Final Exam

600.435 Artificial Intelligence Spring 2017

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Instructions

- Please be sure to write both your name and section in the space above!
- Please be sure to read through the entire exam before you start, and be mindful of the time. If one question is taking too long, it may be worth moving on and coming back to the problem question(s) after the rest of the exam is complete.
- Remember that you are only allowed one sheet (both sides) of notes, everything else besides that and the test itself must be off of your workspace.
- Please show ALL relevant work for your answers and provide explanations when prompted. Failure to do either will result in loss of credit.
- You will have until 5pm to complete this test.

1. (8 points) Consider a self-driving car as an intelligent agent. Name two items for each of the PEAS elements.

• Performance measures:

• Environment:

• Actuators:

speed to read goal accident avoidance traffic (other acr) voad

Motor (accident)

Steem 3

• Sensors:

speedometr causes GPS lider

2. (5 points) Consider a computer program that is playing **online poker**. Is the environment of this intelligent agent ...

• Fully observable?

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• Deterministic?

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• Static?

• Discrete?

In which of these categories is a **Go playing program** different?

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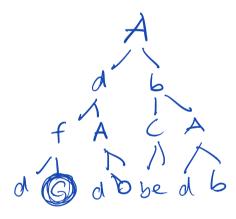
Just provide a yes/no answer to each of these questions.

Basic Search 10 points

In the following grid, we want to find the fastest path from A to G. We may move from every cell to each directly neighboring cell (up, down, left, right). The cell in the center of the grid is unreachable.

A	b	c
d		e
f	G	h

- 3. (7 points) Draw the full search tree of breadth-first search that explores this grid.
 - Note that search may return to already visited cells.
 - The search graph must include all leaf nodes at maximum depth.



- 4. (3 points) If we use depth-first search and move
 - up, whenever possible
 - right, whenever possible (and up is not possible)
 - down, whenever possible (and up and right is not possible)
 - left, otherwise

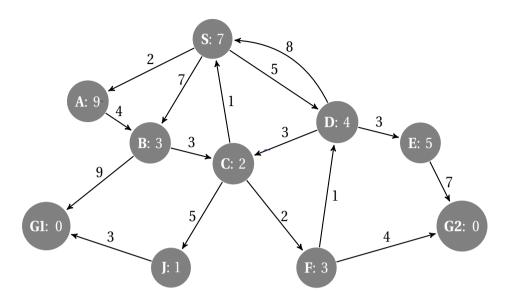
Again, search may return to already visited cells.

Will depth-first succeed? If yes, in how many steps? If no, why not?

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Informed Search 10 points

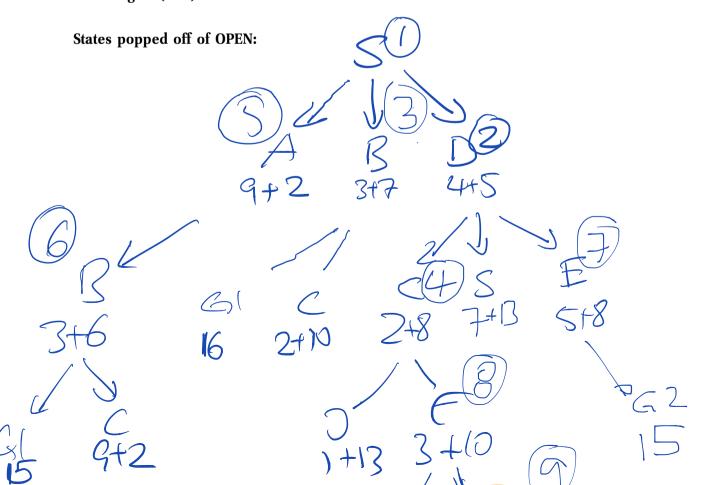
Consider the search space below, where **S** is the start node and **G1** and **G2** satisfy the goal test. Arcs are labeled with the cost of traversing them and the heuristic cost to a goal is reported inside nodes (so lower scores are better).



5. (10 points) For A* search, indicate which goal state is reached at what cost and list, in order, all the states popped off of the OPEN list. You use a search graph to show your work.

Note: When all else is equal, nodes should be removed from OPEN in alphabetical order.

Path to goal (cost):



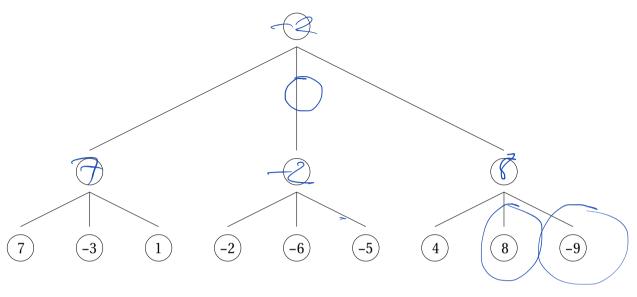
Game Playing



12 points

Apply the *mini-max* algorithm to the partial game tree below, where it is the **minimizer's** turn to play and the game does *not* involve randomness. The values estimated by the static-board evaluator (SBE) are indicated in the leaf nodes (higher scores are better for the maximizer).

