



# Polygon Partitioning

O'Rourke, Chapter 2

de Berg, Chapter 3



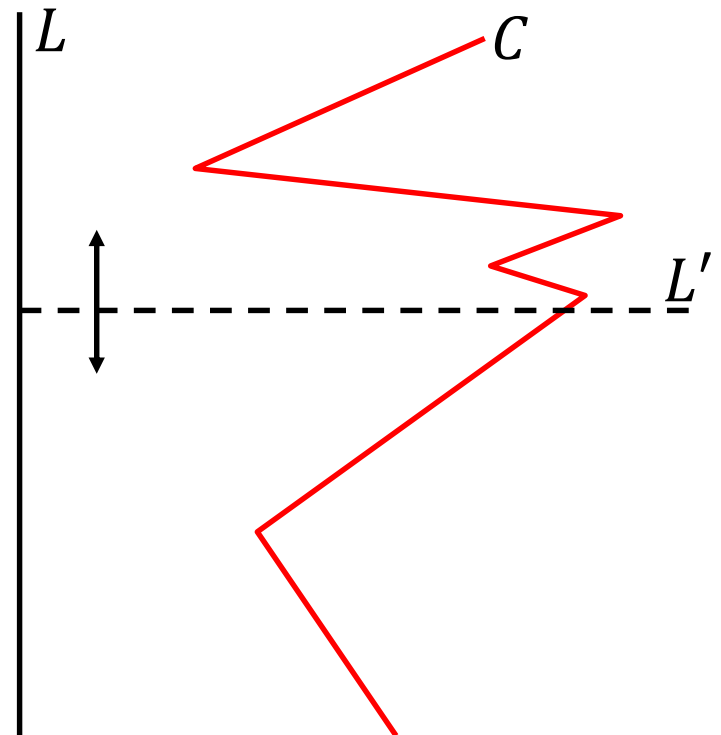
# Announcements

- Assignment 1 posted
- TA office hours:
  - Thursday @ 4PM
  - Malone 239



# Monotonicity

A polygonal chain  $C$  is *strictly monotone w.r.t. a line  $L$*  if every line  $L'$  perp. to  $L$  meets  $C$  at at most one point.

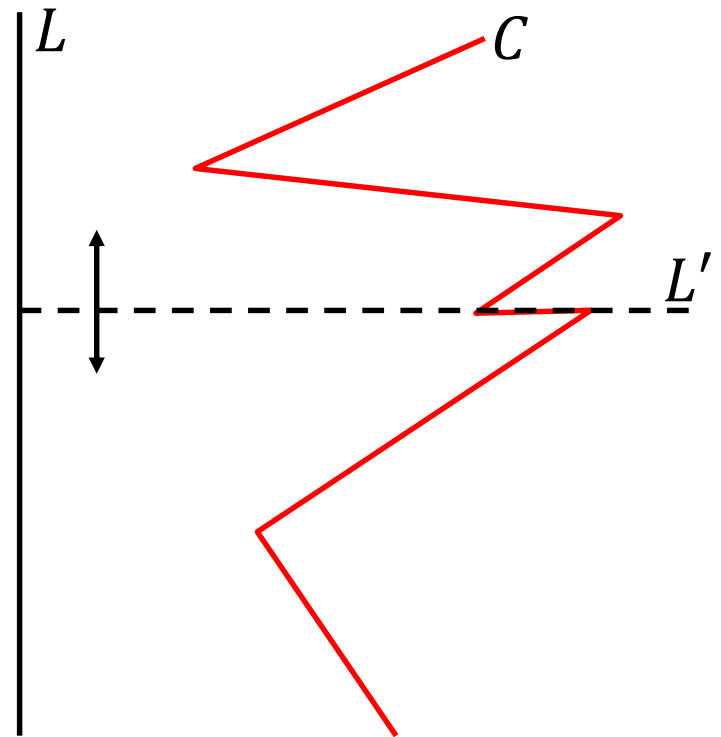




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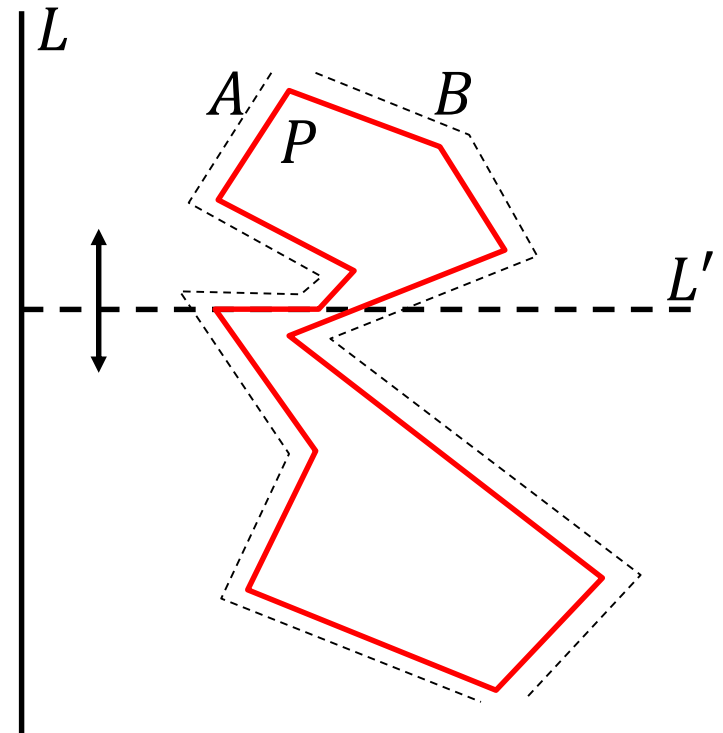
It is *monotone w.r.t. a line  $L$*  if every line  $L'$  perp. to  $L$  intersects  $C$  in at most one connected component.





