

Modeling

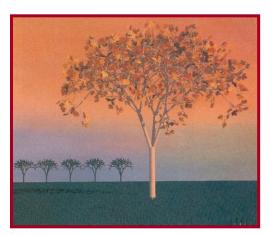
Michael Kazhdan

(601.457/657)

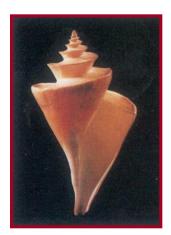
Modeling



 How do we construct 3D models quickly and/or automatically with a computer?



H&B Figure 10.79



Fowler



H&B Figure 10.83b

Model Construction

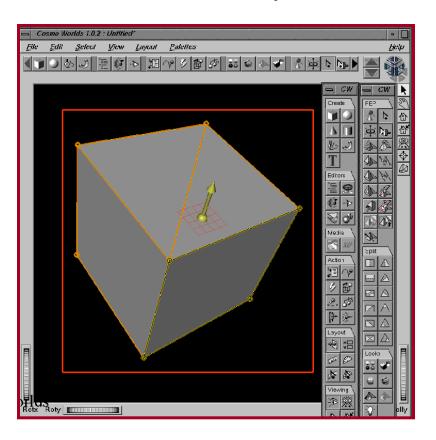


- Interactive modeling tools
 - CAD programs
- Active scanners
 - Light probes, triangulation/LiDAR/CAT/MRI scanners
- Passive scanners
 - Stereo, motion, etc.
- Procedural generation
 - Sweeps, fractals, grammars

Interactive Modeling Tools



- User constructs objects with drawing program
 - Menu commands, direct manipulation, etc.
 - CSG, parametric surfaces, quadrics, etc.



Model Construction



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Active Scanners: Touch Scanner



- Articulated arm with:
 - Angular sensors at the joints
 - Touch probe at the end
- Angles are recorded on contact, and use to compute the position of the head
- ⇒ Position of the probe (relative to the base of the scanner)



Active Scanners: Laser Scanner



Emits a laser from one position

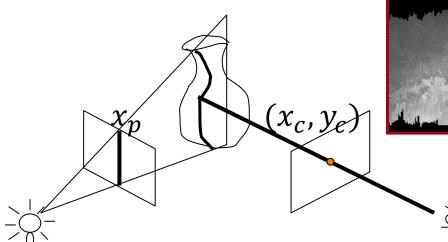
Images the laser-illuminated surface from another

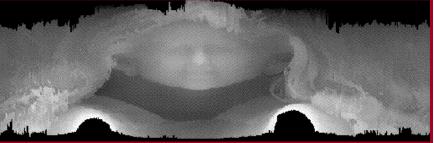
(calibrated position)

⇒ Triangulation



Colo





Depth

Active Scanners: IR Scanner



Emits IR light from one position

Images the IR-illuminated surface from another

(calibrated position)

⇒ Triangulation





Active Scanners: Triangulation (2D)



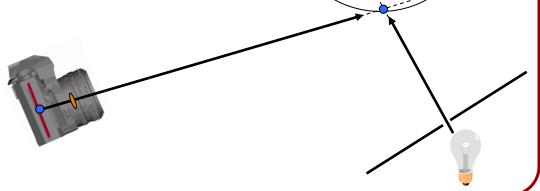
To figure out the position of a point we need:

- 1. The position of the camera
- 2. The position of the light source

Project the light through a slit onto the surface...

Find where the lit points project onto the camera...

Cast rays from the lit pixels, through the camera...



Active Scanners: Triangulation 2D



To figure out the position of a point we need:

- 1. The position of the camera
- 2. The position of the light source

Project the light through a slit onto the surface...

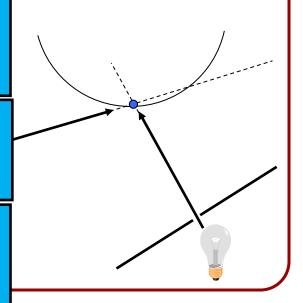
Find where the lit points project

onto the camera...

For the lit point to project onto the pixel, it has to lie along the ray.

