

Parametric Curves

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(601.457/657)

Overview



- What is a Spline?
- Specific Examples:
 - Hermite Splines
 - Cardinal Splines
 - Uniform Cubic B-Splines
- Comparing Cardinal and Uniform Cubic B-Splines

What is a Spline in CG?



A spline is a *piecewise polynomial function* whose derivatives satisfy *continuity constraints* at curve boundaries.

$$\mathbf{P}_{1}(u) \quad u \in [0,1) \leftarrow$$

$$\mathbf{P}_{2}(u) \quad u \in [0,1) \leftarrow$$

$$\mathbf{P}_{3}(x) \quad u \in [0,1) \leftarrow$$

$$\mathbf{A}_{kj} \in \mathbb{R}^{d}$$

$$\mathbf{P}_k(u) = \sum_{j=0}^n \mathbf{a}_{kj} \cdot u^j$$
 with $\mathbf{a}_{kj} \in \mathbb{R}^d$

What is a Spline in CG?



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$$P_{1}(1) = P_{2}(0)$$
 $P'_{1}(1) = P'_{2}(0)$
...

 $P_{2}(1) = P_{3}(0)$
 $P'_{2}(1) = P'_{3}(0)$
...

$$\mathbf{P}_k(u) = \sum_{j=0}^n \mathbf{a}_{kj} \cdot u^j \text{ with } \mathbf{a}_{kj} \in \mathbb{R}^d$$

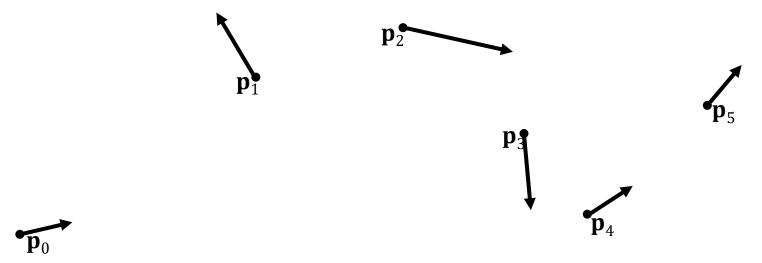
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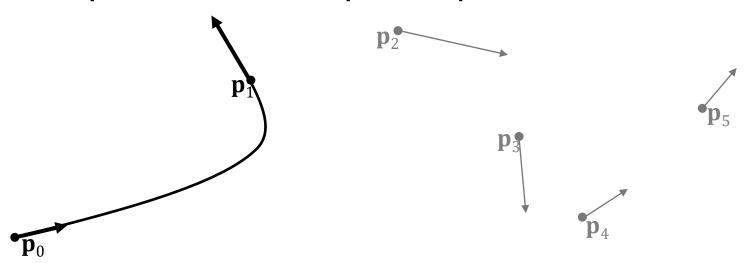


- Interpolating piecewise cubic polynomial, each specified by:
 - Start/end positions
 - Start/end tangents
- Iteratively construct the curve between adjacent end points that interpolate positions and tangents.



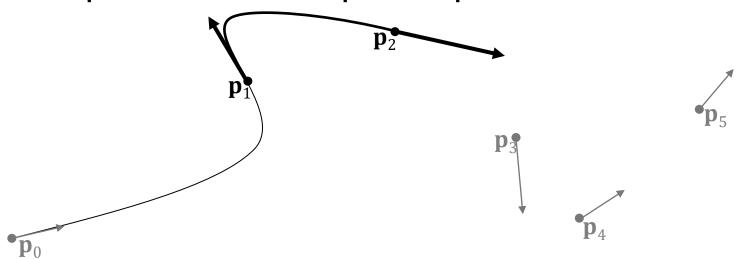


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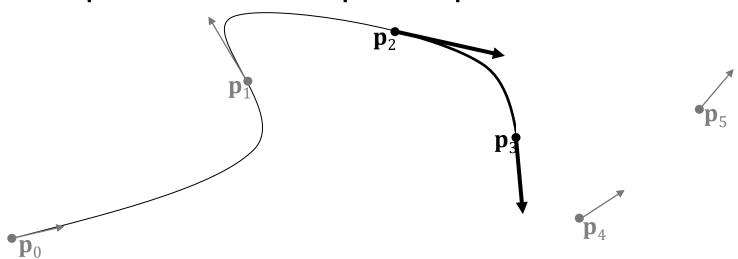


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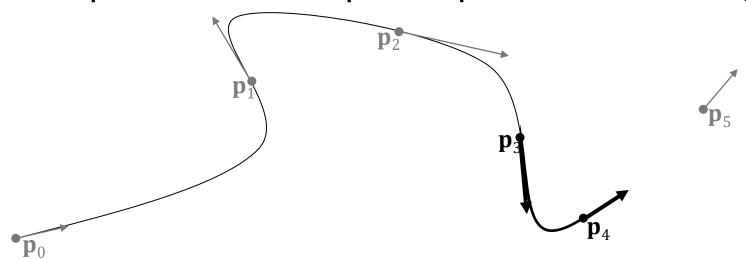


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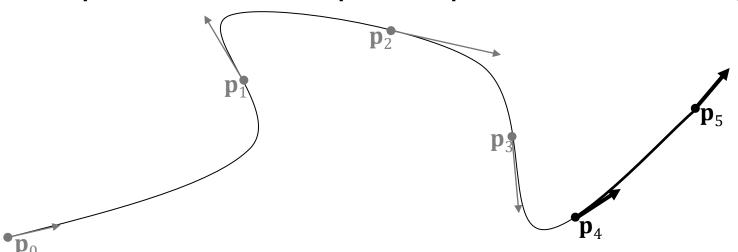


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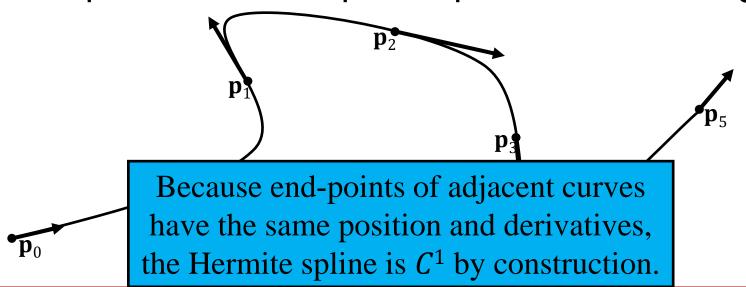


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Given the polynomial:

$$\mathbf{P}_k(u) = \mathbf{a} \cdot u^3 + \mathbf{b} \cdot u^2 + \mathbf{c} \cdot u + \mathbf{d}$$

we can write its derivative as:

$$\mathbf{P}'_k(u) = 3 \cdot \mathbf{a} \cdot u^2 + 2 \cdot \mathbf{b} \cdot u + \mathbf{c}$$

Using the matrix representations:

$$\mathbf{P}_{k}(u) = (u^{3} \quad u^{2} \quad u \quad 1) \cdot \begin{pmatrix} \mathbf{a} \\ \mathbf{b} \\ \mathbf{c} \\ \mathbf{d} \end{pmatrix} \qquad \mathbf{P}'_{k}(u) = (3 \cdot u^{2} \quad 2 \cdot u \quad 1 \quad 0) \cdot \begin{pmatrix} \mathbf{a} \\ \mathbf{b} \\ \mathbf{c} \\ \mathbf{d} \end{pmatrix}$$



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The values/derivatives at the end-points are:

$$\mathbf{p}_{k} = \mathbf{P}_{k}(0) = (0 \quad 0 \quad 0 \quad 1) \cdot \begin{pmatrix} \mathbf{a} \\ \mathbf{b} \\ \mathbf{c} \\ \mathbf{d} \end{pmatrix} \qquad \mathbf{\vec{t}}_{k} = \mathbf{P}_{k}'(0) = (0 \quad 0 \quad 1 \quad 0) \cdot \begin{pmatrix} \mathbf{a} \\ \mathbf{b} \\ \mathbf{c} \\ \mathbf{d} \end{pmatrix}$$

$$\mathbf{p}_{k+1} = \mathbf{P}_{k}(1) = (1 \quad 1 \quad 1 \quad 1) \cdot \begin{pmatrix} \mathbf{a} \\ \mathbf{b} \\ \mathbf{c} \\ \mathbf{d} \end{pmatrix} \qquad \mathbf{\vec{t}}_{k+1} = \mathbf{P}_{k}'(1) = (3 \quad 2 \quad 1 \quad 0) \cdot \begin{pmatrix} \mathbf{a} \\ \mathbf{b} \\ \mathbf{c} \\ \mathbf{d} \end{pmatrix}$$



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Combinging into a single matrix expression:

$$\begin{pmatrix} \mathbf{p}_k \\ \mathbf{p}_{k+1} \\ \vec{\mathbf{t}}_k \\ \vec{\mathbf{t}}_{k+1} \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \\ 3 & 2 & 1 & 0 \end{pmatrix} \begin{pmatrix} \mathbf{a} \\ \mathbf{b} \\ \mathbf{c} \\ \mathbf{d} \end{pmatrix}$$



$$\begin{pmatrix} \mathbf{p}_k \\ \mathbf{p}_{k+1} \\ \vec{\mathbf{t}}_k \\ \vec{\mathbf{t}}_{k+1} \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \\ 3 & 2 & 1 & 0 \end{pmatrix} \begin{pmatrix} \mathbf{a} \\ \mathbf{b} \\ \mathbf{c} \\ \mathbf{d} \end{pmatrix}$$