# Monotonicity

A polygonal  $P$  is *monotone w.r.t. a line  $L$*  if its boundary can be split into two polygon chains,  $A$  and  $B$ , such that each chain is monotonic w.r.t.  $L$ .

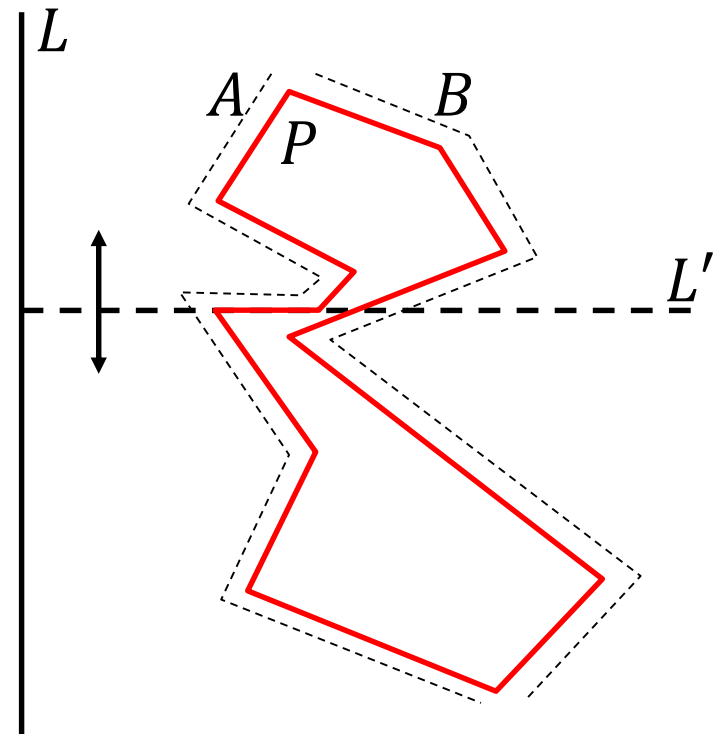




# Monotonicity

A polygonal  $P$  is *monotone w.r.t. a line  $L$*  if its boundary can be split into two polygon chains,  $A$  and  $B$ , such that each chain is monotonic w.r.t.  $L$ .

$\Leftrightarrow$  It is monotone w.r.t.  $L$  if the intersection of  $P$  with any line  $L'$  perp. to  $L$  has at most two connected components.

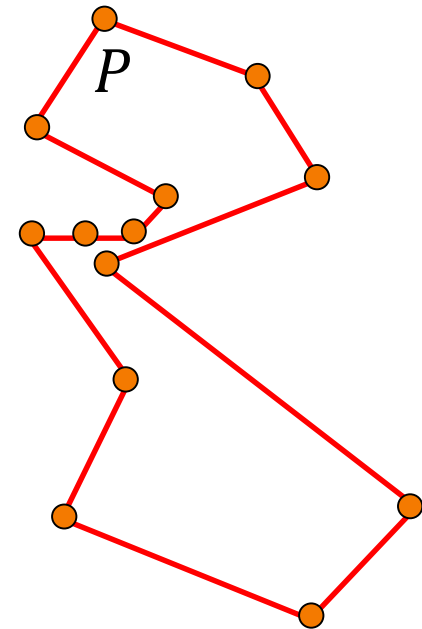




# Note

The vertices of a monotone polygon (w.r.t. the vertical axis) can be sorted by  $y$ -value in linear time.

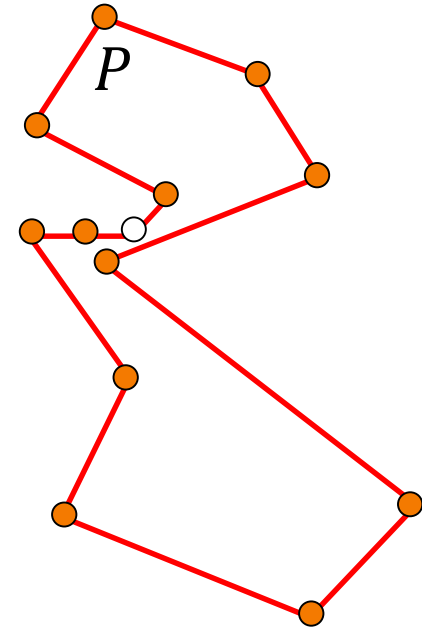
- $O(n)$ : Compute the highest vertex.
- $O(n)$ : Merge the two (sorted) chains.





