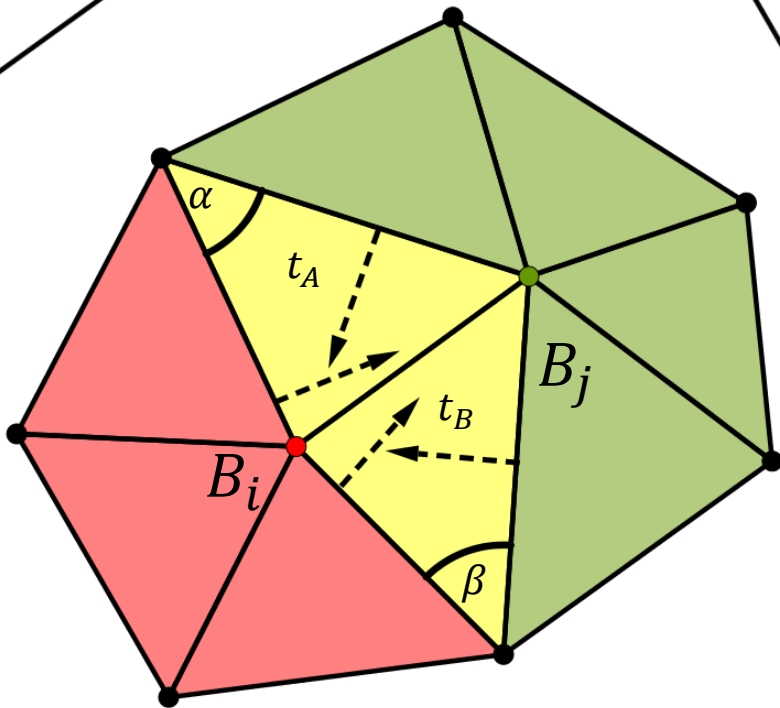
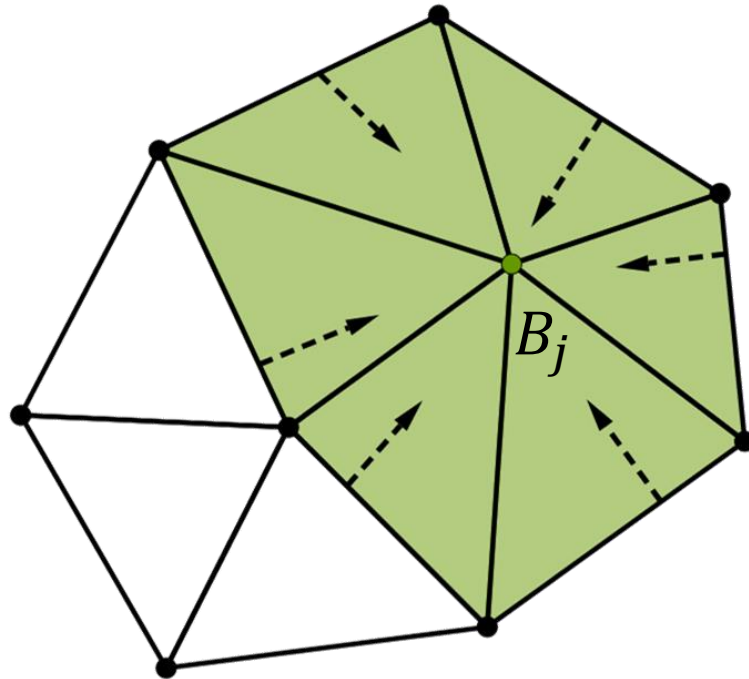
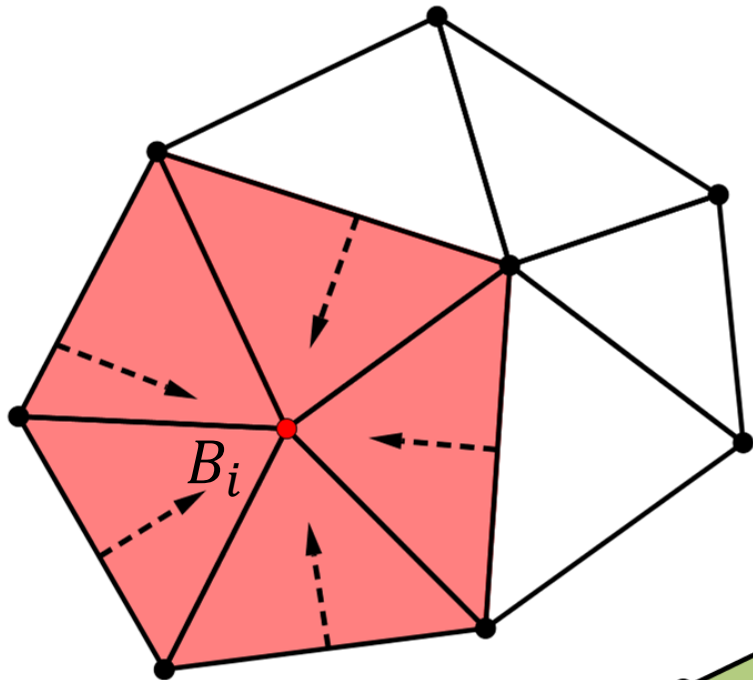


