

1/27/22: 2-player zero-sum games

Notes: - HW 1 released, due in 2 weeks (beginning of lecture)
- Recording not great

Def [One-shot simultaneous-move game]:

- n players $[n] = \{1, 2, \dots, n\}$
- Finite set S_i of strategies/actions for player i
- $S = S_1 \times S_2 \times \dots \times S_n$ set of strategy profiles
- Utility function $u_i: S \rightarrow \mathbb{R}$ for each $i \in [n]$

Notation: $\Delta_k = \{x \in \mathbb{R}^k : x_i \geq 0 \ \forall i \in [k], \sum_{i=1}^k x_i = 1\}$
set of probability vectors/distributions over $[k]$

Def [Nash equilibrium]: Let $\mu_i \in \Delta_{S_i} \ \forall i \in [n]$. Then

$(\mu_1, \mu_2, \dots, \mu_n)$ is a **Nash Equilibrium** if $\forall i \in [n]$ and $\mu'_i \in \Delta_{S_i}$

$$\mathbb{E}_{s_i \sim \mu_i; \forall s_j \in [n]} [u_i(s_1, s_2, \dots, s_n)] \geq \mathbb{E}_{s_i \sim \mu'_i; \forall s_j \neq i} [u_i(s_1, s_2, \dots, s_n)]$$

Notes:

- A single strategy $s \in S_i$, or $\mu \in \Delta_{S_i}$ with exactly one nonzero entry, is a **pure strategy**
- $\mu \in \Delta_{S_i}$ called a **mixed strategy**
- If all μ_i 's are pure strategies, called a **pure Nash equilibrium**
- Sometimes call a NE a **mixed NE** to distinguish from pure

Thm (Nash): Every game with a finite # players,
finite # pure strategies, has at least one NE

possibly weird things to keep in mind:

- implicitly assuming every player knows mixed strategy of every other player, but not action drawn
- "stable", but one-shot

can simplify definition: only need to consider deviations to pure strategies!

Thm: If $(\mu_1, \mu_2, \dots, \mu_n)$ is ~~not~~ a NE, then
 $\exists i \in [n], a \in S_i$ s.t.

$$E_{s_j \sim \mu_j; \forall j \in [n]} [u_i(s_1, s_2, \dots, s_n)] < E_{\substack{s_j \sim \mu_j; \forall j \neq i \\ s_i = a}} [u_i(s_1, s_2, \dots, s_n)]$$

Pf sketch: Since ~~not~~ a NE, $\exists i \in [n], \mu_i' \in \Delta_{S_i}$
 s.t. i has incentive to deviate to μ_i' from μ_i

But μ_i' convex combination of pure strategies!

$\Rightarrow \mu_i'$ no better than best pure strategy

Lots of generalizations and other definitions!

- subgame perfect Nash

- Bayes-Nash

- strong Nash

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Today: $n=2$, "zero-sum"

next class: $n=2$, non-zero-sum

future: $n > 2$

Notation: Bimatrix game

- 2 players - $S_1 = [N]$ - $S_2 = [M]$

- Matrices $A, B \in \mathbb{R}^{N \times M}$

- $u_1(i, j) = A_{ij}$ - $u_2(i, j) = B_{ij}$

useful notation b/c linear algebra!

Claim: Let $x \in \Delta_N$ (mixed strategy for player 1)

$y \in \Delta_M$ (mixed strategy for player 2)

Then $\mathbb{E}_{\substack{i \sim x \\ j \sim y}} [u_1(i, j)] = x^T A y$, and

$\mathbb{E}_{\substack{i \sim x \\ j \sim y}} [u_2(i, j)] = x^T B y$

Pf: $x^T A y = \sum_{i=1}^N \sum_{j=1}^M A_{ij} x_i y_j$ (LA)

$= \sum_{i=1}^N \sum_{j=1}^M u_1(i, j) \cdot \Pr[\text{player 1 plays } i] \cdot \Pr[\text{player 2 plays } j]$ (def)

$$= \sum_{i \sim x} \sum_{j \sim y} [u_1(i, j)]$$



Def: A bimatrix game is **zero-sum** if

$$B_{ij} = -A_{ij} \quad \forall i \in [N], j \in [M]$$

\Rightarrow in zero-sum game, just need single matrix A :

player 1 chooses x to maximize $x^T A y$,

player 2 chooses y to minimize $x^T A y$

Thm [von Neumann]: In a two-player zero-sum game,
we can compute a Nash equilibrium in polynomial
time

Note: Not original formulation!

sp row player uses mixed strategy $x \in \Delta_N$.

$\Rightarrow x^T A \in \mathbb{R}^M$, and $(x^T A)_j$ is expected utility for row
player if column player uses pure strategy j

So what does column player do?

Choose j minimizing $(x^T A)_j$!

\Rightarrow if row player uses x , will end up getting

$$\min_{j \in [M]} (x^T A)_j \text{ utility}$$

So what will row player do?

Choose $x \in \Delta_N$ maximizing $\min_{j \in [M]} (x^T A)_j$

Can we compute this?

$$\begin{aligned} v_r = \max \quad & v \\ \text{s.t.} \quad & x_i \geq 0 \quad \forall i \in [N] \\ & \sum_{i=1}^N x_i = 1 \\ & (x^T A)_j \geq v \quad \forall j \in [M] \end{aligned}$$

$$(x^T A)_j = \sum_{i=1}^N A_{ij} x_i$$

Linear programming!

Let $p \in \Delta_N$ be optimal solution to LP

Thm: Let (p^*, q^*) be a NE, and let $v^* = p^{*T} A q^*$ be expected utility of row player. Then $v_r = v^*$.

PF: $v_r \leq v^*$: Sup $v_r > v^*$. Then if row player switches to p , gets utility

$$p^T A q^* \geq \min_{j \in [M]} (p^T A)_j = v_r > v^*$$

\Rightarrow would have incentive to deviate

$v^* \leq v_r$: Since column player doesn't want to deviate,

$$v^* = \min_{j \in [M]} (p^{*T} A)_j$$

$\leq v_r$, since v^* feasible solution to LP,
 v_r optimal for LP

Now similar thought process for column player:

If column player plays $y \in \Delta_M$, row player chooses $i \in [N]$ maximizing $(A y)_i$

\Rightarrow column player plays $y \in \Delta_M$ minimizing $\max_{i \in [N]} (A y)_i$

compute via LP:

$$\begin{aligned}
v_c &= \min v \\
\text{s.t. } y_j &\geq 0 & j \in [M] \\
\sum_{j=1}^M y_j &= 1 \\
(Ay)_i &\leq v & \forall i \in [N]
\end{aligned}$$

$$(Ay)_i = \sum_{j=1}^M A_{ij} y_j$$

Analogous to before: $v_c = v^*$

Let $p \in \Delta_N$ opt solution to row LP,
 $q \in \Delta_M$ opt solution to column LP

Thm: (p, q) is a Nash equilibrium

$$\text{PF: } p^T A q \geq v_r = v^* \quad \text{since } p \text{ opt sol to row LP}$$

$$p^T A q \leq v_c = v^* \quad \text{since } q \text{ opt sol to col LP}$$

$$\Rightarrow p^T A q = v^*$$

Sps row player deviates to pure strategy $k \in [N]$:

row player gets utility

$$(Aq)_k \leq \max_{i \in [N]} (Aq)_i = v_c = v^*$$

spc col player deviates to pure strategy $k \in [M]$:

has cost

$$(p^T A)_k \geq \min_{j \in [M]} (p^T A)_j = v_r = v^*$$

\Rightarrow Nash!