# Interior Cusps

An *interior cusp* of a polygon  $P$  (w.r.t. the vertical axis) is a reflex\* vertex  $v \in P$  whose neighboring vertices are either at or above, or at or below  $v$ .



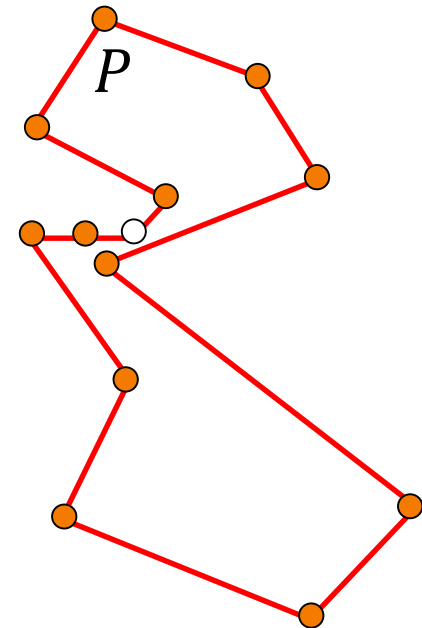
\*Recall that reflex vertices have interior angle strictly greater than  $\pi$ .





# Claim

*If  $P$  has no interior cusps (w.r.t. the vertical axis), it is monotone (w.r.t. the vertical axis).\**



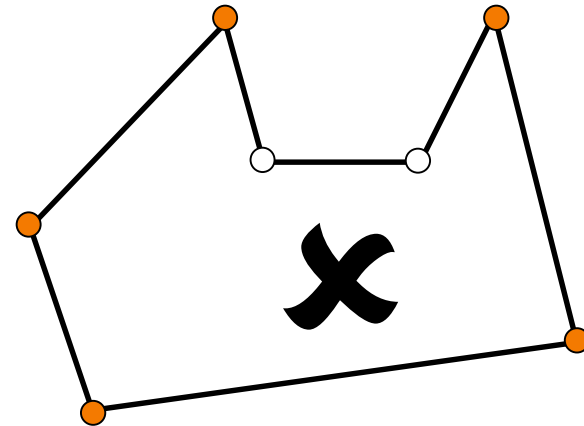
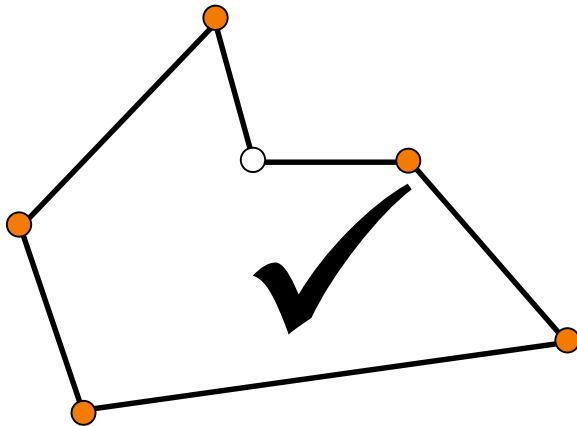
\*Note that it can have interior cusps and still be monotone.



# Claim

*If  $P$  has no interior cusps (w.r.t. the vertical axis), it is monotone (w.r.t. the vertical axis).*

Note: We cannot change the condition so that interior cusps have to be strictly above



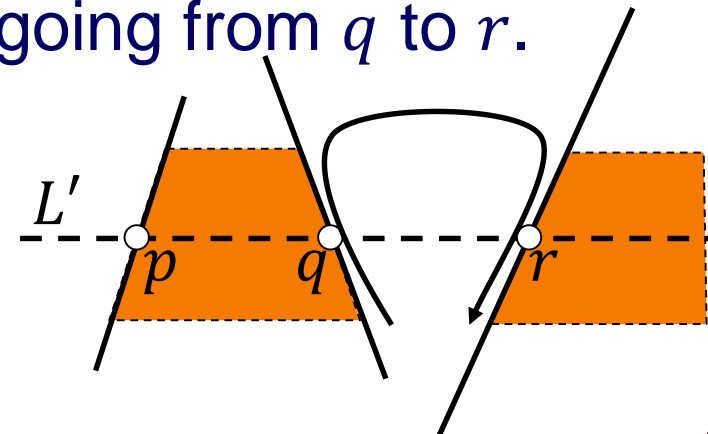


# Proof

If it isn't monotone, there will be a line  $L'$  intersecting  $P$  in three or more points,  $p$ ,  $q$ , and  $r$ . (Assume these are the first three.)

WLOG, assume the polygon interior is to the left of  $q$  (and right of  $p$  and  $r$ ):

- If the order of the vertices in the polygon is  $pqr$  we hit an interior cusp at the top going from  $q$  to  $r$ .