Lecture 8

Introduction to Geometry Processing

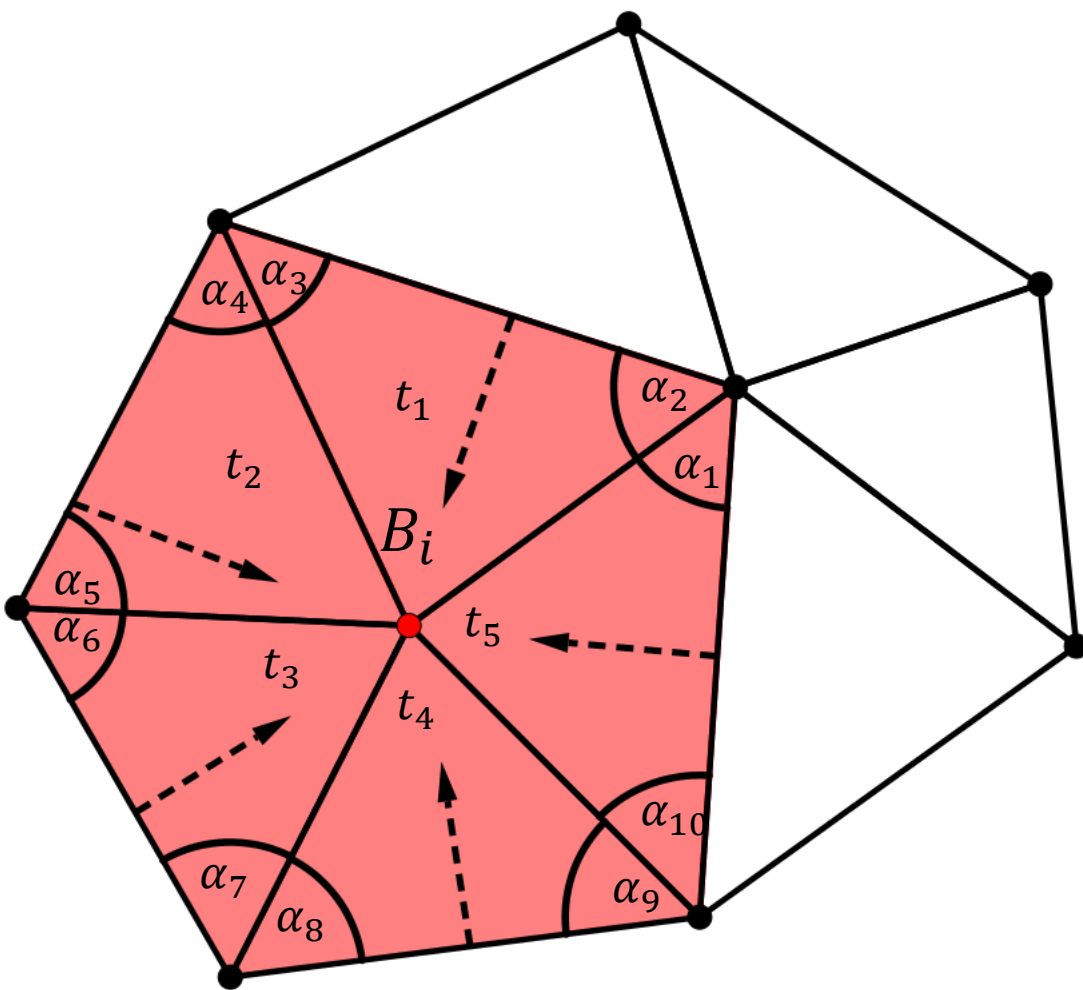
Spring 2017

Johns Hopkins University



$$\int_T B_i B_j = \frac{|t_A| + |t_B|}{12}$$

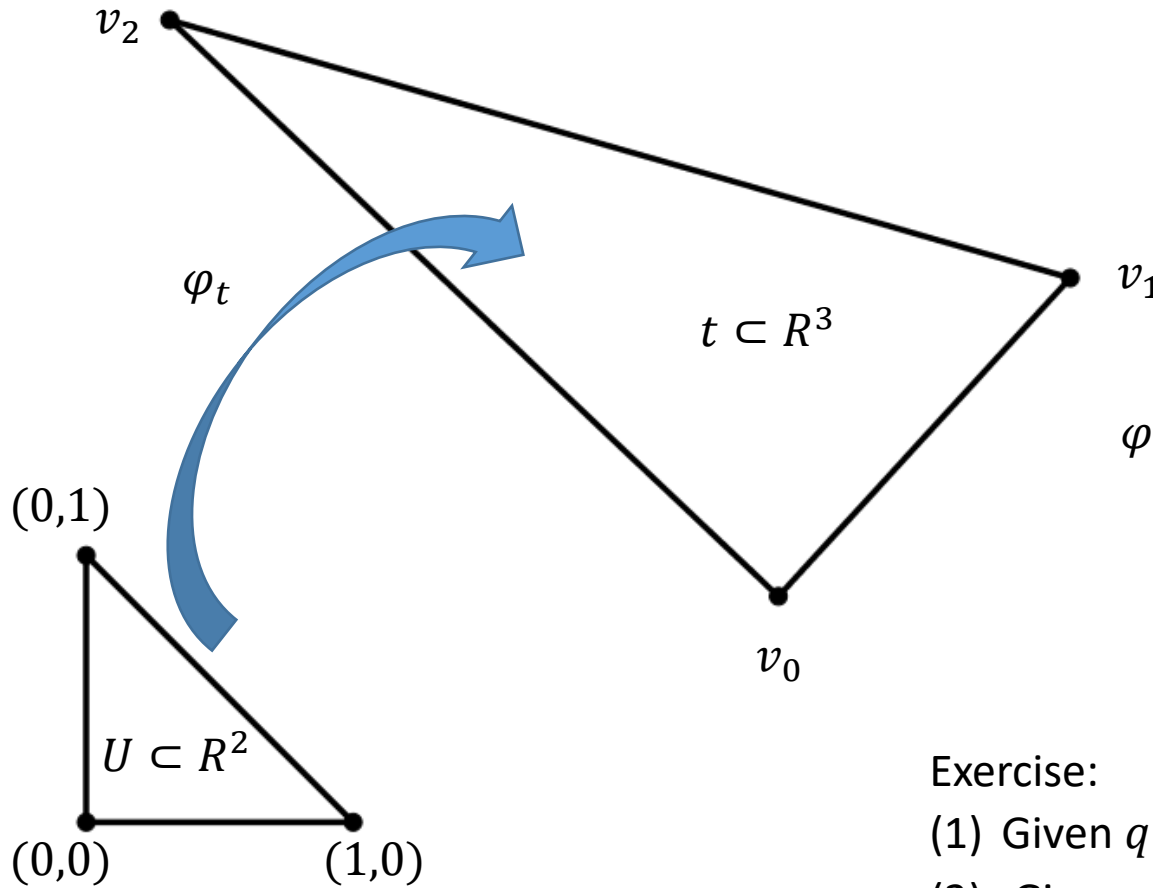
$$\int_T \langle \nabla B_i, \nabla B_j \rangle = -\frac{\cot(\alpha) + \cot(\beta)}{2}$$



$$\int_T B_i^2 = \sum_{t_k \in N(i)} \frac{|t_k|}{6}$$

$$\int_T \langle \nabla B_i, \nabla B_i \rangle = \sum_{\alpha_k \in \partial N(i)} \frac{\cot \alpha_k}{2}$$

