

1/29/25:

Def:  $\ell_1$ -sensitivity, global sensitivity:  $f: \mathcal{D} \rightarrow \mathbb{R}^k$

$$\Delta f = \max_{D, D' \text{ neighboring}} \|f(D) - f(D')\|_1$$

How much can a single individual's data change  $f$ ?

(common case:  $k=1$ , so  $f: \mathcal{D} \rightarrow \mathbb{R}$ )

Ex: counting queries.

"How many people in this database satisfy property  $P$ ?"

$$\Delta f = 1$$

"What fraction":  $\Delta f = \frac{1}{n}$

:

Can be huge: if data is  $\mathbb{R}$ , if query is average, max, etc., then  $\Delta f$  unbounded!

Laplace mechanism: add Laplace noise to each entry,  
scaled by  $\Delta f / \epsilon$ . Formally:

Def: Laplace Mechanism: Given  $f: \mathcal{D} \rightarrow \mathbb{R}^k$ , Laplace mechanism is  $M_L(D, f, \epsilon) = f(D) + (Y_1, \dots, Y_k)$ ,  
where  $Y_i$ 's are i.i.d. random vars from  $\text{Lap}(\frac{\Delta f}{\epsilon})$

Equivalent:  $M_L(D, f, \epsilon) = (Z_1, \dots, Z_k)$  where  
 $Z_i$ 's are i.i.d. random vars from  
 $\text{Lap}(f(D)_i, \frac{\Delta f}{\epsilon})$

Ex: counting queries

1 query:  $\Delta f = 1 \Rightarrow$  add  $\text{Lap}(1/\epsilon)$  noise

k queries: think of  $f$  as vector of answers

for all queries

$\Rightarrow \Delta f$  could be  $k$

$\Rightarrow$  add  $\text{Lap}(k/\epsilon)$  to every query / component!

Ex: histogram queries

Divide range into cells, report count in each cell.

Ex: height.  $5' - 5'2"$ ,  $5'2" - 5'4"$ , etc.

counting query in each bucket

$$\Rightarrow \Delta f = 1$$

$\Rightarrow$  add  $\text{Lap}(1/\epsilon)$  to each query, even though  
k queries

Q: How good is this mechanism (accuracy/utility/privacy).

Fact: If  $X \sim \text{Lap}(b)$ , then

$$\Pr[|X| \geq t \cdot b] = \exp(-t) \quad (\text{tail bound}).$$

Thm: Let  $f: \mathcal{D} \rightarrow \mathbb{R}^k$ , let  $y = M_{\mathcal{L}}(D, f, \epsilon)$ .

then  $\forall \delta \in (0, 1]$ :

$$\Pr\left[\|f(D) - y\|_{\infty} \geq \ln\left(\frac{k}{\delta}\right) \cdot \frac{\Delta f}{\epsilon}\right] \leq \delta$$

Pf:  $\Pr[\|f(D) - g\|_\infty \geq \ln\left(\frac{k}{\delta}\right) \cdot \frac{\Delta f}{\epsilon}]$

$$= \Pr\left[\max_{i \in [k]} |Y_i| \geq \ln\left(\frac{k}{\delta}\right) \cdot \frac{\Delta f}{\epsilon}\right]$$

?   
 noise added to   
 coordinate  $i$

$$\leq k \cdot \Pr\left[|Y_i| \geq \ln\left(\frac{k}{\delta}\right) \cdot \frac{\Delta f}{\epsilon}\right] \quad (\text{union bound, all } Y_i \text{'s i.i.d.})$$

$$= k e^{-\ln\left(\frac{k}{\delta}\right)} \quad (\text{previous fact})$$

$$= \delta$$

Ex: First names.

Given list of 10000 names, how many people from last census had each name?

Histogram query,  $\Delta f = 1$

$\Rightarrow$  add  $\text{Lap}(1)$  noise to each count, get 1-DP

get  $\delta = 0.05$ :

with probability 95%, an estimate off by

noe than  $\ln\left(\frac{10000}{0.05} \cdot 1\right) \approx 12.2$ .