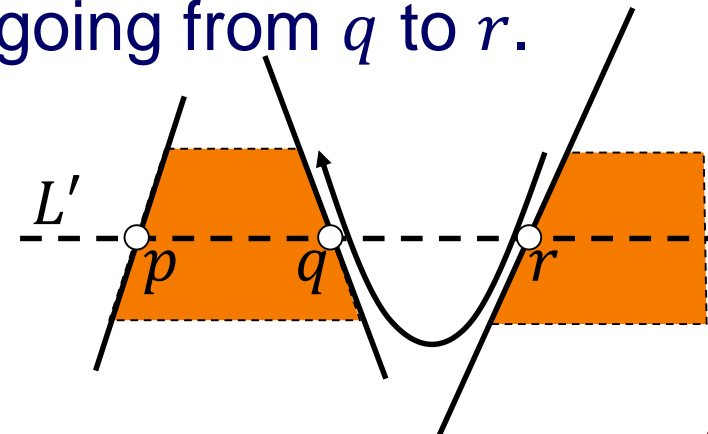


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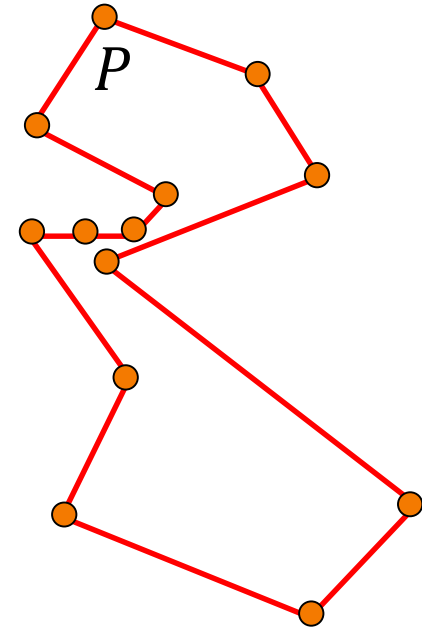
- If the order of the vertices in the polygon is  $pqr$  we hit an interior cusp at the top going from  $q$  to  $r$ .
- Otherwise, we hit an interior cusp at the bottom going from  $r$  to  $q$ .





# Claim

*A monotone polygon can be triangulated in linear time.*



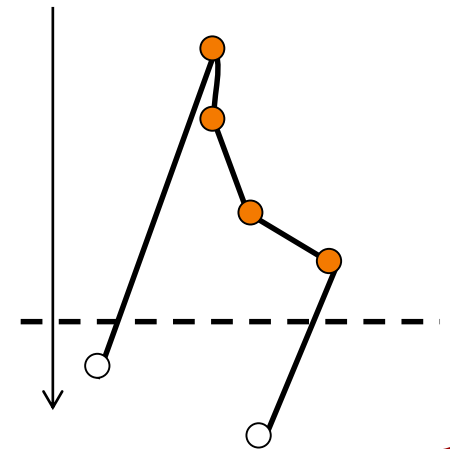


# Outline

## Invariant

When triangulating from the top vertex, at any  $y$ -value, the un-triangulated vertices above  $y$  can be broken up into two chains:

- One contains a single vertex
- The other has only reflex vertices.



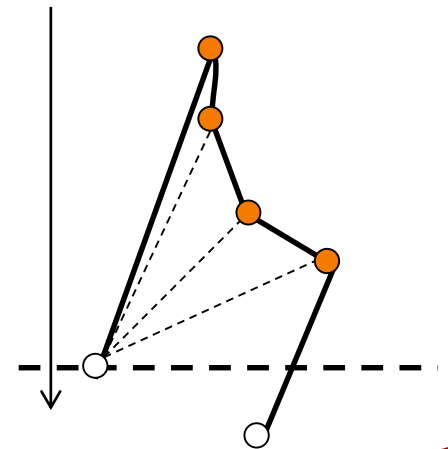


# Outline

When we hit the next vertex it can be:

- On the side with one vertex
  - » Connect the vertex to all vertices on the other side and pop off the triangles.

The invariant is preserved!



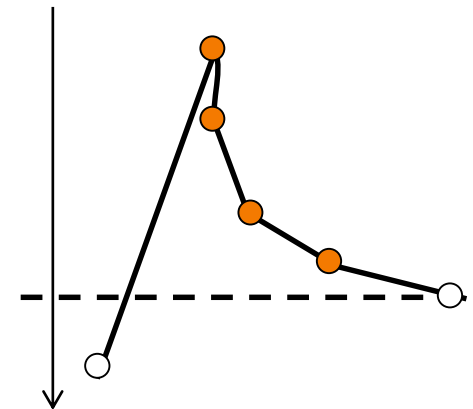


# Outline

When you hit the next vertex it can be:

- On the side with reflex vertices
  - » Either the new vertex makes the previous one reflex
    - Do nothing

The invariant is preserved!







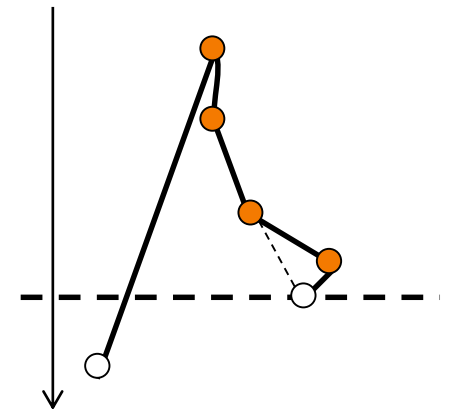
# Outline

When you hit the next vertex it can be:

- On the side with reflex vertices
  - » Either the new vertex makes the previous one reflex
    - Do nothing
  - » Or it doesn't
    - Recursively connect and pop

When we can't connect back anymore, we have a new reflex vertex.

