600.657: Mesh Processing

Chapter 1

Parameteric

– Represent a surface as (continuous) injective function from a domain $\Omega \subset \mathbb{R}^2$ to $S \subset \mathbb{R}^3$.

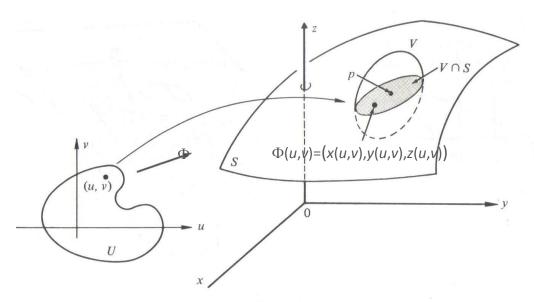


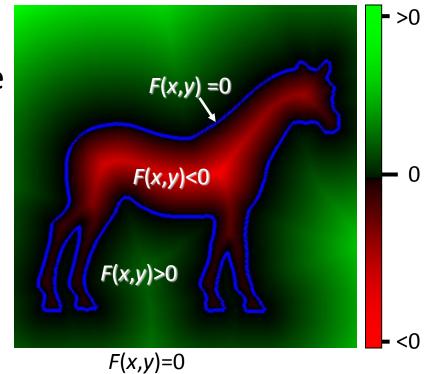
Figure 2-1

Parameteric

- Represent a surface as (continuous) injective function from a domain $\Omega \subset \mathbb{R}^2$ to $S \subset \mathbb{R}^3$.

Implicit

Represent a surface as the zero set of a (regular)
function defined in R³.



Parameteric

– Represent a surface as (continuous) injective function from a domain $\Omega \subset \mathbb{R}^2$ to $S \subset \mathbb{R}^3$.

In practice, it's not easy to find a single function that parameterizes the surface.

So instead, we represent a surface as a collection of functions (charts) from (simple) 2D domains into 3D.

Parameteric

– Represent a surface as (continuous) injective function from a domain $\Omega \subset \mathbb{R}^2$ to $S \subset \mathbb{R}^3$.

Given a set of charts, we say that the manifold S is "smooth" if for any two charts $\phi_1:\Omega_1 \to S$ and $\phi_2:\Omega_2 \to S$, the map $\phi_2^{-1}\circ\phi_1$ is smooth.

Implicit

- Represent a surface as the zero set of a (regular) function defined in \mathbb{R}^3 .
- 1. Why is the condition that the function be regular (i.e. have non-vanishing derivative) necessary?
- 2. How smooth is the surface?

Parameteric

- Easy to enumerate points on the surface
- Easy to find neighbors

• <u>Implicit</u>

- Easy to determine if you are inside or outside
- CSG operations are easy
- Easy to modify the topology of the surface

Parameteric Representations

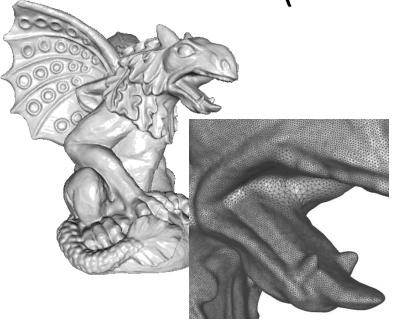
Triangle Meshes:

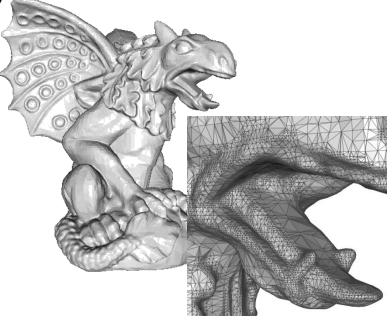
- Geometry: The positions of the vertices on the mesh.
- Topology: The connectivity of the vertices (e.g. which triplets of vertices make up the triangles).

Parameteric Representations

Precision:

 Though accuracy improves with refinement, the error of the approximation depends on the variation (curvature) of the surface.



