

FFTs in Graphics and Vision

More Math Review

Outline



Inner Product Spaces

- Real Inner Products
- Hermitian Inner Products
- Orthogonal Transforms
- Unitary Transforms
- Function Spaces



Given a real vector space V, an inner product is a function $\langle \cdot, \cdot \rangle$ that takes a pair of vectors and returns a real value.



An inner product is a map from VxV into the real numbers that is:

- 1. <u>Linear</u>: For all $u, v, w \in V$ and any real scalar λ $\langle u + v, w \rangle = \langle u, w \rangle + \langle v, w \rangle$ $\langle \lambda v, w \rangle = \lambda \langle v, w \rangle$
- 2. <u>Symmetric</u>: For all *u*,*v*∈ *V*

$$\langle v, w \rangle = \langle w, v \rangle$$

3. Positive Definite: For all $v \in V$:

$$\langle v, v \rangle \ge 0$$

 $\langle v, v \rangle = 0 \iff v = 0$



An inner product defines a notion of distance on a vector space by setting:

$$D(v, w) = \sqrt{\langle v - w, v - w \rangle} \equiv ||v - w||^{\frac{1}{2}}$$



Examples:

1. On the space of *n*-dimensional arrays, the standard inner product is:

$$\langle (a_1, \dots, a_n), (b_1, \dots, b_n) \rangle = a_1 b_1 + \dots + a_n b_n$$
$$= (a_1, \dots, a_n)(b_1, \dots, b_n)^t$$



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$$= (a_1, \dots, a_n)(b_1, \dots, b_n)^t$$

2. On the space of continuous, real-valued functions, defined on a circle, the standard inner product is: 2π

$$\langle f, g \rangle = \int_{0}^{2\pi} f(\theta) g(\theta) d\theta$$



Examples:

3. Suppose we have the space of *n*-dimensional arrays, and suppose we have a matrix:

$$M = \begin{pmatrix} M_{11} \cdots M_{1n} \\ \vdots & \ddots & \vdots \\ M_{n1} \cdots M_{nn} \end{pmatrix}$$

Does the map:

$$\langle v, w \rangle_M = v^t M w$$

define an inner product?



Examples:

3. Does the map:

$$\langle v, w \rangle_M = v^t M w$$

define an inner product?

- Is it linear?
- Is it symmetric?
- Is it positive definite?



Examples:

$$\langle v, w \rangle_M = v^t M w$$

• Is it linear? Yes!

$$\langle u+v,w\rangle_M=(u+v)^tMw$$

$$\langle \lambda v, w \rangle_M = (\lambda v)^t M w$$



Examples:

$$\langle v, w \rangle_{M} = v^{t} M w$$

• Is it symmetric? Only if M is symmetric ($M=M^t$)

$$\langle w, v \rangle_{M} = w^{t} M v$$



Examples:

$$\langle v, w \rangle_M = v^t M w$$

Is it positive definite?

If, M is symmetric, there exists an orthogonal basis $\{v_1, ..., v_n\}$ with respect to which it is diagonal: $\begin{pmatrix} \lambda_1 & 0 & \cdots & 0 & 0 \end{pmatrix}$

$$M = B^{t} \begin{pmatrix} \lambda_{1} & 0 & \cdots & 0 & 0 \\ 0 & \lambda_{2} & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & \lambda_{n-1} & 0 \\ 0 & 0 & \cdots & 0 & \lambda_{n} \end{pmatrix} B$$



Examples:

$$\langle v, w \rangle_M = v^t M w$$

Is it positive definite?

Only if the eigenvalues are all positive

If we express *v* in terms of this basis:

$$v = a_1 v_1 + \dots + a_n v_n$$

then

$$\langle v, v \rangle_M = \lambda_1 a_1^2 + \dots + \lambda_n a_n^2$$



Examples:

4. On the space of continuous, real-valued functions, defined on a circle, does the map:

$$\langle f, g \rangle = \int_{0}^{\pi} f(\theta) g(\theta) \omega(\theta) d\theta$$

define an inner product? No!



Examples:

4. On the space of continuous, real-valued functions, defined on a circle, does the map:

$$\langle f, g \rangle = \int_{0}^{\pi} f(\theta) g(\theta) \omega(\theta) d\theta$$

define an inner product? No!

