

# Geometry Processing (601.458/658)

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# Outline

Recall

The Hat Basis on a Triangle

# Recall

Integration by parts:

Given functions  $f, g: \mathbb{R} \rightarrow \mathbb{R}$ , the derivative of their product is:

$$(f \cdot g)' = f' \cdot g + f \cdot g'$$

Taking the integral of the derivative:

$$f \cdot g = \int (f \cdot g)' = \int (f' \cdot g + f \cdot g')$$

This gives:

$$\int f' \cdot g = f \cdot g - \int f \cdot g'$$

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# Recall

Consider the polynomial  $P_{m,n}(x) = (1 - x)^m \cdot x^n$ :

Setting  $f(x) = (1 - x)^m$  and  $g(x) = x^n$ , integration by parts gives:

$$\begin{aligned} \int_0^1 P_{m,n}(x) \cdot dx &= \int_0^1 (1 - x)^m \cdot x^n \cdot dx \\ &= \left[ \frac{-1}{m+1} (1 - x)^{m+1} \cdot x^n \right]_{x=0}^{x=1} - \int_0^1 \frac{-n}{m+1} (1 - x)^{m+1} \cdot x^{n-1} \cdot dx \\ &= \frac{n}{m+1} \int_0^1 P_{m+1,n-1}(x) \cdot dx \\ &= \frac{n \cdot (n-1)}{(m+1) \cdot (m+2)} \int_0^1 P_{m+2,n-2}(x) \cdot dx \\ &\quad \vdots \\ &= \frac{n! \cdot m!}{(m+n)!} \int_0^1 P_{m+n,0}(x) \cdot dx \end{aligned}$$

$$\int f' \cdot g = f \cdot g - \int f \cdot g'$$

# Recall

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Setting  $f(x) = (1 - x)^m$  and  $g(x) = x^n$ , integration by parts gives:

$$\begin{aligned} \int_0^1 P_{m,n}(x) \cdot dx &= \frac{n! \cdot m!}{(m+n)!} \int_0^1 P_{m+n,0}(x) \cdot dx \\ &= \frac{n! \cdot m!}{(m+n)!} \int_0^1 (1-x)^{m+n} \cdot dx \\ &= \frac{n! \cdot m!}{(m+n)!} \cdot \left[ \frac{-1}{m+n+1} (1-x)^{m+n+1} \right]_{x=0}^{x=1} \\ &= \frac{n! \cdot m!}{(m+n+1)!} \end{aligned}$$

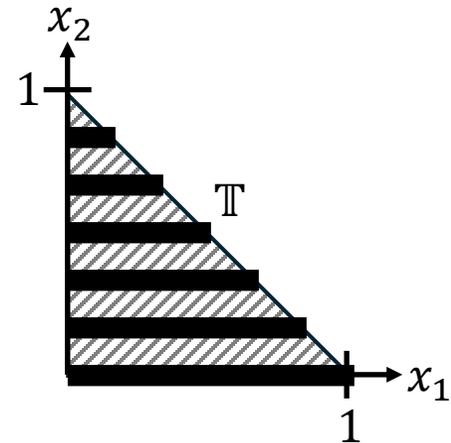
# Recall

$$\int_0^1 (1-x)^m \cdot x^n = \frac{n! \cdot m!}{(m+n+1)!}$$

Consider the monomial in two variables  $P_{m,n}(x_1, x_2) = x_1^m \cdot x_2^n$ :

The integral of  $P_{m,n}$  over the unit right triangle (w.r.t. the Euclidean metric) is:

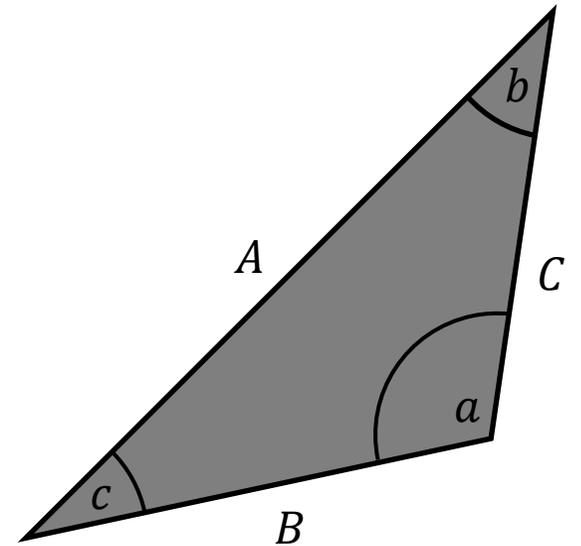
$$\begin{aligned} \int_{\mathbb{T}} x_1^m \cdot x_2^n \cdot dx_1 \wedge dx_2 &= \int_0^1 \int_0^{1-x_2} x_1^m \cdot x_2^n \cdot dx_1 \wedge dx_2 \\ &= \int_0^1 \left[ \int_0^{1-x_2} x_1^m \cdot dx_1 \right] \cdot x_2^n \wedge dx_2 \\ &= \int_0^1 \left[ \frac{1}{m+1} x_1^{m+1} \right]_{x_1=0}^{x_1=1-x_2} \cdot x_2^n \cdot dx_2 \\ &= \frac{1}{m+1} \int_0^1 (1-x_2)^{m+1} \cdot x_2^n \cdot dx_2 \\ &= \frac{1}{m+1} \cdot \frac{n! \cdot (m+1)!}{(m+n+2)!} \\ &= \frac{n! \cdot m!}{(m+n+2)!} \end{aligned}$$



