

1/20/26: Intro, Vertex Cover

Course Staff:

- Me: www.cs.jhu.edu/~mdinitz/
- TAs: None!

Course Webpage: (Not Canvas)

- www.cs.jhu.edu/~mdinitz/classes/ApproxAlgorithms/Spring2026/
- Course love
- Gradescope

Prereq: Intro Algorithms

Grading: - 50% homework
- 35% final project
- 15% Participation

Final project: Flexible!

- Possibly presentations last week of class, reports by scheduled exam

Note: PhD-level class!

- Course schedule more flexible
- Not much handholding
- Hopefully not a ton of work, so you can focus on research

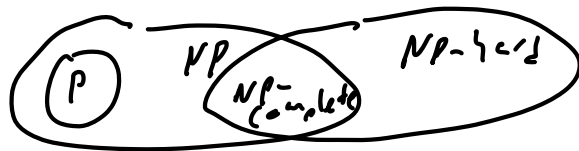
Approximation Algorithms: What and Why

P: Solvable in polytime

NP: Verifiable in polytime

NP-hard: problems that all problems in NP
reduce to in polytime

NP-complete: in NP and NP-hard



Given NP-hard optimization problem, what do we want
that NP-hardness prevents?

1. Find the optimal solution
2. In polynomial time
3. For every instance

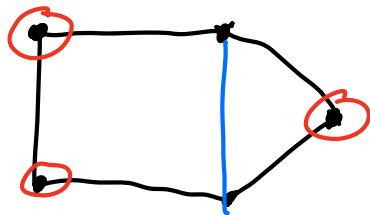
could relax any of these!

Problem consists of:

- 1) Description of inputs/instances
- 2) Description of **feasible** solutions for input
- 3) Objective function

Example: **Vertex Cover**

- Input: Graph $G = (V, E)$
- Feasible solutions: $V' \subseteq V$ s.t. $e \cap V' \neq \emptyset \forall e \in E$
- Objective: minimize $|V'|$



Def: The **optimal solution** is the feasible solution with the best objective value

Def: \mathcal{A} some problem, I instance of \mathcal{A}

- ALG : some algorithm for \mathcal{A}
- $OPT(I)$: objective value of optimal solution for I
- $ALG(I)$: objective value of solution returned by ALG on I

ALG is an α -approximation if:

- always returns a feasible solution
- runs in polytime
- $\frac{ALG(I)}{OPT(I)} \leq \alpha \quad \forall \text{ instances } I \text{ of } \mathcal{A} \text{ (min problem)}$

$$\frac{ALG(I)}{OPT(I)} \geq \alpha \quad \forall \text{ instances } I \text{ of } \mathcal{A} \text{ (max problem)}$$

α is the α -approximation ratio or approximation factor

why?

- Really do need algorithms for NP-hard problems!
- "Fine-grained complexity": not all NP-hard problems are the same!

$\mathcal{A}_1, \mathcal{A}_2$ p-problems.

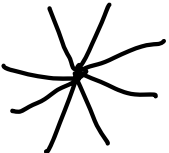
\mathcal{A}_1 : design a 2-approximation

\mathcal{A}_2 : Assuming $P \neq NP$, no α -approx for $\alpha < 10$

- Forcing ourselves to handle worst-case forces new techniques

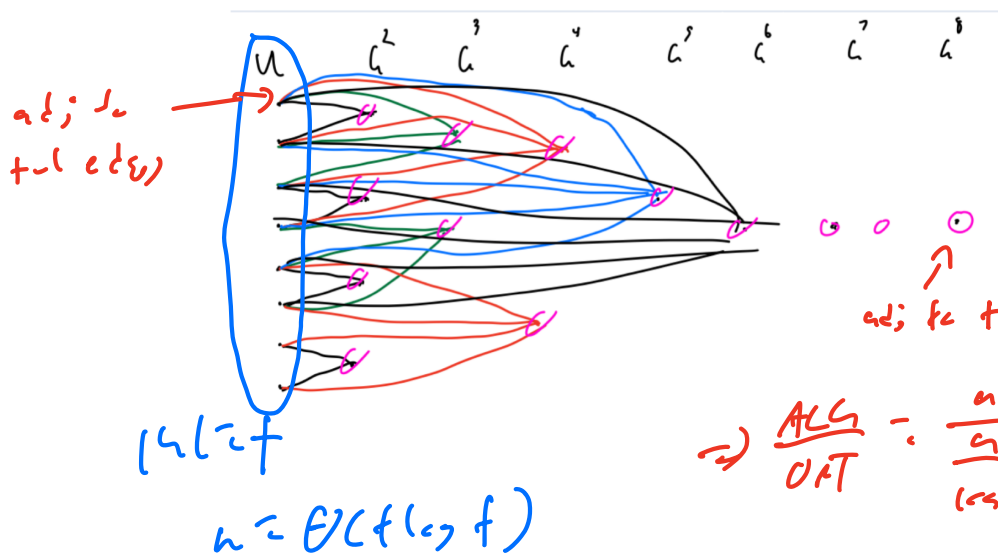
Approximating Vertex Cover

Idea 1: Arbitrarily add vertices until have feasible vertex cover

Star:  OPT: 1
ALG: $n-1$

Idea 2: Greedy algorithm

Add node covering most uncovered edges



$$OPT = |V| \leq t \frac{n}{\log n}$$

$$ALG = n - |V| = \Theta(t \log t) n$$

$$\Rightarrow \frac{ALG}{OPT} = \frac{n}{\frac{n}{\log n}} = \log n$$

$$ALG: n$$

$$OPT: \frac{n}{\log n}$$

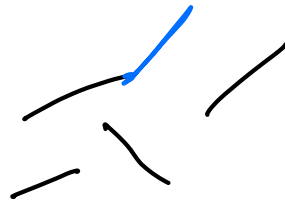
Better Algorithm:

- $S = \emptyset$
- while $E \neq \emptyset$ {
 - Let $\{u, v\}$ be arbitrary edge
 - $S \leftarrow S \cup \{u, v\}$
 - Remove u, v , all incident edges, from G}

Poly time:

Lemma: S feasible (S a vertex cover)

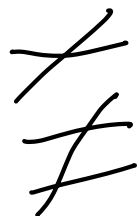
Pf: ✓



Def: $M \subseteq E$ is a **matching** if no two edges in M share an endpoint: $e \cap e' = \emptyset \quad \forall e, e' \in M$ with $e \neq e'$

Lemma: Let M be a matching, and S be a vertex cover. Then $|S| \geq |M|$

Pf:



Thm: Algorithm is a 2-approx.

Pf: polytime, feasible: ✓

Let S^* optimal vertex cover.

WTS: $|S| \leq 2|S^*|$

Structure of edges considered by algorithm: matching M

$\Rightarrow |S| \stackrel{\text{def of ALG}}{=} 2|M| \leq 2|S^*|$

by lemma

Q: Are we happy?

Q1: Is *analysis* tight?

A: yes (star, $k_{s,n}, \dots$)

Q2: Is *algorithm* tight?

- Best known approx: $2 - \frac{1}{\sqrt{1.5n}}$

- Assuming P ≠ NP, no alg better than $|0\sqrt{5}-2| \approx 1.3606$ approx

- Assuming UGC, \forall constant $\epsilon > 0$ there is no $(2-\epsilon)$ -approx