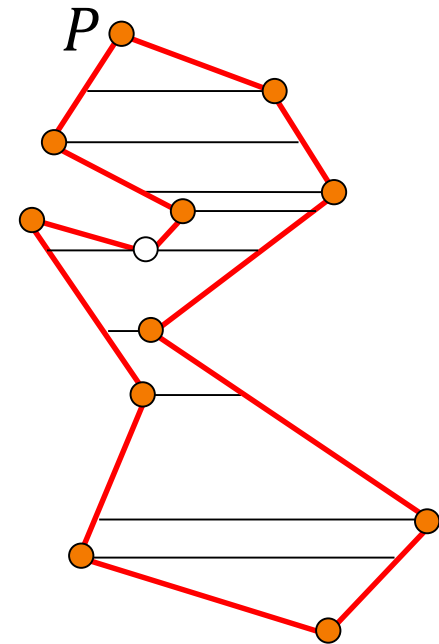
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# Trapezoidalization

A *horizontal trapezoidalization* is obtained by drawing a horizontal line through every vertex of the polygon.\*



\*Assuming distinct vertices have different  $y$ -values.



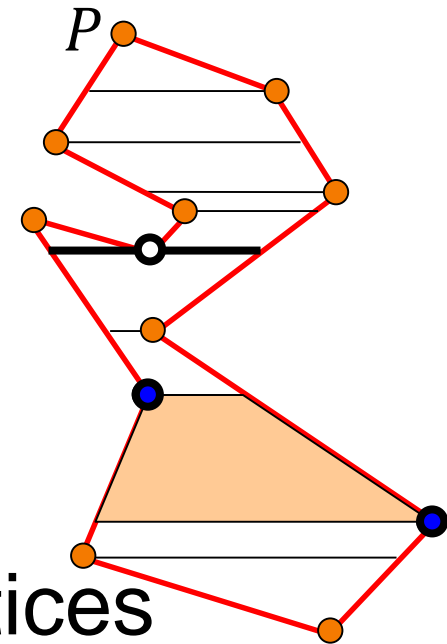
# Trapezoidalization

A *horizontal trapezoidalization* is obtained by drawing a horizontal line through every vertex of the polygon.

The *supporting vertices* of a trapezoid are the two vertices of  $P$  defining the horizontals of the trapezoid.

## Note:

Interior (vertical) cusps are vertices that are internal to their horizontals.

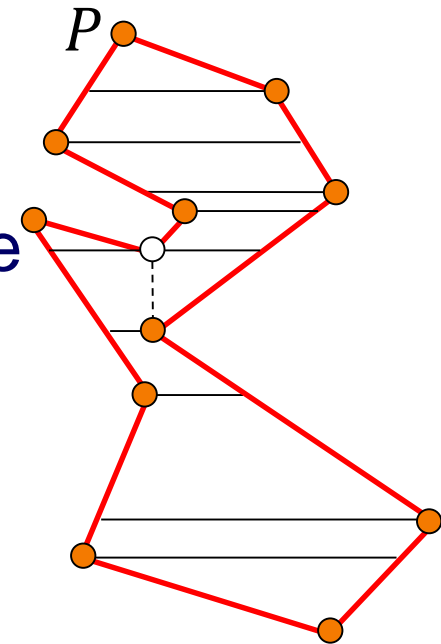




# Trapezoids $\rightarrow$ Monotone Polygons

Given a trapezoidalization of  $P$ , we can obtain a partition into monotone (w.r.t. the vertical axis) polygons:

- For upward cusps, connect the supporting vertices on the trapezoid below the cusp
- For downward cusps, connect the supporting vertices on the trapezoid above the cusp.

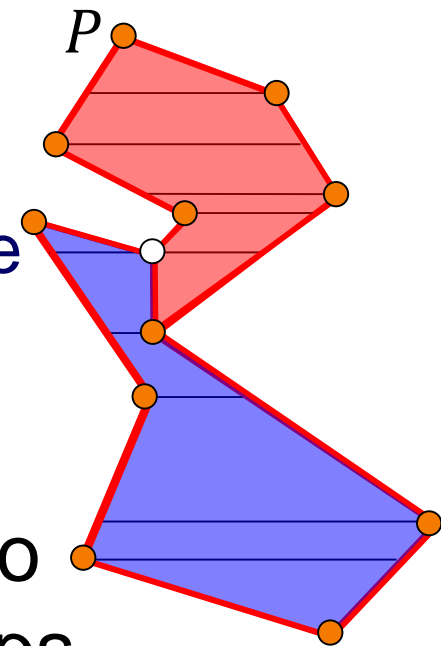




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This decomposes the polygon into sub-polygons without interior cusps.

$\Rightarrow$  Each sub-polygon is monotone.