# Recall

Given a triangle with angles  $a$ ,  $b$ , and  $c$ , and opposite sides  $A$ ,  $B$ , and  $C$ , the ratios of the sines of the angles and the lengths of the opposite edges are equal:

$$\frac{\sin(a)}{\sin(b)} = \frac{A}{B} \quad \frac{\sin(b)}{\sin(c)} = \frac{B}{C} \quad \frac{\sin(c)}{\sin(a)} = \frac{C}{A}$$



# Recall

We denote by  $\mathbb{T} \subset \mathbb{E}^2$  the unit right triangle:

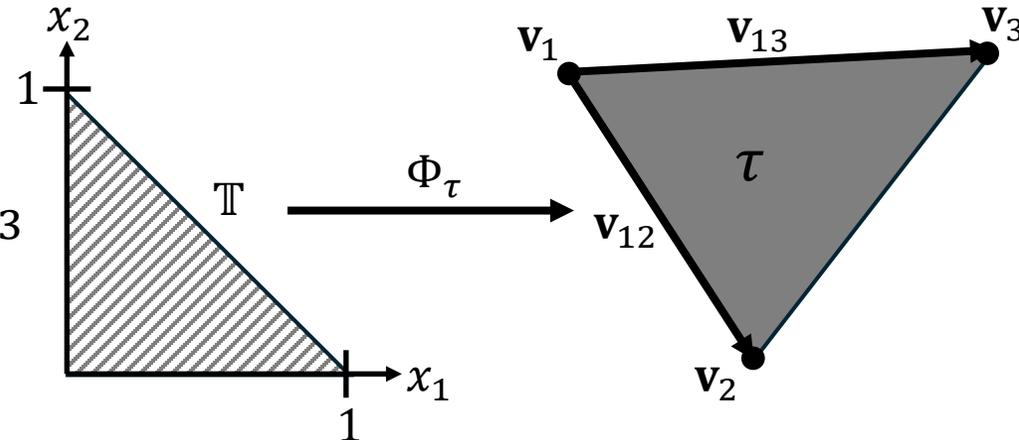
$$\mathbb{T} = \{(x_1, x_2) \in [0,1]^2 \mid x_1 + x_2 \leq 1\}$$

Given a triangle  $\tau \subset \mathbb{E}^3$  with vertices  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3 \in \mathbb{E}^3$ , we parameterize the triangle over the unit-right triangle as:

$$\Phi_\tau(x_1, x_2) = \mathbf{v}_1 + x_1 \cdot (\mathbf{v}_2 - \mathbf{v}_1) + x_2 \cdot (\mathbf{v}_3 - \mathbf{v}_1)$$

Denoting by  $\mathbf{v}_{ij} = \mathbf{v}_j - \mathbf{v}_i$  the direction from vertex  $\mathbf{v}_i$  to vertex  $\mathbf{v}_j$ :

$$\Phi_\tau(x_1, x_2) = \mathbf{v}_1 + x_1 \cdot \mathbf{v}_{12} + x_2 \cdot \mathbf{v}_{13}$$

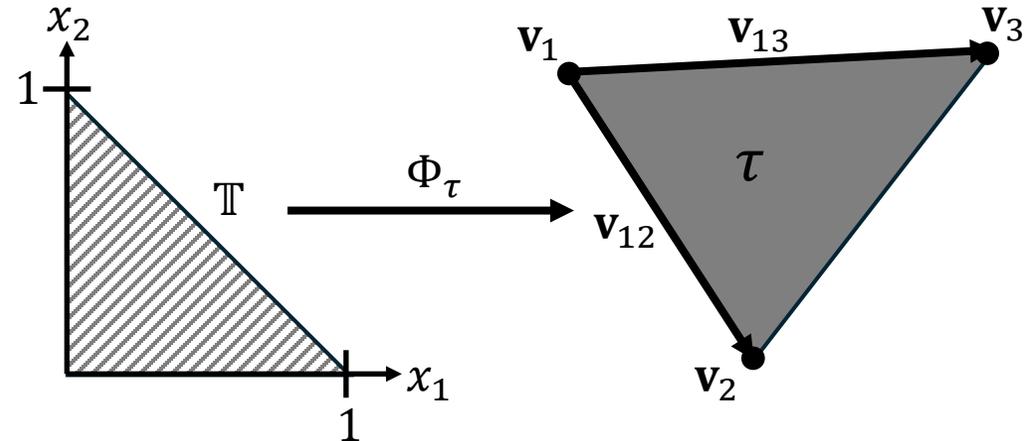


# Recall

$$\Phi_\tau(x_1, x_2) = \mathbf{v}_1 + x_1 \cdot \mathbf{v}_{12} + x_2 \cdot \mathbf{v}_{13}$$

For  $\mathbf{p} \in \mathbb{T}$ , the differential  $\mathbf{d}\Phi_\tau|_{\mathbf{p}} \in \mathbb{R}^{3 \times 2}$  is the matrix whose columns are the differences:

$$\mathbf{d}\Phi_\tau|_{\mathbf{p}} = (\mathbf{v}_{12} \quad \mathbf{v}_{13})$$



# Recall

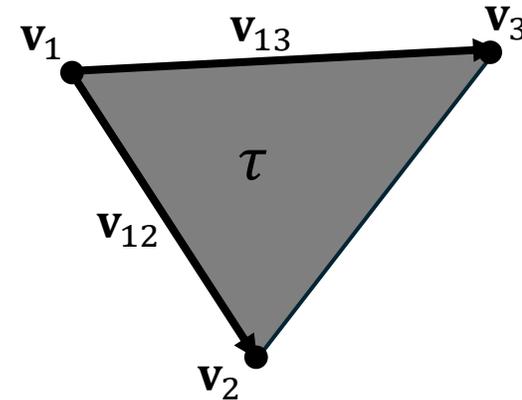
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$$\mathbf{d}\Phi_\tau|_{\mathbf{p}} = (\mathbf{v}_{12} \quad \mathbf{v}_{13})$$

