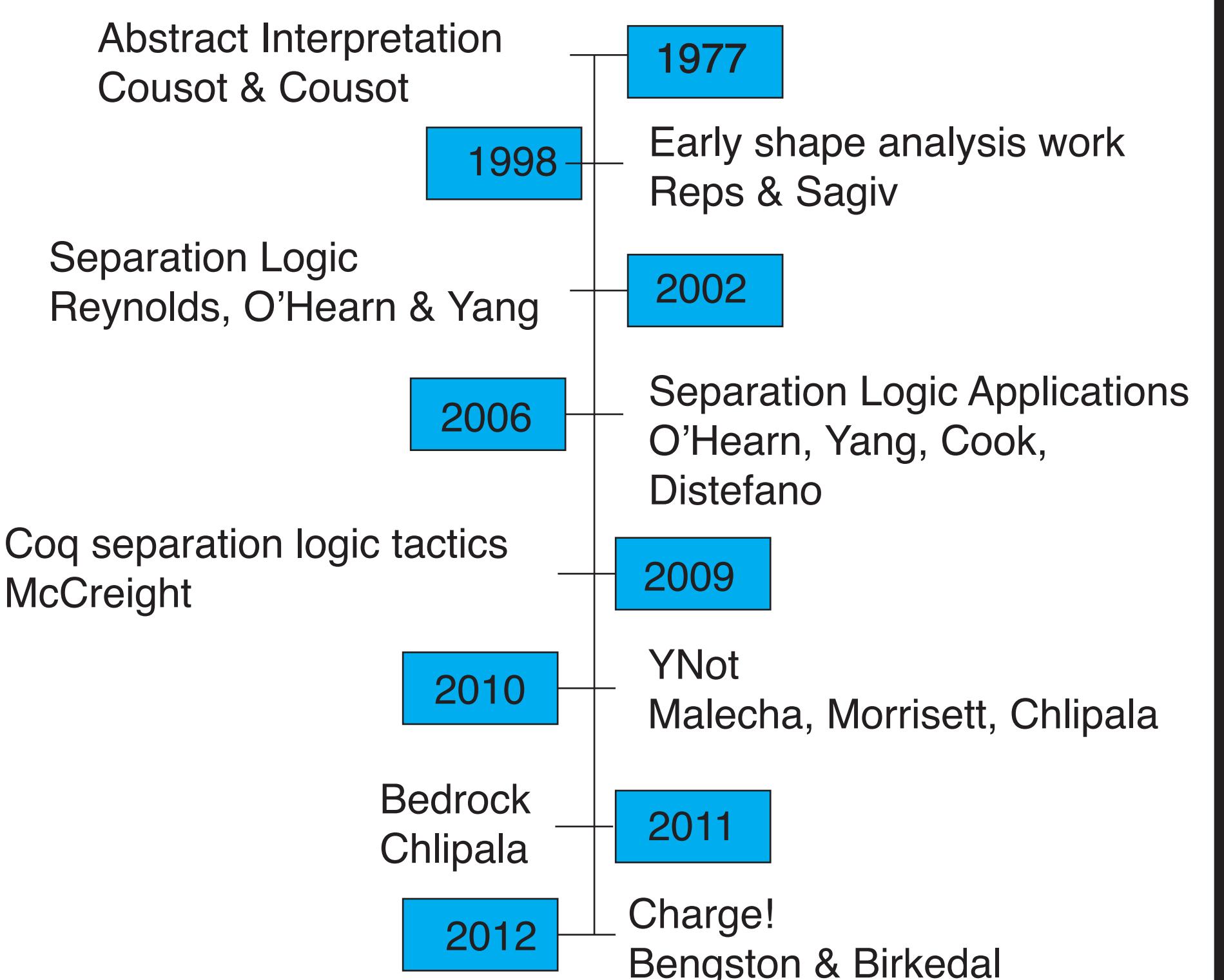
Key challenge: Performance tuning

- Tradeoffs between performance and automation

Development of a powerful simplification tactic

- Simplification tactic executed after every major proof step
- Based on term rewriting (with contextual rewriting) concepts
- Automates reasoning about associativity, commutativity and other simple property classes
- Design decisions in creating canonical form addressed