The lit point is also constrained to lie on the plane from the light source.

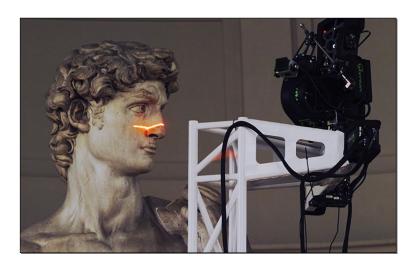
The position of the lit point has to be at the intersection of the ray and the plane.



Laser Range Scanning



- Example: Digital Michelangelo Project
 - 480 individually aimed scans



Stanford Graphics Laboratory



Active Scanners: LiDAR



Emits laser light

Measures the time it takes the light to reflect back

to a sensor.

⇒ Knowing the speed of light gives (twice) the distance travelled.

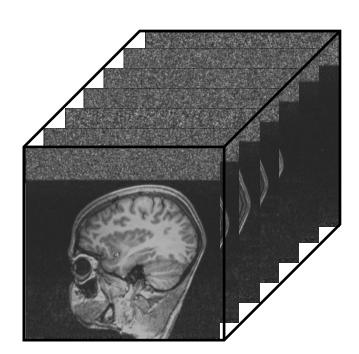


Image courtesy of Wikipedia

Active Scanners: MRI Scanners



•



Model Construction

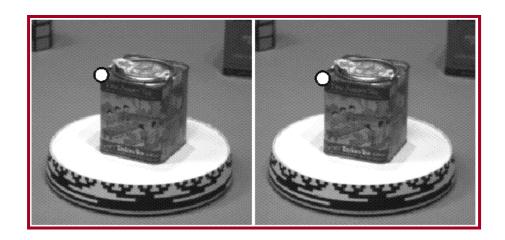


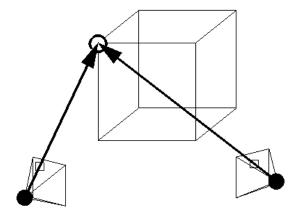
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Passive Scanners: Stereo



Image the scene from multiple calibrated locations

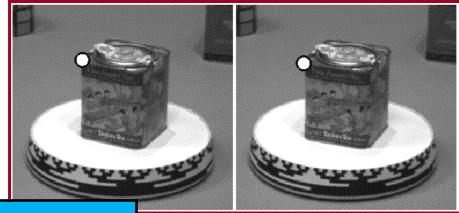




Passive Scanners: Stereo

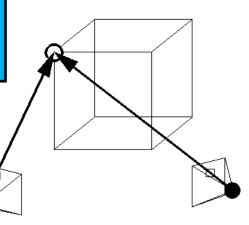


Image the scene from multiple calibrated locations



This is similar to the approach for scanners, but instead of triangulating using a light and a camera, we triangulate using two cameras.

The challenge is to determine pixel pair correspondences across the two images.



Passive Scanners: Motion



Image the scene from multiple uncalibrated locations

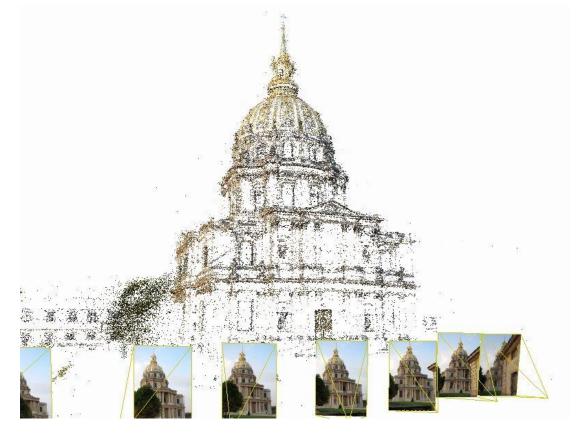


Image courtesy of http://www.maths.lth.se/matematiklth/personal/calle/

Passive Scanners: Motion



 Image the scene from multiple uncalibrated locations

In this case we need to solve simultaneously for the surface points and the camera position.

