Three-Dimensional α Shapes Herbert Edelsbrunner and Ernst P. Mücke ACM Tran. Graph. 13(1), 1994

Presented by Matthew Bolitho

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Background Intuition Definition Delaunay Triangulation

Shape

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- α -shape may be concave or disjoint

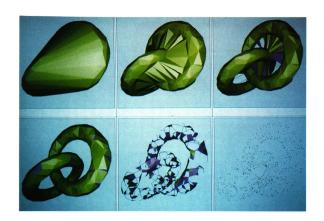


Figure from Edelsbrunner94

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 - At these positions there are at least d points in P touching the scoop.
 - \bullet An edge of the $\alpha\mbox{-shape}$ is defined by connecting those points.
 - ullet Then boundary of the lpha-shape is a collection of these edges



Basic Definitions

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This allows us to ignore special cases

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$$B_{\alpha}(p)$$
 is empty if $p \cap P = 0$

Simplices I

- An *n-simplex* is an *n*-dimensional analogue of a triangle:
 - The 0-simplex is a point
 - The 1-simplex is a line
 - The 2-simplex is a triangle
 - The 3-simplex is a tetrahedron
- A n-simplex has n+1 vertices

Simplices II

Let
$$T \subset P$$
, and $|T| = k + 1 \le d + 1$

The polytope $\triangle_T = conv(T)$ has dimension k and is therefore a k-simplex

Exposed Simplices

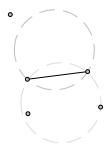
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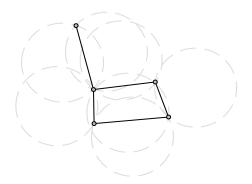
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Building the α -shape

• $S_{\alpha}(P)$ is constructed from all exposed simplices:

$$\delta S_{\alpha}(P) = \{ \triangle_T | T \subset P, |T| \le d \text{ and } \triangle_T \text{ is exposed } \}$$



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Observations

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Claim

 $S(\alpha)$ is a subset of the Delaunay triangulation of P

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- For k=d, an α -ball $B_{\alpha}(p)$ coincides with the circumsphere of \triangle_T
- By definition, this does not contain any other points from P, therefore $B_{\alpha}(p)$ is empty
- Thus the simplices that form the edges of the d-simplex are exposed, and form the boundary for some α -shape.



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- The subset of DT(P) is determined by α

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- A simplex \triangle_T from DT(P) is in $C_{\alpha}(P)$ if either:
 - $\sigma_T < \alpha$ and the α -ball at μ_T is empty
 - \triangle_T is the face of another \triangle_T in $C_\alpha(P)$

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- Extract the boundary of the α -shape from the α -complex
- Steps 1 and 2 can be precomputed for a given P

Complexity

- Delaunay Triangulation: $O(n \log n)$
- Generate α -complex: $O(m \log m)$
- Extract boundary of α -shape: O(m) (could be better?)

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- Solution: Simulation of simplicity H. Edelsbrunner and E. P. Mcke, ACM Trans. Graph. 9(1) 1990

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•
$$S_{\alpha}(P) \subset DT(P)$$

Advantages

- ullet α -shape reconstructions can have arbitrary topology
- The α -shape interpolates the set P

Disadvantages

- The choice of α -value is non-intuative
- The reconstruction may not be water tight
- The reconstruction may be disjoint

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- What about blending several α -shapes together?
- What about defining $\alpha(q)$ for $q \in \mathbb{R}^d$ such that $\alpha(q)$ is proportional to sampling density near q