The pulled-back inner-product, expressed in matrix form w.r.t. the cartesian basis  $\{\partial_1|_{\mathbf{p}}, \partial_2|_{\mathbf{p}}\} \subset T_{\mathbf{p}}\mathbb{T}$  is:

$$\begin{aligned} \mathbf{g}_\tau &= \mathbf{d}\Phi_\tau|_{\mathbf{p}}^\top \cdot \mathbf{d}\Phi_\tau|_{\mathbf{p}} = \begin{pmatrix} \langle \mathbf{v}_{12}, \mathbf{v}_{12} \rangle & \langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle \\ \langle \mathbf{v}_{13}, \mathbf{v}_{12} \rangle & \langle \mathbf{v}_{13}, \mathbf{v}_{13} \rangle \end{pmatrix} \\ &= \begin{pmatrix} \|\mathbf{v}_{12}\|^2 & \langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle \\ \langle \mathbf{v}_{13}, \mathbf{v}_{12} \rangle & \|\mathbf{v}_{13}\|^2 \end{pmatrix} \end{aligned}$$



# Recall

Given a triangle  $\tau \subset \mathbb{R}^n$ , we define the inner-product on the space of real-valued functions on  $\tau$  is:

$$\langle\langle f, h \rangle\rangle_{g_\tau} = \sqrt{\det(\mathbf{g}_\tau)} \cdot \langle\langle f, h \rangle\rangle_E$$

And the Dirichlet energy is defined as:

$$\begin{aligned} E_D(f) &= \langle\langle df, df \rangle\rangle_{g_\tau} \\ &= \left\langle \sqrt{\det(\mathbf{g}_\tau)} \cdot \mathbf{g}_\tau^{-1}, \int_{\mathbb{T}} \mathbf{d}f \cdot \mathbf{d}f^\top \cdot \omega_E \right\rangle_F \end{aligned}$$

with  $\omega_E$  the unit-volume form with respect to the Euclidean inner-product.

# Outline

Recall

The Hat Basis on a Triangle

# Notation

Often, we define the inner-product on the tangent space by pulling back the inner-product from an embedded surfaces.

We will subscript the inner-product on the space of functions and differentials with the geometry for brevity:

$$\begin{aligned}\langle\langle f, h \rangle\rangle_{g_\tau} &\leftrightarrow \langle\langle f, h \rangle\rangle_\tau \\ \langle\langle df, dh \rangle\rangle_{g_\tau} &\leftrightarrow \langle\langle df, dh \rangle\rangle_\tau\end{aligned}$$

# The Hat Basis

Definition:

We say that a function  $f$  on  $\mathbb{T}$  is a *scalar field* if for all  $\mathbf{p} \in \mathbb{T}$ :

$$f(\mathbf{p}) \in \mathbb{R}$$

# The Hat Basis

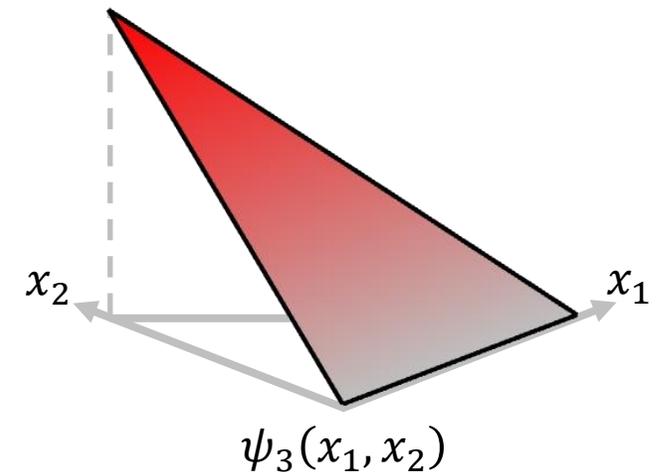
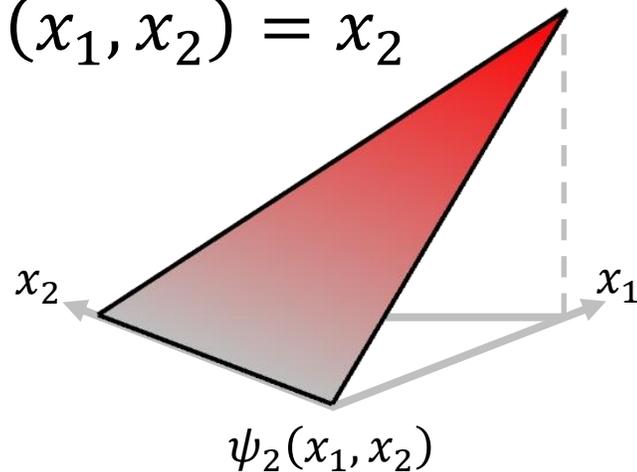
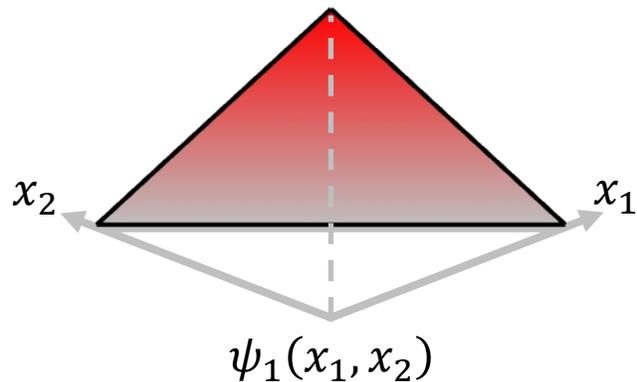
As we cannot work with all functions on the triangle, we restrict ourselves to those we can represent using a finite basis.