Right triangle parametrization



$$\varphi_t: U \subset \mathbb{R}^2 \rightarrow t \subset \mathbb{R}^3$$

$$\varphi_t(0,0) = v_0$$

$$\varphi_t(1,0) = v_1$$

$$\varphi_t(0,1) = v_2$$

$$d\varphi_t: TU \subset \mathbb{R}^2 \rightarrow Tt \subset \mathbb{R}^3$$

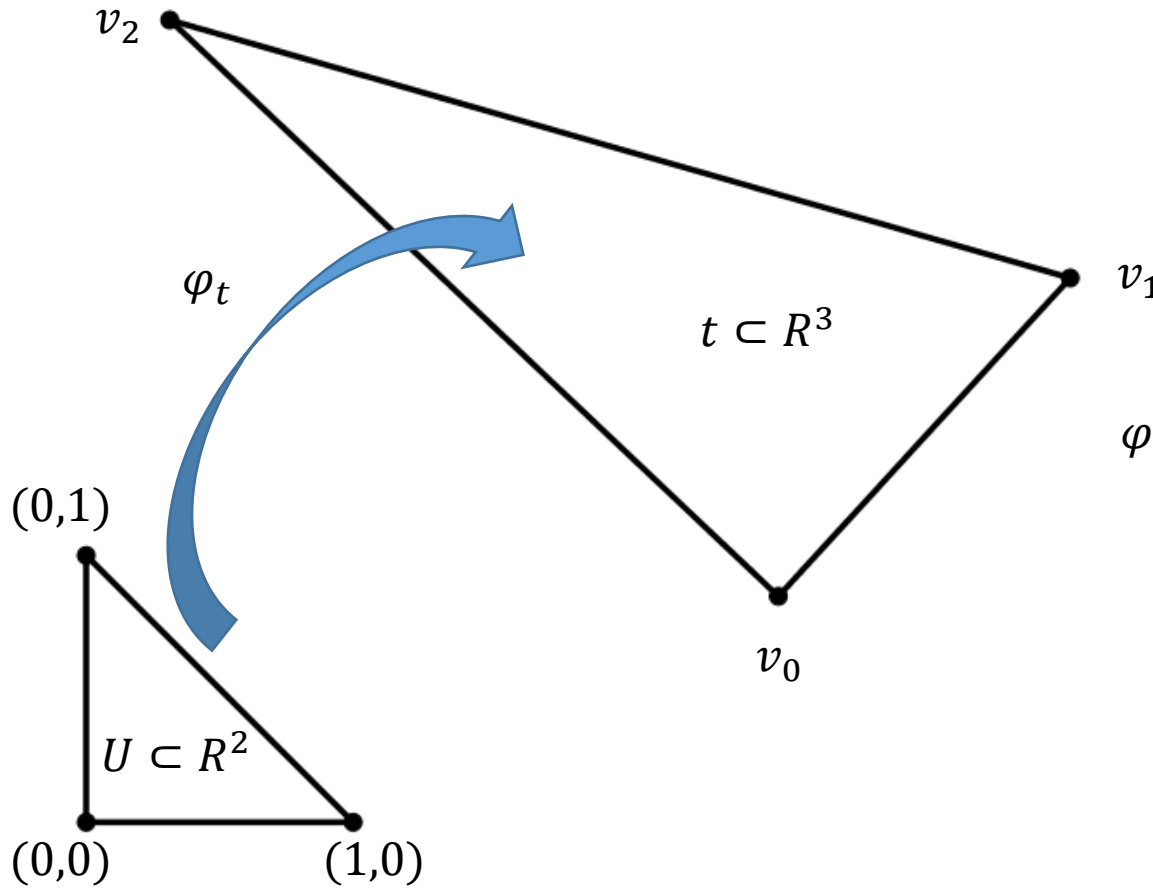
$$d\varphi_t \begin{pmatrix} 1 \\ 0 \end{pmatrix} = v_1 - v_0$$

$$d\varphi_t \begin{pmatrix} 0 \\ 1 \end{pmatrix} = v_2 - v_0$$

Exercise:

- (1) Given $q = (q_x, q_y) \in U$ compute $\varphi_t(q)$.
- (2) Given $p = (p_x, p_y, p_z) \in t$ compute $\varphi_t^{-1}(p)$.
- (3) Given $v = (v_x, v_y) \in TU$ compute $d\varphi_t(v)$.
- (4) Given $w = (w_x, w_y, w_z) \in Tt$ compute $d\varphi_t^{-1}(w)$.

