

DP APSD:

Graph DP, but can't do node- or edge-DP!

- One edge removed: distance jumps from finite to ∞
- \Rightarrow infinite sensitivity, can't do anything.

Instead: graph public, weights private.

- Graph $G = (V, E)$
- $w: E \rightarrow \mathbb{R}_{\geq 0}$
- w, w' neighboring databases if $\|w - w'\|_1 \leq 1$
- APSD: output $d(u, v) \forall u, v \in V$
- want to do privately!
- error of $\hat{d} := \max_{u, v \in V} |\hat{d}(u, v) - d(u, v)| = \|\hat{d} - d\|_{\infty}$

Intuition: models situations where graph known, but weights influenced by private behavior.

E.g., $w(u, v)$ a function of traffic on edge, so weights function of where people are driving.

Approach 1: add noise to all distances after computing them!

$$\Delta_{1d} = \Theta(n^2) \Rightarrow \text{not good}$$

\Rightarrow Laplace: add $\text{Lap}(\frac{n^2}{\epsilon})$ noise

$\Rightarrow \epsilon$ -DP, but error $\sim \frac{n^2}{\epsilon}$!

$$\Delta_{2d} = \Theta(n) (\sqrt{\sum_{i,j} 1^2})$$

\Rightarrow Gaussian: add $N(0, \sigma^2)$ noise for $\sigma = \Theta(\frac{n \sqrt{1.3} \sqrt{\delta}}{\epsilon})$

\Rightarrow error $\sim \tilde{O}(\frac{n}{\epsilon})$, (ϵ, δ) -DP

Q1: can we get $\tilde{O}(n)$ error for ϵ -DP?

Idea: instead of computing distances then adding noise, add noise then compute distances!

$$\hat{w} = w + \text{Noise} \Rightarrow \Delta_{1w} = 1 \text{ (def)}$$

$\Rightarrow \hat{w}(e) = w(e) + \text{Lap}(\frac{1}{\epsilon})$ best is ϵ -DP.

$$(\epsilon, \delta)\text{-DP}: \Delta_{2w} = 1 \Rightarrow \hat{w}(e) = w(e) + N(0, \frac{1.3 \sqrt{\delta}}{\epsilon^2})$$

is (ϵ, δ) -DP \Rightarrow no gain over ϵ -DP.

$\Rightarrow \hat{d}$ = shortest paths in \hat{w} : post-processing!

Issue: what if negative cycle!

Solution: If $\hat{w}(e) < 0 \Rightarrow \hat{w}(e) = 0$ (post-processing).

Thm: w.h.p., $\text{err}(\hat{f}) \leq \tilde{O}(\frac{1}{\epsilon})$

Incorrect proof: for gaussian noise, noise on path is
sum of gaussian w/ variance $\frac{1.5 \log \frac{1}{\delta}}{\epsilon^2} \Rightarrow$ since

gaussian w/ variance $\frac{1.5 \log \frac{1}{\delta}}{\epsilon^2} \Rightarrow \frac{\sqrt{1.5 \log \frac{1}{\delta}}}{\epsilon}$ error w.h.p.

True, but lots of paths! Too many to union bound.

Pt: Laplace tail bound: $\Pr[|Lap(\frac{1}{\epsilon})| \geq t \cdot \frac{1}{\epsilon}] = e^{-t^2}$

$\Rightarrow \Pr[N_e > \frac{1}{\epsilon} \ln n] \leq n^{-1}$

$\Rightarrow \Pr[\max_{e \in E} N_e > \frac{1}{\epsilon} \ln n] \leq n^{-c+2}$

$c \geq 3$: w.h.p. $\max_{e \in E} \text{error} \leq O(\frac{1}{\epsilon} \ln n)$

Fix $u, v \in V$, consider arbitrary $u-v$ path P .

$\Rightarrow |\hat{w}(P) - w(P)| \stackrel{\text{triangle}}{\leq} \left| \sum_{e \in P} (w(e) + N_e) - \sum_{e \in P} w(e) \right|$

$= \left| \sum_{e \in P} N_e \right| \leq |P| \cdot \frac{1}{\epsilon} \ln n \leq O(n \cdot \frac{1}{\epsilon} \ln n)$

Let $\hat{p} = \argmin_{u-v \text{ path } P} \hat{w}(P)$

$p^* = \argmin_{u-v \text{ path } P} w(P)$

$\hat{f}(u,v) = \hat{w}(\hat{p}) \leq \hat{w}(p^*) \leq w(p^*) + O(\frac{1}{\epsilon} \ln n) = d(u,v) + O(\frac{1}{\epsilon} \ln n)$

$\hat{f}(u,v) = \hat{w}(\hat{p}) \geq w(\hat{p}) - O(\frac{1}{\epsilon} \ln n) \geq w(p^*) - O(\frac{1}{\epsilon} \ln n) = d(u,v) - O(\frac{1}{\epsilon} \ln n)$

$$\Rightarrow |\hat{d}(u,v) - d(u,v)| \leq O\left(\frac{1}{\epsilon} \ln n\right)$$

Can we do better?

Idea: - want to only consider few-hop paths.

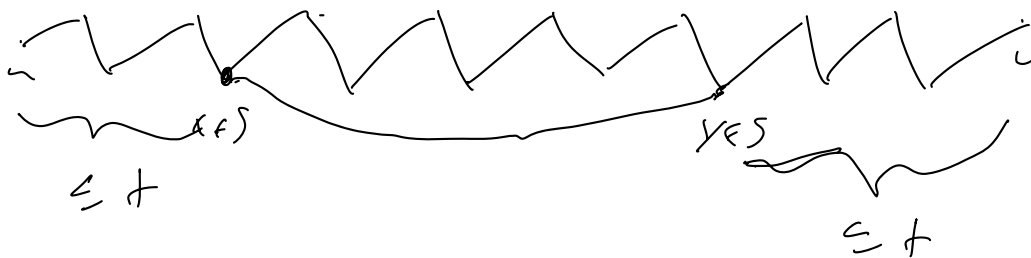
- But what if shortest paths has many hops?