What if $\omega(\theta)>0$? Yes!

Hermitian Inner Product Spaces



Given a complex vector space *V*, a Hermitian inner product is a function $\langle \cdot, \cdot \rangle$ that takes a pair of vectors and returns a complex value.

Hermitian Inner Product Spaces



A Hermitian inner product is a map from VxV into the complex numbers that is:

- 1. <u>Linear</u>: For all $u, v, w \in V$ and any real scalar λ $\langle u + v, w \rangle = \langle u, w \rangle + \langle v, w \rangle$ $\langle \lambda v, w \rangle = \lambda \langle v, w \rangle$
- 2. Conjugate Symmetric: For all *u*,*v*∈ *V*

$$\langle v, w \rangle = \overline{\langle w, v \rangle}$$

3. Positive Definite: For all $v \in V$:

$$\langle v, v \rangle \ge 0$$

 $\langle v, v \rangle = 0 \iff v = 0$



As in the real case, a Hermitian inner product defines a notion of distance on a complex vector space by setting:

$$D(v, w) = \sqrt{\langle v - w, v - w \rangle} \equiv ||v - w||^{\frac{1}{2}}$$

Hermitian Inner Product Spaces



Examples:

1. On complex-valued, *n*-dimensional arrays, the standard Hermitian inner product is:

$$\langle (a_1, \dots, a_n), (b_1, \dots, b_n) \rangle = \overline{a_1} \overline{b_1} + \dots + \overline{a_n} \overline{b_n}$$
$$= (a_1, \dots, a_n) \overline{(b_1, \dots, b_n)}^t$$

Hermitian Inner Product Spaces



Examples:

1. On complex-valued, *n*-dimensional arrays, the standard Hermitian inner product is:

$$\langle (a_1, \dots, a_n), (b_1, \dots, b_n) \rangle = \overline{a_1} \overline{b_1} + \dots + \overline{a_n} \overline{b_n}$$
$$= (a_1, \dots, a_n) \overline{(b_1, \dots, b_n)}^t$$

On the space of continuous, complex-valued functions, defined on a circle, the standard Hermitian inner product is:

$$\langle f, g \rangle = \int_{0}^{2\pi} f(\theta) \overline{g(\theta)} d\theta$$



Recall:

If we have an n-dimensional vector space V then a linear map L is just a function from V to V that preserves the linear structure:

$$L(av_1 + bv_2) = a \cdot L(v_1) + b \cdot L(v_2)$$

for all $v, w \in V$ and all scalars a and b.



Recall:

If we have an n-dimensional vector space V then a linear map L is just a function from V to V that preserves the linear structure:

$$L(av_1 + bv_2) = a \cdot L(v_1) + b \cdot L(v_2)$$

for all $v, w \in V$ and all scalars a and b.

If *L* is invertible, then we can think of *L* as a function that renames all the elements in *V* while preserving the underlying vector space structure.



Orthogonal Transformations:

For a real vector space V that has an inner product, we would also like to consider those functions that rename the elements of V while preserving the underlying structure.



Orthogonal Transformations:

For a real vector space *V* that has an inner product, we would also like to consider those functions that rename the elements of *V* while preserving the underlying structure.

If R is such a function, then:

- R must be an invertible linear operator, in order to preserve the underlying vector space structure.
- R must also preserve the underlying inner product.



Orthogonal Transformations:

For a real vector space V, an invertible linear operator R is called <u>orthogonal</u> if it preserves the inner product:

$$\langle R(v), R(w) \rangle = \langle v, w \rangle$$

for all $v, w \in V$.



Example:

On the space of real-valued, *n*-dimensional arrays, a matrix is orthogonal if:

$$\langle Rv, Rw \rangle = \langle v, w \rangle$$

$$(Rv)^{t} (Rw) = v^{t} w$$

$$v^{t} R^{t} Rw = v^{t} w$$

$$R^{t} = R^{-1}$$



Example:

On the space of real-valued, *n*-dimensional arrays, a matrix is orthogonal if:

$$R^t = R^{-1}$$

Note: The determinant of an orthogonal matrix always has absolute value 1.



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On the space of real-valued, *n*-dimensional arrays, a matrix is orthogonal if:

$$R^t = R^{-1}$$

Note: The determinant of an orthogonal matrix always has absolute value 1.