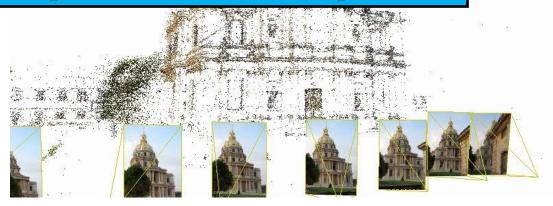


Image courtesy of http://www.maths.lth.se/matematiklth/personal/calle/

Model Construction



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Procedural Modeling



- Goal:
 - Describe 3D models algorithmically
- Best for models resulting from...
 - Repeating processes
 - Self-similar processes
 - Random processes
- Advantages:
 - Automatic generation
 - Concise representation
 - Parameterized classes of models

Similar to Perlin noise

Procedural Modeling: Sweeps



Transform a generating curve along a sweep curve



- Defining property:
 - Self-similar with infinite resolution



Mandelbrot Set

H&B Figure 10.100

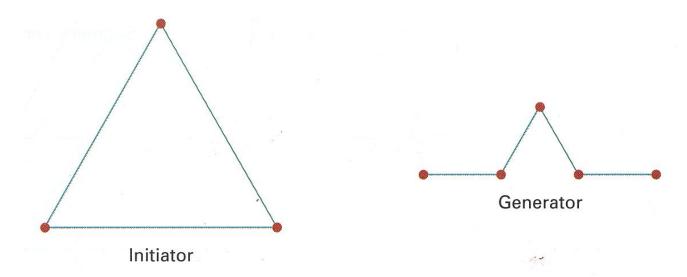


- Deterministically self-similar fractals
 - Parts are scaled copies of original

- Statistically self-similar fractals
 - Parts have same statistical properties as original

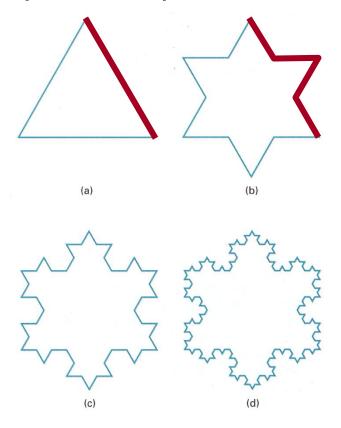


- Deterministic fractal generation:
 - Initiator: start with a shape
 - Generator: replace subparts with scaled copy of original
 - Repeat





- Deterministic fractal generation:
 - Initiator: start with a shape
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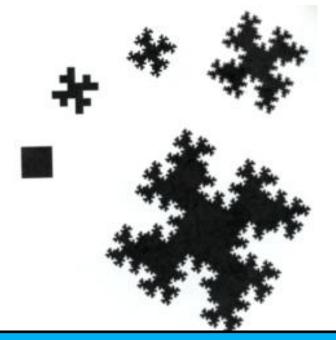


Koch Curve H&B Figure 10.69



- Deterministic fractal generation:
 - Initiator: start with a shape
 - Generator: replace subparts with scaled copy of original





Useful for creating "interesting" shapes.

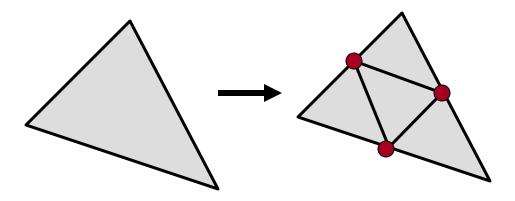


- Deterministically self-similar fractals
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- Statistically self-similar fractals
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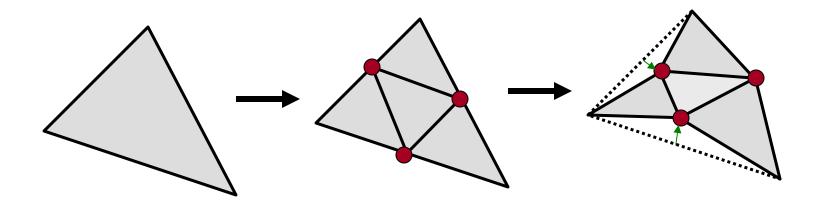


