Satisfiability

Generate-and-test / NP / NP-complete SAT, weighted MAX-SAT, CNF-SAT, DNF-SAT, 3-CNF-SAT, Tseitin, TAUT, QSAT Some applications: LSAT ⊕, register allocation

From a previous lecture ...

- So, Prof. Eisner, what are declarative methods??
 - A declarative program states only what is to be achieved
 - A procedural program describes explicitly how to achieve it

Sorting in a declarative <u>language</u>

- □ "Given array X, find an array Y such that
 - (1) Y is a permutation of X
 - (2) Y's elements are in non-decreasing order"
- Compiler is free to invent any sorting algorithm! (Hard?!)
- You should be aware of when compiler will be efficient/inefficient

Sorting in a procedural <u>language</u>

- "Given array X, run through it from start to finish, swapping adjacent elements that are out of order ..."
- Longer and probably buggier
- Never mentions conditions (1) and (2), except in comments

Generate-and-test problems

(a common form of declarative programming)

- Problem specified by a fast "checking" function f(X,Y)
- Input: string x
- Output: Some string y such that f(x,y) = true x, y may encode any data you like

Examples:

- \Box f(x,y) is true iff y is sorted permutation of x
- f(x,y) is true iff y is timetable that satisfies everyone's preferences x (note that x and y are encodings as strings)
- NP = {all generate-and-test problems with "easy" f}
 - □ f(x,y) can be computed in polynomial time $O(|x|^k)$, for any y we should consider (e.g., legal timetables)
 - Could do this for all y in parallel (NP = "nondeterministic polynomial time")

Generate-and-compare problems (a common form of declarative programming)

- Problem is specified by a fast "scoring" function f(X,Y)
- Input: string x
- Output: Some string y such that f(x,y) is maximized
 x, y may encode any data you like

Examples:

- f(x,y) evaluates how well the timetable y satisfies everyone's preferences x (note that x and y are encodings as strings)
- OptP = {all generate-&-compare problems with easy f}
 - □ f(x,y) can be computed in polynomial time $O(|x|^k)$, for any y we should consider (e.g., legal timetables)

An LSAT Practice Problem

(can we encode this in logic?)

When the animated "Creature Buddies" go on tour, they are played by puppets.

Creatures: Dragon, Gorilla, Kangaroo, Tiger

Names: Audrey, Hamish, Melville, Rex

Chief Puppeteers: Ben, Jill, Paul, Sue

Asst. Puppeteers: Chris, Emily, Faye, Zeke

An LSAT Practice Problem

(can we encode this in logic?)

