Lecture 20: Linear Programming

Michael Dinitz

November 4, 2021 601.433/633 Introduction to Algorithms

Introduction

Today: What, why, and juste a taste of how

- Entire course on linear programming over in AMS. Super important topic!
- Fast algorithms in theory and in practice.

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- Entire course on linear programming over in AMS. Super important topic!
- Fast algorithms in theory and in practice.

Why: Even more general than max-flow, can still be solved in polynomial time!

- Max flow important in its own right, but also because it can be used to solve many other things (max bipartite matching)
- Linear programming: important in its own right, but also even more general than max-flow.
- Can model many, many problems!

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- Everything else (**E**)

- E ≥ 56 (at least 8 hours/day sleep, shower, etc.)
- $P + E \ge 70$ (need to stay sane)
- $S \ge 60$ (to pass your classes)
- S + E − 3P ≥ 150 (too much partying requires studying or sleep)

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Yes! S = 80, P = 20, E = 68

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Question: Suppose "happiness" is 2P + 3E. Can we find a feasible solution maximizing this?

Linear Programming

Input (a "linear program"):

- **n** variables x_1, \ldots, x_n (take values in \mathbb{R})
- m non-strict linear inequalities in these variables (constraints)
 - E.g.: $3x_1 + 4x_2 \le 6$, $0 \le x_1 \le 3$ $x_2 3x_3 + 2x_7 = 17$
- Possibly a *linear* objective function
 - $\max 2x_3 4x_5$, $\min \frac{5}{2}x_4 + x_2$, .

Goals:

- Feasibility: Find values for x's that satisfy all constraints
- Optimization: Find feasible solutions maximizing/minimizing objective function

Both achievable in polynomial time, reasonably fast!

Planning your week as an LP

Variables: P, E, S

Planning your week as an LP

Variables: **P**, **E**, **S**

max 2P + E

Planning your week as an LP Variables: **P**,**E**,**S**

 $\begin{array}{ll} \mbox{max} & 2\mathsf{P}+\mathsf{E} \\ \mbox{subject to} & \mathsf{E} \geq 56 \\ & \mathsf{S} \geq 60 \\ & 2\mathsf{S}+\mathsf{E}-3\mathsf{P} \geq 150 \\ & \mathsf{P}+\mathsf{E} \geq 70 \end{array}$

Planning your week as an LP Variables: **P**,**E**,**S**

> max 2P + Esubject to $E \ge 56$ S ≥ 60 $2S + E - 3P \ge 150$ $P + E \ge 70$ P + S + E = 168 $P \ge 0$ S ≥ 0 **E** ≥ **0**

Planning your week as an LP Variables: **P**,**E**,**S**

> 2P + E max subject to $E \ge 56$ $S \ge 60$ $2S + E - 3P \ge 150$ $P + E \ge 70$ P + S + E = 168 $\mathbf{P} \ge \mathbf{0}$ S ≥ 0 E > 0

When using an LP to model your problem, need to be sure that *all* aspects of your problem included!

Michael Dinitz

Operations Research-style Example

Four different manufacturing plants for making cars:

	labor	materials	pollution
Plant 1	2	3	15
Plant 2	3	4	10
Plant 3	4	5	9
Plant 4	5	6	7

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- Need to produce at least 400 cars at plant
 3 (labor agreement) ×₅ ≥ 400
- Have 3300 total hours of labor, 4000 units of material
- Environmental law: produce at most 12000 pollution
- Make as many cars as possible

OR example as an LP

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OR example as an LP

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Objective: max $x_1 + x_2 + x_3 + x_4$

$\mathsf{OR}\xspace$ example as an $\mathsf{LP}\xspace$

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Constraints:

$\mathsf{OR}\xspace$ example as an $\mathsf{LP}\xspace$

Four different manufacturing plants for making cars:

Variables: $x_i = \#$ cars produced at plant i, for $i \in \{1, 2, 3, 4\}$ materials pollution labor **Objective:** max $x_1 + x_2 + x_3 + x_4$ **Constraints:** 3 Plant 1 2 15 $x_3 \ge 400$ Plant 2 4 3 10 5 Plant 3 4 9 6 Plant 4 5 7