- Statistical fractal generation:
 - Initiator: start with a shape
 - Generator: replace subparts with a scaled copy
 - Repeat





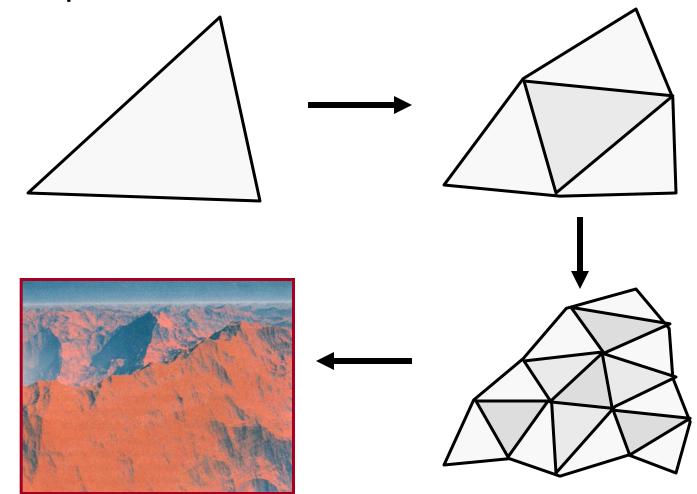
- Statistical fractal generation:
 - Initiator: start with a shape
 - Statistically self-similar
 Generator: replace subparts with a scaled copy
 - Repeat



