



Convex Hulls (3D)

O'Rourke, Chapter 4

Announcements



- Assignment 2 has been posted



Outline

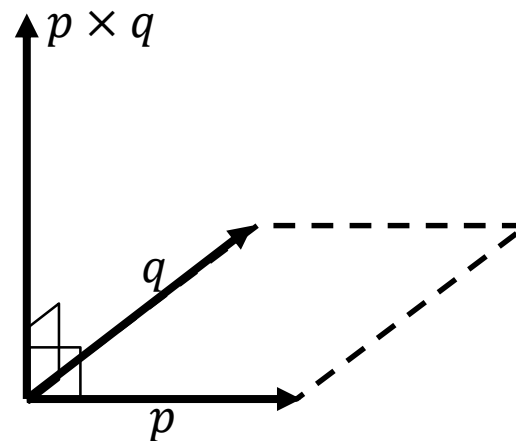
- Review
- Gift-Wrapping
- Divide-and-Conquer



Recall

Given points $p, q \in \mathbb{R}^3$, the *cross-product* $p \times q \in \mathbb{R}^3$ is the vector:

- perpendicular to both p and q ,
- oriented according to the right-hand-rule,
- with length equal to the area of the parallelogram defined by p and q .

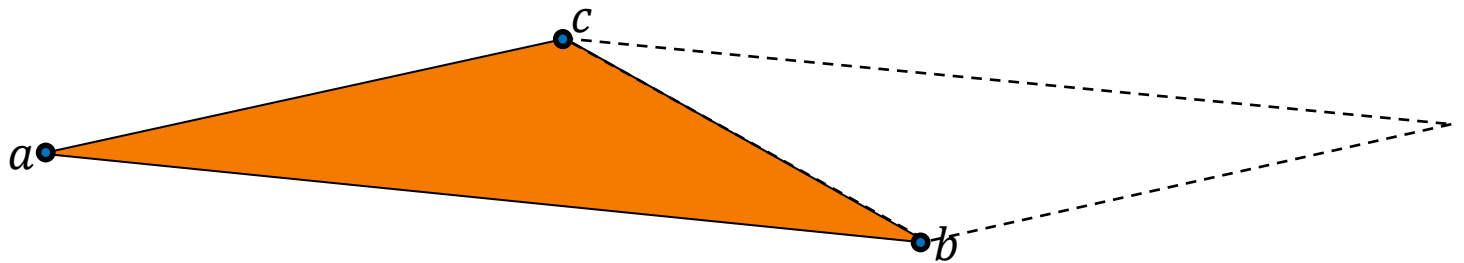




Recall

Given a triangle T with vertices $(a, b, c) \in \mathbb{R}^3$, the area of the triangle is:

$$\text{Area}(T) = \frac{1}{2} \times \|(b - a) \times (c - a)\|$$

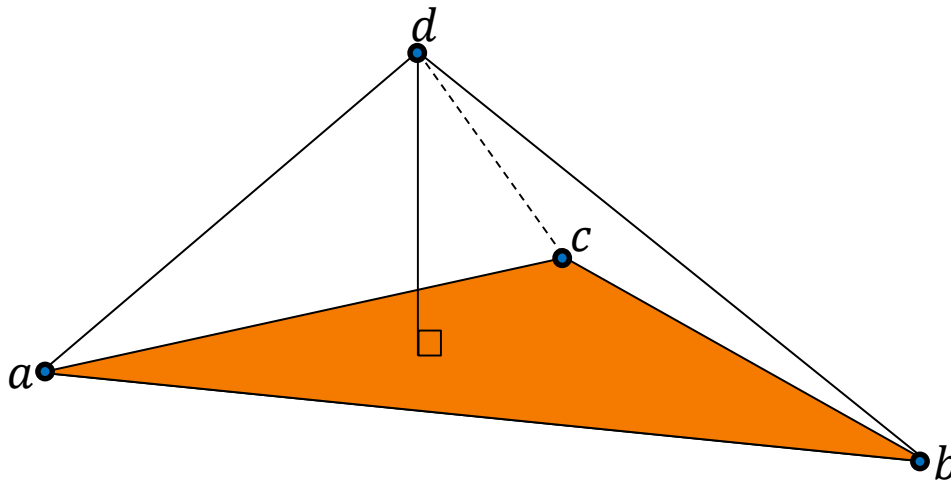




Recall

Given a tetrahedron T with vertices $(a, b, c, d) \in \mathbb{R}^3$, the volume of the tetrahedron is:

$$\text{Volume}(T) = \frac{1}{3} \times \text{base} \times \text{height}$$

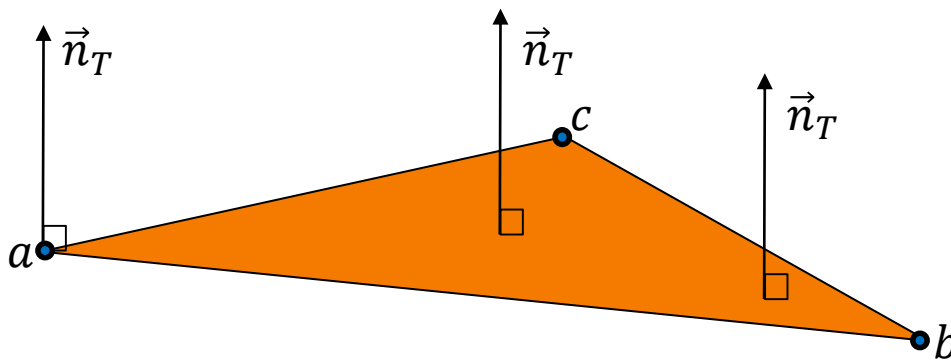




Recall

Given a triangle T with vertices $(a, b, c) \in \mathbb{R}^3$, the triangle normal is:

$$\vec{n}_T = \frac{(b - a) \times (c - a)}{\|(b - a) \times (c - a)\|}$$

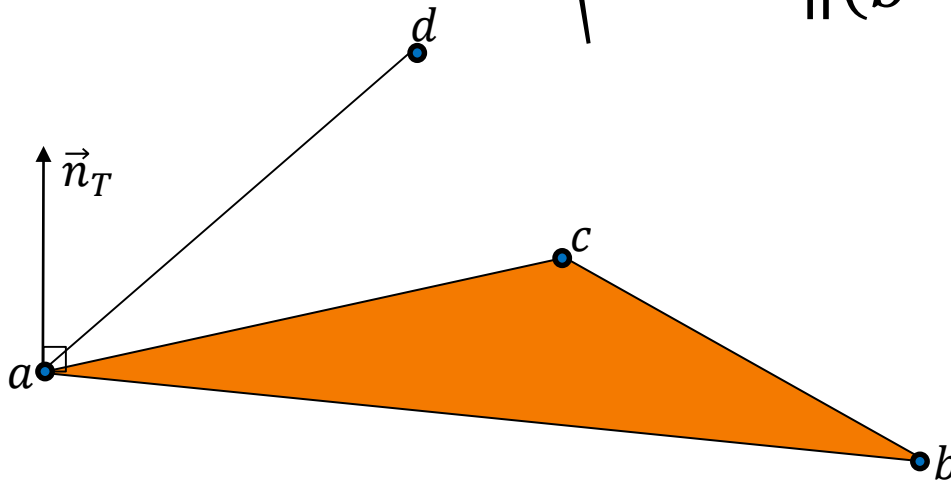




Recall

Given a triangle T with vertices $(a, b, c) \in \mathbb{R}^3$ and given a point $d \in \mathbb{R}^3$, the signed perpendicular height of d from the plane containing (a, b, c) is:

$$\begin{aligned} \text{Height}(T, d) &= \langle d - a, \vec{n}_T \rangle \\ &= \left\langle d - a, \frac{(b - a) \times (c - a)}{\|(b - a) \times (c - a)\|} \right\rangle \end{aligned}$$