Inverting:

$$\begin{pmatrix} \mathbf{a} \\ \mathbf{b} \\ \mathbf{c} \\ \mathbf{d} \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \\ 3 & 2 & 1 & 0 \end{pmatrix}^{-1} \begin{pmatrix} \mathbf{p}_k \\ \mathbf{p}_{k+1} \\ \vec{\mathbf{t}}_k \\ \vec{\mathbf{t}}_{k+1} \end{pmatrix} = \begin{pmatrix} 2 & -2 & 1 & 1 \\ -3 & 3 & -2 & -1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \mathbf{p}_k \\ \mathbf{p}_{k+1} \\ \vec{\mathbf{t}}_k \\ \vec{\mathbf{t}}_{k+1} \end{pmatrix}$$



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Using the fact that:

$$\mathbf{P}_k(u) = \begin{pmatrix} u^3 & u^2 & u & 1 \end{pmatrix} \cdot \begin{pmatrix} \mathbf{a} \\ \mathbf{b} \\ \mathbf{c} \\ \mathbf{d} \end{pmatrix}$$

We get:

$$\mathbf{P}_{k}(u) = (u^{3} \quad u^{2} \quad u \quad 1) \begin{pmatrix} 2 & -2 & 1 & 1 \\ -3 & 3 & -2 & -1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \mathbf{p}_{k} \\ \mathbf{p}_{k+1} \\ \mathbf{t}_{k} \\ \mathbf{t}_{k+1} \end{pmatrix}$$
parameters
$$\mathbf{M}_{\text{Hermite}} \quad \text{boundary info}$$



$$\mathbf{P}_{k}(u) = \begin{pmatrix} u^{3} & u^{2} & u & 1 \end{pmatrix} \begin{pmatrix} 2 & -2 & 1 & 1 \\ -3 & 3 & -2 & -1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \mathbf{p}_{k} \\ \mathbf{p}_{k+1} \\ \mathbf{t}_{k} \\ \mathbf{t}_{k+1} \end{pmatrix}$$

Pre-multiplying to get blending functions:

$$\mathbf{P}_k(u) = H_0(u) \cdot \mathbf{p}_k + H_1(u) \cdot \mathbf{p}_{k+1} + H_2(u) \cdot \mathbf{t}_k + H_3(u)$$

with:

$$H_0(u) = 2u^3 - 3u^2 + 1$$

$$H_1(u) = -2u^3 + 3u^2$$

$$H_2(u) = u^3 - 2u^2 + u$$

$$\circ H_3(u) = u^3 - u^2$$



Pre-multiplying to get blending functions:

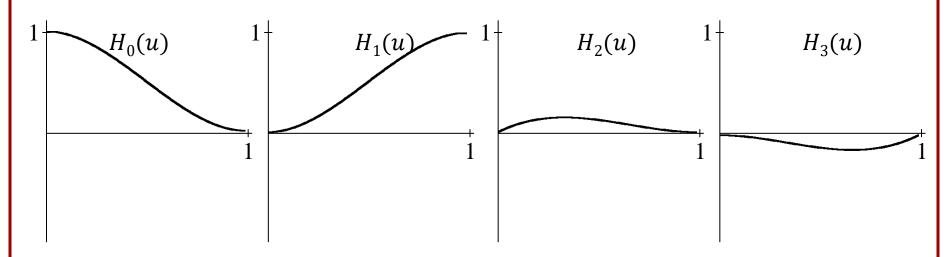
$$\circ H_0(u) = 2u^3 - 3u^2 + 1$$

$$\circ H_1(u) = -2u^3 + 3u^2$$

$$H_2(u) = u^3 - 2u^2 + u$$

$$\circ H_3(u) = u^3 - u^2$$

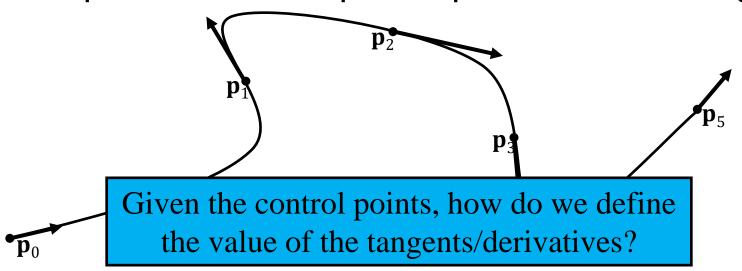
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$$\mathbf{P}_k(u) = H_0(u) \cdot \mathbf{p}_k + H_1(u) \cdot \mathbf{p}_{k+1} + H_2(u) \cdot \mathbf{t}_k + H_3(u) \cdot \mathbf{t}_{k+1}$$



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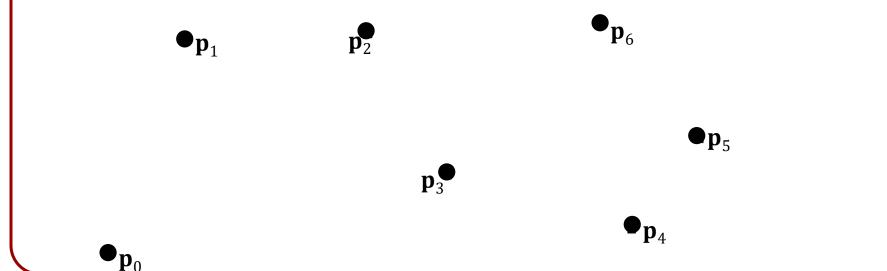
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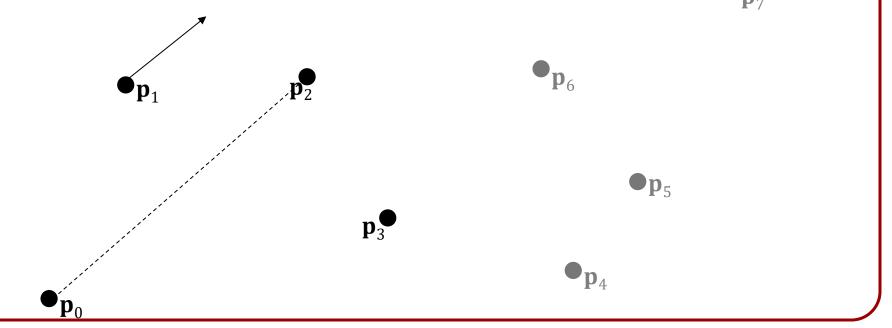


- Interpolating piecewise cubic polynomial, each specified by four control points.
- Iteratively construct the curve through middle two points using adjacent points to define positions and tangents.



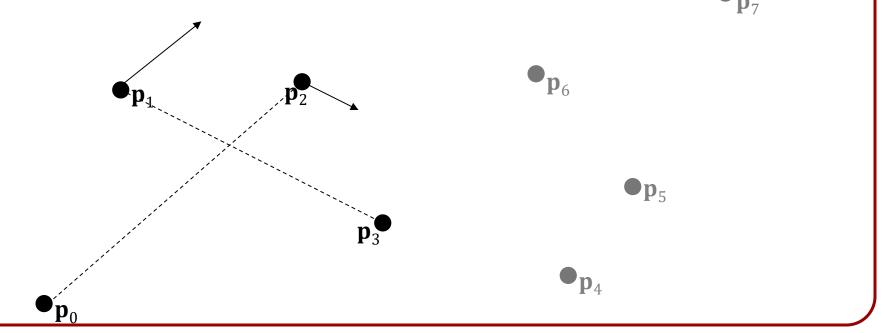


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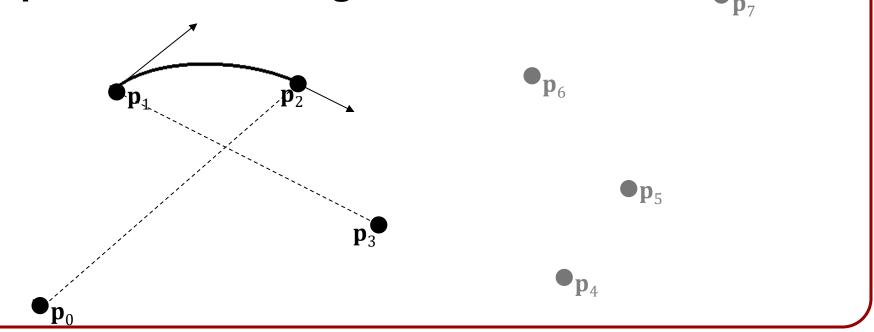