Pretty good!

Gaussian Mechanism: will talk about more  
ways get to RDP/CDP/2CDP.

Mechanism: add  $N(0, \underbrace{(\frac{1}{\epsilon} \Delta f)^2}_{\text{variance}} \ln \frac{1}{\delta})$  noise

$\Delta f$ : can even use  $\ell_2$ -sensitivity!

$\max_{D, D' \text{ neighbors}}$

Thm: For  $\epsilon \in (0, 1)$ , this is  $(\epsilon, \delta)$ -DP.

See Appendix A.

Differentially private selection:

- In first names example, sps want to know which name is most popular, not actual counts?
- Release less information: can we be more accurate?
- Generalize: sps  $k$  counting queries (not histogram).
- Laplace: add  $Lap(\frac{k}{\epsilon})$  noise to each

Report Noisy Max:

- Add  $\text{Lap}(\frac{1}{\epsilon})$  to each, return which is largest.

Thm: RNMA is  $\epsilon$ -DP

Pr: - Let  $D = D' \cup \{a\}$ .

- Let  $c \in \mathbb{N}^k$  true counts for  $D$ ,  $c' \in \mathbb{N}^k$  for  $D'$

- Fix  $i \in [k]$ . WTS:  $P_i(c; D) \in [e^{-\epsilon} P_i(c; D'), e^{\epsilon} P_i(c; D')]$

- Fix  $r_{-i}$ , a draw from  $(\text{Lap}(\frac{1}{\epsilon}))^{k-1}$  used for all noisy counts other than  $i$ .

First: show  $P_i(c; D, r_{-i}) \leq e^{\epsilon} P_i(c; D', r_{-i})$

Let  $r^+ = \min_{r_i} : c_i + r_i > c_j + r_j \quad \forall j \neq i$

(min value of  $r_i$  so RNMA returns  $i$  when other noisy fixed)

$\forall j \neq i$ :

$$c_i^{\uparrow} + (r^+ + 1) \geq \overset{\text{counts}}{c_i + r^+} \geq \overset{\text{def}}{c_j + r_j}$$

$$\geq c_j^{\uparrow} + r_j \quad (\text{def of } i, c)$$

so if  $r_i \geq r^+ + 1$ , will return  $i$  in  $D'$ ,  $r_i$

$$\Rightarrow \Pr[C_i | D', r_{-i}] \geq \Pr[r_i \geq r_i^* + 1]$$

$$= e^{-\epsilon} \Pr[r_i \geq r_i^*] \quad (\text{Laplace distribution w/ parameter } \frac{1}{\epsilon})$$

$$= e^{-\epsilon} \Pr[C_i | D, r_{-i}]$$

$$\Rightarrow \Pr[C_i | D, r_{-i}] \leq e^{\epsilon} \Pr[C_i | D', r_{-i}] \quad \checkmark$$

Second: Show  $\Pr[C_i | D', r_{-i}] \leq e^{\epsilon} \Pr[C_i | D, r_{-i}]$

$$\text{Let } r^* = \min_{r_i} : c_i + r_i > c_j + r_j \quad \forall j \neq i$$

$\forall j \neq i$ :

$$c_i + (r^* + 1) \geq c_i + (r^* + 1) \quad (\text{def of } c, c')$$

$$> c_j + (r_j + 1) \quad (\text{def of } r^*)$$

$$\geq c_j + r_j \quad (\text{rounding } \{r_j\})$$

$$\Rightarrow \text{If } r_i \geq r^* + 1, \text{ will return } i \text{ in } D, r_{-i}$$

$$\Rightarrow \Pr[C_i | D, r_{-i}] \geq \Pr[r_i \geq r^* + 1]$$

$$= e^{-\epsilon} \Pr[r_i \geq r^*] \quad (\text{Lap}(\frac{1}{\epsilon}))$$

$$= e^{-\epsilon} \Pr[C_i | D', r_{-i}]$$

$$\Rightarrow \Pr[C_i | D', r_{-i}] \leq e^{\epsilon} \Pr[C_i | D, r_{-i}] \quad \checkmark$$