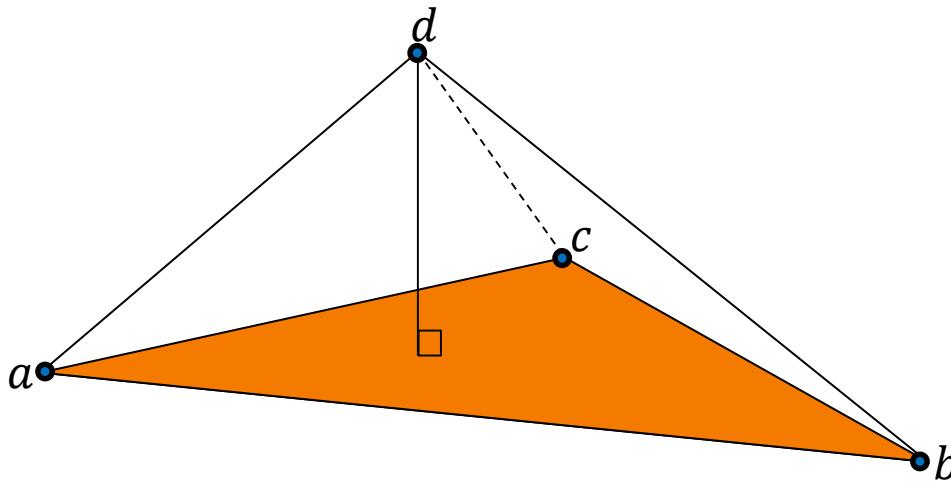




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$$\begin{aligned}\text{Volume}(T) &= \frac{1}{3} \times \text{base} \times \text{height} \\ &= \frac{1}{6} \times \langle d - a, (b - a) \times (c - a) \rangle\end{aligned}$$

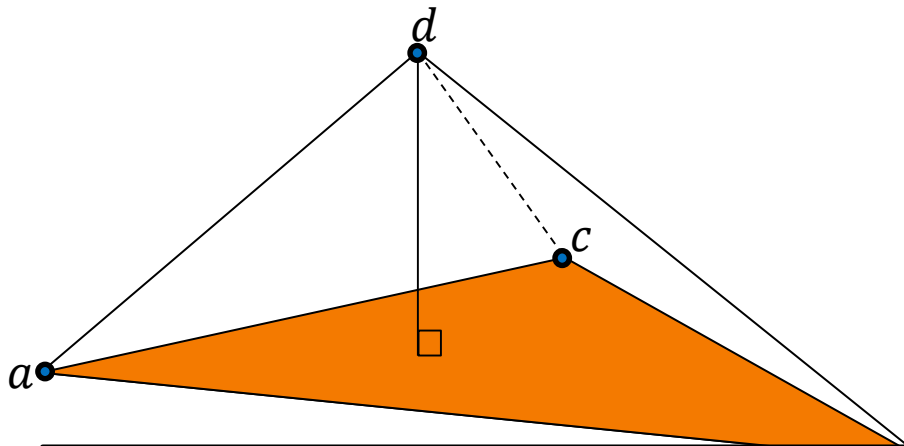




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The volume is positive if d is to the left of the plane defined by the triangle (a, b, c) .



Recall

If we have a graph G with bounded degree, we can identify the connected component containing a node v by performing a flood-fill.

FloodFill(v , G)

- if(NotMarked(v))
 - » Mark(v)
 - » for $w \in$ Neighbors(v)
 - FloodFill(w , G)

Complexity: $O(|G|)$



Recall

If we have a graph G with bounded degree, we can identify the connected component containing a node v by performing a flood-fill.

In particular given a winged-edge representation of a triangle mesh and given a face in the mesh, we can compute the connected component of the face in linear time.



Outline

- Review
- Gift-Wrapping
- Divide-and-Conquer



Gift-Wrapping

Initialization:

Find a triangle on the hull.

Iteratively:

Until the hull closes, pivot around a boundary edge.



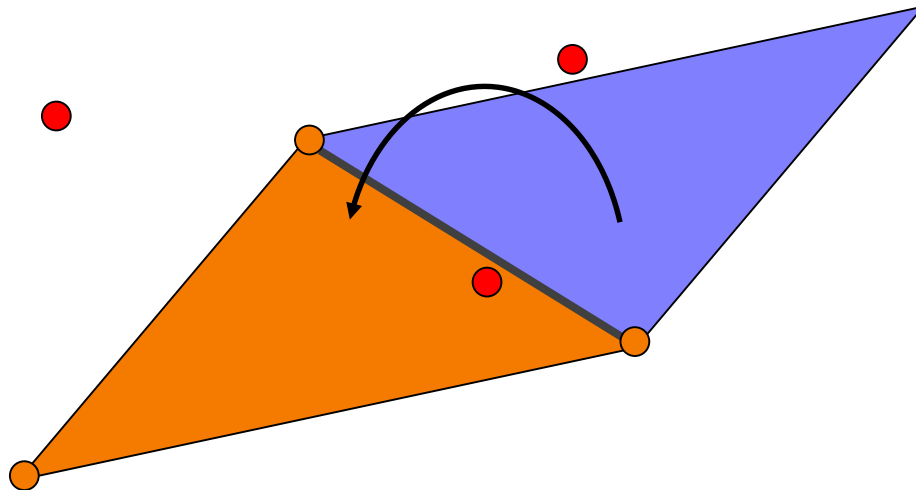
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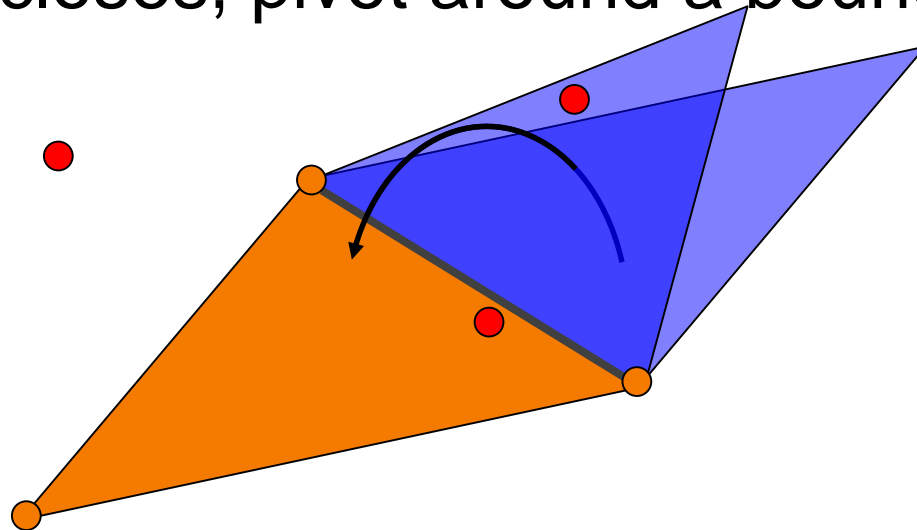
Gift-Wrapping

Initialization:

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Iteratively:

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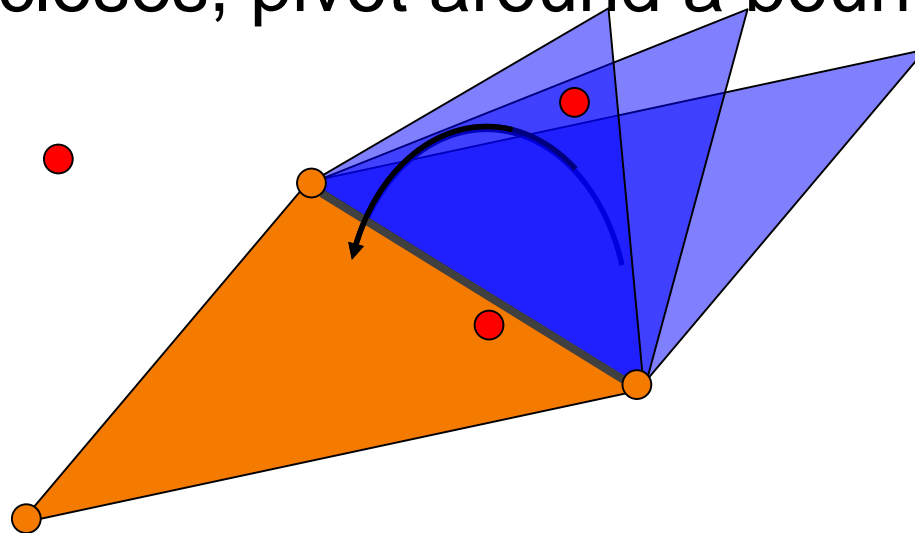
Gift-Wrapping