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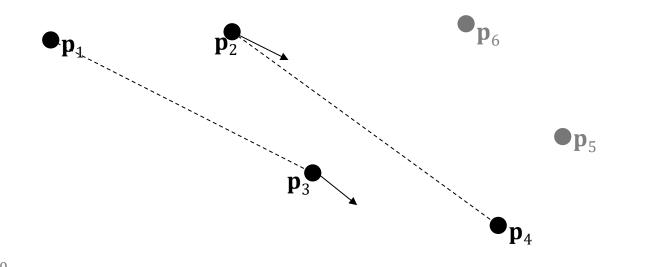


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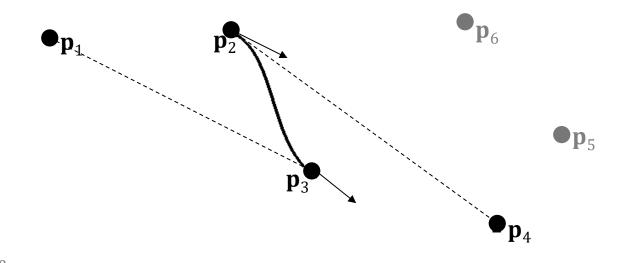


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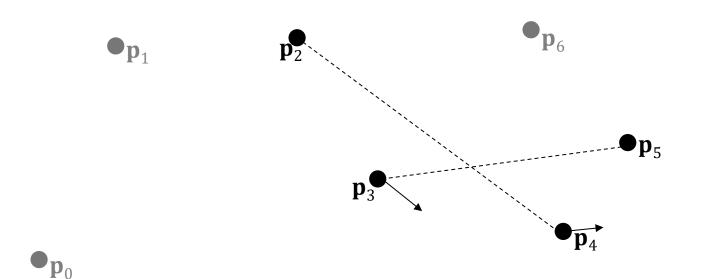


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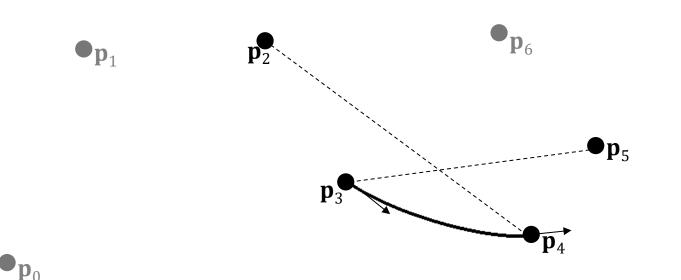


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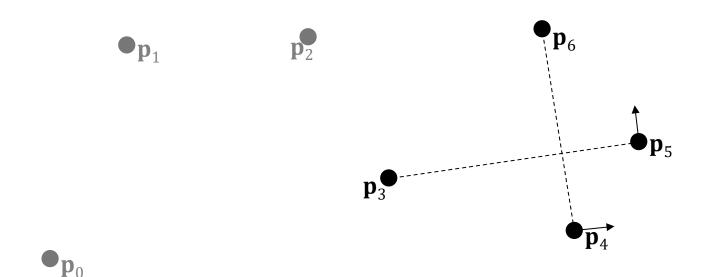


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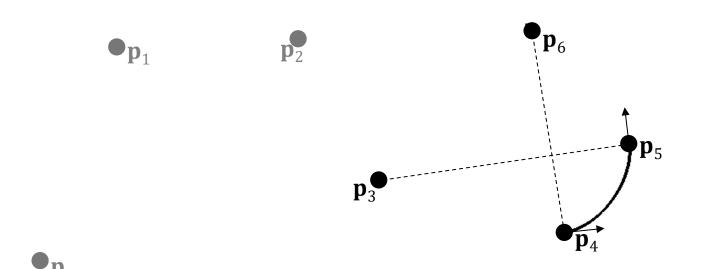


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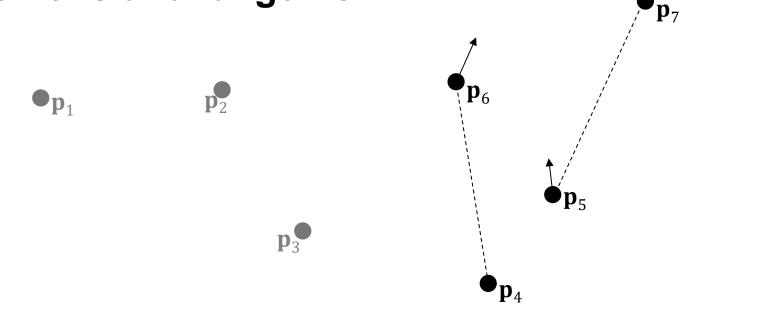


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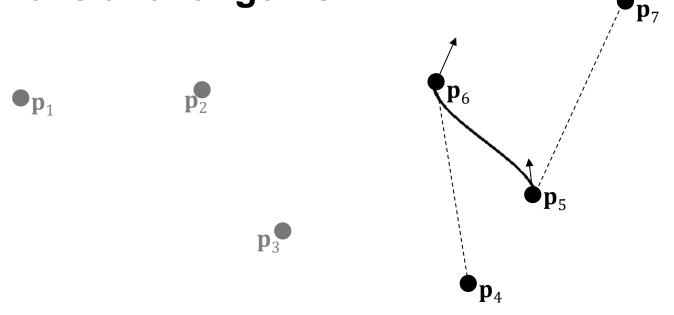


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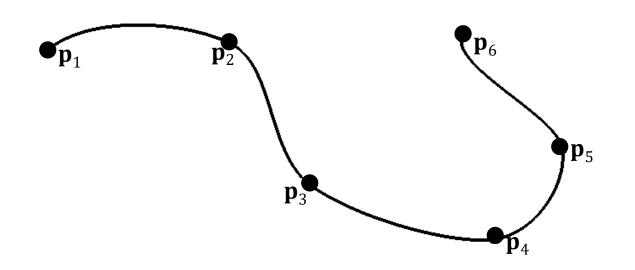


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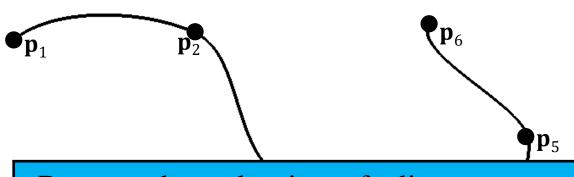


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Because the end-points of adjacent curves share the same position and derivatives, the Cardinal spline has C^{I} continuity.

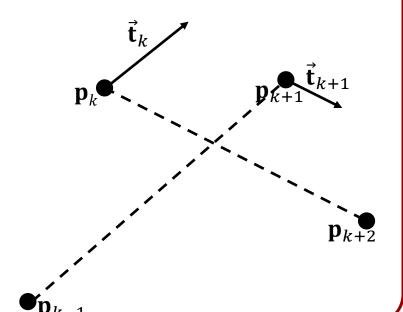


Using Hermite splines, we have:

$$\mathbf{P}_{k}(u) = (u^{3} \quad u^{2} \quad u \quad 1) \begin{pmatrix} 2 & -2 & 1 & 1 \\ -3 & 3 & -2 & -1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \mathbf{p}_{k} \\ \mathbf{p}_{k+1} \\ \mathbf{t}_{k} \\ \mathbf{t}_{k+1} \end{pmatrix}$$

$$\vec{\mathbf{t}}_k = s(\mathbf{p}_{k+1} - \mathbf{p}_{k-1})$$

$$\vec{\mathbf{t}}_{k+1} = s(\mathbf{p}_{k+2} - \mathbf{p}_k)$$





We can express the boundary constraints as:

$$\begin{pmatrix} \mathbf{p}_{k} \\ \mathbf{p}_{k+1} \\ \vec{\mathbf{t}}_{k} \\ \vec{\mathbf{t}}_{k+1} \end{pmatrix} = \begin{pmatrix} \mathbf{p}_{k} \\ \mathbf{p}_{k+1} \\ s(\mathbf{p}_{k+1} - \mathbf{p}_{k-1}) \\ s(\mathbf{p}_{k+2} - \mathbf{p}_{k}) \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -s & 0 & s & 0 \\ 0 & -s & 0 & s \end{pmatrix} \begin{pmatrix} \mathbf{p}_{k-1} \\ \mathbf{p}_{k} \\ \mathbf{p}_{k+1} \\ \mathbf{p}_{k+2} \end{pmatrix}$$

So using the approach of Hermite spline, we get:

$$\mathbf{p}_{k}(u) = (u^{3} \quad u^{2} \quad u \quad 1) \begin{pmatrix} 2 & -2 & 1 & 1 \\ -3 & 3 & -2 & -1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -s & 0 & s & 0 \\ 0 & -s & 0 & s \end{pmatrix} \begin{pmatrix} \mathbf{p}_{k-1} \\ \mathbf{p}_{k} \\ \mathbf{p}_{k+1} \\ \mathbf{p}_{k+2} \end{pmatrix}$$



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Multiplying, we get the Cardinal matrix representation:

$$\mathbf{p}_{k}(u) = (u^{3} \quad u^{2} \quad u \quad 1) \begin{pmatrix} -s & 2-s & s-2 & s \\ 2s & s-3 & 3-2s & -s \\ -s & 0 & s & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} \mathbf{p}_{k-1} \\ \mathbf{p}_{k} \\ \mathbf{p}_{k+1} \\ \mathbf{p}_{k+2} \end{pmatrix}$$

