

5.1 Max-Cut

- Input: a graph $G = (V, E)$, where V is the set of vertexes and E is the set of edges.
- Feasible solution: a set $S \subseteq V$. Here S is also called a cut of G .
- Objective: Maximize $|E(S, \bar{S})|$. Here $E(S, \bar{S}) = \{\{u, v\} : \{u, v\} \in E, u \in S, v \in \bar{S}\}$.

5.1.1 The Algorithm

Algorithm 1 Local Search Algorithm for Max-Cut

Input: A graph $G = (V, E)$

Output: A set $S \subseteq V$

Initialize S arbitrarily

while $\exists u \in V$ with more edges to the same side than across **do**
 move u to the other side

end while

return S

5.1.2 Time Complexity

Theorem 5.1.1 *The Local Search algorithm for Max-Cut runs in polynomial time.*

Proof:

1. If there exists a vertex u with less than $\frac{1}{2}d(u)$ edges across, we can find u in polynomial time. ($d(u)$ denotes the degree of u)
2. Initially $|E(S, \bar{S})| \geq 0$. Finally $|E(S, \bar{S})| \leq m \leq n^2$. Every vertex switch increases $|E(S, \bar{S})|$ by at least 1.

So the overall running time is polynomial. ■

5.1.3 Approximation Factor

Theorem 5.1.2 *The local search algorithm is a 2-approximation.*

Proof: Say S is a local OPT if there is no improving step. No improving step means that $\forall u \in V$, there are more $\{u, v\}$ edges across the cut than connecting the same side.

Suppose S is a local OPT. Let $d_{across}(u)$ denote the number of edges incident on u that cross the cut. The since S is a local optimum, we know that

$$|E(S, \bar{S})| = \frac{1}{2} \sum_{u \in V} (d_{across}(u)) \geq \frac{1}{2} \sum_{u \in V} \frac{1}{2} d(u) = \frac{1}{4} \sum_{u \in V} d(u) = \frac{1}{4} \cdot 2m = m/2,$$

where $m = |E|$. We know $OPT \leq m$, and hence the algorithm is a 2-approximation. ■

5.2 Min-Degree Spanning Tree

- Input: a connected graph $G = (V, E)$.
- Feasible solution: A spanning tree T .
- Objective: Minimize $\max_{u \in V} d_T(u)$. Here $d_T(u)$ is the degree of u in the spanning tree T .

Theorem 5.2.1 *Min-Degree Spanning Tree is NP-hard.*

Proof: There is a reduction from Hamiltonian Path to Min-Degree Spanning Tree: given a graph G , it contains a Hamiltonian path if and only if it contains a spanning tree with maximum degree at most 2. ■

5.2.1 Local Search 1

We first define a local move. A local move is a pair (e, e') , where e is a non-tree edge and e' is a tree edge on the fundamental cycle of e (the cycle created in the tree by adding e).

Algorithm 2 Local Search Algo 1 for Min-Degree Spanning Tree

Input: A graph $G = (V, E)$

Output: A spanning tree T

Find a spanning tree T of G

while There is a local move which decreases the max degree of the current T **do**
do the move

end while

Output T

As shown in figure 5.2.1, the algorithm may not work well. There is a local optimum with maximum degree d as shown in the left figure (each non-leaf node in the tree has degree d) while the OPT is 3 as shown in the right figure.

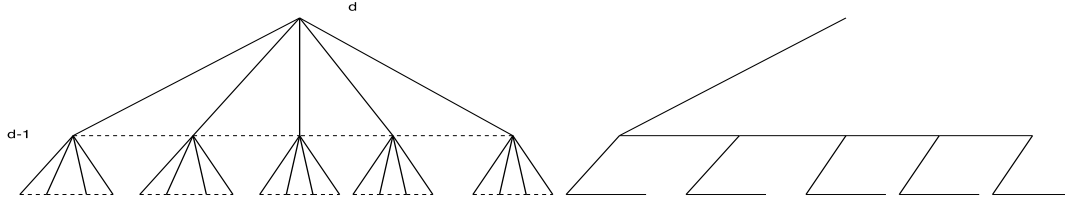


Figure 5.2.1: Example

5.2.2 Local Search 2

Let's improve Local Search 1.