## Timeline of related work:



## Separation Logic basics

The following constructs come from Bedrock/YNot/Charge!:

- (1) Higher order separation \* operator
- (2) Lifted AbsAll, AbsExists
- (3) [P] - a separation logic predicate that asserts P and that the heap is empty

We have added the following:

- (1) TREE is a generic recursive predicate for constructing linked lists and trees in the heap.
- (2) Path (See the DPLL example) is like TREE but it creates a list or tree structure embedded inside another list or tree.
- (3) (SUM x in R, e)==total is used to sum up values over a range
- (4) Foreach x in R, P. P is evaluated for all values of x in R. The results are composed together using the separation \*
- (5) \*V\* - separation "or"
- (6) library of useful functions for separation predicates

## Property classes

Soundness of invariants

Termination or completeness proofs not produced

## Result summary

The work on the examples so far indicate that the approach is promising.

Proof size, invariant size, and Coq verification times are all reasonable.

## Verifying a small tree traversal program

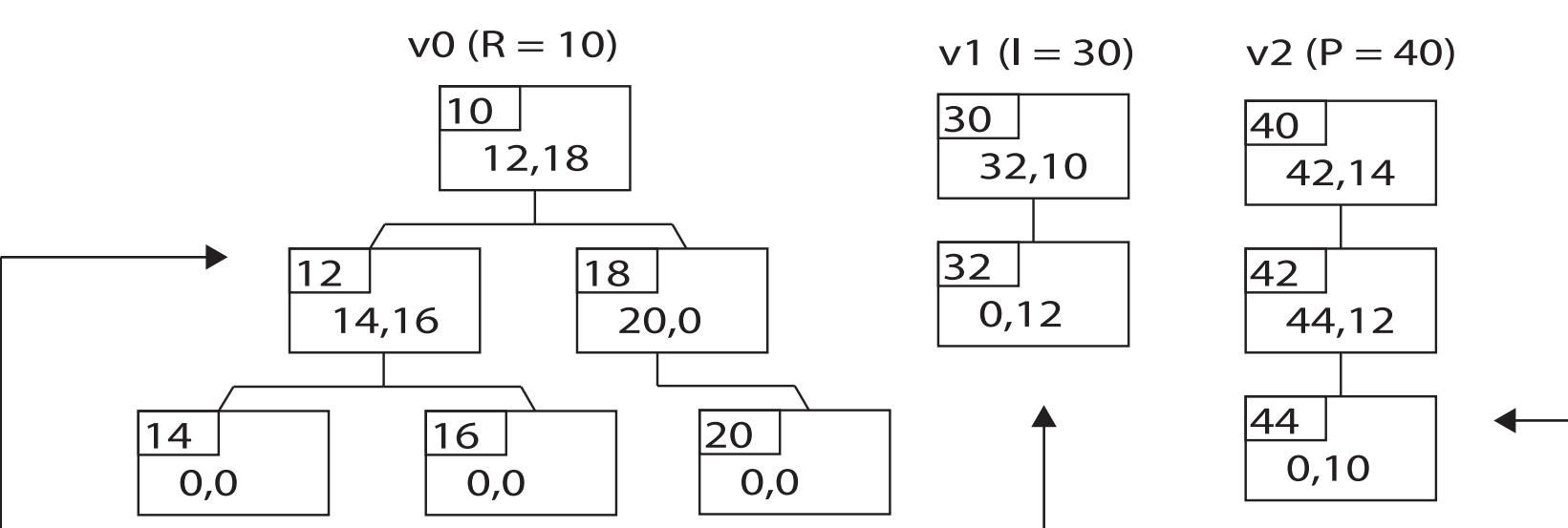
The main function, pre\_order, takes as input a pointer to a tree structure and generates a list which represents a traversal of the tree.

```
struct list {
    struct list *n;
    struct tree *t;
    int data;
};

struct tree {
    struct tree *l;
    int value;
};

struct list *void build_pre_order(struct tree *r) {
    struct list *n = NULL;
    struct list *t = r;
    n = malloc(sizeof(struct list));
    t = r->l;
    p->r = n;
    if (t == NULL) {
        if (t->r == NULL) {
            n->n = p;
            n->t = t->l;
            t->l = n;
            t->r = p;
        }
    }
}
```