Random Midpoint Displacement



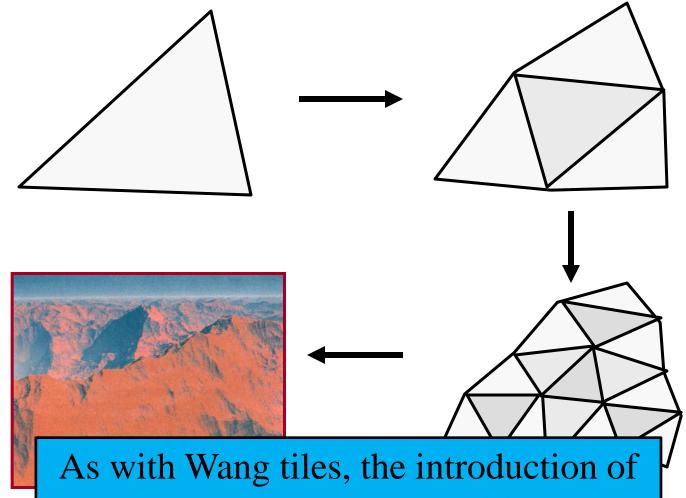
• Example: terrain



H&B Figure 10.83b



Example: terrain



randomness removes repetitiveness

Statistical Fractal Generation



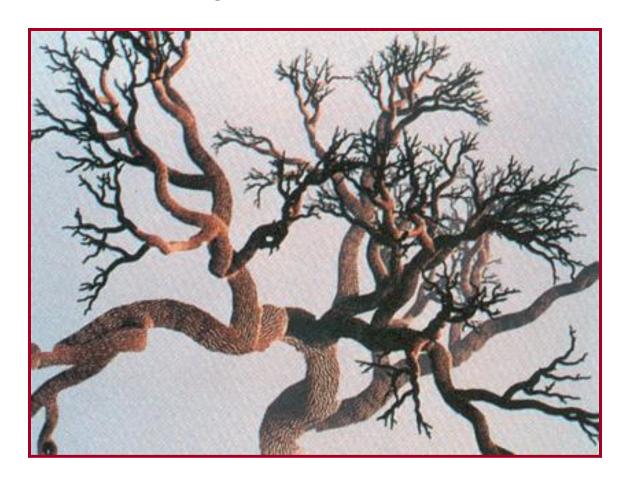
Useful for creating mountains



Statistical Fractal Generation



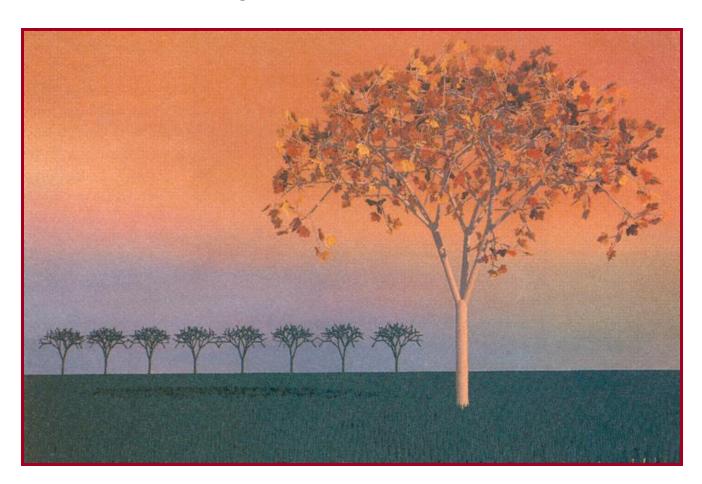
Useful for creating 3D plants



Statistical Fractal Generation



Useful for creating 3D plants



Procedural Modeling: Grammars



 Generate description of geometric model by applying production rules

$$S \rightarrow AB$$
 $A \rightarrow Ba \mid a$
 $B \rightarrow Ab \mid b$

Procedural Modeling: Grammars



 Generate description of geometric model by applying production rules

$$S \rightarrow AB$$

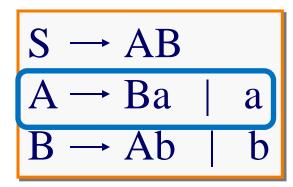
$$A \rightarrow Ba \mid a$$

$$B \rightarrow Ab \mid b$$

AB



 Generate description of geometric model by applying production rules







 Generate description of geometric model by applying production rules

$$S \rightarrow AB$$

$$A \rightarrow Ba \mid a$$

$$B \rightarrow Ab \mid b$$

AB BaB BaAb



 Generate description of geometric model by applying production rules

$$S \rightarrow AB$$

$$A \rightarrow Ba \mid a$$

$$B \rightarrow Ab \mid b$$

AB
BaB
BaAb
AbaAb



 Generate description of geometric model by applying production rules

$$S \rightarrow AB$$
 $A \rightarrow Ba \mid a$
 $B \rightarrow Ab \mid b$

AB
BaB
BaAb
AbaAb



```
Start → [Root]
Root → Junction Root | leaf
Junction → [Root] | edge
```

```
    ■ = leaf
    | = edge
    ■ = Junction
    ∴ = [Root]
```



Useful for creating plants

[R]

```
Start → [Root]

Root → Junction Root | leaf

Junction → [Root] | edge
```

```
    ■ = leaf
    | = edge
    ■ = Junction
    ∴ = [Root]
```





```
[R]
↓
JR
```

```
Start \rightarrow [Root]
Root \rightarrow Junction Root \mid leaf
Junction \rightarrow [Root] \mid edge
```

```
    = leaf
    | = edge
    = Junction
    ∴ = [Root]
```

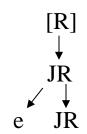




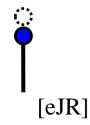
```
Start → [Root]

Root → Junction Root | leaf

Junction → [Root] | edge
```

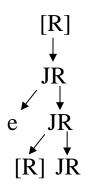


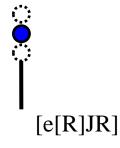
```
    ■ = leaf
    | = edge
    ■ = Junction
    ∴ = [Root]
```





```
Start \rightarrow [Root]
Root \rightarrow Junction Root | leaf
Junction \rightarrow [Root] | edge
```







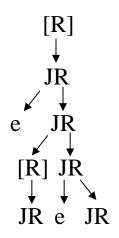
Useful for creating plants

```
Start → [Root]

Root → Junction Root | leaf

Junction → [Root] | edge
```

[e[JR]eJR]