A standard basis is the “hat” basis, consisting of:

$$\psi_1(x_1, x_2) = 1 - x_1 - x_2$$

$$\psi_2(x_1, x_2) = x_1$$

$$\psi_3(x_1, x_2) = x_2$$



$$\begin{aligned}\psi_1(x_1, x_2) &= 1 - x_1 - x_2 \\ \psi_2(x_1, x_2) &= x_1 \\ \psi_3(x_1, x_2) &= x_2\end{aligned}$$

# The Hat Basis

Properties:

**Partition of unity:** The functions sum to one:

$$\psi_1(x_1, x_2) + \psi_2(x_1, x_2) + \psi_3(x_1, x_2) = 1$$

**Lagrange property:** The functions interpolate the vertex values:

$$\begin{aligned}\psi_1(0,0) &= \psi_2(1,0) = \psi_3(0,1) = 1 \\ \psi_2(0,0) &= \psi_3(0,0) = \psi_1(1,0) = \psi_3(1,0) = \psi_1(0,1) = \psi_2(0,1) = 0\end{aligned}$$

↓

**Linear reproduction:** Any linear polynomial  $f: \mathbb{T} \rightarrow \mathbb{R}$  is expressed as:

$$f = f(0,0) \cdot \psi_0 + f(1,0) \cdot \psi_1 + f(0,1) \cdot \psi_2$$

$$\begin{aligned}\psi_1(x_1, x_2) &= 1 - x_1 - x_2 \\ \psi_2(x_1, x_2) &= x_1 \\ \psi_3(x_1, x_2) &= x_2\end{aligned}$$

# The Hat Basis

Questions:

Given functions:

$$f(x_1, x_2) = \mathbf{f}_1 \cdot \psi_1(x_1, x_2) + \mathbf{f}_2 \cdot \psi_2(x_1, x_2) + \mathbf{f}_3 \cdot \psi_3(x_1, x_2)$$

$$h(x_1, x_2) = \mathbf{h}_1 \cdot \psi_1(x_1, x_2) + \mathbf{h}_2 \cdot \psi_2(x_1, x_2) + \mathbf{h}_3 \cdot \psi_3(x_1, x_2)$$

what is the inner-product of  $f$  and  $h$ ?

Given a function:

$$f(x_1, x_2) = \mathbf{f}_1 \cdot \psi_1(x_1, x_2) + \mathbf{f}_2 \cdot \psi_2(x_1, x_2) + \mathbf{f}_3 \cdot \psi_3(x_1, x_2)$$

what is the Dirichlet energy of  $f$ ?

$$f(x_1, x_2) = \mathbf{f}_1 \cdot \psi_1(x_1, x_2) + \mathbf{f}_2 \cdot \psi_2(x_1, x_2) + \mathbf{f}_3 \cdot \psi_3(x_1, x_2)$$

$$h(x_1, x_2) = \mathbf{h}_1 \cdot \psi_1(x_1, x_2) + \mathbf{h}_2 \cdot \psi_2(x_1, x_2) + \mathbf{h}_3 \cdot \psi_3(x_1, x_2)$$

# The Hat Basis: Inner Product

The inner-product is:

$$\langle\langle f, h \rangle\rangle_\tau = \sqrt{\det(\mathbf{g}_\tau)} \cdot \langle\langle f, h \rangle\rangle_{\mathbb{E}^2}$$

Expanding the second term gives:

$$\langle\langle f, h \rangle\rangle_{\mathbb{E}^2} = \left\langle\left\langle \sum_{i=1}^3 \mathbf{f}_i \cdot \psi_i, \sum_{j=1}^3 \mathbf{h}_j \cdot \psi_j \right\rangle\right\rangle_{\mathbb{E}^2}$$

$$= \sum_{i,j=1}^3 \mathbf{f}_i \cdot \mathbf{h}_j \cdot \langle\langle \psi_i, \psi_j \rangle\rangle_{\mathbb{E}^2}$$

$$\begin{aligned} f(x_1, x_2) &= \mathbf{f}_1 \cdot \psi_1(x_1, x_2) + \mathbf{f}_2 \cdot \psi_2(x_1, x_2) + \mathbf{f}_3 \cdot \psi_3(x_1, x_2) \\ h(x_1, x_2) &= \mathbf{h}_1 \cdot \psi_1(x_1, x_2) + \mathbf{h}_2 \cdot \psi_2(x_1, x_2) + \mathbf{h}_3 \cdot \psi_3(x_1, x_2) \end{aligned}$$

# The Hat Basis: Inner Product

The inner-product is:

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Expanding the second term gives:

$$\langle\langle f, h \rangle\rangle_{\mathbb{E}^2} = \sum_{i,j=1}^3 \mathbf{f}_i \cdot \mathbf{h}_j \cdot \langle\langle \psi_i, \psi_j \rangle\rangle_\mathbb{T}$$

Setting  $\mathbf{m}^\tau \in \mathbb{R}^{3 \times 3}$  to be the triangle's *mass matrix*:

$$\begin{aligned} \mathbf{m}_{ij}^\tau &= \sqrt{\det(\mathbf{g}_\tau)} \cdot \langle\langle \psi_i, \psi_j \rangle\rangle_\mathbb{T} \\ &\Downarrow \\ \langle\langle f, h \rangle\rangle_\tau &= \mathbf{f}^\top \cdot \mathbf{m}^\tau \cdot \mathbf{h} \end{aligned}$$

# The Hat Basis: Inner Product

$$\mathbf{m}_{ij}^\tau = \sqrt{\det(\mathbf{g}_\tau)} \cdot \langle\langle \psi_i, \psi_j \rangle\rangle_{\mathbb{T}}$$
$$\psi_1(x_1, x_2) = 1 - x_1 - x_2$$
$$\psi_2(x_1, x_2) = x_1$$
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$$\langle\langle f, h \rangle\rangle_\tau = \mathbf{f}^\top \cdot \mathbf{m}^\tau \cdot \mathbf{h}$$

⇒ If we can integrate the product of the hat functions **over the unit right triangle**, computing the inner-product of functions expressed in the hat basis w.r.t. to the pull-back metric  $g_\tau$  is not hard.