$\mathsf{OR}\xspace$ example as an $\mathsf{LP}\xspace$

Four different manufacturing plants for making cars:

 $i \in \{1, 2, 3, 4\}$ materials pollution labor **Objective:** max $x_1 + x_2 + x_3 + x_4$ **Constraints:** 3 Plant 1 2 15 $x_3 \ge 400$ Plant 2 4 3 10 $2x_1 + 3x_2 + 4x_3 + 5x_4 \le 3300$ Plant 3 4 5 9 6 Plant 4 5 7

Variables: $x_i = \#$ cars produced at plant i, for

OR example as an LP

Plant 1

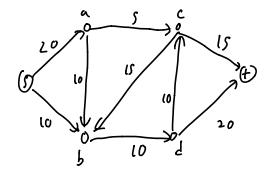
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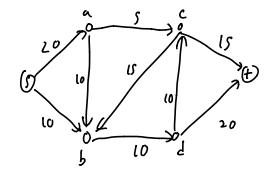
OR example as an LP

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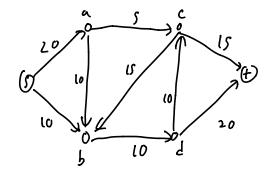
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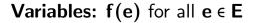


Variables:

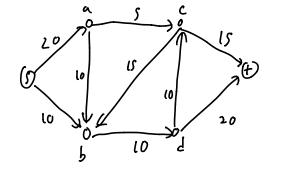


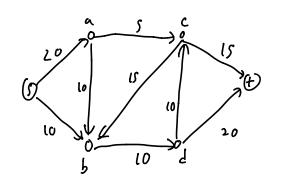
Variables: f(e) for all $e \in E$



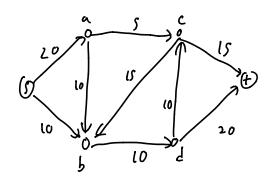


Objective:

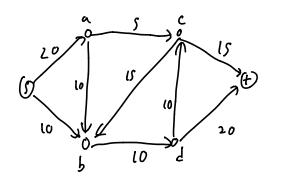




Variables: f(e) for all $e \in E$ Objective: max $\sum_{v} (f(s, v) - \sum_{v} f(v, s))$

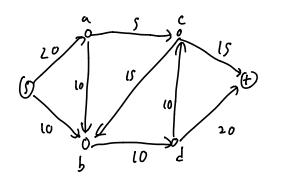


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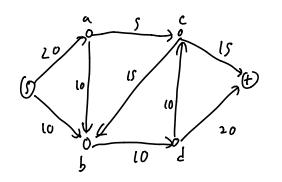
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$$\sum_{v} f(v, u) - \sum_{v} f(u, v) = 0 \qquad \forall u \in V \setminus \{s, t\}$$



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$$\sum_{v} f(v, u) - \sum_{v} f(u, v) = 0 \qquad \forall u \in V \setminus \{s, t\}$$
$$f(e) \le c(e) \qquad \forall e \in E$$

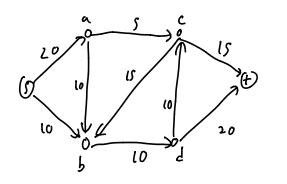


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$$f(e) \ge 0 \qquad \forall e \in E$$



 $\begin{array}{ll} \mbox{Variables: } f(e) \mbox{ for all } e \in E \\ \mbox{Objective: } \max \sum_v f(s,v) - \sum_v f(v,s) \\ \mbox{Constraints:} \\ & \sum_v f(v,u) - \sum_v f(u,v) = 0 \qquad \forall u \in V \smallsetminus \{s,t\} \\ & f(e) \leq c(e) \qquad \forall e \in E \end{array}$

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So can solve max-flow and min-cut (slower) by using generic LP solver

Multicommodity Flow

Generalization of max-flow with multiple commodities that can't mix, but use up same capacity

Generalization of max-flow with multiple commodities that can't mix, but use up same capacity

Setup:

- Directed graph G = (V, E)
- Capacities $\mathbf{c} : \mathbf{E} \to \mathbb{R}_{\geq \mathbf{0}}$
- **k** source-sink pairs $\{(s_i, t_i)\}_{i \in [k]}$
- Goal: send flow of commodity **i** from \mathbf{s}_i to \mathbf{t}_i , max total flow sent across all commodities

Generalization of max-flow with Wariables: multiple commodities that can't mix, but use up same capacity

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$$\begin{split} \sum_{v} f_{i}(v, u) &- \sum_{v} f_{i}(u, v) = 0 \qquad \forall i \in [k], \ \forall u \in V \smallsetminus \{s_{i}, t_{i}\} \\ &\sum_{i=1}^{k} f_{i}(e) \leq c(e) \qquad \forall e \in E \end{split}$$

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Constraints:

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Multicommodity flow, but:

- Also given *demands* d: [k] → ℝ_{≥0}
- ▶ Question: Is there a multicommodity flow that sends at least d(i) commodity-i flow from s_i to t_i for all i ∈ [k]?

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Maximum Concurrent Flow

If answer is no: how much do we need to scale down demands so that there is a multicommodity flow?

Maximum Concurrent Flow

Variables:

• $f_i(e)$ for all $e \in E$ and for all $i \in [k]$.

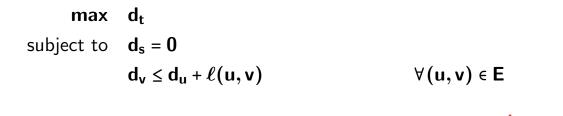
► **λ**

Objective: $\max \lambda$

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Very surprising LP! Variables: d_v for all $v \in V$: shortest-path distance from s to v



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Very surprising LP! Variables: d_v for all $v \in V$: shortest-path distance from s to v

 $\begin{array}{ll} \max & d_t \\ \mbox{subject to} & d_s = 0 \\ & d_v \leq d_u + \ell(u,v) \end{array} \quad \forall (u,v) \in \mathsf{E} \end{array}$

Correctness Theorem: Let $\vec{d^*}$ denote the optimal LP solution. Then $d_t^* = d(s,t)$

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Correctness Theorem: Let $\vec{d^*}$ denote the optimal LP solution. Then $d_t^* = d(s,t)$ **Proof Sketch:** \geq : Let $d_v = d(s,v)$ for all $v \in V$. Feasible $\implies d_t^* \geq d_t = d(s,t)$.

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≤: Let $P = (s = v_0, v_1, ..., v_k = t)$ be shortest $s \rightarrow t$ path. Prove by induction: $d_{v_i}^* \le d(s, v_i)$ for all iBase case: $i = 0 \checkmark$

Very surprising LP! Variables: d_v for all $v \in V$: shortest-path distance from s to v

 $\begin{array}{ll} \max & d_t \\ \mbox{subject to} & d_s = 0 \\ & d_v \leq d_u + \ell(u,v) \end{array} \quad \forall (u,v) \in \mathsf{E} \end{array}$

Correctness Theorem: Let $\vec{d^*}$ denote the optimal LP solution. Then $d_t^* = d(s,t)$ **Proof Sketch:** \geq : Let $d_v = d(s,v)$ for all $v \in V$. Feasible $\implies d_t^* \geq d_t = d(s,t)$.

November 4, 2021 12 / 20

Algorithms for LPs

Geometry

To get intuition: think of LPs geometrically

- Space: \mathbb{R}^n (one dimension per variable
- Linear constraint: halfspace (one side of a hyperplane)
- Feasible region: intersection of halfspaces. Convex Polytope (usually just called a polytope)

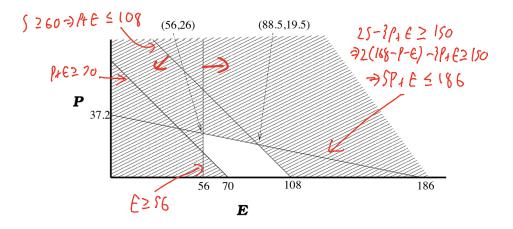
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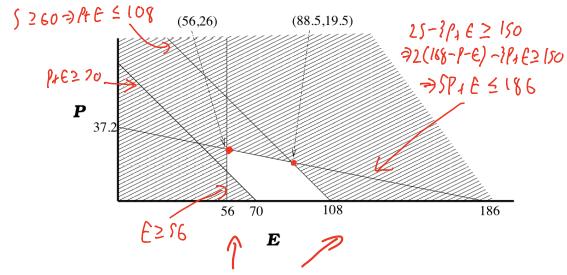
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Example: planning your week