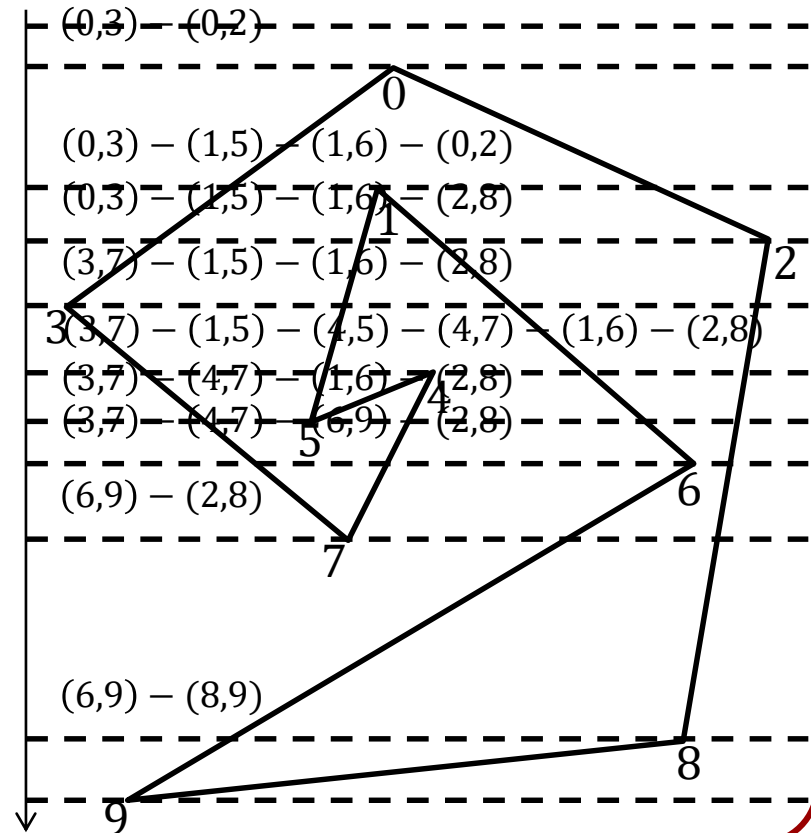


# Line/Plane Sweep

Given a polygon  $P$ , sweep a horizontal line downwards maintaining a sorted “active edge” list – those edges that are intersected by the current horizontal.

## Note:

The list of active edges can only change when the horizontal passes through a vertex.





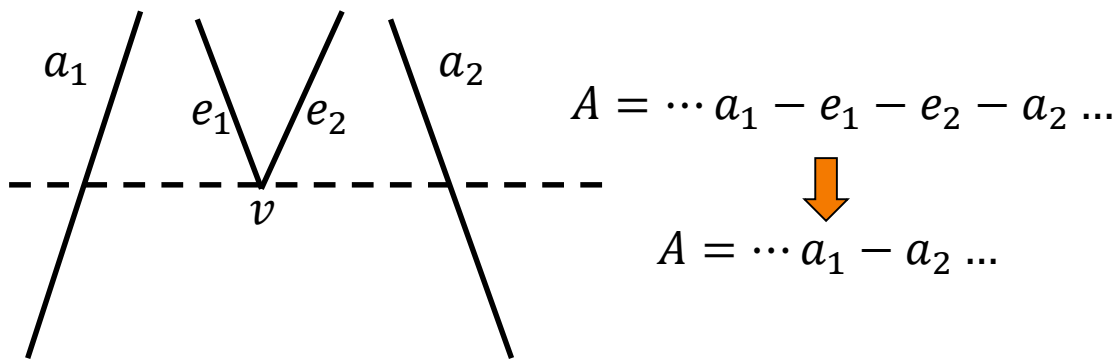
# Algorithm

- $\text{PlaneSweep}( V , E \subset V \times V )$ :
  - $\text{SortByLargestToSmallestHeight}( V )$
  - $A \leftarrow \emptyset$
  - For each  $v \in V$ 
    - $(e_1, e_2) \leftarrow \text{EndPoints}( v )$
    - If(  $\text{Before}( v , e_1 )$  ):  $\text{Remove}( A , e_1 )$
    - Else:  $\text{Insert}( A , e_1 )$
    - If(  $\text{Before}( v , e_2 )$  ):  $\text{Remove}( A , e_2 )$
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# Algorithm

- PlaneSweep(  $V$  ,  $E \subset V \times V$  ):
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    - If( Before(  $v$  ,  $e_1$  ) : Remove(  $A$  ,  $e_1$  )
    - Else: Insert(  $A$  ,  $e_1$  )
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    - Else: Insert(  $A$  ,  $e_2$  )