The value of  $\langle\langle \psi_i, \psi_j \rangle\rangle_{\mathbb{T}}$  is independent of the inner-product  $g_\tau$ .

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It can be computed once in a pre-processing step.

# The Hat Basis: Inner Product

$$\mathbf{m}_{ij}^\tau = \sqrt{\det(\mathbf{g}_\tau)} \cdot \langle\langle \psi_i, \psi_j \rangle\rangle_{\mathbb{T}}$$

$$\psi_1(x_1, x_2) = 1 - x_1 - x_2$$

$$\psi_2(x_1, x_2) = x_1$$

$$\psi_3(x_1, x_2) = x_2$$

Example:

$$\begin{aligned} \langle\langle \psi_2, \psi_3 \rangle\rangle_{\mathbb{T}} &= \int_{\mathbb{T}} x_1 \cdot x_2 \cdot dx_1 \wedge dx_2 \\ &= \frac{1}{4!} \\ &= \frac{1}{24} \end{aligned}$$

$$\int_{\mathbb{T}} x_1^m \cdot x_2^n \cdot dx_1 \wedge dx_2 = \frac{n! \cdot m!}{(m+n+2)!}$$

You'll need to work this out for the other pairs.

$$f(x_1, x_2) = \mathbf{f}_1 \cdot \psi_1(x_1, x_2) + \mathbf{f}_2 \cdot \psi_2(x_1, x_2) + \mathbf{f}_3 \cdot \psi_3(x_1, x_2)$$

# The Hat Basis: Dirichlet Energy

The Dirichlet energy is defined as:

$$E_D(f) = \langle\langle df, df \rangle\rangle_\tau = \left\langle \sqrt{\det(\mathbf{g}_\tau)} \cdot \mathbf{g}_\tau^{-1}, \int_{\mathbb{T}} \mathbf{d}f \cdot \mathbf{d}f^\top \cdot \omega_E \right\rangle_F$$

Expanding the second term gives:

$$\begin{aligned} \int_{\mathbb{T}} \mathbf{d}f \cdot \mathbf{d}f^\top \cdot \omega_E &= \int_{\mathbb{T}} \left( \mathbf{d} \left( \sum_{i=1}^3 \mathbf{f}_i \cdot \psi_i \right) \right) \cdot \left( \mathbf{d} \left( \sum_{j=1}^3 \mathbf{f}_j \cdot \psi_j \right) \right)^\top \cdot \omega_E \\ &= \int_{\mathbb{T}} \sum_{i,j=1}^3 \mathbf{f}_i \cdot \mathbf{f}_j \cdot \mathbf{d}\psi_i \cdot \mathbf{d}\psi_j^\top \cdot \omega_E \\ &= \sum_{i,j=1}^3 \mathbf{f}_i \cdot \mathbf{f}_j \cdot \int_{\mathbb{T}} \mathbf{d}\psi_i \cdot \mathbf{d}\psi_j^\top \cdot \omega_E \end{aligned}$$

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Setting  $\mathbf{d}^{ij} \in \mathbb{R}^{2 \times 2}$  to be the integrated outer-product of derivatives:

$$\mathbf{d}^{ij} = \int_{\mathbb{T}} \mathbf{d}\psi_i \cdot \mathbf{d}\psi_j^\top \cdot \omega_E$$

↓

$$E_D(f) = \left\langle \sqrt{\det(\mathbf{g}_\tau)} \cdot \mathbf{g}_\tau^{-1}, \sum_{i,j=1}^3 \mathbf{f}_i \cdot \mathbf{f}_j \cdot \mathbf{d}^{ij} \right\rangle_F$$

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# The Hat Basis: Dirichlet Energy

$$\mathbf{d}^{ij} = \int_{\mathbb{T}} \mathbf{d}\psi_i \cdot \mathbf{d}\psi_j^\top \cdot \omega_E$$

With respect to  $\mathbf{d}^{ij} \in \mathbb{R}^{2 \times 2}$ , the Dirichlet energy becomes:

$$\begin{aligned} E_D(f) &= \left\langle \sqrt{\det(\mathbf{g}_\tau)} \cdot \mathbf{g}_\tau^{-1}, \sum_{i,j=1}^3 \mathbf{f}_i \cdot \mathbf{f}_j \cdot \mathbf{d}^{ij} \right\rangle_F \\ &= \sum_{i,j=1}^3 \mathbf{f}_i \cdot \mathbf{f}_j \cdot \left\langle \sqrt{\det(\mathbf{g}_\tau)} \cdot \mathbf{g}_\tau^{-1}, \mathbf{d}^{ij} \right\rangle_F \end{aligned}$$

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# The Hat Basis: Dirichlet Energy

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Setting  $\mathbf{s}^\tau \in \mathbb{R}^{3 \times 3}$  to be the *stiffness matrix*:

$$\mathbf{s}_{ij}^\tau = \left\langle \sqrt{\det(\mathbf{g}_\tau)} \cdot \mathbf{g}_\tau^{-1}, \mathbf{d}^{ij} \right\rangle_F$$