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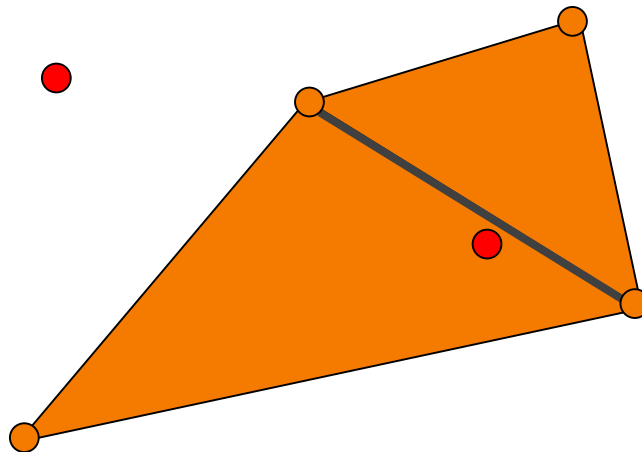
Gift-Wrapping

Initialization:

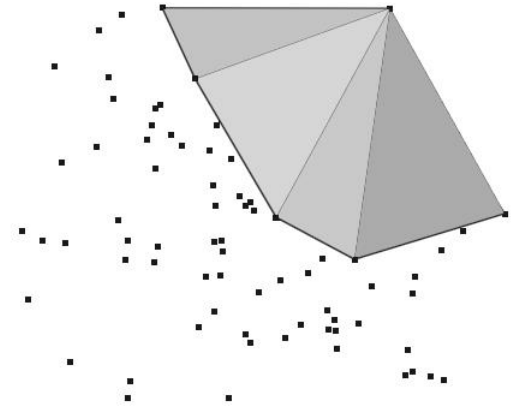
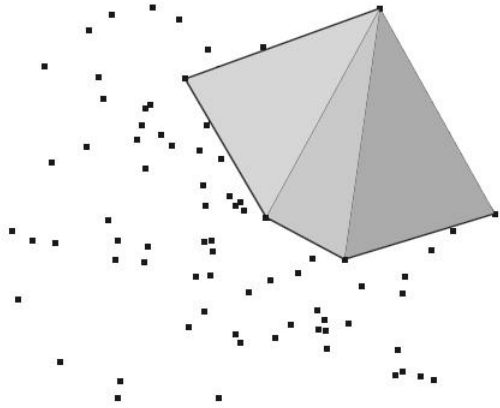
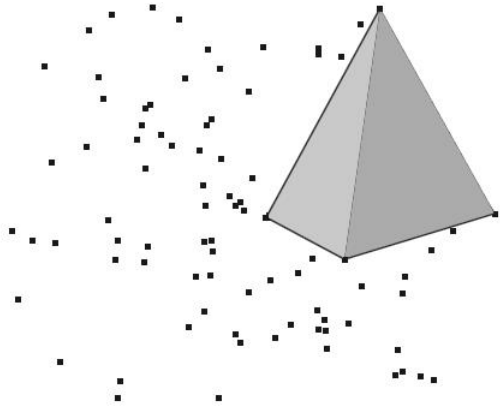
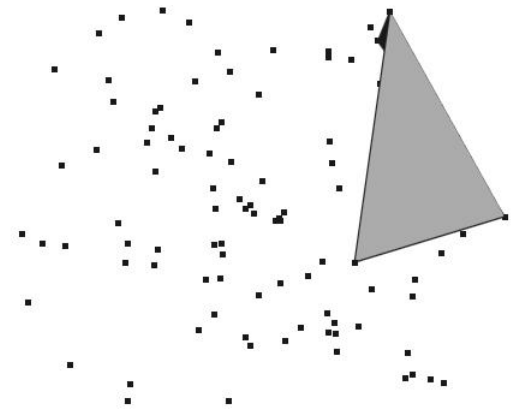
Find a triangle on the hull.

Iteratively:

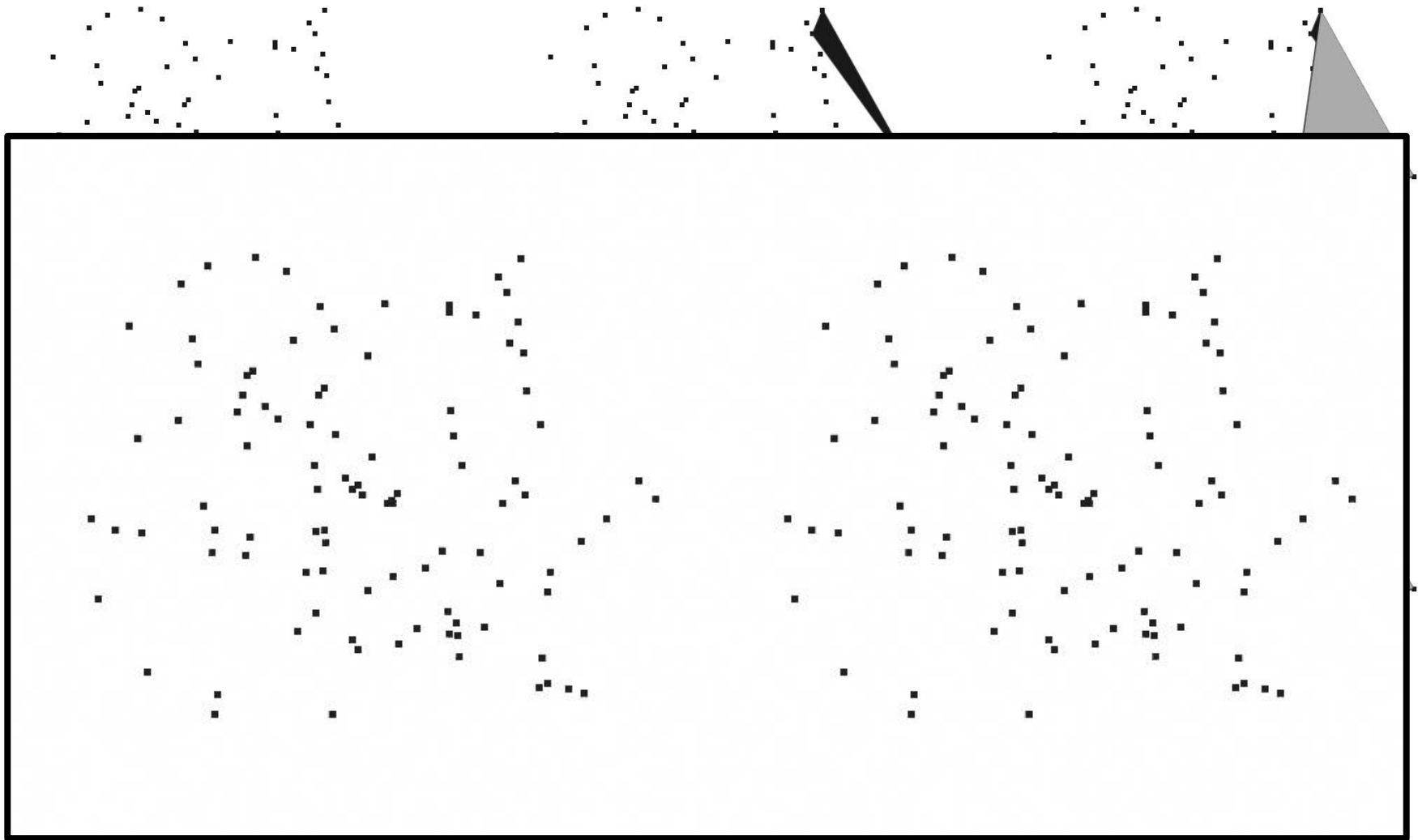
Until the hull closes, pivot around a boundary edge.