Creatures: Dragon, Gorilla, Kangaroo, Tiger

Names: Audrey, Hamish, Melville, Rex

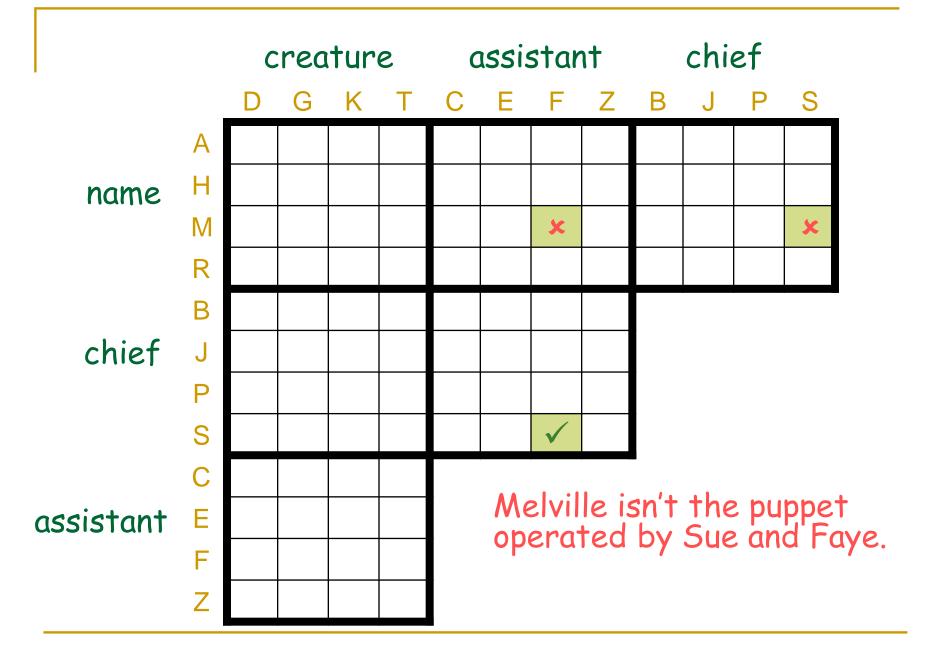
Chief Puppeteers: Ben, Jill, Paul, Sue

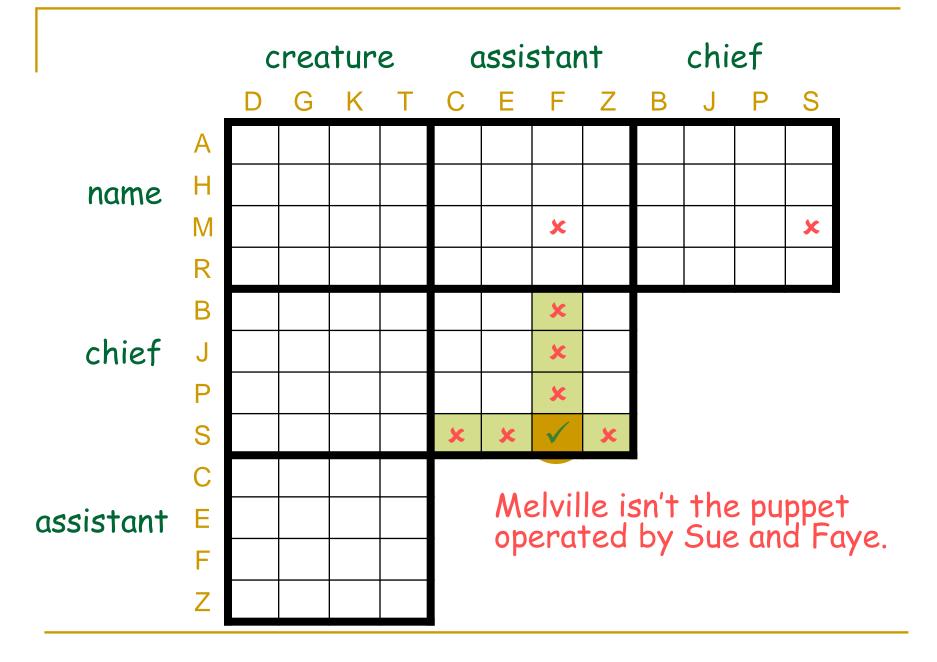
Asst. Puppeteers: Chris, Emily, Faye, Zeke

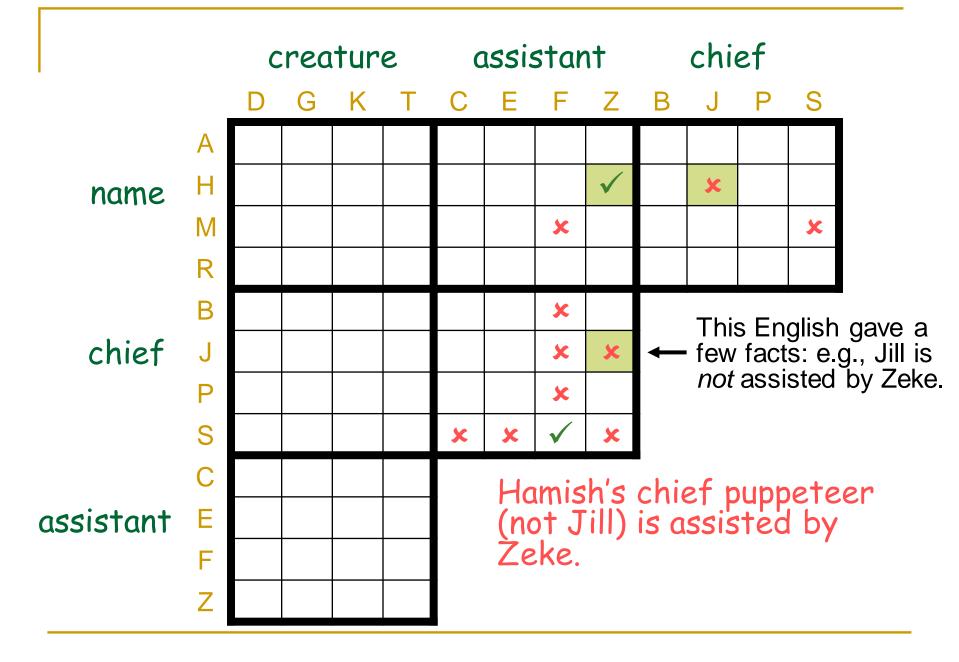
- Melville isn't the puppet operated by Sue and Faye.
- Hamish's chief puppeteer (not Jill) is assisted by Zeke.
- Ben does the dragon, but Jill doesn't do the kangaroo.
- Chris assists with the tiger.
- Rex (operated by Paul) isn't the gorilla (not named Melville).
- What is the Dragon's name?
- 2. Who assists with puppet Melville?
- 3. Which chief puppeteer does Zeke assist?
- 4. What kind of animal does Emily assist with?