↓

$$E_D(f) = \mathbf{f}^\top \cdot \mathbf{s}^\tau \cdot \mathbf{f}$$

# The Hat Basis: Dirichlet Product

$$\mathbf{s}_{ij}^\tau = \left\langle \sqrt{\det(\mathbf{g}_\tau)} \cdot \mathbf{g}_\tau^{-1} \mathbf{d}^{ij} \right\rangle_F$$
$$\mathbf{d}^{ij} = \int_{\mathbb{T}} \mathbf{d}\psi_i \cdot \mathbf{d}\psi_j^\top \cdot \omega_E$$

$$E_D(f) = \mathbf{f}^\top \cdot \mathbf{s}^\tau \cdot \mathbf{f}$$

⇒ If we can integrate the product of the partial derivatives of the hat functions **over the unit right triangle**, computing the Dirichlet energy of functions expressed in the hat basis w.r.t. to the pull-back metric  $g_\tau$  is not hard.

The matrices  $\mathbf{d}^{ij}$  are independent of the inner-product  $g_\tau$ .

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⇓

Can be computed once in a pre-processing step.

# The Hat Basis: Dirichlet Product

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$$\int_{\mathbb{T}} x_1^m \cdot x_2^n \cdot dx_1 \wedge dx_2 = \frac{n! \cdot m!}{(m+n+2)!}$$

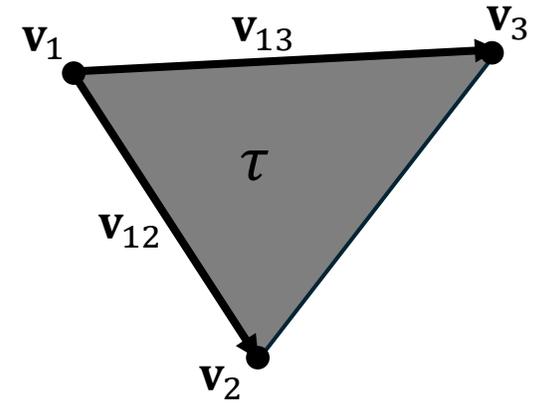
$$\begin{aligned} \mathbf{d}^{23} &= \int_{\mathbb{T}} \mathbf{d}\psi_2 \cdot \mathbf{d}\psi_3^\top \cdot dx_1 \wedge dx_2 \\ &= \int_{\mathbb{T}} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix}^\top \cdot dx_1 \wedge dx_2 \\ &= \int_{\mathbb{T}} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cdot (0 \quad 1) \cdot dx_1 \wedge dx_2 \\ &= \int_{\mathbb{T}} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \cdot dx_1 \wedge dx_2 \\ &= \begin{pmatrix} 0 & 0 \\ 0 & 1/2 \end{pmatrix} \end{aligned}$$

You'll need to work this out for the other pairs.

# The Hat Basis

$$\mathbf{m}_{ij}^{\tau} = \sqrt{\det(\mathbf{g}_{\tau})} \cdot \langle \langle \psi_i, \psi_j \rangle \rangle_E$$
$$\mathbf{s}_{ij}^{\tau} = \left\langle \sqrt{\det(\mathbf{g}_{\tau})} \cdot \mathbf{g}_{\tau}^{-1}, \mathbf{d}^{ij} \right\rangle_F$$

$$\mathbf{g}_{\tau} = \begin{pmatrix} \|\mathbf{v}_{12}\|^2 & \langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle \\ \langle \mathbf{v}_{13}, \mathbf{v}_{12} \rangle & \|\mathbf{v}_{13}\|^2 \end{pmatrix}$$

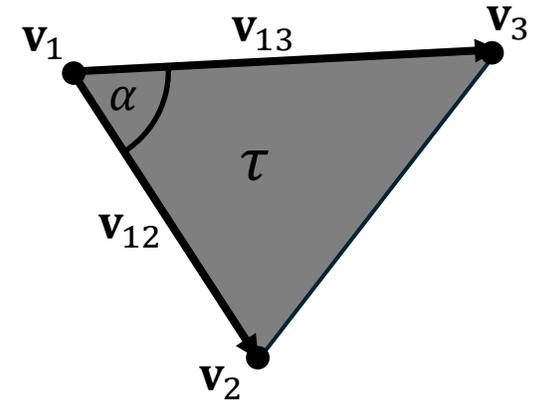


What components of the inner-product affect the mass and stiffness matrices?

# The Hat Basis

For the mass matrix:

$$\mathbf{m}_{ij}^{\tau} = \sqrt{\det(\mathbf{g}_{\tau})} \langle \langle \psi_i, \psi_j \rangle \rangle_E$$
$$\mathbf{s}_{ij}^{\tau} = \left\langle \sqrt{\det(\mathbf{g}_{\tau})} \cdot \mathbf{g}_{\tau}^{-1}, \mathbf{d}^{ij} \right\rangle_F$$
$$\mathbf{g}_{\tau} = \begin{pmatrix} \|\mathbf{v}_{12}\|^2 & \langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle \\ \langle \mathbf{v}_{13}, \mathbf{v}_{12} \rangle & \|\mathbf{v}_{13}\|^2 \end{pmatrix}$$