Gift-Wrapping



Gift-Wrapping





Gift-Wrapping

PivotAroundEdge($e = \{q_0, q_1\}$, $P = \{p_0, \dots, p_{n-1}\}$)

- $p \leftarrow p_0$
- $area2 \leftarrow \text{SquaredArea}(q_0, q_1, p)$
- for $p' \in \{p_1, \dots, p_{n-1}\}$:
 - » $volume \leftarrow \text{SignedVolume}(q_0, q_1, p, p')$
 - » if($volume < 0$)
 - $p \leftarrow p'$
 - » else if($volume == 0$)
 - $_area2 \leftarrow \text{SquaredArea}(q_0, q_1, p')$
 - if($_area2 > area2$)
 - $p \leftarrow p'$
 - $area2 \leftarrow _area2$
- return p

Complexity: $O(n)$



Gift-Wrapping

FindTriangleOnHull($P = \{p_0, \dots, p_{n-1}\}$)

- $\{p, q\} \leftarrow \text{FindEdgeOnHull}(P)$
- $r \leftarrow \text{PivotAroundEdge}(\{p, q\}, P)$
- return $\{p, q, r\}$



Gift-Wrapping

FindEdgeOnHull($P = \{p_0, \dots, p_{n-1}\}$)

- $p \leftarrow \text{BottomMostLeftMostBackMost}(P)$
- $q \leftarrow p$
- for $r \in P$:
 - » if($q_z == r_z \ \&\& \ q_y == r_y \ \&\& \ q_x < r_x$)
 - $q \leftarrow r$
- if($q == p$)
 - » $q \leftarrow p + (1, 0, 0)$
- $q \leftarrow \text{PivotOnEdge}(\{p, q\}, P)$
- return $\{p, q\}$



Gift-Wrapping

GiftWrap(P):

- $t \leftarrow \text{FindTriangleOnHull}(P)$
- $Q \leftarrow \{ (t_1, t_0), (t_2, t_1), (t_0, t_2) \}$
- $H \leftarrow \{ t \}$
- while($Q \neq \emptyset$)
 - » $e \leftarrow Q.\text{pop_back}()$
 - » if(NotProcessed(e))
 - $q \leftarrow \text{PivotOnEdge}(e)$
 - $t \leftarrow \text{Triangle}(e, q)$
 - $H \leftarrow H \cup \{ t \}$
 - $Q \leftarrow Q \cup \{ (t_1, t_0), (t_2, t_1), (t_0, t_2) \}$
 - MarkProcessedEdges(e)

Complexity: $O(n^2)$



Outline

- Review
- Gift-Wrapping
- Divide-and-Conquer



Divide And Conquer

DivideAndConquer(P):

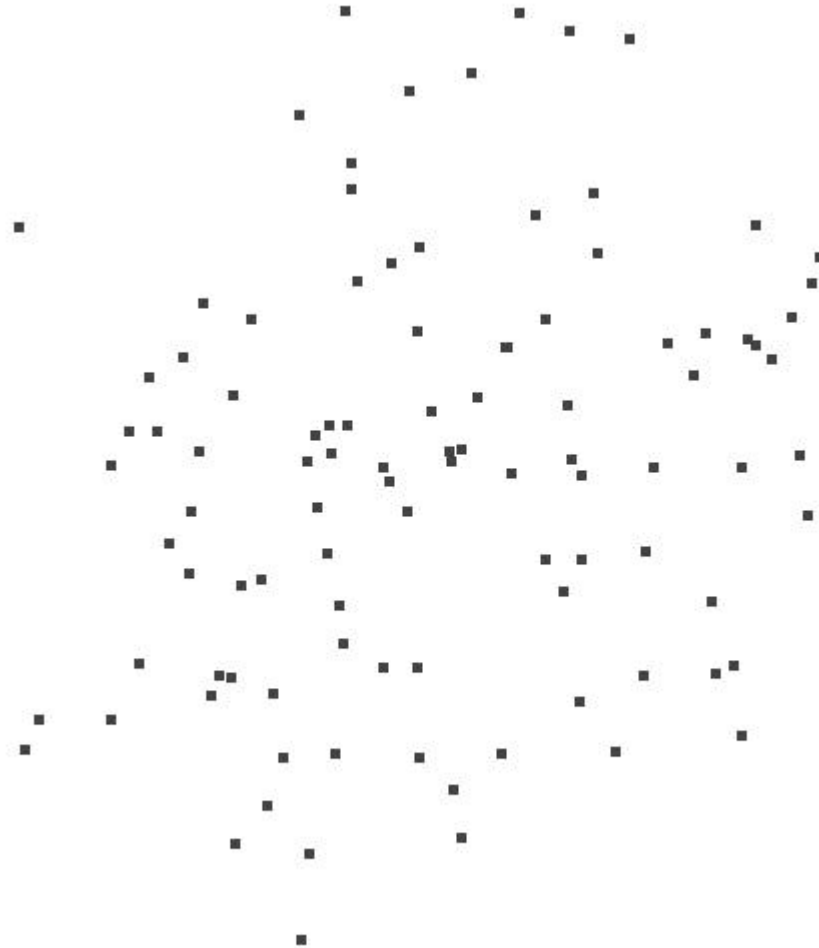
- $P \leftarrow \text{SortByX}(P)$
- return $_DivideAndConquer(P)$

$_DivideAndConquer(P)$

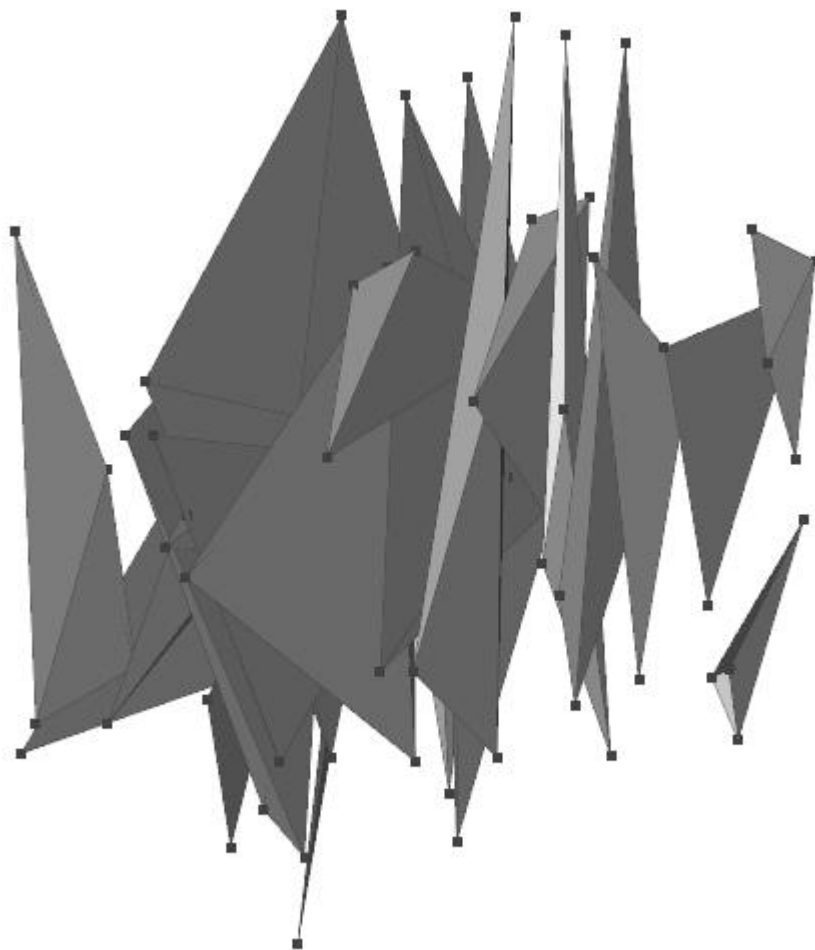
- if($|P| < 8$) return $\text{Incremental}(P)$
- $(P_1, P_2) \leftarrow \text{SplitInHalf}(P)$
- $H_1 \leftarrow _DivideAndConquer(P_1)$
- $H_2 \leftarrow _DivideAndConquer(P_2)$
- return $\text{Merge}(H_1 , H_2)$