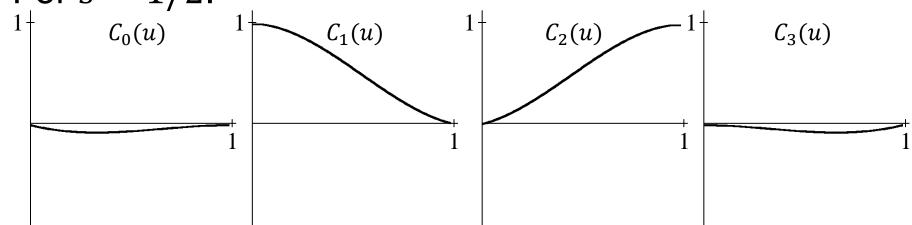


Setting:

- $\circ C_0(u) = -su^3 + 2su^2 su$
- $\circ C_1(u) = (2-s)u^3 + (s-3)u^2 + 1$
- $C_2(u) = (s-2)u^3 + (3-2s)u^2 + su^2$
- \circ $C_3(u) = su^3 su^2$

Blending Functions

For s = 1/2:



$$\mathbf{P}_k(u) = C_0(u) \cdot \mathbf{p}_{k-1} + C_1(u) \cdot \mathbf{p}_k + C_2(u) \cdot \mathbf{p}_{k+1} + C_3(u) \cdot \mathbf{p}_{k+2}$$



- Interpolating piecewise cubic polynomial, each specified by four control points.
- Iteratively construct the curve through middle two points using adjacent points to define positions and tangents.



At the first and last end-points, you can:

- Not draw the final segments
- Double up end points
- Loop the spline around

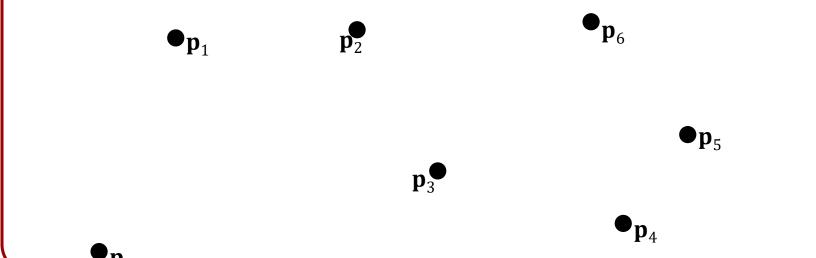
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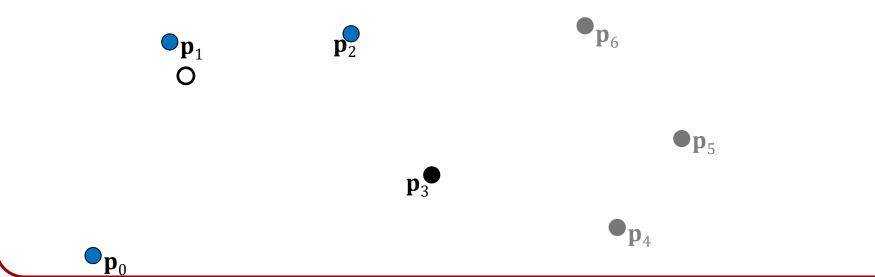
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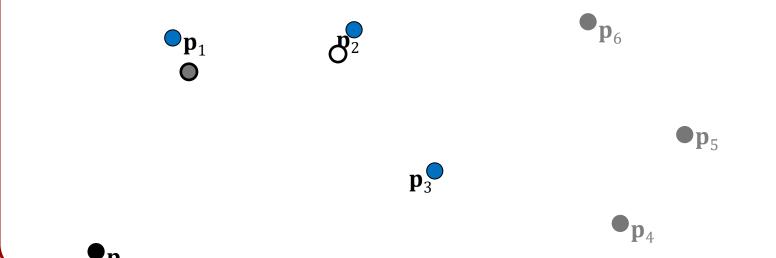
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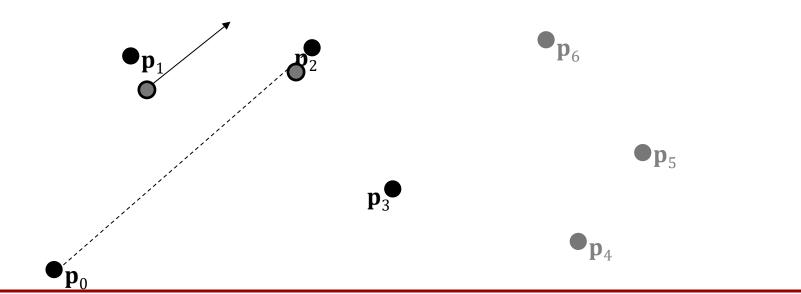
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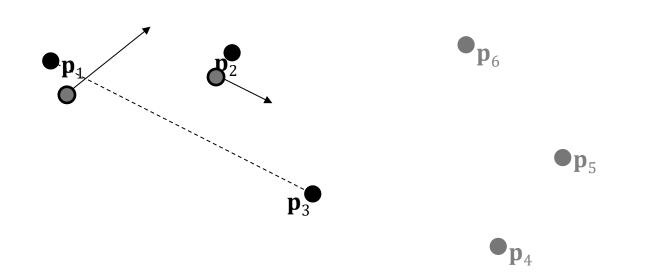
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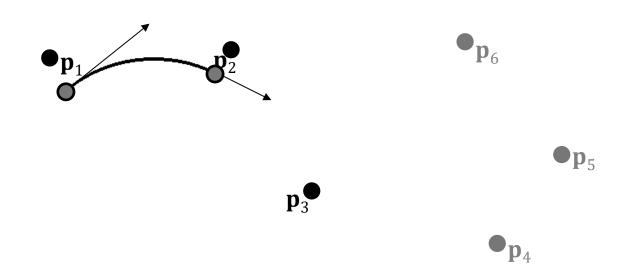


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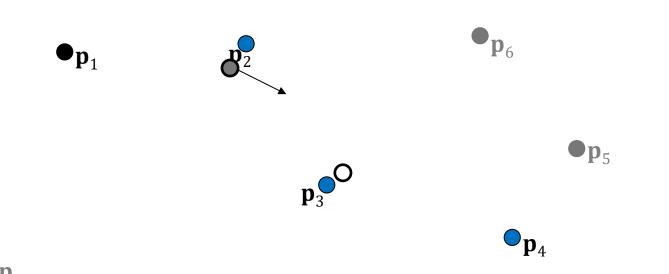




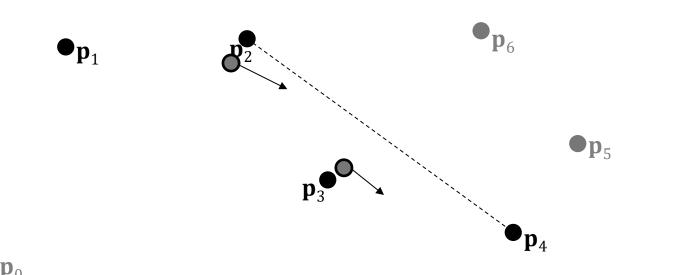
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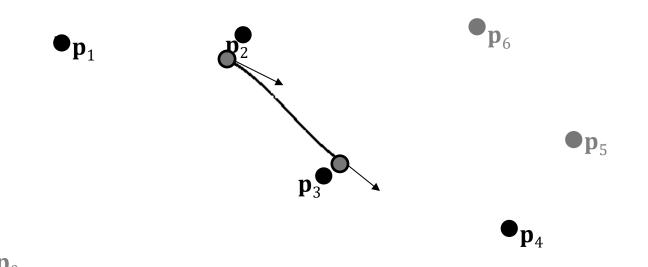
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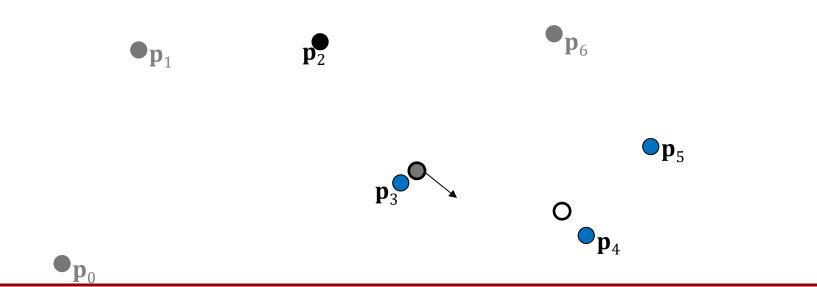
- Approximating piecewise cubic polynomial, each specified by four control points.
- Iteratively construct the curve near middle two points using adjacent points to define positions and tangents.