If the determinant of an orthogonal matrix is equal to 1, the matrix is called a <u>rotation</u>.

Orthogonal Matrices and Eigenvalues

If R is an orthogonal transformation and R has an eigenvalue λ , then $|\lambda|=1$.

Orthogonal Matrices and Eigenvalues

If R is an orthogonal transformation and R has an eigenvalue λ , then $|\lambda|=1$.

To see this, let v be the eigenvector corresponding to the eigenvalue λ . Then since R is orthogonal, we have:

$$\langle v, v \rangle = \langle Rv, Rv \rangle$$



Unitary Transformations:

For a complex vector space V, an invertible linear operator R is called <u>unitary</u> if it preserves the hermitian inner product:

$$\langle R(v), R(w) \rangle = \langle v, w \rangle$$

for all $v, w \in V$.



Example:

On the space of complex-valued, *n*-dimensional arrays, a matrix is unitary if:

$$\langle Rv, Rw \rangle = \langle v, w \rangle$$

$$(Rv)^{t} \overline{(Rw)} = v^{t} \overline{w}$$

$$v^{t} R^{t} \overline{R} \overline{w} = v^{t} \overline{w}$$

$$\overline{R}^{t} = R^{-1}$$



Example:

On the space of complex-valued, *n*-dimensional arrays, a matrix is unitary if:

$$\overline{R}^t = R^{-1}$$

Note: The determinant of a unitary matrix always has norm 1.

Unitary Matrices and Eigenvalues



If R is a unitary transformation and R has an eigenvalue λ , then $|\lambda|=1$.

Unitary Matrices and Eigenvalues



If R is a unitary transformation and R has an eigenvalue λ , then $|\lambda|=1$.

To see this, let v be the eigenvector corresponding to the eigenvalue λ . Then since R is unitary, we have:

$$\langle v, v \rangle = \langle Rv, Rv \rangle$$

Function Spaces



In this course, the vector spaces we will be looking at most often are the vector spaces of functions defined on some domain:

- Continuous functions on the unit circle (S¹)
- Continuous functions on the unit disk (D²)
- Continuous, periodic functions on the plane (R²)
- Continuous functions on the unit sphere (S²)
- Continuous functions on the unit ball (B³)



Continuous functions on the unit circle (S^1):

This is the set of points (x,y) such that $x^2+y^2=1$.

If we have functions f(x,y), and g(x,y) the inner product is:

$$\langle f, g \rangle = \int_{p \in S^1} f(p) \overline{g}(p) dp$$



Continuous functions on the unit circle (S^1) :

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If we have functions f(x,y), and g(x,y) the inner product is:

$$\langle f, g \rangle = \int_{p \in S^1} f(p) \overline{g}(p) dp$$

Or, we can represent points on the circle in terms of angle $\theta \in [0,2\pi]$:

$$\theta \to (\cos \theta, \sin \theta)$$

For functions $f(\theta)$ and $g(\theta)$ the inner product is:

$$\langle f, g \rangle = \int_{0}^{2\pi} f(\theta) \overline{g}(\theta) d\theta$$



Continuous functions on the unit disk (D^2) :

This is the set of points (x,y) such that $x^2+y^2 \le 1$.

If we have functions f(x,y), and g(x,y) the inner product is:

$$\langle f, g \rangle = \int_{p \in D^2} f(p) \overline{g}(p) dp$$



Continuous functions on the unit disk (D^2) :

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If we have functions f(x,y), and g(x,y) the inner product is:

$$\langle f, g \rangle = \int_{p \in S^1} f(p) \overline{g}(p) dp$$

Or, we can represent points on the circle in terms of radius $r \in [0,1]$ and angle $\theta \in [0,2\pi]$:

$$(r,\theta) \rightarrow \{\cos\theta, r\sin\theta\}$$

For functions $f(r,\theta)$ and $g(r,\theta)$ the inner product is:

$$\langle f, g \rangle = \int_{0.0}^{2\pi} \int_{0}^{1} f(r, \theta) \overline{g}(r, \theta) r dr d\theta$$



Continuous, periodic functions on the plane (\mathbb{R}^2):

This is the set of functions f(x,y) satisfying the property that:

$$f(x, y) = f(x + 2\pi, y) = f(x, y + 2\pi)$$

If we have functions f(x,y), and g(x,y) the inner product is:

$$\langle f, g \rangle = \int_{0}^{2\pi^2\pi} \int_{0}^{2\pi} f(x, y) \overline{g}(x, y) \, dy \, dx$$



Continuous functions on the unit sphere (S^2):

This is the set of points (x,y,z) such that $x^2+y^2+z^2=1$.