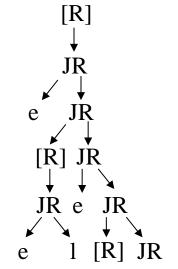


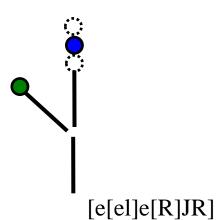
= leaf

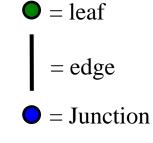


Useful for creating plants

```
Start \rightarrow [Root]
Root \rightarrow Junction Root \mid leaf
Junction \rightarrow [Root] \mid edge
```







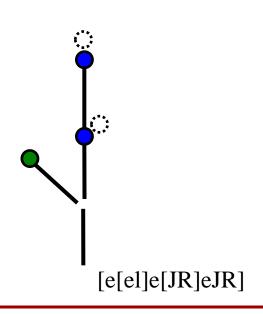
::=[Root]

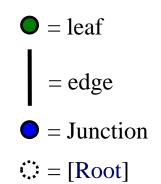


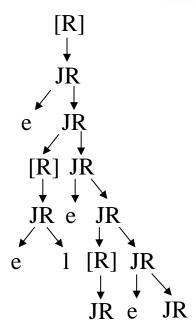
```
Start → [Root]

Root → Junction Root | leaf

Junction → [Root] | edge
```





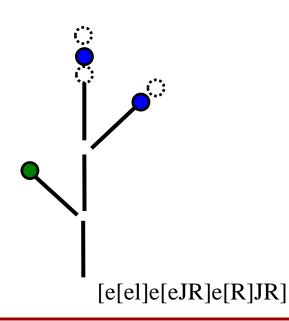


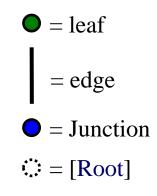


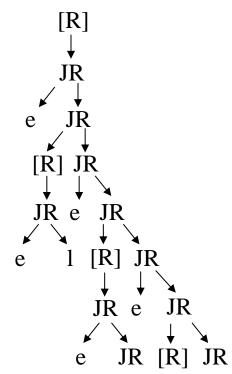
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Junction → [Root] | edge
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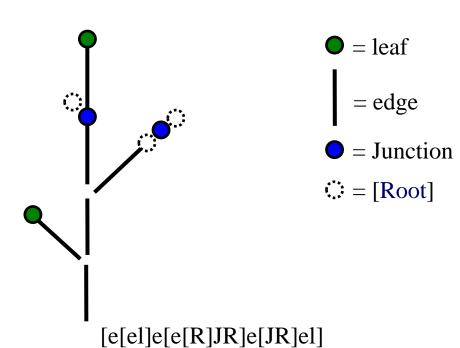


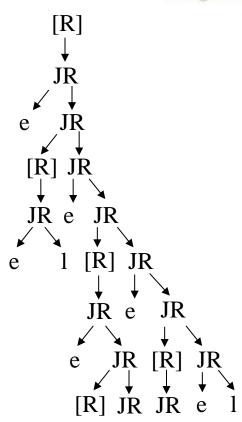


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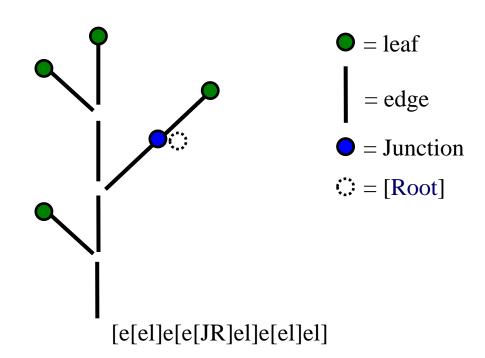


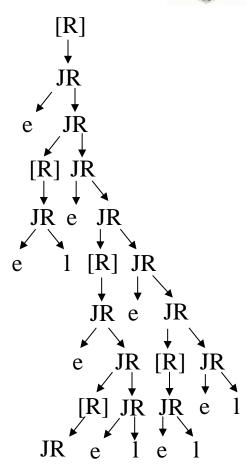


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Start → [Root]