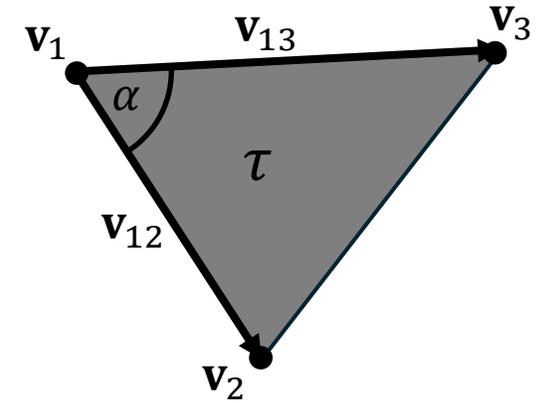


$$\begin{aligned} \sqrt{\det(\mathbf{g}_{\tau})} &= \sqrt{\|\mathbf{v}_{12}\|^2 \cdot \|\mathbf{v}_{13}\|^2 - \langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle^2} \\ &= \|\mathbf{v}_{12}\| \cdot \|\mathbf{v}_{13}\| \cdot \sqrt{1 - \frac{\langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle^2}{\|\mathbf{v}_{12}\|^2 \cdot \|\mathbf{v}_{13}\|^2}} \\ &= \|\mathbf{v}_{12}\| \cdot \|\mathbf{v}_{13}\| \cdot \sqrt{1 - \left( \frac{\langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle}{\|\mathbf{v}_{12}\| \cdot \|\mathbf{v}_{13}\|} \right)^2} \\ &= \|\mathbf{v}_{12}\| \cdot \|\mathbf{v}\| \cdot \sqrt{1 - \cos^2(\alpha)} \\ &= \|\mathbf{v}_{12}\| \cdot \|\mathbf{v}_{13}\| \cdot \sqrt{\sin^2(\alpha)} \\ &= \|\mathbf{v}_{12}\| \cdot \|\mathbf{v}_{13}\| \cdot \sin(\alpha) \\ &= 2 \cdot |\tau| \end{aligned}$$

# The Hat Basis

For the mass matrix:

$$\mathbf{m}_{ij}^{\tau} = \sqrt{\det(\mathbf{g}_{\tau})} \langle \langle \psi_i, \psi_j \rangle \rangle_E$$
$$\mathbf{s}_{ij}^{\tau} = \left\langle \sqrt{\det(\mathbf{g}_{\tau})} \cdot \mathbf{g}_{\tau}^{-1}, \mathbf{d}^{ij} \right\rangle_F$$
$$\mathbf{g}_{\tau} = \begin{pmatrix} \|\mathbf{v}_{12}\|^2 & \langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle \\ \langle \mathbf{v}_{13}, \mathbf{v}_{12} \rangle & \|\mathbf{v}_{13}\|^2 \end{pmatrix}$$



⇒ The mass matrix only “sees” area, not angles.

⇒ It is invariant under transformations of the triangle that preserve the area.

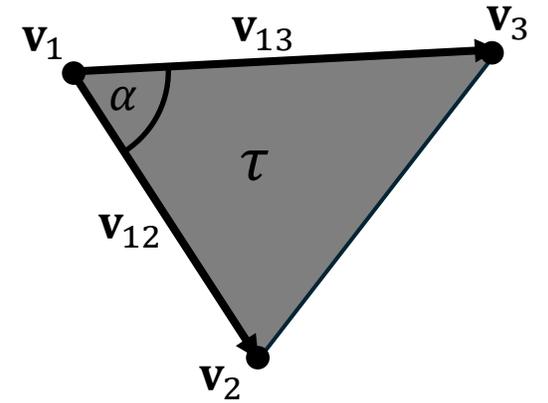
⇒ It is defined by the *authalic* structure of the geometry.

# The Hat Basis

$$\mathbf{m}_{ij}^\tau = \sqrt{\det(\mathbf{g}_\tau)} \cdot \langle \langle \psi_i, \psi_j \rangle \rangle_E$$

$$\mathbf{s}_{ij}^\tau = \left\langle \left\langle \sqrt{\det(\mathbf{g}_\tau)} \cdot \mathbf{g}_\tau^{-1}, \mathbf{d}^{ij} \right\rangle \right\rangle_F$$

$$\mathbf{g}_\tau = \begin{pmatrix} \|\mathbf{v}_{12}\|^2 & \langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle \\ \langle \mathbf{v}_{13}, \mathbf{v}_{12} \rangle & \|\mathbf{v}_{13}\|^2 \end{pmatrix}$$



For the stiffness matrix.

$$\begin{aligned} \sqrt{\det(\mathbf{g}_\tau)} \cdot \mathbf{g}_\tau^{-1} &= \sqrt{\det(\mathbf{g}_\tau)} \cdot \begin{pmatrix} \|\mathbf{v}_{12}\|^2 & \langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle \\ \langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle & \|\mathbf{v}_{13}\|^2 \end{pmatrix}^{-1} \\ &= \sqrt{\det(\mathbf{g}_\tau)} \cdot \frac{1}{\det(\mathbf{g}_\tau)} \begin{pmatrix} \|\mathbf{v}_{13}\|^2 & -\langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle \\ -\langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle & \|\mathbf{v}_{12}\|^2 \end{pmatrix} \\ &= \frac{1}{\sqrt{\det(\mathbf{g}_\tau)}} \begin{pmatrix} \|\mathbf{v}_{13}\|^2 & -\langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle \\ -\langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle & \|\mathbf{v}_{12}\|^2 \end{pmatrix} \\ &= \frac{1}{\|\mathbf{v}_{12}\| \cdot \|\mathbf{v}_{13}\| \cdot \sin(\alpha)} \begin{pmatrix} \|\mathbf{v}_{13}\|^2 & -\langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle \\ -\langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle & \|\mathbf{v}_{12}\|^2 \end{pmatrix} \\ &= \frac{1}{\sin(\alpha)} \begin{pmatrix} \frac{\|\mathbf{v}_{13}\|}{\|\mathbf{v}_{12}\|} & -\frac{\langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle}{\|\mathbf{v}_{12}\| \cdot \|\mathbf{v}_{13}\|} \\ -\frac{\langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle}{\|\mathbf{v}_{12}\| \cdot \|\mathbf{v}_{13}\|} & \frac{\|\mathbf{v}_{12}\|}{\|\mathbf{v}_{13}\|} \end{pmatrix} \\ &= \frac{1}{\sin(\alpha)} \begin{pmatrix} \|\mathbf{v}_{13}\|/\|\mathbf{v}_{12}\| & -\cos(\alpha) \\ -\cos(\alpha) & \|\mathbf{v}_{12}\|/\|\mathbf{v}_{13}\| \end{pmatrix} \end{aligned}$$