Complexity: $O(n \log n)$

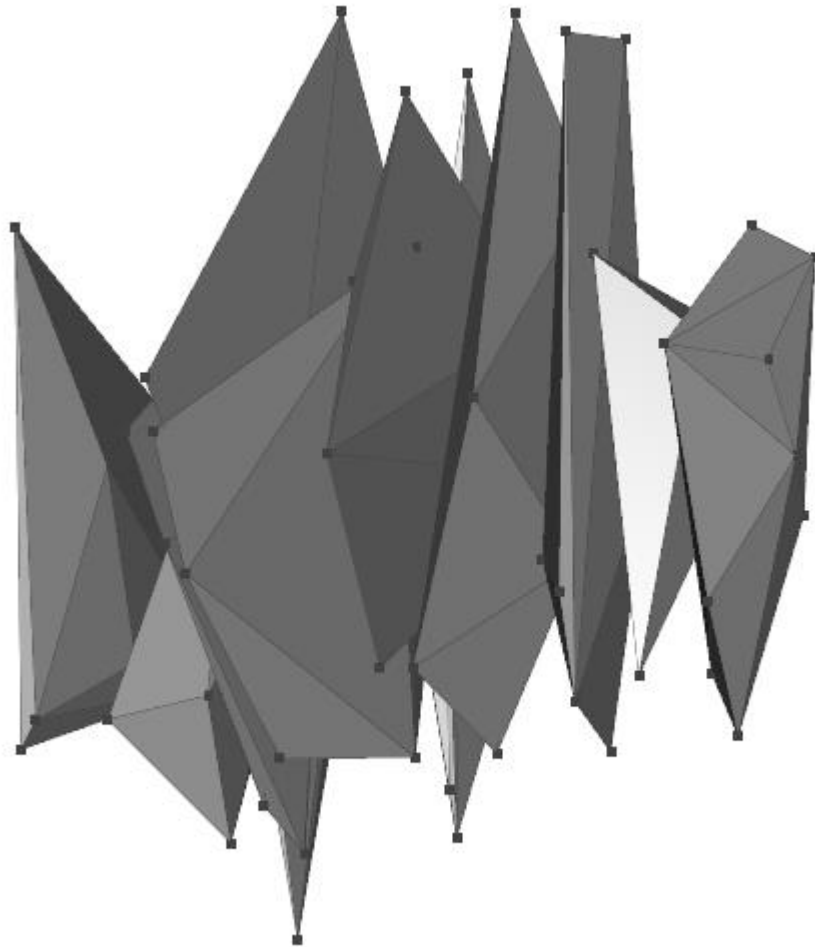
Divide And Conquer



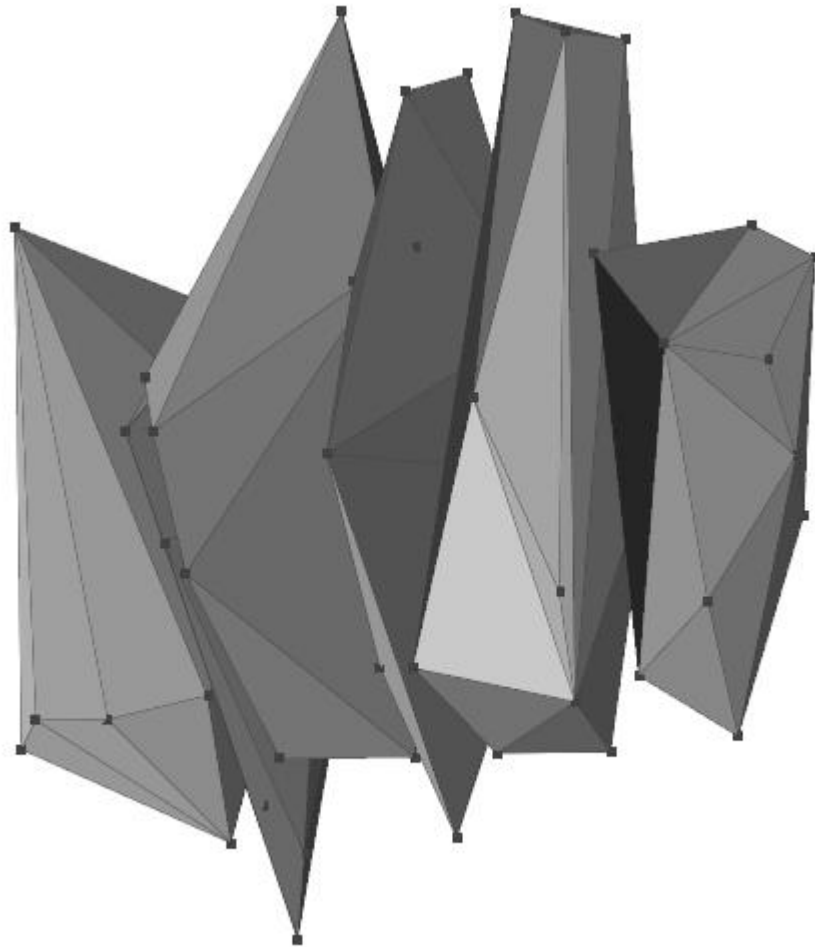
Divide And Conquer



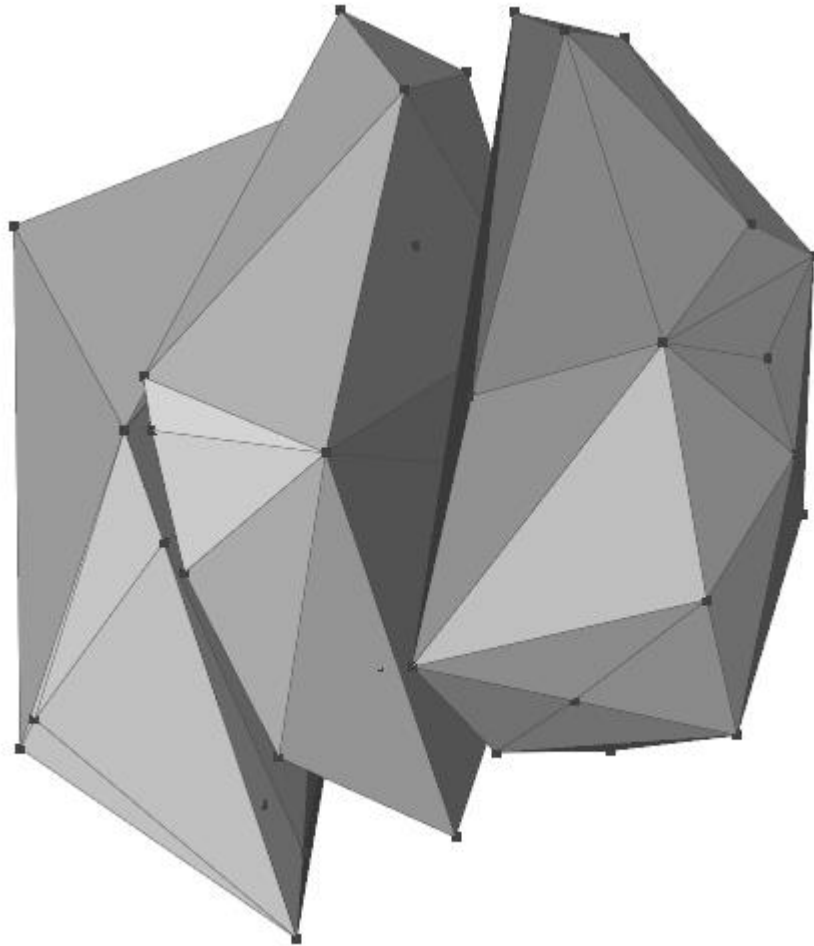
Divide And Conquer



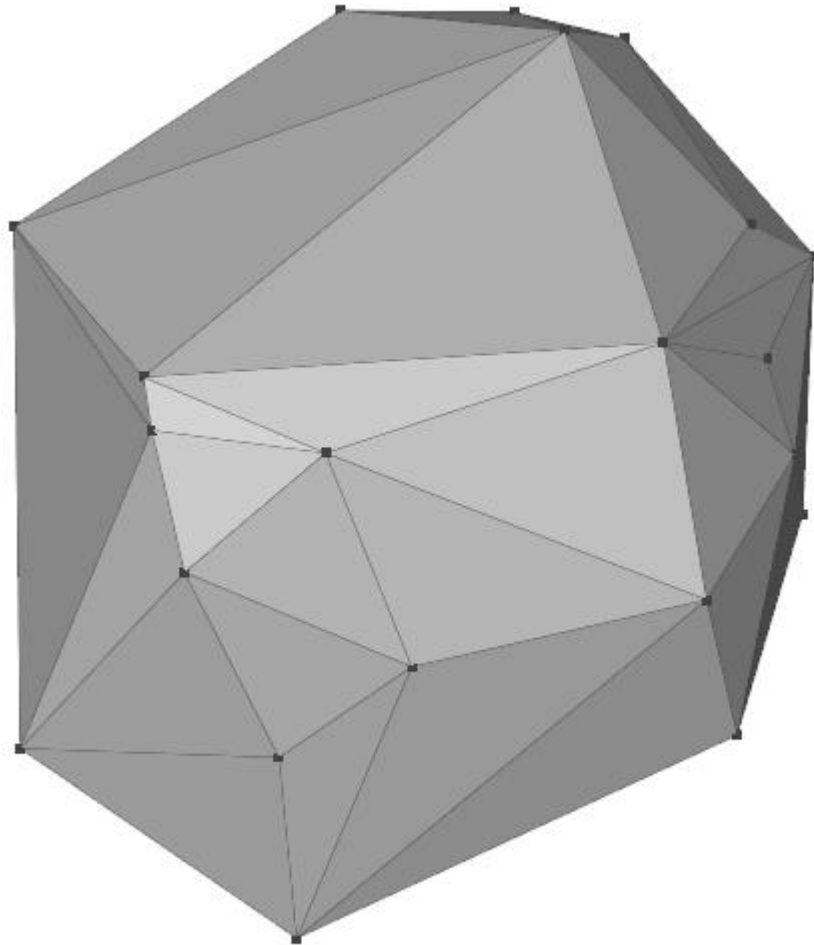
Divide And Conquer



Divide And Conquer



Divide And Conquer