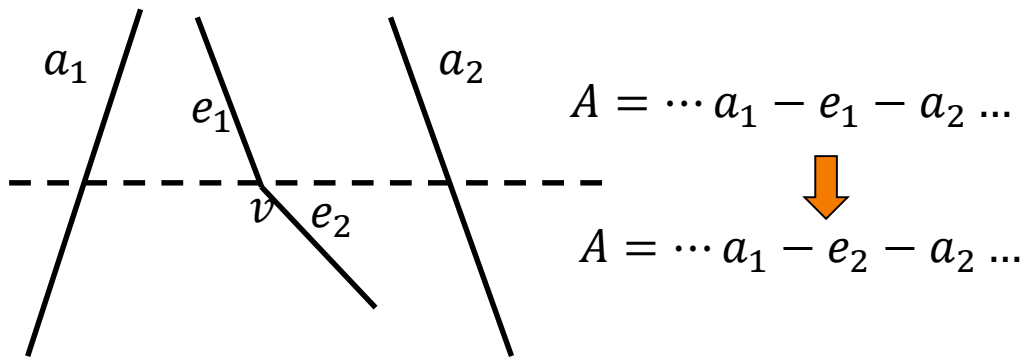






# Algorithm

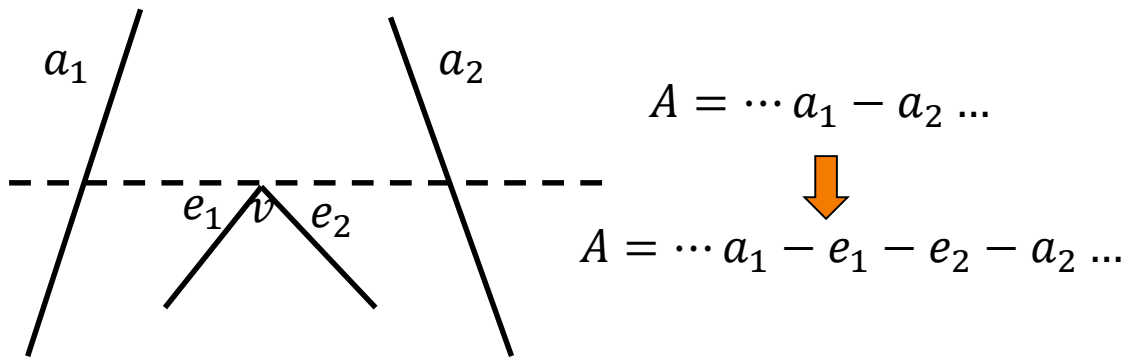
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# Algorithm

◦ PlaneSweep(  $V$  ,  $E \subset V \times V$  ):

- SortByLargestToSmallestHeight(  $V$  )

$O(n \log n)$

-  $A \leftarrow \emptyset$

- For each  $v \in V$

$O(n)$

•  $(e_1, e_2) \leftarrow \text{EndPoints}(v)$

• If( Before(  $v$  ,  $e_1$  )): Remove(  $A$  ,  $e_1$  )

• Else: Insert(  $A$  ,  $e_1$  )

• If( Before(  $v$  ,  $e_2$  )): Remove(  $A$  ,  $e_2$  )

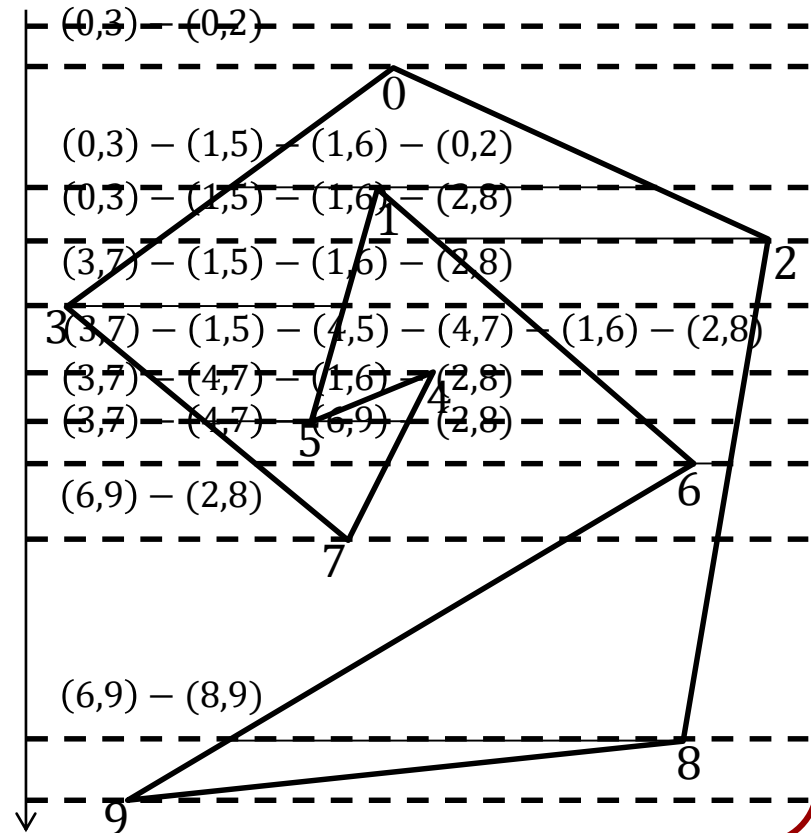
• Else: Insert(  $A$  ,  $e_2$  )

$O(\log n)$   
w/ balanced tree  
(e.g. std::map)



# Constructing a Trapezoidalization

A trapezoidal partition can be computed in  $O(n \log n)$  time by performing a line-sweep and adding (part of) the horizontal to the left and right neighbors as we hit new vertices.



# Constructing a Trapezoidalization



## Note:

We had assumed that the vertices have different  $y$ -coordinates.