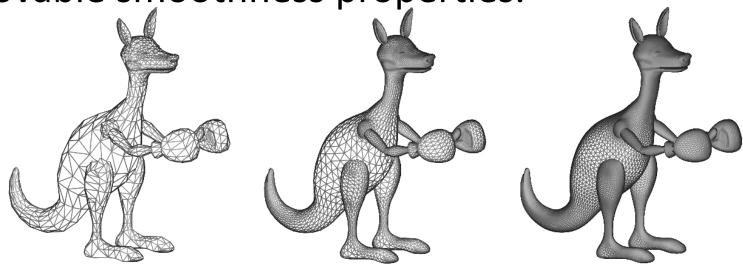


Parameteric Representations

Subdivision Surfaces:

Given a base (triangle) mesh and a set of rules for refining the geometry.

Repeated subdivision results in a surface with provable smoothness properties.



Triangle Meshes

- 1. What properties does the mesh have to satisfy to be manifold?
- 2. How continuous is the mesh?
- 3. What are the charts that define the manifold?

Euler's Formula

For a closed, connected, water-tight mesh with genus g, the number of vertices (V), edges (E), and faces (F) satisfy:

$$V-E+F = 2-2g$$

For a triangle mesh:

- –What is the ratio of triangles to vertices?
- –What is the ratio of edges to vertices?
- –What is the average vertex valence?

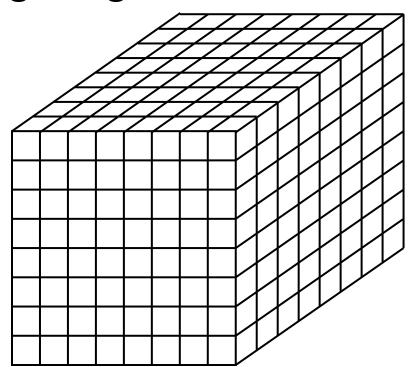
How about for a quad (dominant) mesh?

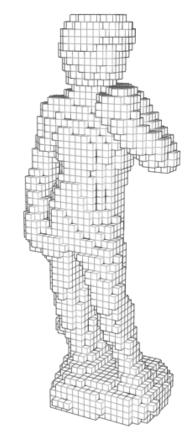
Implicit Representations

Voxel Grids:

Represented by the values of the function on a

regular grid.





Implicit Representations

Voxel Grids:

Represented by the values of the function on a regular grid.

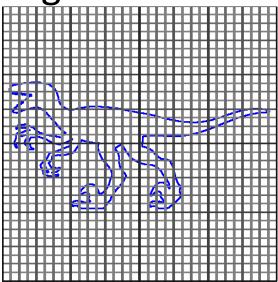
Though binary voxel grids are simplest, often represent the (signed) Euclidean Distance Transform:

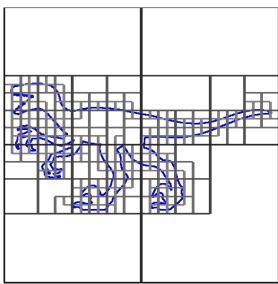
$$EDT^{2}(p) = \min_{q \in S} ||p - q||^{2}$$

Implicit Representations

Adaptive Grids:

In practice, we may only need a high-precision representation of the implicit function near the surface, so represent the function over an adaptive grid.





Transitioning Between Representations

Parameteric to Implicit

Assign distance values to points on a voxel grid:

Naïve:

For each voxel, find the closest point on the surface and use that to set the voxel's value.

Efficient:

For each voxel near the surface, find the closest point on the surface (using a kd-tree) and use that to set the voxel's value.

Use the *fast marching* method to define distance values away from the surface.

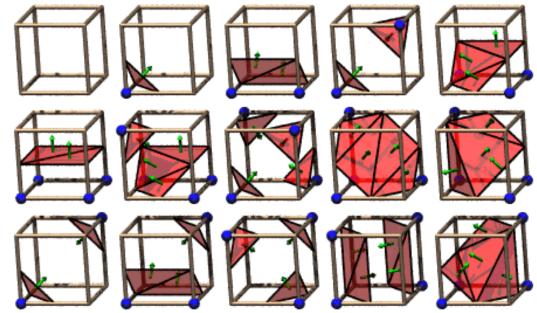
Transitioning Between Representations

Implicit to Parameteric

Extract the zero-set of the implicit function:

Marching cubes (for voxel grids)

Dual marching cubes, etc. (octrees)



The 15 Cube Combinations