Right triangle parametrization



$$\varphi_t: U \subset \mathbb{R}^2 \rightarrow t \subset \mathbb{R}^3$$

$$\varphi_t(0,0) = v_0$$

$$\varphi_t(1,0) = v_1$$

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$$d\varphi_t: TU \subset \mathbb{R}^2 \rightarrow Tt \subset \mathbb{R}^3$$

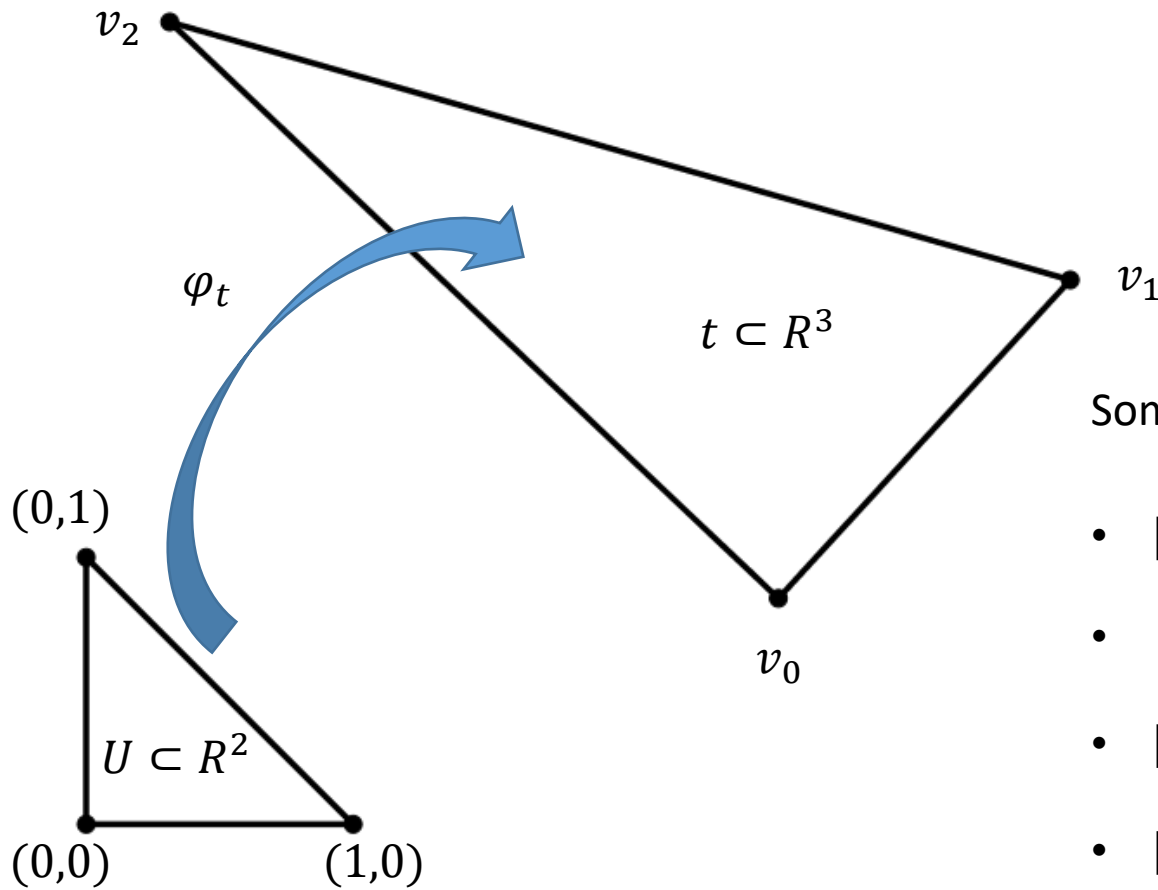
$$d\varphi_t \begin{pmatrix} 1 \\ 0 \end{pmatrix} = v_1 - v_0$$