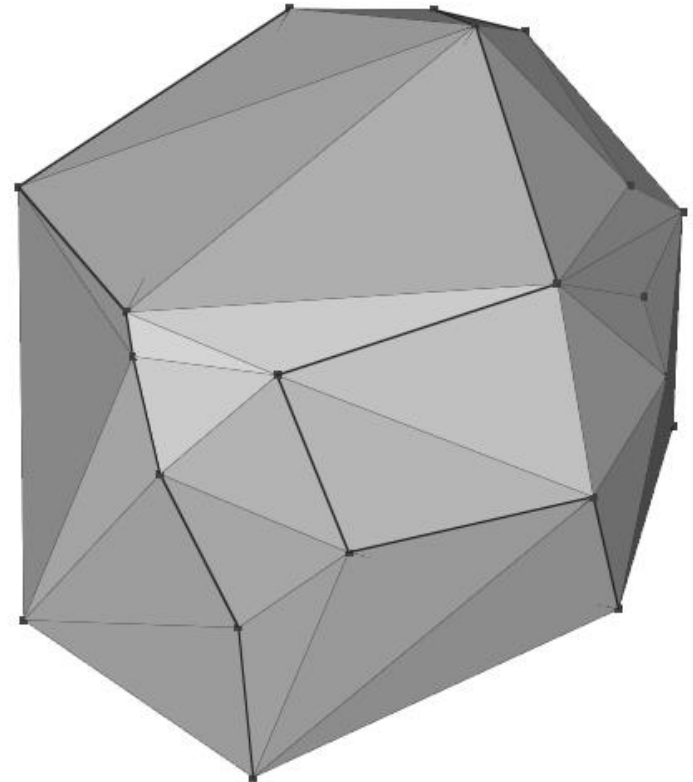




Divide And Conquer

Merge:

- Construct the fillet that merges the two hulls
- Remove the triangles that are no longer visible



Note:

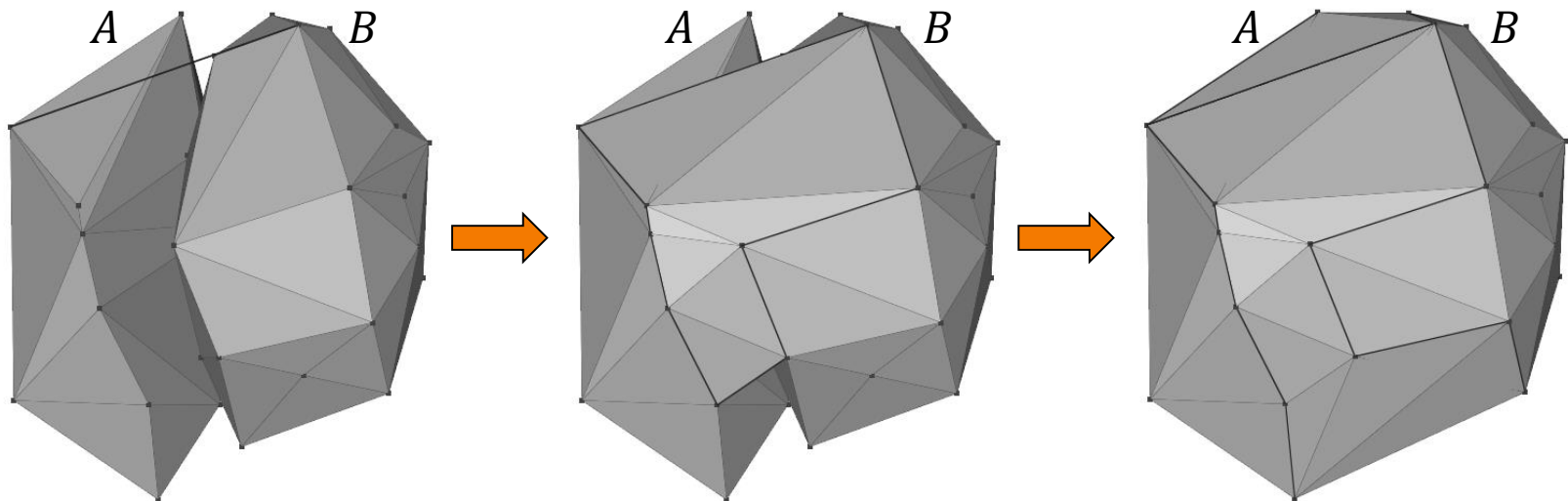
The fillet has linear complexity since each triangle on the fillet uses an edge from one of the two hulls.