If we have functions f(x,y,z), and g(x,y,z) the inner product is:

$$\langle f, g \rangle = \int_{p \in S^2} f(p) \overline{g}(p) dp$$



Continuous functions on the unit sphere (S^2):

This is the set of points (x,y,z) such that $x^2+y^2+z^2=1$.

If we have functions f(x,y,z), and g(x,y,z) the inner product is:

$$\langle f, g \rangle = \int_{p \in S^2} f(p) \overline{g}(p) dp$$

Or, we can represent points on the sphere in terms of spherical angle $\theta \in [0,\pi]$ and $\varphi \in [0,2\pi]$:

$$(\theta, \varphi) \rightarrow \{ \sin \theta \cos \varphi, \cos \theta, \sin \theta \sin \varphi \}$$

For functions $f(\theta, \varphi)$ and $g(\theta, \varphi)$ the inner product is:

$$\langle f, g \rangle = \int_{0}^{2\pi\pi} \int_{0}^{\pi} f(\theta, \varphi) \overline{g}(\theta, \varphi) \sin \theta \, d\theta \, d\varphi$$



Continuous functions on the unit ball (B^3):

This is the set of points (x,y,z) such that $x^2+y^2+z^2 \le 1$.

If we have functions f(x,y,z), and g(x,y,z) the inner product is:

$$\langle f, g \rangle = \int_{p \in B^3} f(p) \overline{g}(p) dp$$



Continuous functions on the unit ball (B^3):

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$$\langle f, g \rangle = \int_{p \in B^3} f(p) \overline{g}(p) dp$$

Or, we can represent points in the ball in terms of radius $r \in [0,1]$ and spherical angle $\theta \in [0,\pi]$, $\varphi \in [0,2\pi]$: $(r,\theta,\varphi) \rightarrow \P \sin\theta \cos\varphi, r\cos\theta, r\sin\theta \sin\varphi$

For functions $f(\theta, \varphi)$ and $g(\theta, \varphi)$ the inner product is:

$$\langle f, g \rangle = \int_{0}^{2\pi} \int_{0}^{\pi} \int_{0}^{1} f(r, \theta, \varphi) \overline{g}(r, \theta, \varphi) r^{2} \sin \theta \, dr \, d\theta \, d\varphi$$



Examples

If we consider the space of continuous, complexvalued functions on the unit circle:

Is the map:

$$f(p) \rightarrow f(p) + 1$$

a linear transformation?

No!



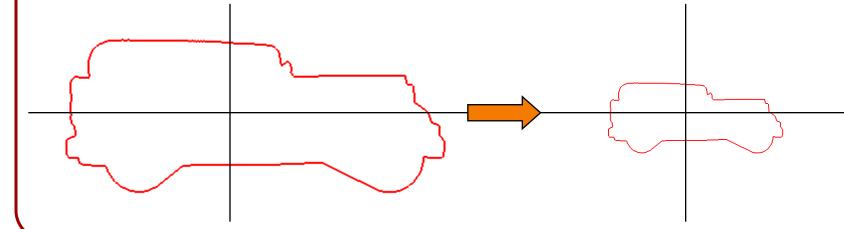
Examples

If we consider the space of continuous, complexvalued functions on the unit circle:

• For any scalar value λ , is:

$$f(p) \rightarrow \lambda f(p)$$

a linear transformation? Yes!





Examples

If we consider the space of continuous, complexvalued functions on the unit circle:

• For any scalar value λ , is:

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a linear transformation?

Yes

• Is it unitary? No!



Examples

If we consider the space of continuous, complexvalued functions on the unit circle:

• For any scalar value λ , is:

$$f(p) \rightarrow \lambda f(p)$$

a linear transformation? Yes!

- Is it unitary? No!
- How about if $|\lambda|=1$? Yes!



Examples

If we consider the space of continuous, complexvalued functions on the unit circle:

Is the differentiation operator:

$$f(p) \rightarrow f'(p)$$

a linear transformation?