$$d\varphi_t \begin{pmatrix} 0 \\ 1 \end{pmatrix} = v_2 - v_0$$

Definition: The metric tensor on the right unit triangle induced by the triangle embedding is given by,

$$g_t = d\varphi_t^\top d\varphi_t$$

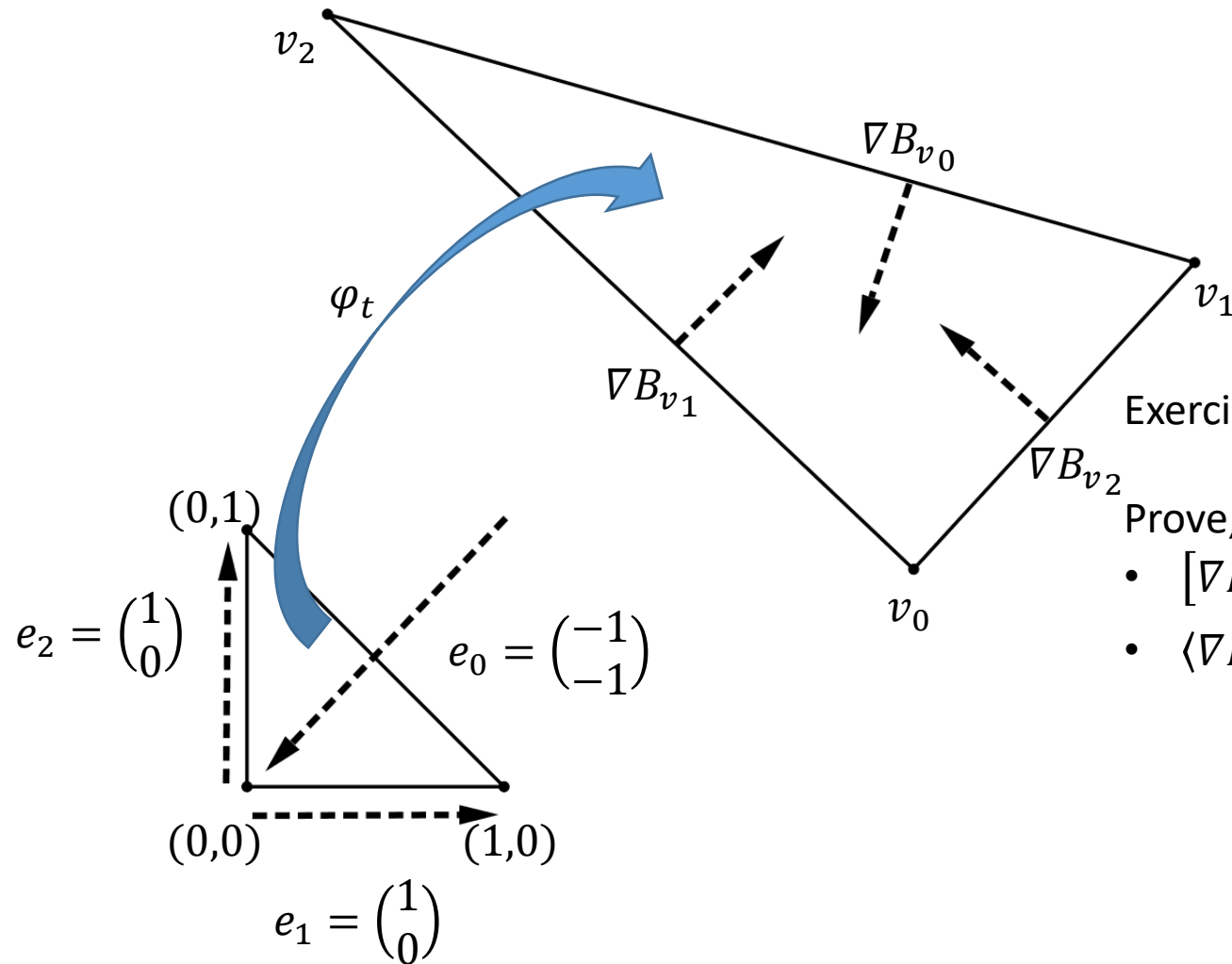
Right triangle parametrization



Some properties of $g_t = d\varphi_t^\top d\varphi_t$:

- $|t| = \frac{1}{2} \sqrt{\det g_t}$
- $|v_1 - v_0|^2 = \langle \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix} \rangle_{g_t} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}^\top g_t \begin{pmatrix} 1 \\ 0 \end{pmatrix}$
- $|v_2 - v_0|^2 = \langle \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \rangle_{g_t} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}^\top g_t \begin{pmatrix} 0 \\ 1 \end{pmatrix}$
- $|v_2 - v_1|^2 = \langle \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \end{pmatrix} \rangle_{g_t} = \begin{pmatrix} -1 \\ 1 \end{pmatrix}^\top g_t \begin{pmatrix} -1 \\ 1 \end{pmatrix}$

Right triangle parametrization

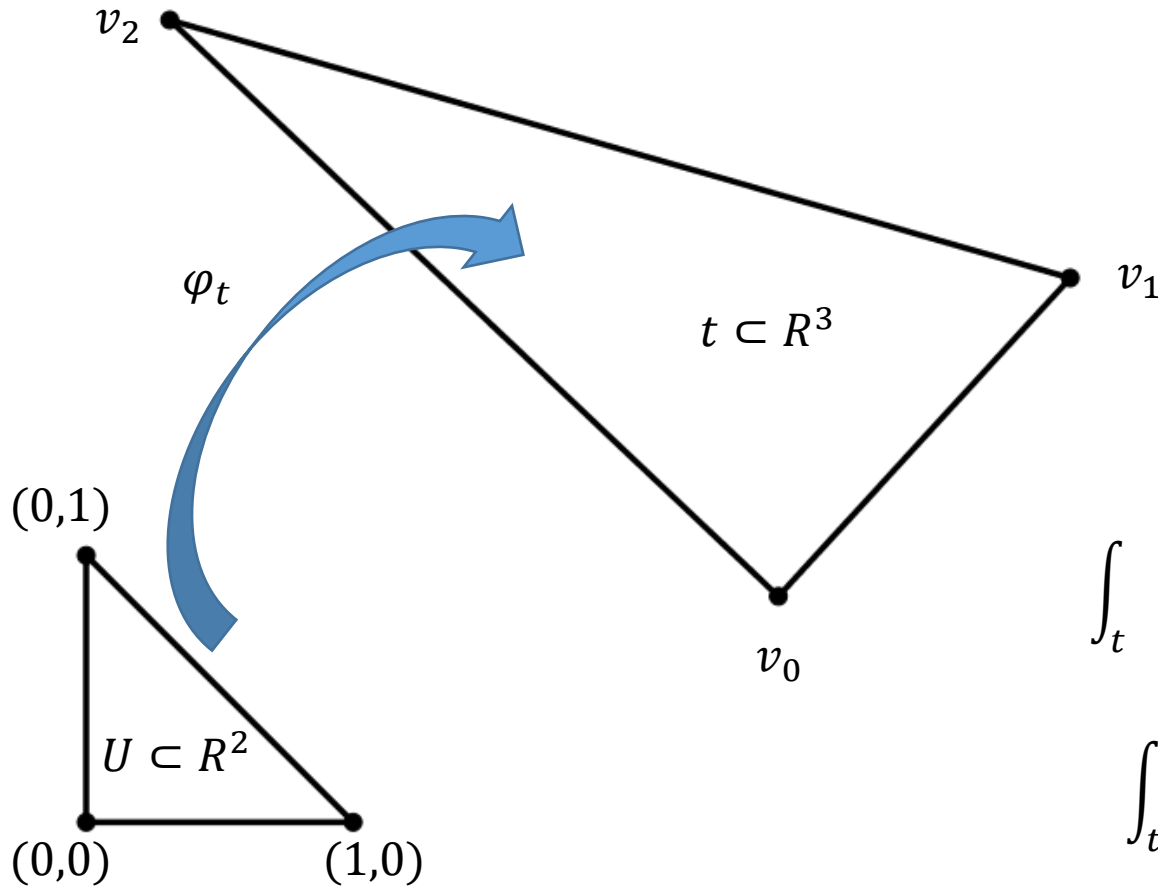


Exercise:

Prove,

- $[\nabla B_{v_i}] := d\varphi_t^{-1}(\nabla B_{v_i}) = g_t^{-1}e_i$
- $\langle \nabla B_{v_i}, \nabla B_{v_j} \rangle = \langle [\nabla B_{v_i}], [\nabla B_{v_j}] \rangle_{g_t} = e_i^\top g_t^{-1}e_j$

Right triangle parametrization



$$\int_t B_{v_i} B_{v_j} = \frac{\sqrt{\det g_t}}{24}$$

$$\int_t B_{v_i} B_{v_i} = \frac{\sqrt{\det g_t}}{12}$$

$$\int_t \langle \nabla B_{v_i}, \nabla B_{v_j} \rangle = e_i^\top g_t^{-1} e_j \frac{\sqrt{\det g_t}}{2}$$

$$M_{ij} = \int_T B_i B_j \rightarrow \text{Mass matrix}$$

$$S_{ij} = \int_T \langle \nabla B_i, \nabla B_j \rangle \rightarrow \text{Stiffness matrix}$$

Exercise:

Let $\vec{1}$, be the vector of ones.

(a) Prove $\vec{1}^T M \vec{1} = \sum_{t \in T} |t|$.

(b) Prove $S \vec{1} = \vec{0}$

(c) Whats the null space of S ?

Filtering

Given, $g = \sum_i g_i B_i$, find $f = \sum_i f_i B_i$, that minimize:

$$\min_f ||f - g||^2 + \alpha ||\nabla f - \beta \nabla g||^2$$

$$||f - g||^2 := \int_T (f - g)^2 = ([f] - [g])^\top M ([f] - [g])$$

$$||\nabla f - \beta \nabla g||^2 := \int_T \langle \nabla f - \beta \nabla g, \nabla f - \beta \nabla g \rangle = ([f] - \beta [g])^\top S ([f] - \beta [g])$$

$$\min_{[f]} [f]^\top (M + \alpha S) [f] - [f]^\top (M + \alpha \beta S) [g]$$

$$[f] = (M + \alpha S)^{-1} (M + \alpha \beta S) [g]$$

Example



$$\alpha = 0, \beta = 0$$



$$\alpha = 10^{-4}, \beta = 0$$



$$\alpha = 10^{-4}, \beta = 2$$

Poisson Problem

Compute the closest gradient field to a vector field v :

$$\min_f ||\nabla f - v||^2$$

Q. How many degrees of freedom has v ?

$$G: R^V \rightarrow R^{2T}, G_{i \in V, t \in T} = \begin{cases} g_t^{-1} e_{c(i)} & \text{If } i \text{ is the } c(i)\text{-corner of } t \\ 0 & \text{Otherwise} \end{cases}$$

Gradient matrix

$$[\nabla f] = G[f]$$

Prove: $S = G^T N G$

Prove: $\min_f ||\nabla f - v||^2$, is given by $S [\nabla f] = (G^T N[v])$.

$$N: R^{2T} \rightarrow R^{2T} = \begin{pmatrix} \frac{g_1^{-1} \sqrt{\det g_1}}{2} & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \frac{g_N^{-1} \sqrt{\det g_N}}{2} \end{pmatrix}$$

Vector product matrix

$$\langle u, v \rangle = [u]N[v]$$

How many solution does this equation have?

Application: Approximate Geodesic Distances

Algorithm:

Input: $i \leftarrow$ Vertex index

Output: $d \leftarrow$ approximate geodesic distance to v_i .

1. Solve for

$$\min_f ||f - \delta_i||^2 + \alpha ||\nabla f||^2$$

2. For each triangle let $v_t = \frac{\nabla f|_t}{||\nabla f|_t||}$

3. Solve for

$$\min_d ||\nabla d - v||^2$$

4. Offset d by a constant to have $d[i] = 0$.