- 3 variables S, P, E so \mathbb{R}^3
- But S + P + E = 168 ⇒ S = 168 - P - E
- Make this substitution, get \mathbb{R}^2



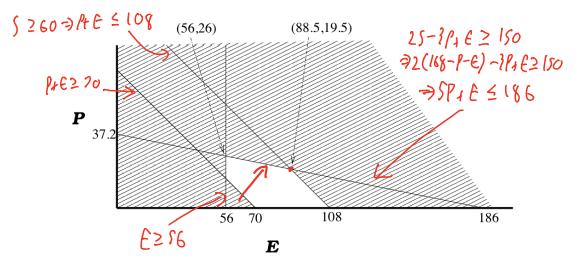
Geometry (cont'd)



Objective: feasible solution "furthest" along specified direction

- max P: (56, 26)
- max 2P + E: (88.5, 19.5)

Geometry (cont'd)



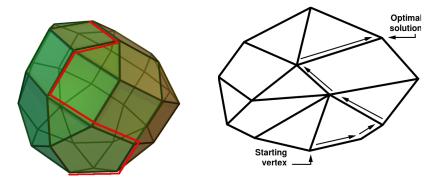
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- max P: (56, 26)
- max 2P + E: (88.5, 19.5)

Main theorem: optimal solution is always at a "corner" (also called a "vertex")

Simplex Algorithm [Dantzig 1940's]

```
Initialize \vec{x} to an arbitrary corner
while(a neighboring corner \vec{x}' of \vec{x} has better objective value) {
\vec{x} \leftarrow \vec{x}'
}
return \vec{x}
```



Theorem: Simplex returns the optimal solution.

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Proof Sketch:

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- Feasible set convex + linear objective \implies any local opt is global opt
- \implies Once simplex terminates, at global opt

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Problem: Exponential number of corners!

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- Fast in practice!
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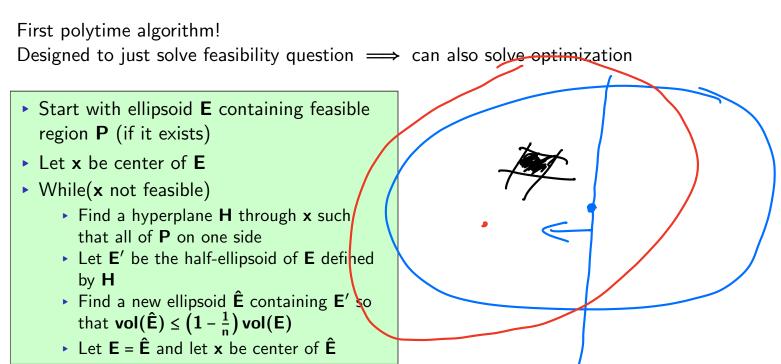
- Slow in theory
- Fast in practice!
 - Much of AMS LP course really about simplex: traditionally favorite algorithm of people who want to actually solve LPs
- Some theory to explain discrepancy ("smoothed analysis")

Ellipsoid Algorithm [Khachiyan 1980]

First polytime algorithm!

Designed to just solve feasibility question \implies can also solve optimization

Ellipsoid Algorithm [Khachiyan 1980]



Analysis

Extremely complicated!

Geometry of ellipsoids: can always find an ellipsoid containing a half-ellipsoid with at most (1 - 1/n) of the volume of the original

- Using inequality from last time: after **n** iterations, volume drops by $(1 \frac{1}{n})^n \le 1/e$ factor
- Crucial fact: if volume "too small", P must be empty

 \rightarrow Polynomial time!

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- \rightarrow Polynomial time!

In practice: horrible.

Interior Point Methods (Karkmarkar's Algorithm)

Fast in both theory and practice!