Definition 5.2.2 Let $u \in V$. Then $(u, \{v, w\})$ is a u -improvement if there is an edge $\{u, x\}$ on the fundamental cycle of $\{v, w\}$ so that we can swap $\{v, w\}$ for $\{u, x\}$ to get T' so that $\max\{d_{T'}(v), d_{T'}(w)\} \leq d_{T'}(u) = d_T(u) - 1$

However, the running time is not polynomial if we just keep finding u -improvement for all vertices until we can't find any. Thus we will only perform u -improvements on nodes which have large degree. This gives us the algorithm Local Search 2.

Definition 5.2.3 $\Delta(T) = \max_{v \in V} d_T(v)$.

Algorithm 3 Local Search Algo 2 for Min-Degree Spanning Tree

Input: A graph $G = (V, E)$

Output: A spanning tree T

Find a spanning tree T of G

while There is u -improvement with $d_T(u) \geq \Delta(T) - \log n$ for the current T **do**
do the improvement

end while

Output T

5.2.3 Time Complexity

Theorem 5.2.4 The running time of Local Search 2 is polynomial.

Proof: The proof works by analyzing a potential function. Let $\Phi(v) = 3^{d_T(v)}$, and let $\Phi(T) = \sum_{v \in V} \Phi(v) = \sum_{v \in V} 3^{d_T(v)}$.

First note that $\Phi(T) \geq \sum_{v \in V} 3 = 3n$, since all nodes have degree at least 1 in T . Also, $\Phi(T) \leq n \cdot 3^n$. The following claim states the decrease on $\Phi(T)$ after each improvement.

Claim 5.2.5 *Suppose we make a u -improvement $(u, \{v, w\})$ with $d_T(u) \geq \Delta(T) - \log n$, obtaining a new spanning tree T' . Then $\Phi(T') \leq (1 - \frac{2}{9n^3})\Phi(T)$.*

Proof: Suppose $d_T(u) = i$ with $i \geq \Delta(T) - \log n$. Then $d_{T'}(u) = i - 1$, so the decrease in $\Phi(u)$ is $3^i - 3^{i-1} = 2 \cdot 3^{i-1}$. The increase of $\Phi(v)$ is $3^{d_{T'}(v)} - 3^{d_T(v)} \leq 3^{i-1} - 3^{i-2} = 2 \cdot 3^{i-2}$, and the same is true for $\Phi(w)$.

So the overall decrease in Φ is at least

$$\begin{aligned} 2 \cdot 3^{i-1} - 4 \cdot 3^{i-2} &= \frac{2}{9} \cdot 3^i \\ &\geq \frac{2}{9} \cdot 3^{\Delta(T) - \log n} \\ &= \frac{2}{9 \cdot 3^{\log n}} 3^{\Delta(T)} \\ &\geq \frac{2}{9n^{\log 3}} 3^{\Delta(T)} \\ &\geq \frac{2}{9n^2} \cdot \frac{1}{n} \Phi(T) \\ &= \frac{2}{9n^3} \Phi(T). \end{aligned}$$

Note that x (the other endpoint of the edge incident on u that we removed to add $\{v, w\}$) might also have a different degree in T' than in T , but in this case its degree will be smaller so this only helps us. ■

Suppose we run $\frac{9}{2}n^4 \ln 3$ iterations. Then $\Phi(T) \leq (1 - \frac{2}{9n^3})^{-\frac{9}{2}n^4 \ln 3} \cdot n3^n \leq n$. As $\Phi(T) \geq 3n$, this means that the algorithm must stop in less than $\frac{9}{2}n^4 \ln 3$ iterations. ■

5.2.4 Approximation Parameter

We will prove this next class.

Theorem 5.2.6 *The output spanning tree of Local Search 2 has max-degree at most $2 \cdot OPT + \log n$.*

The best known (and possible) result is a different algorithm which is still based on local search:

Theorem 5.2.7 [FR94] *There is a polynomial time algorithm which returns a spanning tree with max-degree at most $OPT + 1$.*

References

FR94 M. FURER and B. RAGHAVACHARI. Approximating the minimum-degree Steiner tree to within one of optimal, *Journal of Algorithms* 17.3, 1994, pp. 409–423.