- Shortcuts! (hopcuts!)

Let S = sub-sample each node indep. w/ prob. $p = \Theta\left(\frac{\ln n}{t}\right)$

$$\Rightarrow |S| = \Theta\left(\frac{n \ln n}{t}\right) \text{ w.h.p.}$$

Idea: use S as shortcuts! If we have good estimate for distances $u \in S, v \in S$, can we detect to "jump"?



For $u, v \in S$, let $\hat{d}(u,v) = d(u,v) + O_p\left(\frac{1}{\epsilon}\right)$ (Approach 1)

$$\forall u, v \in V, \text{ let } \hat{d}^+(u,v) = \min_{\substack{x \rightarrow v \text{ path } P \\ \text{w/ } |x \rightarrow v| \leq t}} \hat{w}(e)$$

$\forall u, v : (u,v) \in E \setminus S$, let

$$\hat{d}(u,v) = \min\left(\hat{d}^+(u,v), \min_{x,y \in S} \left(\hat{d}^+(u,x) + \hat{d}(x,y) + \hat{d}^+(y,v)\right)\right)$$

Thm: ε -DP.

pf: For distances in $S \subseteq \mathbb{S}$, sensitivity $\leq s^2$

$\Rightarrow \varepsilon$ -DP by Laplace mechanism

$\hat{v}(e)$ DP by previous analysis

Everything else post-processing

About t error from \hat{d}^t , about $s^2 \approx \frac{s^2}{t^2}$ error from $S \subseteq \mathbb{S}$

$$\Rightarrow t = \frac{n^2}{t^2} \Rightarrow t = n^{2/3}$$

So set $t = n^{2/3}$

Thm: w.h.p., error $\leq \tilde{O}\left(\frac{n^{2/3}}{\varepsilon}\right)$

pf: Fix $u, v \in V$.

If $u, v \in S \Rightarrow$ error from $L_{\varepsilon}\left(\frac{s^2}{\varepsilon}\right) = \tilde{O}(n^{2/3})$ w.h.p.

Or let P^* shortest path (true).

$$\text{Claim: } \hat{d}(u, v) \leq d(u, v) + O\left(\frac{n^{2/3}}{\varepsilon}\right)$$

$$\text{If } |P^*| \leq t \Rightarrow \hat{d}(u, v) \leq \hat{d}^t(u, v) \leq \hat{w}(P^*)$$

$$\leq w(P^*) + O\left(t \frac{1}{\varepsilon}\right)$$

$$\approx d(u, v) + \tilde{O}\left(\frac{n^{2/3}}{\varepsilon}\right) \quad \checkmark$$

else, w.h.p. $P^* \cap S \neq \emptyset$

Let x closest node in $P \cap S$ to u
 y " " " " " " v

w.l.o.p. x is first to u , y is last to v

$$\Rightarrow \hat{d}(u, v) \leq \hat{d}^+(u, x) + \hat{d}(x, y) + \hat{d}^+(y, v)$$

$$\text{w.l.o.p.} \rightarrow \leq d(u, x) + O(t \cdot \frac{1}{\epsilon} \ln n) + d(x, y) + \tilde{O}(n^{\frac{2}{\epsilon}}) + d(y, v) + O(t \cdot \frac{1}{\epsilon} \ln n)$$

$$\leq d(u, v) + \tilde{O}\left(\frac{n^{\frac{2}{\epsilon}}}{\epsilon}\right)$$

$$\underline{C(a, b)}: \hat{d}(u, v) \geq d(u, v) - \tilde{O}\left(\frac{n^{\frac{2}{\epsilon}}}{\epsilon}\right)$$

$$\hat{d}^+(a, b) \geq d^+(a, b) - O\left(\frac{t \ln n}{\epsilon}\right) \quad \forall a, b \in V$$

(by earlier lemma).

$$\Rightarrow \text{if } \hat{d}(u, v) = \hat{d}^+(u, v), \text{ done } \checkmark$$

$$\text{else } \hat{d}(u, v) = \hat{d}^+(u, x) + \hat{d}(x, y) + \hat{d}^+(y, v) \text{ for some } x, y$$

$$\geq d^+(u, x) - O\left(\frac{t \ln n}{\epsilon}\right) + d(x, y) - \tilde{O}\left(\frac{n^{\frac{2}{\epsilon}}}{\epsilon}\right) + d(y, v) - O\left(\frac{t \ln n}{\epsilon}\right)$$

$$\geq d(u, x) + d(x, y) + d(y, v) - \tilde{O}\left(\frac{n^{\frac{2}{\epsilon}}}{\epsilon}\right)$$

$$\geq d(u, v) - \tilde{O}\left(\frac{n^{\frac{2}{\epsilon}}}{\epsilon}\right) \quad \checkmark$$

For (ϵ, δ) -DP: use Gaussian mechanism for $S \times S$ distances

$$\Rightarrow \tilde{O}\left(\frac{\sqrt{n}}{\epsilon}\right) - \text{error!}$$

Further results:

- Can't do better than $\tilde{\Omega}\left(\frac{n^{1/4}}{\epsilon}\right)$ -error.

- On trees, can do polylog error! Generalizes paths,
where distances \approx interval queries

\Rightarrow binary tree mechanism gives polylog error

- Minor free graphs (e.g., planar graphs): $\tilde{O}((nw)^{1/3})$, where
 w = max edge weight allowed

(generalized binary tree mechanism).