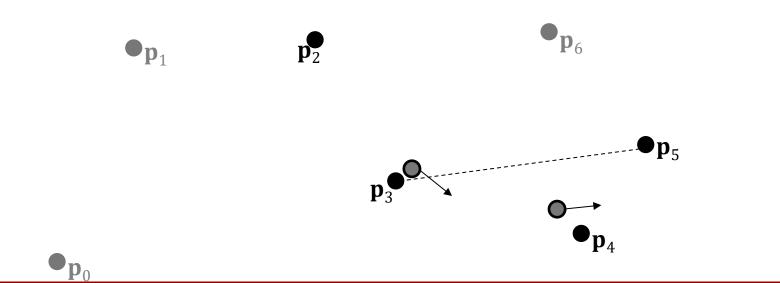
- Approximating piecewise cubic polynomial, each specified by four control points.
- Iteratively construct the curve near middle two points using adjacent points to define positions and tangents.



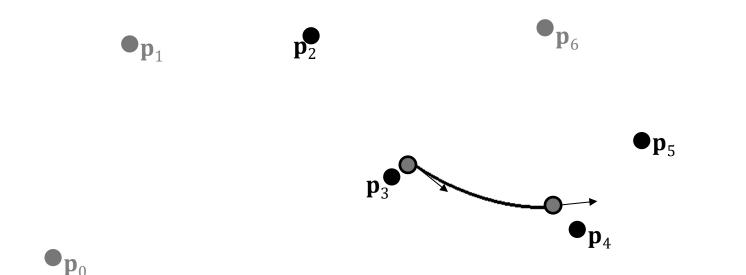
- Approximating piecewise cubic polynomial, each specified by four control points.
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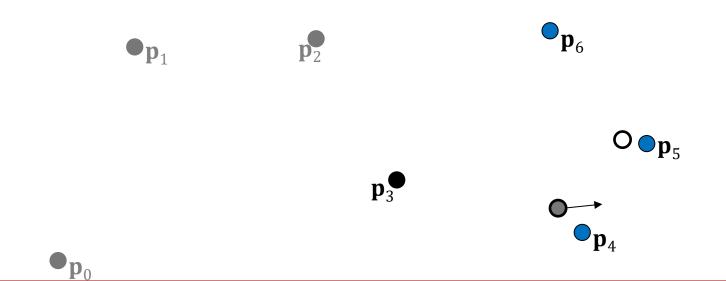
- Approximating piecewise cubic polynomial, each specified by four control points.
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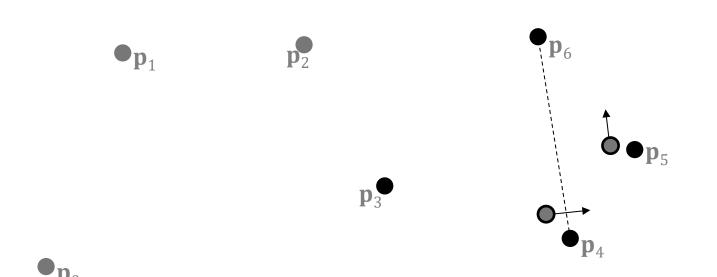
- Approximating piecewise cubic polynomial, each specified by four control points.
- Iteratively construct the curve near middle two points using adjacent points to define positions and tangents.



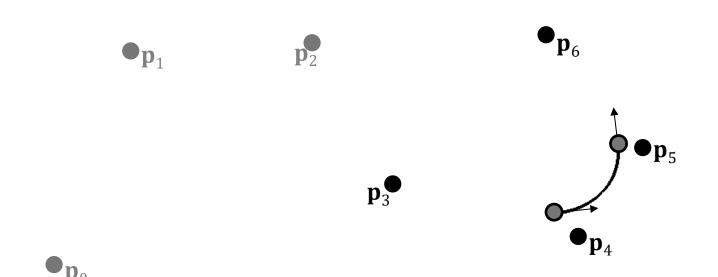
- S
- Approximating piecewise cubic polynomial, each specified by four control points.
- Iteratively construct the curve near middle two points using adjacent points to define positions and tangents.



- Approximating piecewise cubic polynomial, each specified by four control points.
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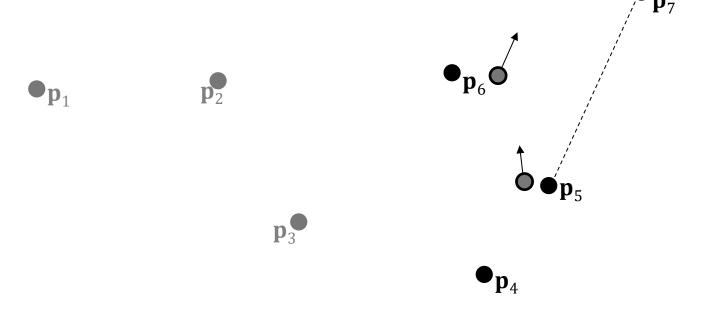
- Approximating piecewise cubic polynomial, each specified by four control points.
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- S
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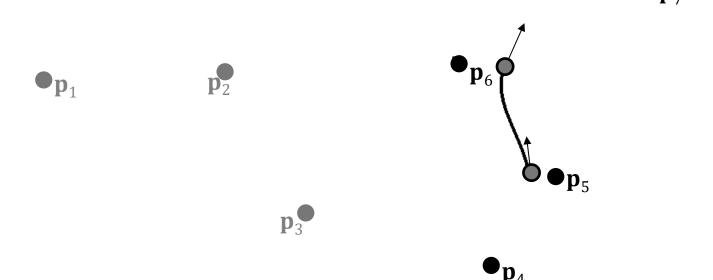


- Approximating piecewise cubic polynomial, each specified by four control points.
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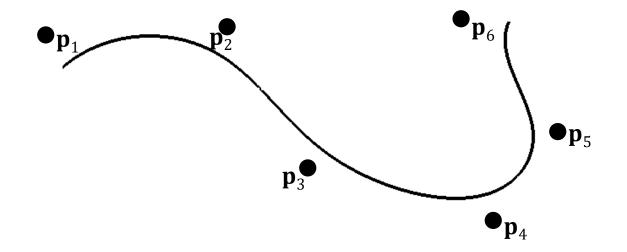


- Approximating piecewise cubic polynomial, each specified by four control points.
- Iteratively construct the curve near middle two points using adjacent points to define positions and tangents.





- Approximating piecewise cubic polynomial, each specified by four control points.
- Iteratively construct the curve near middle two points using adjacent points to define positions and tangents.





Using Hermite splines, we have:

$$\mathbf{P}_{k}(u) = (u^{3} \quad u^{2} \quad u \quad 1) \begin{pmatrix} 2 & -2 & 1 & 1 \\ -3 & 3 & -2 & -1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \mathbf{p}'_{k} \\ \mathbf{p}'_{k+1} \\ \mathbf{t}_{k} \\ \mathbf{t}_{k+1} \end{pmatrix}$$

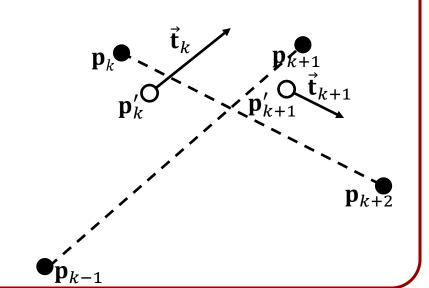
$$\mathbf{M}_{\text{Harmite}}$$

$$\mathbf{p}_{k}' = \frac{(\mathbf{p}_{k-1} + 4\mathbf{p}_{k} + \mathbf{p}_{k+1})}{6}$$

$$\mathbf{p}'_{k+1} = \frac{(\mathbf{p}_k + 4\mathbf{p}_{k+1} + \mathbf{p}_{k+2})}{6}$$

$$\vec{\mathbf{t}}_k = s(\mathbf{p}_{k+1} - \mathbf{p}_{k-1})$$

$$\vec{\mathbf{t}}_{k+1} = s(\mathbf{p}_{k+2} - \mathbf{p}_k)$$



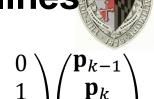


We can express the boundary constraints as:

$$\begin{pmatrix} \mathbf{p}'_{k} \\ \mathbf{p}'_{k+1} \\ \mathbf{\vec{t}}_{k} \\ \mathbf{\vec{t}}_{k+1} \end{pmatrix} = \frac{1}{6} \begin{pmatrix} \mathbf{p}_{k-1} + 4\mathbf{p}_{k} + \mathbf{p}_{k+1} \\ \mathbf{p}_{k} + 4\mathbf{p}_{k+1} + \mathbf{p}_{k+2} \\ 6s(\mathbf{p}_{k+1} - \mathbf{p}_{k-1}) \\ 6s(\mathbf{p}_{k+2} - \mathbf{p}_{k}) \end{pmatrix} = \frac{1}{6} \begin{pmatrix} 1 & 4 & 1 & 0 \\ 0 & 1 & 4 & 1 \\ -6s & 0 & 6s & 0 \\ 1 & -6s & 0 & 6s \end{pmatrix} \begin{pmatrix} \mathbf{p}_{k-1} \\ \mathbf{p}_{k} \\ \mathbf{p}_{k+1} \\ \mathbf{p}_{k+2} \end{pmatrix}$$