This isn't actually necessary. It suffices to sort lexicographically. (If two vertices have the same  $y$ -coordinates then the one with larger  $x$ -coordinate is first.)

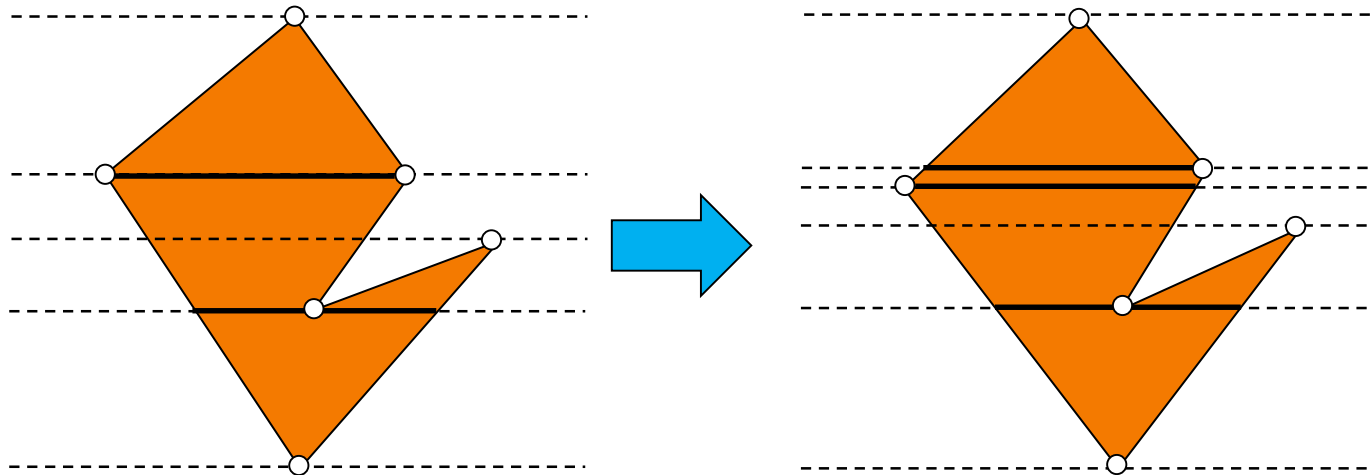


# Constructing a Trapezoidalization

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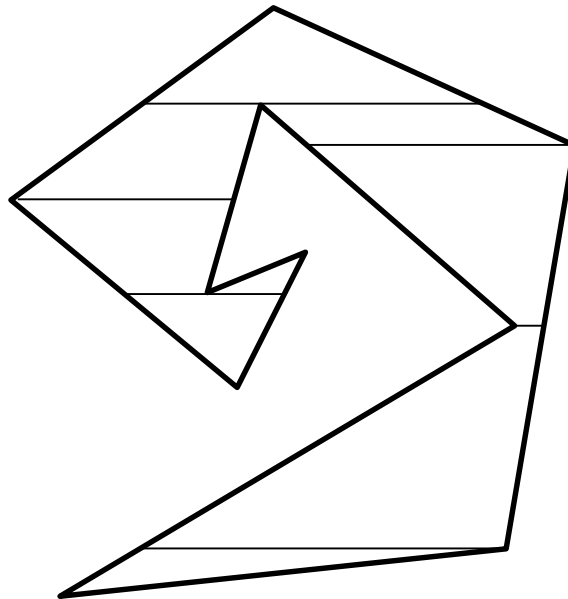
Conceptually, this amounts to applying a tiny rotation in the CCW direction.





# Triangulation

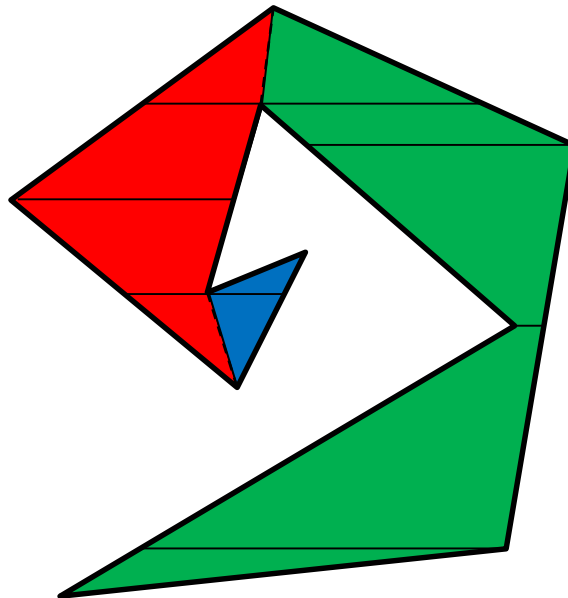
- $\text{Triangulate}(P)$ :
  - Construct a trapezoidalization





# Triangulation

- $\text{Triangulate}(P)$ :
  - Construct a trapezoidalization
  - Partition into monotone polygons







# Triangulation

- $\text{Triangulate}(P)$ :
  - Construct a trapezoidalization
  - Partition into monotone polygons
  - Triangulate the monotone polygons