## Heap snapshot



## Invariant

- (1) There is a tree and two lists all properly formed--no cycles, no dangling points
- (2) Each of the nodes in the two lists contains a pointer a node in the tree.

## Coq Representation:

```
AbsExists v0.AbsExists v1.AbsExists v2.
TREE(R,v0,2,[0,1])
TREE(l,v1,2,[0])
TREE(P,v2,2,[0])
AbsAll v3 in TreeRecords(v1).
[nth(find(v1,v3),2) inTree v0]
AbsAll v3 in TreeRecords(v2).
[nth(find(v2,v3),2) inTree v0]
[T == 0 V T inTree v0]
```

## Explanation of Coq representation

The three TREE assertions characterize the tree and the two lists of the heap. Parameters:

- (1) the root of the tree
- (2) a variable holding an equivalent functional representation (discussed below);
- (3) the size of a record in words;
- (4) and, a list of offsets for all the child node pointers. The tree needs two such offsets, [0,1] and the lists only need one, [0].

Two AbsAll clauses assert for each list that the pointers in the second field of each node in the list point into the tree.

## Functional Equivalent Representation

Characterize data fields saved, structure of the tree or list and the locations of records on the heap.

Represented by lists whose elements are either naturals or (recursively) lists of lists or naturals.

For the snapshot from the picture above, v0 would for example be the list

[10,([12,[14,[0],[0]], [16,[0],[0]]], ([18,[20,[0],[0]], [0]]])]

## Other Constructs

- (1) TreeRecords is a function that returns the list of record pointers given a functional representation.

\* TreeRecords([12,[14,[0],[0]], [16,[0],[0]]]) returns [12,14,16].  
(2) "x inTree y" is shorthand for "x in TreeRecords(y)"  
(3) find takes an address in a tree and a tree functional representation, and returns the subtree rooted at that address. find(14,[12,[14,[0],[0]], [16,[0],[0]]]) returns [14,[0],[0]].

## Proof excerpt

Goals are Hoare triples of form {{pre}}stmts{{post}}

Proof steps involve the following:

- (1) forward propagating over unit statements
- (2) applying Hoare rules to break up if-then-else, while and statement sequences
- (3) folding or unfolding recursive predicates
- (4) merging two states at the end of an if-then-else
- (5) proving one state implies another state

Theorem loopInvariant : {{afterInitAssigns}}loop{{afterWhile\_NoResult}}.