Root → Junction Root | leaf

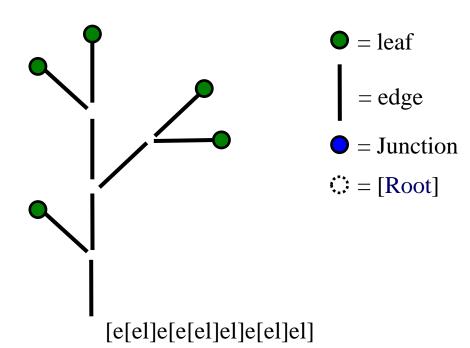
Junction → [Root] | edge
```

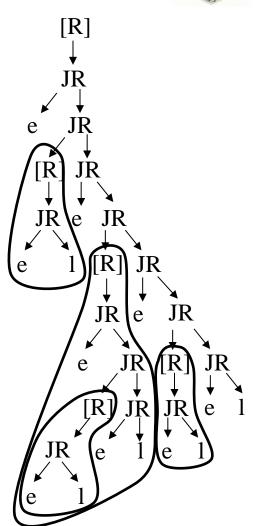






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Start \rightarrow [Root]
Root \rightarrow Junction Root | leaf
Junction \rightarrow [Root] | edge
```





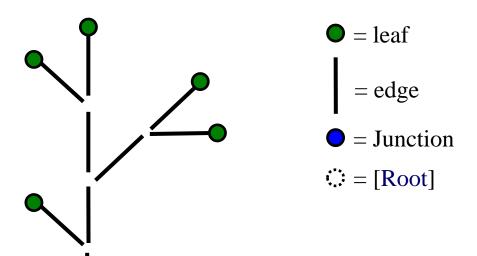


Useful for creating plants

```
Start → [Root]

Root → Junction Root | leaf

Junction → [Root] | edge
```



As with Wang tiles, the ability to make a choice creates a variety and removes periodicity.





```
    ■ = leaf
    | = edge
    ■ = Branch
    ∴ = [End]
```



Useful for creating plants

[E]

```
    ■ = leaf
    | = edge
    ■ = Branch
    □ = [End]
```



```
[E]

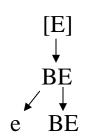
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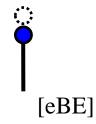
BE
```

```
    ■ = leaf
    | = edge
    ■ = Branch
    ∴ = [End]
```

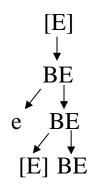


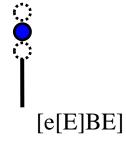








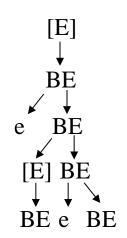


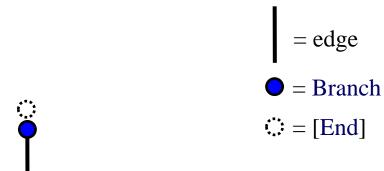




Useful for creating plants

[e[BE]eBE]

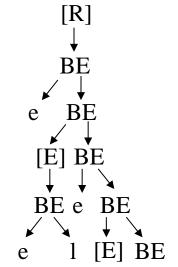




 \bullet = leaf

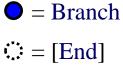


Useful for creating plants





[e[el]e[E]BE]