Using the approach of Hermite spline, we get:

$$\mathbf{p}_{k}(u) = (u^{3} \quad u^{2} \quad u \quad 1) \begin{pmatrix} 2 & -2 & 1 & 1 \\ -3 & 3 & -2 & -1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \underbrace{\frac{1}{6} \begin{pmatrix} 1 & 4 & 1 & 0 \\ 0 & 1 & 4 & 1 \\ -6s & 0 & 6s & 0 \\ 1 & -6s & 0 & 6s \end{pmatrix} \begin{pmatrix} \mathbf{p}_{k-1} \\ \mathbf{p}_{k} \\ \mathbf{p}_{k+1} \\ \mathbf{p}_{k+2} \end{pmatrix}}_{\mathbf{M}_{k+2}}$$



$$\mathbf{p}_{k}(u) = (u^{3} \quad u^{2} \quad u \quad 1) \begin{pmatrix} 2 & -2 & 1 & 1 \\ -3 & 3 & -2 & -1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \frac{1}{6} \begin{pmatrix} 1 & 4 & 1 & 0 \\ 0 & 1 & 4 & 1 \\ -6s & 0 & 6s & 0 \\ 1 & -6s & 0 & 6s \end{pmatrix} \begin{pmatrix} \mathbf{p}_{k-1} \\ \mathbf{p}_{k} \\ \mathbf{p}_{k+1} \\ \mathbf{p}_{k+2} \end{pmatrix}$$

Multiplying, we get the uniform cubic B-spline matrix representation:

$$\mathbf{p}_{k}(u) = (u^{3} \quad u^{2} \quad u \quad 1) \frac{1}{6} \begin{pmatrix} 2 - 6s & 6 - 6s & -6 + 6s & -2 + 6s \\ -3 + 12s & -9 + 6s & 9 - 12s & 3 - 6s \\ -6s & 0 & 6s & 0 \\ 1 & 4 & 1 & 0 \end{pmatrix} \begin{pmatrix} \mathbf{p}_{k-1} \\ \mathbf{p}_{k} \\ \mathbf{p}_{k+1} \\ \mathbf{p}_{k+2} \end{pmatrix}$$

$$\mathbf{M}_{\mathbf{RSpline}}$$



Setting the blending functions to:

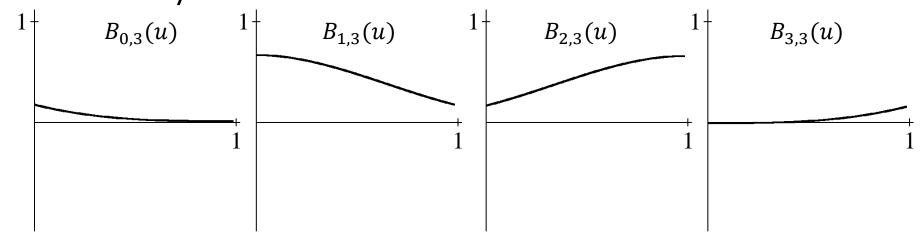
$$B_{0,3}(u) = (\frac{1}{3} - s)u^3 + (-\frac{1}{2} + 2s)u^2 - su + \frac{1}{6}$$

$$B_{1.3}(u) = (1-s)u^3 + (-3/2 + s)u^2 + 2/3$$

$$B_{2,3}(u) = (-1+s)u^3 + (3/2-2s)u^2 + su + 1/6$$

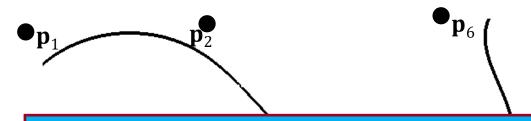
$$B_{3,3}(u) = (-1/3 + s)u^3 + (1/2 - s)u^2$$

For s = 1/2:



$$\mathbf{P}_{k}(u) = B_{0,3}(u) \cdot \mathbf{p}_{k-1} + B_{1,3}(u) \cdot \mathbf{p}_{k} + B_{2,3}(u) \cdot \mathbf{p}_{k+1} + B_{3,3}(u) \cdot \mathbf{p}_{k+2}$$

- Approximating piecewise cubic polynomial, each specified by four control points.
- Iteratively construct the curve near middle two points using adjacent points to define positions and tangents.



At the first and last end-points, you can:

- Not draw the final segments
- Double up end points
- Loop the spline around

Overview

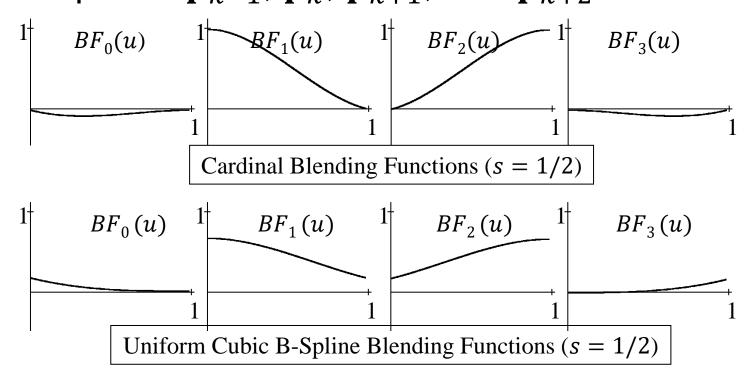


- What is a Spline?
- Specific Examples:
 - Hermite Splines
 - Cardinal Splines
 - Uniform Cubic B-Splines
- Comparing Cardinal and Uniform Cubic B-Splines

Blending Functions



Blending functions provide a way for expressing the functions $\mathbf{P}_k(u)$ as a weighted sum of the four control points \mathbf{p}_{k-1} , \mathbf{p}_k , \mathbf{p}_{k+1} , and \mathbf{p}_{k+2} :



$$\mathbf{P}_k(u) = BF_0(u) \cdot \mathbf{p}_{k-1} + BF_1(u) \cdot \mathbf{p}_k + BF_2(u) \cdot \mathbf{p}_{k+1} + BF_3(u) \cdot \mathbf{p}_{k+2}$$

Blending Functions



Properties:

- Translation Equivariance:
 - o If we translate all the control points by the same vector \mathbf{q} , the position of the new curve at value u should be the position of the old curve at u, translated by \mathbf{q} .
 - \Rightarrow Given control points $\{\mathbf{p}_{k-1}, \mathbf{p}_k, \mathbf{p}_{k+1}, \mathbf{p}_{k+2}\}$ and translation vector \mathbf{q} : Let $\mathbf{P}_k(u)$ be the curve defined by $\{\mathbf{p}_{k-1}, \mathbf{p}_k, \mathbf{p}_{k+1}, \mathbf{p}_{k+2}\}$. Let $\mathbf{Q}_k(u)$ be the curve defined by $\{\mathbf{q} + \mathbf{p}_{k-1}, \mathbf{q} + \mathbf{p}_k, \mathbf{q} + \mathbf{p}_{k+1}, \mathbf{q} + \mathbf{p}_{k+2}\}$. We want:

$$\mathbf{Q}_k(u) = \mathbf{q} + \mathbf{P}_k(u)$$

 \Rightarrow Writing out $\mathbf{Q}_k(u)$, we have:

$$\mathbf{Q}_{k}(u) = BF_{0}(u)(\mathbf{q} + \mathbf{p}_{k-1}) + BF_{1}(u)(\mathbf{q} + \mathbf{p}_{k}) + BF_{2}(u)(\mathbf{q} + \mathbf{p}_{k+1}) + BF_{3}(u)(\mathbf{q} + \mathbf{p}_{k+2})$$

$$= (BF_{0}(u) + BF_{1}(u) + BF_{2}(u) + BF_{3}(u))\mathbf{q} + \mathbf{P}_{k}(u)$$

⇒ To satisfy translation equivariance, we must have:

$$BF_0(u) + BF_1(u) + BF_2(u) + BF_3(u) = 1$$



Cardinal Splines (s = 1/2)

Cubic B-Splines (s = 1/2)



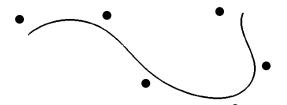
$$BF_0(u) = -\frac{1}{2}u^3 + u^2 - \frac{1}{2}u$$

$$BF_1(u) = \frac{3}{2}u^3 - \frac{5}{2}u^2 + +1$$

$$BF_2(u) = -\frac{3}{2}u^3 + 2u^2 + \frac{1}{2}u$$

$$BF_3(u) = \frac{1}{2}u^3 - \frac{1}{2}u^2$$

$$BF_0(u) + BF_1(u) + BF_2(u) + BF_3(u) = 1$$



$$BF_{0}(u) = -\frac{1}{6}u^{3} + \frac{1}{2}u^{2} - \frac{1}{2}u + \frac{1}{6}$$

$$BF_{1}(u) = \frac{1}{2}u^{3} - u^{2} + \frac{2}{3}$$

$$BF_{2}(u) = -\frac{1}{2}u^{3} + \frac{1}{2}u^{2} + \frac{1}{2}u + \frac{1}{6}$$

$$BF_{3}(u) = \frac{1}{6}u^{3}$$

$$BF_0(u) + BF_1(u) + BF_2(u) + BF_3(u) = 1$$

$$\mathbf{P}_k(u) = BF_0(u) \cdot \mathbf{p}_{k-1} + BF_1(u) \cdot \mathbf{p}_k + BF_2(u) \cdot \mathbf{p}_{k+1} + BF_3(u) \cdot \mathbf{p}_{k+2}$$

Blending Functions



Properties:

Translation Equivariance:

$$BF_0(u) + BF_1(u) + BF_2(u) + BF_3(u) = 1$$
 for all $0 \le u \le 1$.

