Lecture 26: Algorithmic Game Theory

Michael Dinitz

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Introduction

Algorithmic game theory: (some) intersections of algorithms and game theory (or economics more broadly)

Three subareas:

- Computation of equilibria
- Inefficiency of equilibria
- Algorithmic mechanism design

Today: very fast examples of first two

► See 601.436/636 for a whole class on this!

Two-Player Zero-Sum Games: Penalty Kicks

Penalty kicks in soccer:

- Two players: goalie and kicker
- Too fast to react: both players have to guess.

Model as matrix game: matrix M, each entry of form (a, b)

- Kicker picks row and goalie picks column (simultaneously)
- ▶ (a, b): kicker (row player) gets "utility" a, goalie (column player) gets "utility" b
- "Zero-sum": a + b = 0 (so usually just write first value: row player's utility)

What should each player do?

4 = 9 1, 8	
Left	Right
(0,0)	(1,-1)
(1, -1)	(0,0)

Left

Right

k icker

1 .

Minimax

Two-player zero-sum matrix game: $\mathbf{M} \in \mathbb{R}^{\mathbf{n} \times \mathbf{m}}$, row player tries to maximize, column player tries to minimize.

Natural approach: assume other player knows you well, do as best as possible.

- ▶ Row player: choose *distribution* over rows, so that no matter what column player does (even if they know distribution), still get utility
- Penalty kicks:
 - ▶ Probability 1/2 for each direction. Even if goalie knows, still get utility 1 with probability 1/2!
 - ▶ If we bias at all, then goalie who knows this is more likely to block us: get utility less than 1/2 in expectation

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- ▶ Choose *minimax* strategy: probability distribution **p** over [n] to maximize

$$V_p = \min_{j \in [m]} \sum_{i \in [n]} p_i M_{ij}$$

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$$V = \max_{\substack{\text{probability distributions } p \\ \text{over } [n]}} V_p = \max_{\substack{\text{probability distributions } p \\ \text{over } [n]}} \min_{j \in [m]} \sum_{i \in [n]} p_i M_{ij}$$

Computing Minimax

How to compute minimax strategy?

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$$\begin{array}{ll} \text{max} & \textbf{V} \\ \text{subject to} & \displaystyle \sum_{i=1}^n p_i = 1 \\ & \displaystyle \sum_{i=1}^n p_i M_{ij} \geq \textbf{V} \qquad \forall j \in [m] \\ & 0 \leq p_i \ \text{\o} \qquad \qquad \forall i \in [n] \end{array}$$

	Left	Right
Left	(0,0)	(1,-1)
Right	(1, -1)	(0,0)

Kicker (row) minimax:

- ▶ 1/2 on each direction
- Guarantees at least 1/2 utility in expectation

Goalie (column) minimax:

- ▶ 1/2 on each direction
- ► Guarantees at least −1/2 utility in expectation (at most 1/2 loss)

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		1	\bigcirc
		Left	Right
1	Left	$(\frac{1}{2},-\frac{1}{2})$	(1,-1)
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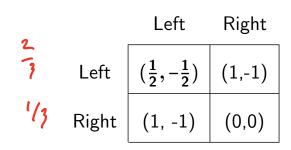
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Kicker (row) minimax:

- **▶** (2/3, 1/3)
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Minimax Theorem

Theorem (Minimax Theorem (von Neumann))

Every 2-player zero-sum game has a unique value V such that the minimax strategy for the row player guarantees expected gain of at least V, and the minimax strategy for the column player also guarantees expected loss of at most V.

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Proof outside the scope of the course, but not hard.

Easiest proof: LP duality

General Games and Nash Equilibria

General (one-shot) games: allow more than 2 players, utilities don't have to add to 0.

No longer a unique value!

Replace minimax strategies with Nash equilibria

• (Randomized) strategy for every player so that no one has incentive to deviate (knowing all other strategies)

Example: two people walking down the sidewalk

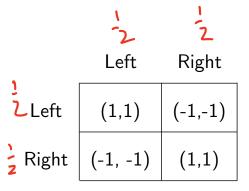
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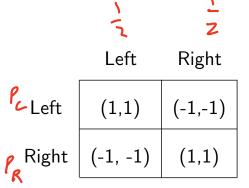
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- Both left
- Both right
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 - Row player: expected utility is 0

Example: two people walking down the sidewalk



- Both left
- ▶ Both right
- Both (1/2, 1/2)
 - ▶ Row player: expected utility is **0**
 - Suppose deviated to (p_L, p_R) (column player stays at (1/2, 1/2)):

$$\frac{1}{2}(1 \cdot p_{L} - 1 \cdot p_{R}) + \frac{1}{2}(-1 \cdot p_{L} + 1 \cdot p_{R}) = 0$$

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Nash's proof: through Brouwer's fixed-point theorem

- "Every continuous function from a convex compact subset K of a Euclidean space to K itself has a fixed point."
- Famous and fundamental result in topology
- Non-constructive!

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New complexity class: **PPAD** (Polynomial Parity Argument (Directed))

Answer always YES, but (we think) it is hard to find solution.

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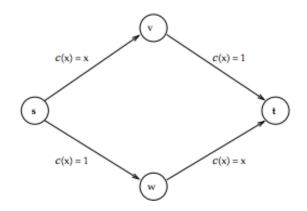
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Other equilibria (e.g., coarse correlated equilibria) can be computed efficiently: online learning!

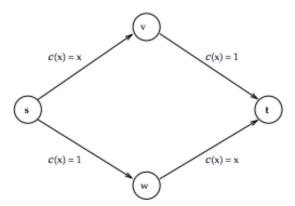
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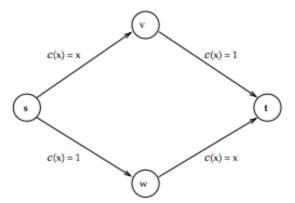
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- Actions: path from s to t
- Cost of edge: c(x) where x is fraction of flow through edge
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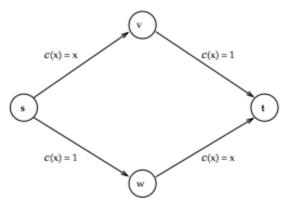
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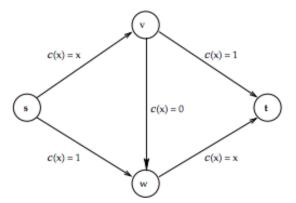


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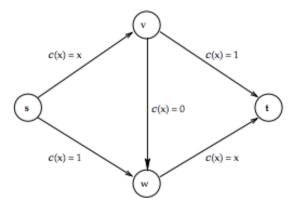


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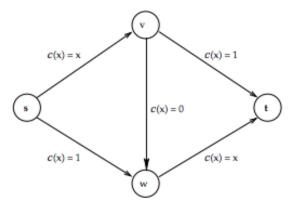
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So improved edges leads to worse performance!

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Theorem (Roughgarden)

The price of anarchy in any routing game with linear edge costs is at most 4/3

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