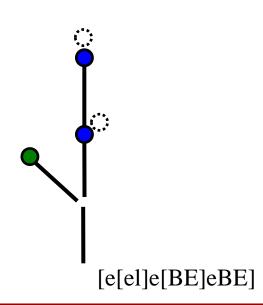


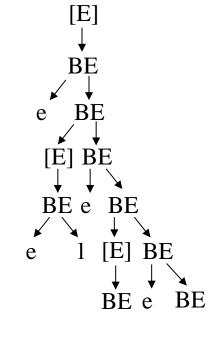
= edge

= leaf



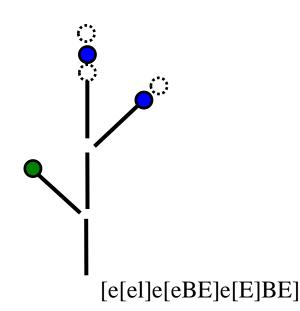
Useful for creating plants

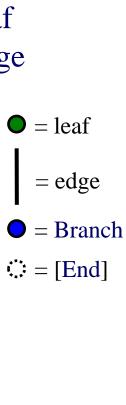


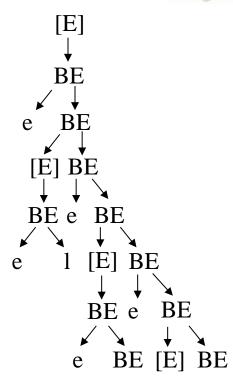


= leaf



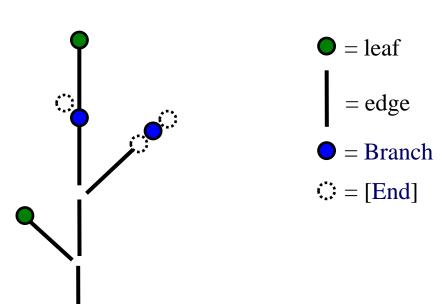


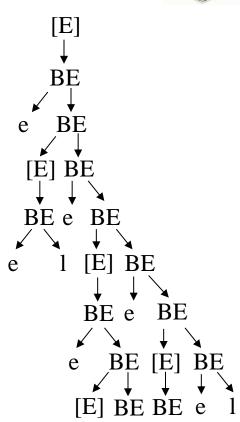






Useful for creating plants

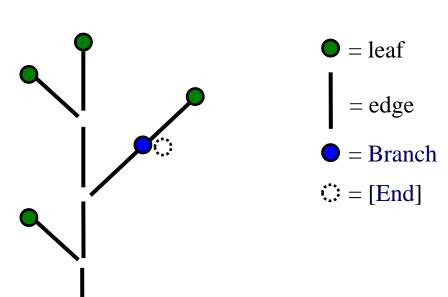


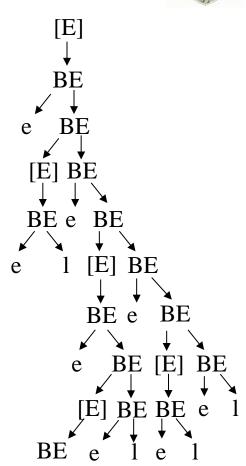


[e[el]e[e[E]BE]e[BE]el]



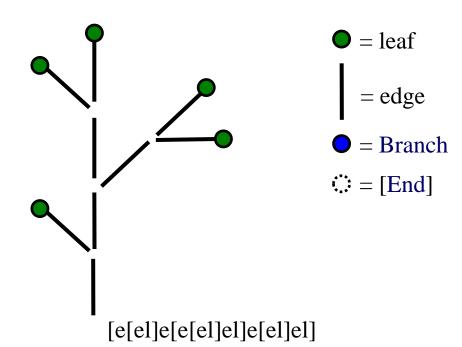
Useful for creating plants

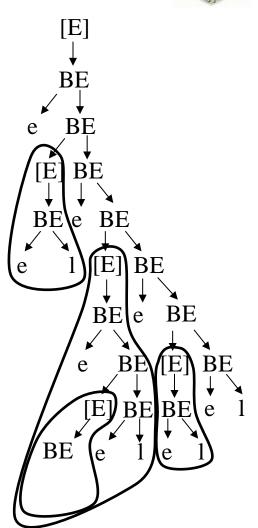




[e[el]e[e[BE]el]e[el]el]

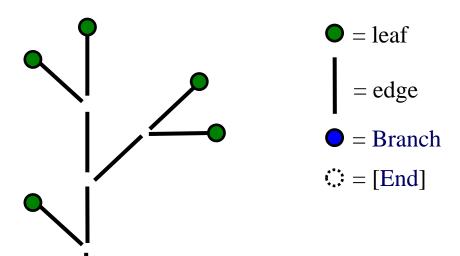








Useful for creating plants



As with Wang tiles, the ability to make a choice creates a variety and removes periodicity.