- Continuity:
 - We need the curve $P_{k+1}(u)$ to begin where $P_k(u)$ ended.
 - ⇒ Taking the difference, we get:

$$0 = \mathbf{P}_{k+1}(0) - \mathbf{P}_{k}(1)$$

⇒ Expanding this out, we get:

$$0 = (-BF_0(1))\mathbf{p}_{k-1} + (BF_0(0) - BF_1(1))\mathbf{p}_k + (BF_1(0) - BF_2(1))\mathbf{p}_{k+1} + (BF_2(0) - BF_3(1))\mathbf{p}_{k+2} + (BF_3(0))\mathbf{p}_{k+3}$$

 \Rightarrow For this to b true for all control points $\{\mathbf{p}_{k-1}, \mathbf{p}_k, \mathbf{p}_{k+1}, \mathbf{p}_{k+2}, \mathbf{p}_{k+3}\}$, we must have:

$$0 = BF_0(1)$$

$$BF_0(0) = BF_1(1)$$

$$BF_1(0) = BF_2(1)$$

$$BF_2(0) = BF_3(1)$$

$$BF_3(0) = 0$$

$$\mathbf{P}_k(u) = BF_0(u) \cdot \mathbf{p}_{k-1} + BF_1(u) \cdot \mathbf{p}_k + BF_2(u) \cdot \mathbf{p}_{k+1} + BF_3(u) \cdot \mathbf{p}_{k+2}$$

Blending Functions



Properties:

More Generally, for the spline to have continuous n-th order derivatives, the blending functions need to satisfy:

$$0 = BF_0^{(n)}(1)$$

$$BF_0^{(n)}(0) = BF_1^{(n)}(1)$$

$$BF_1^{(n)}(0) = BF_2^{(n)}(1)$$

$$BF_2^{(n)}(0) = BF_3^{(n)}(1)$$

$$BF_3^{(n)}(0) = 0$$

 \Rightarrow For this to b true for all control points $\{\mathbf{p}_{k-1},\mathbf{p}_k,\mathbf{p}_{k+1},\mathbf{p}_{k+2},\mathbf{p}_{k+3}\}$, we must have: $0=BF_0(1)$ $BF_0(0)=BF_1(1)$ $BF_1(0)=BF_2(1)$ $BF_2(0)=BF_3(1)$

$$\mathbf{P}_k(u) = BF_0(u) \cdot \mathbf{p}_{k-1} + BF_1(u) \cdot \mathbf{p}_k + BF_2(u) \cdot \mathbf{p}_{k+1} + BF_3(u) \cdot \mathbf{p}_{k+2}$$

 $BF_3(0) = 0$



Cardinal Splines (s = 1/2)

Cubic B-Splines (s = 1/2)



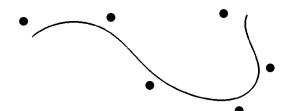
$$BF_0(u) = -\frac{1}{2}u^3 + u^2 - \frac{1}{2}u$$

$$BF_1(u) = -\frac{3}{2}u^3 - \frac{5}{2}u^2 + 1$$

$$BF_2(u) = -\frac{3}{2}u^3 + 2u^2 + \frac{1}{2}u$$

$$BF_3(u) = -\frac{1}{2}u^3 - \frac{1}{2}u^2$$

$$BF_0(0) = 0$$
 $BF_0(1) = 0$
 $BF_1(0) = 1$ $BF_1(1) = 0$
 $BF_2(0) = 0$ $BF_2(1) = 1$
 $BF_3(0) = 0$ $BF_3(1) = 0$



$$BF_0(u) = -\frac{1}{6}u^3 + \frac{1}{2}u^2 - \frac{1}{2}u + \frac{1}{6}$$

$$BF_1(u) = -\frac{1}{2}u^3 - u^2 + \frac{2}{3}$$

$$BF_2(u) = -\frac{1}{2}u^3 + \frac{1}{2}u^2 + \frac{1}{2}u + \frac{1}{6}$$

$$BF_3(u) = -\frac{1}{6}u^3$$

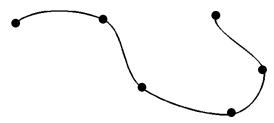
$$BF_0(0) = \frac{1}{6}$$
 $BF_0(1) = 0$
 $BF_1(0) = \frac{2}{3}$ $BF_1(1) = \frac{1}{6}$
 $BF_2(0) = \frac{1}{6}$ $BF_2(1) = \frac{2}{3}$
 $BF_3(0) = 0$ $BF_3(1) = \frac{1}{6}$

$$\mathbf{P}_k(u) = BF_0(u) \cdot \mathbf{p}_{k-1} + BF_1(u) \cdot \mathbf{p}_k + BF_2(u) \cdot \mathbf{p}_{k+1} + BF_3(u) \cdot \mathbf{p}_{k+2}$$



Cardinal Splines (s = 1/2)

Cubic B-Splines (s = 1/2)



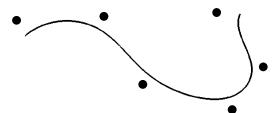
$$BF'_0(u) = -\frac{3}{2}u^2 + 2u - \frac{1}{2}$$

$$BF'_1(u) = -\frac{9}{2}u^2 - 5u$$

$$BF'_2(u) = -\frac{9}{2}u^2 + 4u + \frac{1}{2}$$

$$BF'_3(u) = -\frac{3}{2}u^2 - u$$

$$BF'_0(0) = -\frac{1}{2}$$
 $BF'_0(1) = 0$
 $BF'_1(0) = 0$ $BF'_1(1) = -\frac{1}{2}$
 $BF'_2(0) = \frac{1}{2}$ $BF'_2(1) = 0$
 $BF'_3(0) = 0$ $BF'_3(1) = \frac{1}{2}$



$$BF'_0(u) = -\frac{1}{2}u^2 + u - \frac{1}{2}$$

$$BF'_1(u) = \frac{3}{2}u^2 - 2u$$

$$BF'_2(u) = -\frac{3}{2}u^2 + u + \frac{1}{2}$$

$$BF'_3(u) = \frac{1}{2}u^2$$

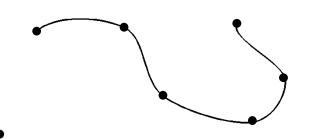
$$BF'_{0}(0) = -\frac{1}{2}$$
 $BF'_{0}(1) = 0$
 $BF'_{1}(0) = 0$ $BF'_{1}(1) = -\frac{1}{2}$
 $BF'_{2}(0) = \frac{1}{2}$ $BF'_{2}(1) = 0$
 $BF'_{3}(0) = 0$ $BF''_{3}(1) = \frac{1}{2}$

$$\mathbf{P}_k(u) = BF_0(u) \cdot \mathbf{p}_{k-1} + BF_1(u) \cdot \mathbf{p}_k + BF_2(u) \cdot \mathbf{p}_{k+1} + BF_3(u) \cdot \mathbf{p}_{k+2}$$



Cardinal Splines (s = 1/2)

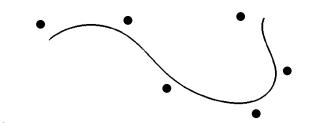




$$BF_0''(u) = -3u + 2$$

 $BF_1''(u) = 9u - 5$
 $BF_2''(u) = -9u + 4$
 $BF_3''(u) = 3u - 1$

$$BF_0''(0) = 2$$
 $BF_0''(1) = -1$
 $BF_1''(0) = -5$ $BF_1''(1) = 4$
 $BF_2''(0) = 4$ $BF_2''(1) = -5$
 $BF_3''(0) = -1$ $BF_3''(1) = 2$



$$BF_0''(u) = -u + 1$$

 $BF_1''(u) = 3u - 2$
 $BF_2''(u) = -3u + 1$
 $BF_3''(u) = u$

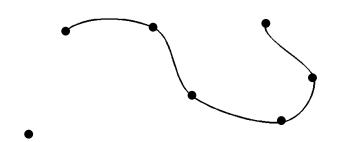
$$BF_0''(0) = 1$$
 $BF_0''(1) = 0$
 $BF_1''(0) = -2$ $BF_1''(1) = 1$
 $BF_2''(0) = 1$ $BF_2''(1) = -2$
 $BF_3''(0) = 0$ $BF_3''(1) = 1$

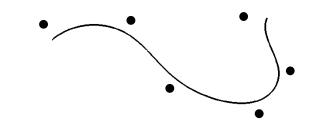
$$\mathbf{P}_k(u) = BF_0(u) \cdot \mathbf{p}_{k-1} + BF_1(u) \cdot \mathbf{p}_k + BF_2(u) \cdot \mathbf{p}_{k+1} + BF_3(u) \cdot \mathbf{p}_{k+2}$$



Cardinal Splines (s = 1/2)

Cubic B-Splines (s = 1/2)





$$BF_0'''(u) = -1$$

 $BF_1'''(u) = 3$
 $BF_2'''(u) = -3$
 $BF_3'''(u) = 1$

$$BF_0'''(0) = -1$$
 $BF_0'''(1) = -1$
 $BF_1'''(0) = 3$ $BF_1'''(1) = 3$
 $BF_2'''(0) = -3$ $BF_2'''(1) = -3$
 $BF_3'''(0) = 1$

$$\mathbf{P}_k(u) = BF_0(u) \cdot \mathbf{p}_{k-1} + BF_1(u) \cdot \mathbf{p}_k + BF_2(u) \cdot \mathbf{p}_{k+1} + BF_3(u) \cdot \mathbf{p}_{k+2}$$

Blending Functions



Properties:

Translation Equivariance:

$$BF_0(u) + BF_1(u) + BF_2(u) + BF_3(u) = 1$$
 for all $0 \le u \le 1$.