Process this game tree working left-to-right.



- 6. (5 points) Write the estimated values of the intermediate nodes inside their circles.
- 7. (2 points) Indicate the proper move of the minimizer by circling one of the root's outgoing arcs.
- 8. (5 points) **Circle** each leaf node (if any) whose SBE score does not need to be consulted. Briefly explain why:

5=4 after vinhay 4 node byt x is already -2 9. (5 points) Convert the following sentence into first-order predicate calculus logic:

There is a lacrosse player who has played in every game this season.

=> Lacross Player (x) 1

fy Game (y) 1 This Season (4) => Played (x, y)

10. (10 points) Given the following propositional-logic clauses, show E must be true by adding $\neg E$ and using only the **resolution inference rule** to derive a contradiction.

Use the notation presented in class (and in the book) where the resulting clause is connected by lines to the two clauses resolved.

- $A \vee \neg C$
- B ∨ ¬A
- B ∨ ¬D
- $\bullet \ \ E \vee \neg A \vee \neg B$
- C
- ¬D

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Probabilistic Reasoning

11. (5 points) Suppose we roll a die 2 times. What is the probability that the sum of the numbers is 3?

36 possible events

12. (5 points) In the general population, 0.1% have the disease X.

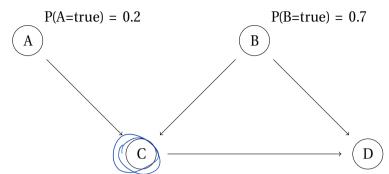
Doctors developed a test with the following properties:

- If a person has the disease, the test detects it 90% of the time, and fails to detect it in 10% of the time.
- If a person *does not* have the disease, the test gives false positive indication 10% of the time, and a correct negative indication 90% of the time.

What is the probability that a random person who receives a positive test result, does indeed have the disease (round numbers when appropriate)?

P(T|D) = 0.9 P(T(-D) = 0.1 P(T(D) P(D)) = P(T(D) P(D) = P(T(D) P(D)) = P(T(D) P(D) + P(T(D)) P(D) $= .9 \times .001$ $= .9 \times .001$ $= .9 \times .001$ $= .9 \times .001$ $= .9 \times .001$

Consider the following Bayesian Network, where variables A-D are all Boolean valued (when answering the questions be sure to show your work, if a computation gets too convoluted it's fine just state terms with numbers):



A	В	P(C=true A,B)
false	false	0.2
false	true	0.3
true	false	0.1
true	true	0.6

В	C	P(D=true B,C)
false	false	0.9
false	true	0.8
true	false	0.4
true	true	0.3

13. (5 points) What is the probability that *all four* of these Boolean variables are false?

P(A) P(B) P(-C/A), P(D/B, -C) .8x.3 x.8 x.1 = .0192

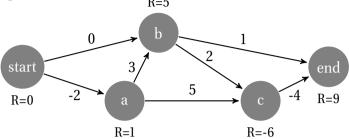
14. (5 points) What is the probability that **A** is true, **C** is true and **D** is false?

p(A,C,D) = p(A,B,C,D)+p(A,B,C,D)

15. (5 points) What is the probability that A is true given that C is thue and D is false?

Reinforcement Learning

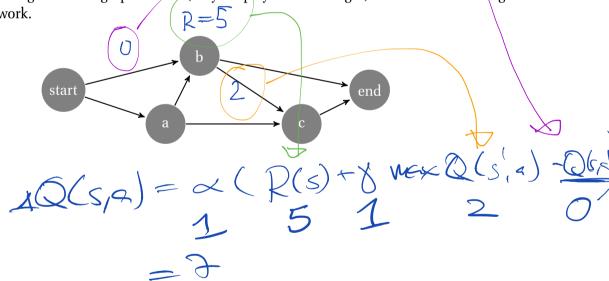
Consider the *deterministic* reinforcement environment drawn below, where the current state of the Q table is indicated on the arcs. Let $\gamma=1$. *Immediate* rewards are indicated inside nodes. Once the agent reaches the **end** state the current episode ends.



16. (5 points) Assuming our RL agent exploits its policy (with learning turned off), what is the path it will take from start to end? Briefly explain your answer.



17. (5 points) Assuming the RL agent is using one-step Q learning and moves from node **start** to node **b**. Report below the changes to the graph above (only display what changes). Assume a learning rate of $\alpha = 1$. Show your work.



18. (5 points) Show the final state of the Q table after a very large number of training episodes (i.e., show the Q table where the Bellman Equation is satisfied everywhere). No need to show your work nor explain your answer.