Proof.

```
(*{AbsExistsT v0 .
(AbsExistsT v1.
(AbsExistsT v2.
(TREE(R, v0, 2, [0,1]) *
TREE(l, v1, 2, [0]) *
TREE(P, v2, 2, [0])) *
AbsAll v3 in TreeRecords(v1). ([nth(find(v1, v3), 2) inTree v0]) *
AbsAll v3 in TreeRecords(v2). ([nth(find(v2, v3), 2) inTree v0]) *
[T == 0 V T inTree v0]))}*)

WHILE not (T == 0)
DO N := P;
NEW P, 2;
*(P + 1) := T;
*P := N;
Tmp_I := *T;
Tmp_r := *(T + 1);
IF (Tmp_I == 0) and (Tmp_r == 0)
THEN IF I == 0 THEN T := *0
ELSE T := *(I + 1);
Tmp_I := *(I + A0); DELETE I, 2; I := Tmp_I
ELSE IF Tmp_I == 0 THEN T := *(T + 1)
ELSE IF Tmp_r == A0 THEN T := *T
ELSE N := I;
I := NEW 2;
*(I + 0) := N;
Tmp_I := *(T + 1);
*(I + 1) := !(ITmp_I); T := 12,13,Additive_dq@Q@P@P3
Allocating clause 42c03980
{AbsExistsT v0 .
(AbsExistsT v1.
(AbsExistsT v2.
(TREE(R, v0, 2, [0,1]) *
TREE(l, v1, 2, [0]) *
TREE(P, v2, 2, [0])) *
AbsAll v3 in TreeRecords(v1).
[nth(find(v1, v3), 2) inTree v0]*
AbsAll v3 in TreeRecords(v2).
[nth(find(v2, v3), 2) inTree v0]*
[T == 0 V T inTree v0]))}*)

(* WHILE not (T == 0) DO *)
apply strengthenPost.
apply while with (invariant := loopInv). unfold loopInv.
apply strengthenPost.
(* N := P; *)
apply compose. (apply basicAssign; prunch).

...  
Forward Propagations
```

```
(* IF (Tmp_I == 0) and (Tmp_r == 0) *)
apply if_statement.
(* IF (I == 0) *)
apply if_statement.
(* T := *0 *)
apply basicAssign; prunch.
* ELSE *
simp. simp. simp. simp.

...  
State Merging
startMerge.
doMergeStates. DMRemoveZeroTree2 (((!)) : absExpBasic).
DMRemoveZeroAll2.
(* Special case where two predicates need to be or'd together *)
apply DMORPredicates1. instantiate (2 := (!)(T) ==# 0).
solveSPickElement.
instantiate (2 := (!)(T) inTree v(3)). solveSPickElement. prunch.
finishMerge.

(* ELSE *)
simp. simp. simp.
(* IF Tmp_I == 0 THEN T := *T *)
apply if_statement. simpl.
simp. simp. simp.
(* T := *(T + 1) *)
load_traverse.
(* ELSE *)
...  
Forward Propagation
```

## Statistics

Code size: ~30 lines  
Invariant size: ~10 lines  
Proof check time: ~5 minutes  
Main proof size: ~220 lines

## Status

Top level proof complete  
Many lemmas need to be proven

## Verifying the DPLL algorithm

Efficient SAT solving algorithm for CNF expressions such as:

(A v ~B v C) ^  
(A v ~C v D)

DPLL algorithm:

- (1) Choose a variable and assign it a value
- (2) Perform unit propagation to find additional assignments by the choices already made.
- (3) Backtrack and change choices when a contradiction is found

## Watch variables

- (1) Makes unit propagation very efficient
- (2) Two unassigned variables chosen at random
- (3) If a watch variable in a clause is assigned, then choose a replacement. If one cannot be found, then there is only one assigned variable left and a unit propagation needs to be performed.

Blue variables in the example above are initial watch variables  
After A is assigned false, we move the watch that was on A in the two clauses to C and D respectively (the brown variables).

Our C program uses the following data structures to store the clauses, the watch variable linked lists, the assignments and a "todo" queue.:.

#define VAR\_COUNT 4

char assignments[VAR\_COUNT];

struct clause {
 struct clause \*next;
 char positive\_int[VAR\_COUNT];
 char negative\_int[VAR\_COUNT];
 char watch\_var[VAR\_COUNT];
 struct clause \*watch\_next[VAR\_COUNT];
 struct clause \*watch\_prev[VAR\_COUNT];
};  
\* clauses;

struct clause \*watches[VAR\_COUNT];

struct assignments\_to\_do {
 struct assignments\_to\_do \*next, \*prev;
 int var;
 char value;
 int unit\_prop;
};  
\* assignments\_to\_do\_head, \*assignments\_to\_do\_tail;

struct assignment\_stack {
 struct assignment\_stack \*next;
 int var;
 char value;
 char unit\_prop;
};  
\* stack;