• Continuity:

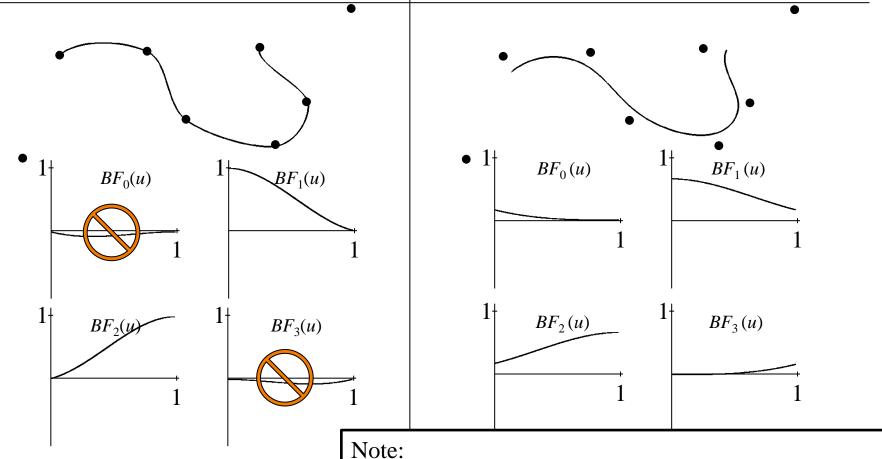
$$0 = BF_0(1), BF_0(0) = BF_1(1), BF_1(0) = BF_2(1), BF_2(0) = BF_3(1), BF_3(0) = 0$$

- Convex Hull Containment:
 - A point is inside the convex hull of a collection of points if and only if it can be expressed as the weighted average of the points, where all the weights are non-negative.
 - $\Rightarrow BF_0(u), BF_1(u), BF_2(u), BF_3(u) \ge 0$, for all $0 \le u \le 1$.





Cubic B-Splines (s = 1/2)



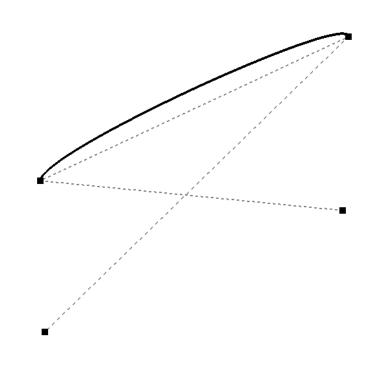
We've only shown convex hull containment of uniform cubic B-splines for a particular choice of s,

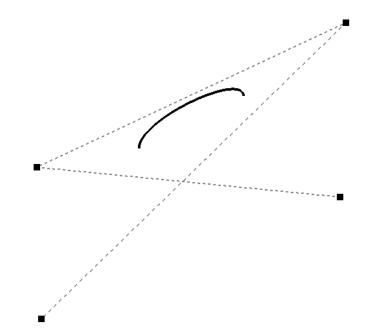
 $\mathbf{P}_k(u) = BF_0(u) \cdot \mathbf{p}_{k-1} + BF_0(u)$



Cardinal Splines (s = 1/2)

Cubic B-Splines (s = 1/2)





 $\mathbf{P}_k(u) = BF_0(u) \cdot \mathbf{p}_{k-1} + BF_1(u) \cdot \mathbf{p}_k + BF_2(u) \cdot \mathbf{p}_{k+1} + BF_3(u) \cdot \mathbf{p}_{k+2}$

Blending Functions



Properties:

• Translation Equivariance : $BF_0(u) + BF_1(u) + BF_2(u) + BF_3(u) = 1$ for all $0 \le u \le 1$.

Continuity:

$$0 = BF_0(1), BF_0(0) = BF_1(1), BF_1(0) = BF_2(1), BF_2(0) = BF_3(1), BF_3(0) = 0$$

Convex Hull Containment:

$$BF_0(u), BF_1(u), BF_2(u), BF_3(u) \ge 0$$
, for all $0 \le u \le 1$.

- Interpolation:
 - We want the spline segments to satisfy:

$$\mathbf{P}_k(0) = \mathbf{p}_k$$
 and $\mathbf{P}_k(1) = \mathbf{p}_{k+1}$

⇒ At the end-points, the blending functions satisfy:

$$BF_0(0) = 0$$
 $BF_0(1) = 0$
 $BF_1(0) = 1$ and $BF_1(1) = 0$
 $BF_2(0) = 0$ $BF_2(1) = 1$
 $BF_3(0) = 0$ $BF_3(1) = 0$

$$\mathbf{P}_k(u) = BF_0(u) \cdot \mathbf{p}_{k-1} + BF_1(u) \cdot \mathbf{p}_k + BF_2(u) \cdot \mathbf{p}_{k+1} + BF_3(u) \cdot \mathbf{p}_{k+2}$$



Cardinal Splines (s = 1/2)

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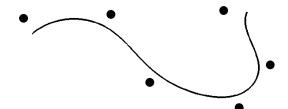
$$BF_0(u) = -\frac{1}{2}u^3 + u^2 - \frac{1}{2}u$$

$$BF_1(u) = \frac{3}{2}u^3 - \frac{5}{2}u^2 + 1$$

$$BF_2(u) = -\frac{3}{2}u^3 + 2u^2 + \frac{1}{2}u$$

$$BF_3(u) = \frac{1}{2}u^3 - \frac{1}{2}u^2$$

$$BF_0(0) = 0$$
 $BF_0(1) = 0$
 $BF_1(0) = 1$ $BF_1(1) = 0$
 $BF_2(0) = 0$ $BF_2(1) = 1$
 $BF_3(0) = 0$ $BF_3(1) = 0$



$$BF_0(u) = -\frac{1}{6}u^3 + \frac{1}{2}u^2 - \frac{1}{2}u + \frac{1}{6}$$

$$BF_1(u) = -\frac{1}{2}u^3 - u^2 + \frac{2}{3}$$

$$BF_2(u) = -\frac{1}{2}u^3 + \frac{1}{2}u^2 + \frac{1}{2}u + \frac{1}{6}$$

$$BF_3(u) = -\frac{1}{2}u^3$$

$$BF_0(0)$$
 $= \frac{1}{6}$ $= \frac{1}{6}$

$$\mathbf{P}_k(u) = BF_0(u) \cdot \mathbf{p}_{k-1} + BF_1(u) \cdot \mathbf{p}_k + BF_2(u) \cdot \mathbf{p}_{k+1} + BF_3(u) \cdot \mathbf{p}_{k+2}$$

Blending Functions



Properties:

Translation Equivariance :

$$BF_0(u) + BF_1(u) + BF_2(u) + BF_3(u) = 1$$
 for all $0 \le u \le 1$.

Continuity:

$$0 = BF_0(1)$$

$$BF_0(0) = BF_1(1)$$

$$BF_1(0) = BF_2(1)$$

$$BF_2(0) = BF_3(1)$$

$$BF_3(0) = 0$$

Required Conditions

Convex Hull Containment:

$$BF_0(u), BF_1(u), BF_2(u), BF_3(u) \ge 0$$
, for all $0 \le u \le 1$.

Interpolation:

$$BF_0(0) 0 BF_0(1) 0 BF_1(0) = 1 and BF_1(1) = 0 BF_2(1) = 1 BF_3(0) 0 BF_3(1) 0$$

Desirable Conditions

$$\mathbf{P}_k(u) = BF_0(u) \cdot \mathbf{p}_{k-1} + BF_1(u) \cdot \mathbf{p}_k + BF_2(u) \cdot \mathbf{p}_{k+1} + BF_3(u) \cdot \mathbf{p}_{k+2}$$

Summary



 A spline is a piecewise polynomial function whose derivatives satisfy some continuity constraints across curve junctions.

Looked at specification for 3 splines:

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    Hermite
    Cardinal

Interpolating, cubic, C<sup>1</sup>
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• Uniform Cubic B-Spline Approximating, convex-hull containment, cubic, C^2

Spline Demo (t = 1 - 2s)