Divide And Conquer

Constructing the Fillet:

- Find a supporting line
- Pivot around the supporting line

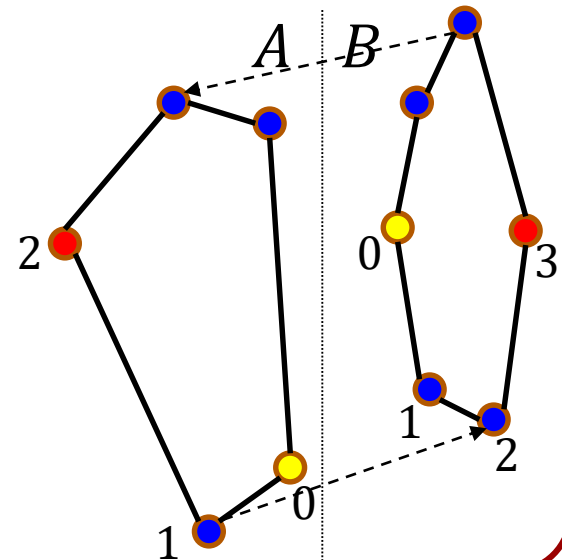




Divide And Conquer

Finding a Supporting Line:

- While computing the 3D hull (recursively), simultaneously compute the 2D hull of the projection of the points onto the xy -plane.
- The supporting lines in 2D correspond to supporting lines in 3D.





Divide And Conquer

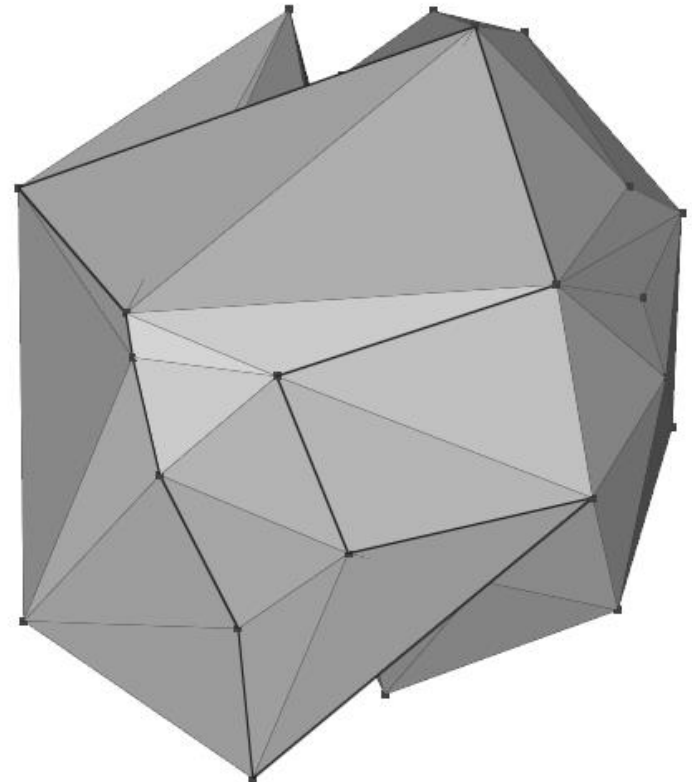
Pivot Around the Supporting Line:

- Proceed as in the gift-wrap algorithm.

Challenge:

- To run in linear time, we can't try all points.

When we pivot, the first point we hit is one of the neighbors of the line's end-points.





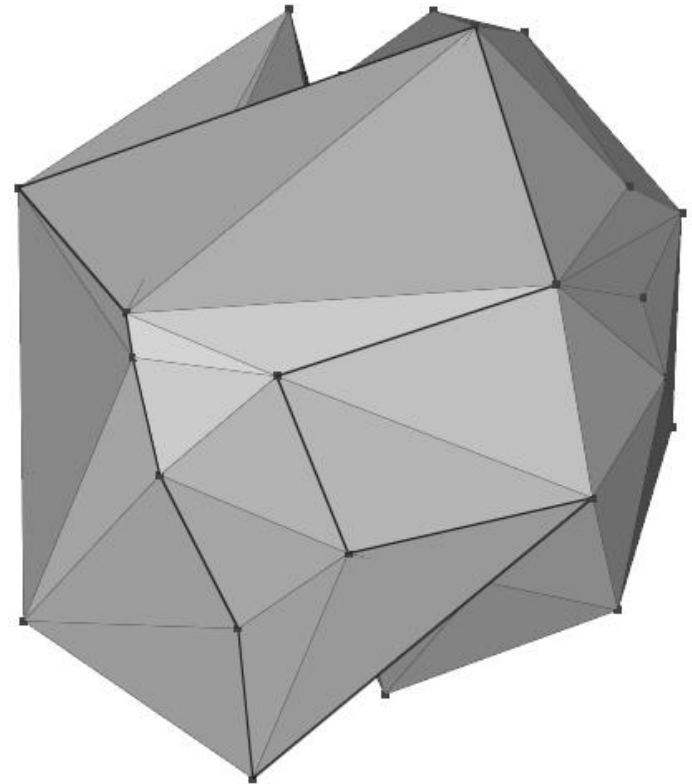
Divide And Conquer

Pivot Around the Supporting Line:

- Proceed as in the gift-wrap algorithm.

Challenge:

- This could still be costly since a vertex can have many neighbors.
(e.g. If the right endpoint has many neighbors but the pivot keeps hitting a vertex on the left.)





Divide And Conquer

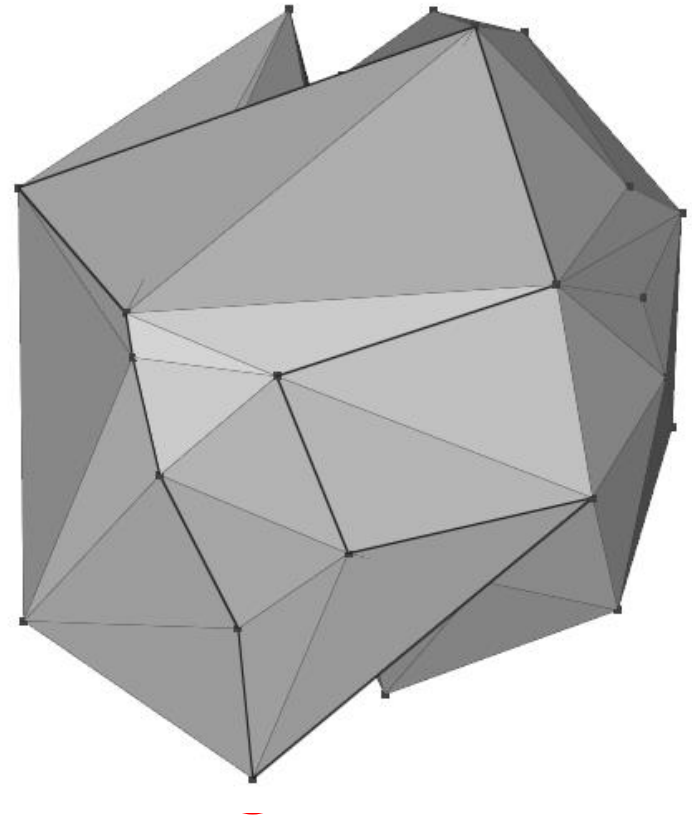
Pivot Around the Supporting Line:

- Proceed as in the gift-wrap algorithm.

Challenge:

- This could still be costly since a vertex can have many neighbors.

We can use the previous estimated (failed) hit to constrain the next one.

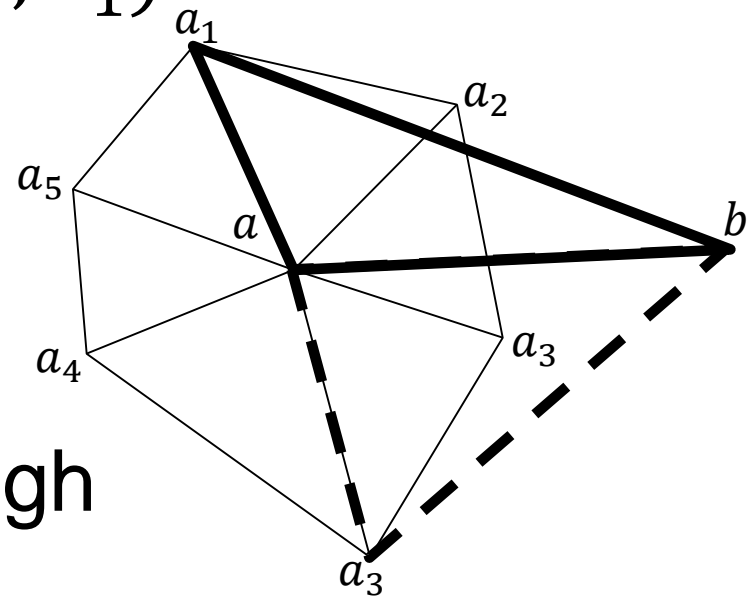




Divide And Conquer

More Specifically:

- Assume the fillet is at edge (a, b) having just added triangle (a, b, a_1) .
- Sort the neighbors of a CW starting from a_1 .
- Let a_s be the neighbor of a s.t. the plane through (b, a, a_s) supports A .