Here is a diagram showing what the data structures look like right after A is assigned false.

assignments\_to\_do\_head=nil  
assignments\_to\_do\_tail=nil

assignments [0 (A)] 2 (True) 1 (B) 0 2 (C) 0 3 (D) 0

stack next 0 (nil) var 0 (A) value 2 (True) unit\_prop 0 (no)

watches [0 (A)] 0 (nil) 1 (B) 2 (C) 3 (D) 0

clauses next positive\_int[0] positive\_int[1] positive\_int[2] positive\_int[3]

negative\_int[0] negative\_int[1] negative\_int[2] negative\_int[3]

watch\_var[0] 1 watch\_var[1] 1 watch\_var[2] 0 watch\_var[3] 0

watch\_next[0] 0 (nil) watch\_next[1] 0 (nil) watch\_next[2] 0 (nil) watch\_next[3] 0 (nil)

watch\_prev[0] 0 (nil) watch\_prev[1] 0 (nil) watch\_prev[2] 0 (nil) watch\_prev[3] 0 (nil)

positive\_int[0] 0 (D) negative\_int[0] 0 (D) negative\_int[1] 0 (D) negative\_int[2] 0 (D) negative\_int[3] 0 (D)

negative\_int[0] 0 (A) negative\_int[1] 0 (A) negative\_int[2] 0 (C) negative\_int[3] 0 (D)

watch\_var[0] 1 watch\_var[1] 1 watch\_var[2] 0 watch\_var[3] 0

watch\_next[0] 0 (nil) watch\_next[1] 0 (nil) watch\_next[2] 0 (nil) watch\_next[3] 0 (nil)

watch\_prev[0] 0 (nil) watch\_prev[1] 0 (nil) watch\_prev[2] 0 (nil) watch\_prev[3] 0 (nil)

positive\_int[1] 0 (B) positive\_int[2] 0 (C) positive\_int[3] 0 (D)

negative\_int[0] 0 (A) negative\_int[1] 0 (A) negative\_int[2] 0 (C) negative\_int[3] 0 (D)

watch\_var[0] 1 watch\_var[1] 1 watch\_var[2] 0 watch\_var[3] 0

watch\_next[0] 0 (nil) watch\_next[1] 0 (nil) watch\_next[2] 0 (nil) watch\_next[3] 0 (nil)

watch\_prev[0] 0 (nil) watch\_prev[1] 0 (nil) watch\_prev[2] 0 (nil) watch\_prev[3] 0 (nil)

positive\_int[2] 0 (C) positive\_int[3] 0 (D)

negative\_int[0] 0 (A) negative\_int[1] 0 (A) negative\_int[2] 0 (C) negative\_int[3] 0 (D)

watch\_var[0] 1 watch\_var[1] 1 watch\_var[2] 0 watch\_var[3] 0

watch\_next[0] 0 (nil) watch\_next[1] 0 (nil) watch\_next[2] 0 (nil) watch\_next[3] 0 (nil)

watch\_prev[0] 0 (nil) watch\_prev[1] 0 (nil) watch\_prev[2] 0 (nil) watch\_prev[3] 0 (nil)

positive\_int[3] 0 (D)

negative\_int[0] 0 (A) negative\_int[1] 0 (A) negative\_int[2] 0 (C) negative\_int[3] 0 (D)

watch\_var[0] 1 watch\_var[1] 1 watch\_var[2] 0 watch\_var[3] 0

watch\_next[0] 0 (nil) watch\_next[1] 0 (nil) watch\_next[2] 0 (nil) watch\_next[3] 0 (nil)

watch\_prev[0] 0 (nil) watch\_prev[1] 0 (nil) watch\_prev[2] 0 (nil) watch\_prev[3] 0 (nil)

positive\_int[1] 0 (B) positive\_int[2] 0 (C) positive\_int[3] 0 (D)

negative\_int[0] 0 (A) negative\_int[1] 0 (