No!



Examples

If we consider the space of continuous, complexvalued functions on the unit circle:

Is the differentiation operator:

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a linear transformation?

No!

 What if we only consider the functions that are infinitely differentiable? Yes!



Examples

If we consider the space of continuous, complexvalued functions on the unit circle:

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a linear transformation?

No!

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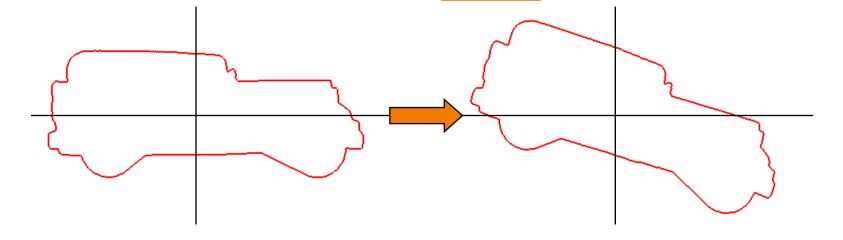
Examples

If we consider the space of continuous, complexvalued functions on the unit circle:

For any 2D rotation R is the transformation:

$$f(p) \rightarrow f(R^{-1}p)$$

a linear transformation? Yes!





Examples

If we consider the space of continuous, complexvalued functions on the unit circle:

For any 2D rotation R is the transformation:

$$f(p) \rightarrow f(R^{-1}p)$$

a linear transformation?

Yes!

• Is it unitary? Yes!



Examples

If we consider the space of continuous, periodic, complex-valued functions on the plane:

• For any 2D point (x_0, y_0) , is the transformation:

$$f(x, y) \rightarrow f(x - x_0, y - y_0)$$

a linear transformation?

Yes!



Examples

If we consider the space of continuous, periodic, complex-valued functions on the plane:

• For any 2D point (x_0, y_0) , is the transformation:

$$f(x, y) \rightarrow f(x - x_0, y - y_0)$$

a linear transformation?

Is it unitary? Yes!



Examples

If we consider the space of continuous, infinitelydifferentiable, periodic, complex-valued functions on the plane:

Is differentiation with respect to x:

$$f(x,y) \to \frac{\partial}{\partial x} f(x,y)$$

a linear transformation? Yes!



Examples

If we consider the space of continuous, infinitelydifferentiable, periodic, complex-valued functions on the plane:

Is differentiation with respect to x:

$$f(x,y) \to \frac{\partial}{\partial x} f(x,y)$$

a linear transformation? Yes!

Is it unitary? No!

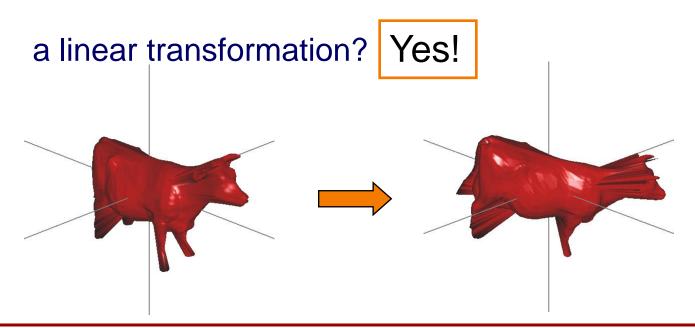


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If we consider the space of continuous, complexvalued functions on the sphere:

• For any rotation *R*, is the transformation:

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Examples

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• For any rotation *R*, is the transformation:

$$f(p) \rightarrow f(R^{-1}p)$$

a linear transformation? Yes!

Is it unitary?



Change of Variables:

Given a real/complex-valued function *f* defined on some domain *D*, and given some differentiable, invertible, map:

$$\Phi: D \to \Phi(D)$$

We have:

$$\int_{x \in D} f(x) \left| \partial \Phi \right| dx = \int_{y \in \Phi(x)} f(y) dy$$

where $|\partial\Phi|$ denotes the Jacobian of Φ (i.e. the determinant of the derivative matrix)



Examples

If we consider the space of continuous, complex-valued functions on the sphere:

• For any rotation *R*, is the transformation:

$$f(p) \rightarrow f(R^{-1}p)$$

a linear transformation? Yes!

• Is it unitary? Yes!