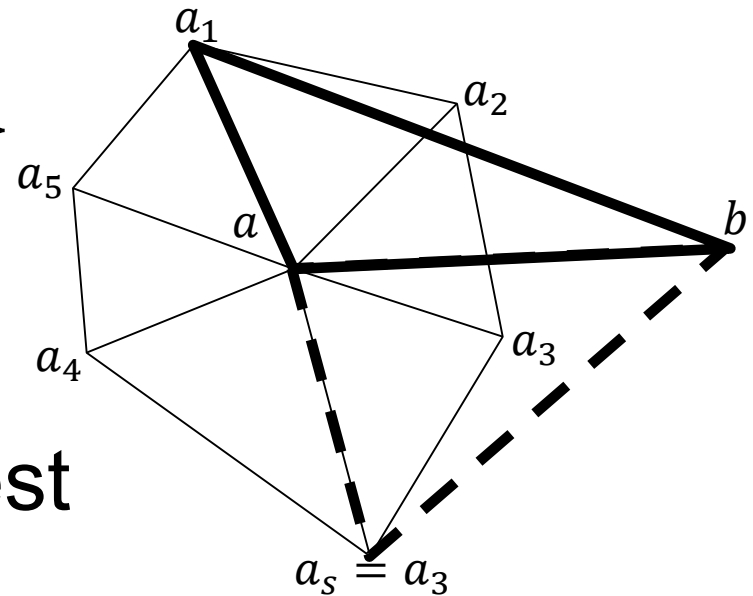




Divide And Conquer

More Specifically:

- Let a_s be the neighbor s.t. the plane through (b, a, a_s) supports A .
- The points $\{a_2, \dots, a_{s-1}\}$ must be inside the hull.
- Even if we advance on b we won't need to retest these points.





Divide And Conquer

Merge(H_1 , H_2):

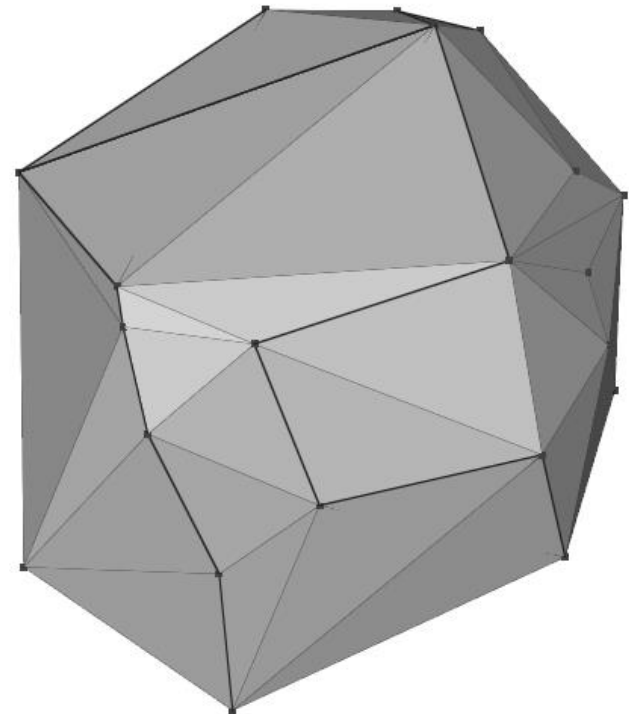
- $(v_1, v_2) \leftarrow \text{FindSupportingLine}(H_1 , H_2)$
- $Q \leftarrow \{(v_1, v_2)\}$
- $F \leftarrow \emptyset$
- While ($Q \neq \emptyset$)
 - » $e \leftarrow Q.\text{pop_back}()$
 - » if($e \neq \{v_2, v_1\}$)
 - $t \leftarrow \text{SupportingTriangle}(H_1 , H_2 , e)$
 - $F \leftarrow F \cup \{t\}$
 - $Q \leftarrow Q \cup \text{CrossingEdges}(t) / \{e\}$
- CleanUp



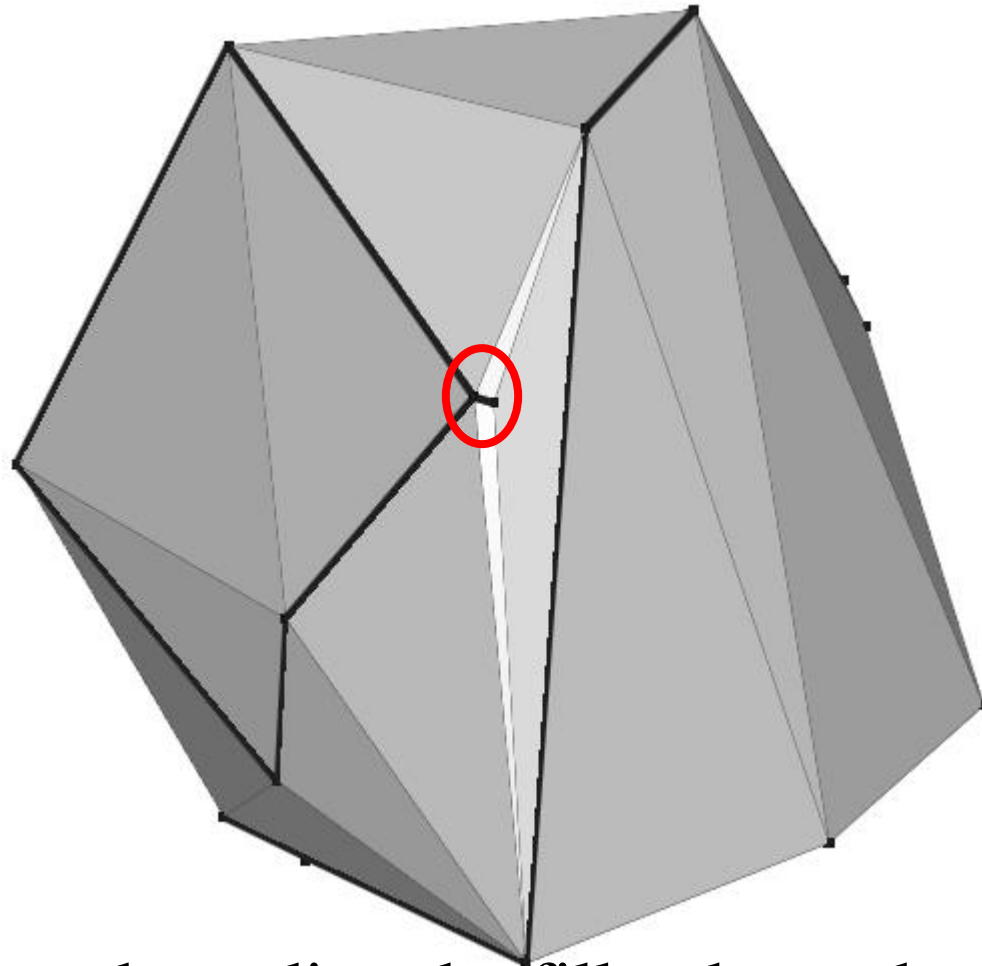
Divide And Conquer

Clean-Up:

- Represent the two hulls with a winged-edge data structure.
- Replace the opposite edges of the silhouette with the edges of the new triangles.
- Flood-fill to find interior triangles.



Divide And Conquer



Note: The curves bounding the fillet do not have to be simple