# The Hat Basis

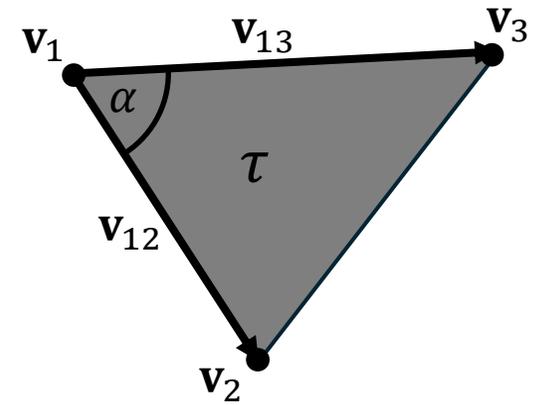
$$\mathbf{m}_{ij}^\tau = \sqrt{\det(\mathbf{g}_\tau)} \cdot \langle \langle \psi_i, \psi_j \rangle \rangle_E$$

$$\mathbf{s}_{ij}^\tau = \left\langle \left\langle \sqrt{\det(\mathbf{g}_\tau)} \cdot \mathbf{g}_\tau^{-1}, \mathbf{d}^{ij} \right\rangle \right\rangle_F$$

$$\mathbf{g}_\tau = \begin{pmatrix} \|\mathbf{v}_{12}\|^2 & \langle \mathbf{v}_{12}, \mathbf{v}_{13} \rangle \\ \langle \mathbf{v}_{13}, \mathbf{v}_{12} \rangle & \|\mathbf{v}_{13}\|^2 \end{pmatrix}$$

For the stiffness matrix.

$$\sqrt{\det(\mathbf{g}_\tau)} \cdot \mathbf{g}_\tau^{-1} = \frac{1}{\sin(\alpha)} \begin{pmatrix} \|\mathbf{v}_{13}\|/\|\mathbf{v}_{12}\| & -\cos(\alpha) \\ -\cos(\alpha) & \|\mathbf{v}_{12}\|/\|\mathbf{v}_{13}\| \end{pmatrix}$$



⇒ The stiffness matrix only “sees” angles, not areas.

⇒ It is invariant under similarity transformations.

⇒ It is defined by the *conformal* structure of the geometry.

# Algebraic Interpretation

The linear scalar field basis defines a 3-dimensional space of functions:

$$V = \text{Span}(\psi_1, \psi_2, \psi_3)$$

Mass matrix:

Letting  $m^\tau$  be the symmetric, positive-definite bilinear map:

$$\begin{aligned} m^\tau: V \times V &\rightarrow \mathbb{R} \\ (f, h) &\mapsto \langle\langle f, h \rangle\rangle_\tau \end{aligned}$$

this makes  $V$  into an inner-product space  $\{V, m^\tau: V \rightarrow V^*\}$ .

$\Rightarrow$  The mass matrix  $\mathbf{m}^\tau \in \mathbb{R}^{3 \times 3}$  gives the expression for the map  $m^\tau: V \rightarrow V^*$  w.r.t. the bases  $\{\psi_1, \psi_2, \psi_3\}$  and  $\{\psi_1^*, \psi_2^*, \psi_3^*\}$ .

# Algebraic Interpretation

The linear scalar field basis defines a 3-dimensional space of functions:

$$V = \text{Span}(\psi_1, \psi_2, \psi_3)$$

Stiffness matrix:

Similarly, we have a symmetric, positive semi-definite bilinear map:

$$\begin{aligned} s^\tau: V \times V &\rightarrow \mathbb{R} \\ (f, h) &\mapsto \langle\langle df, dh \rangle\rangle_\tau \end{aligned}$$

$\Rightarrow$  The stiffness matrix  $\mathbf{s}^\tau \in \mathbb{R}^{3 \times 3}$  gives the expression for the map  $s^\tau: V \rightarrow V^*$  w.r.t. the bases  $\{\psi_1, \psi_2, \psi_3\}$  and  $\{\psi_1^*, \psi_2^*, \psi_3^*\}$ .

# Caution

We are now working with two types of inner-product spaces.

$$\{T_{\mathbf{p}}\mathbb{T}, g_{\mathbf{p}}: T_{\mathbf{p}}\mathbb{T} \rightarrow T_{\mathbf{p}}^*\mathbb{T}\}:$$

The space of tangent vectors at the point  $\mathbf{p} \in \mathbb{T}$ , with inner-product  $g_{\mathbf{p}}$  defined by pulling back the Euclidean inner-product using the differential of the parametrization  $\Phi_{\tau}: \mathbb{T} \rightarrow \tau$ .

$$\{V, M: V \rightarrow V^*\}:$$

The space of piecewise-linear functions on the triangle, with inner-product  $M$  defined by integrating functions over the triangle.