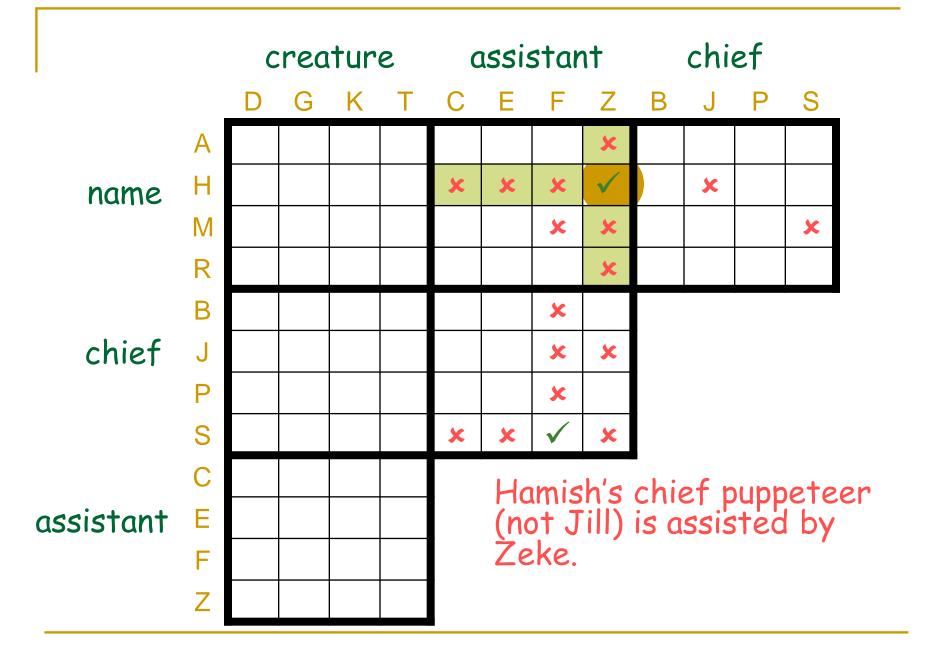
Is there a technique that is guaranteed to solve these?

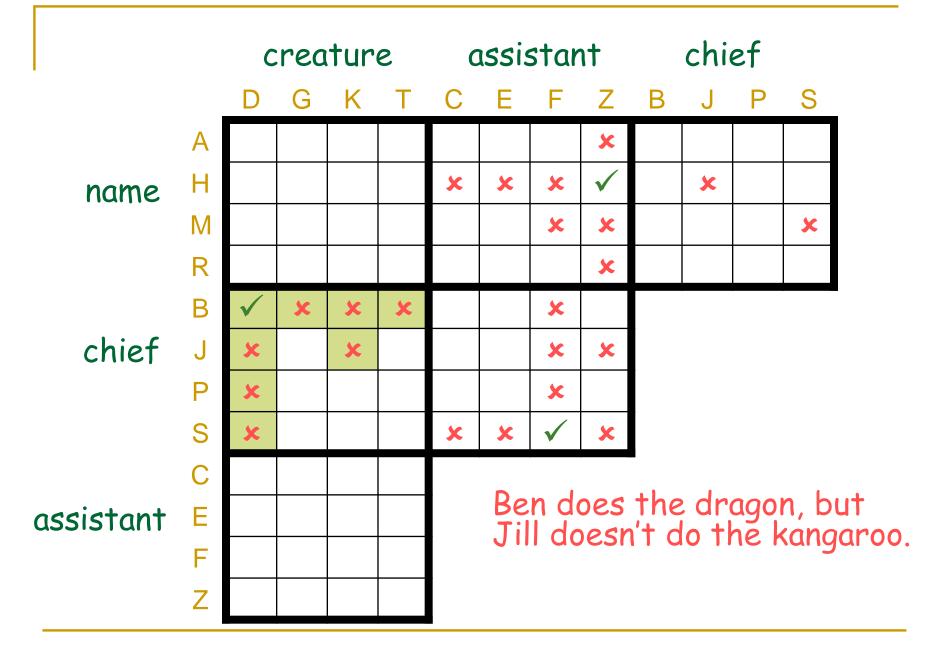
- Generate & test?
- Is the "grid method" faster? Always works?

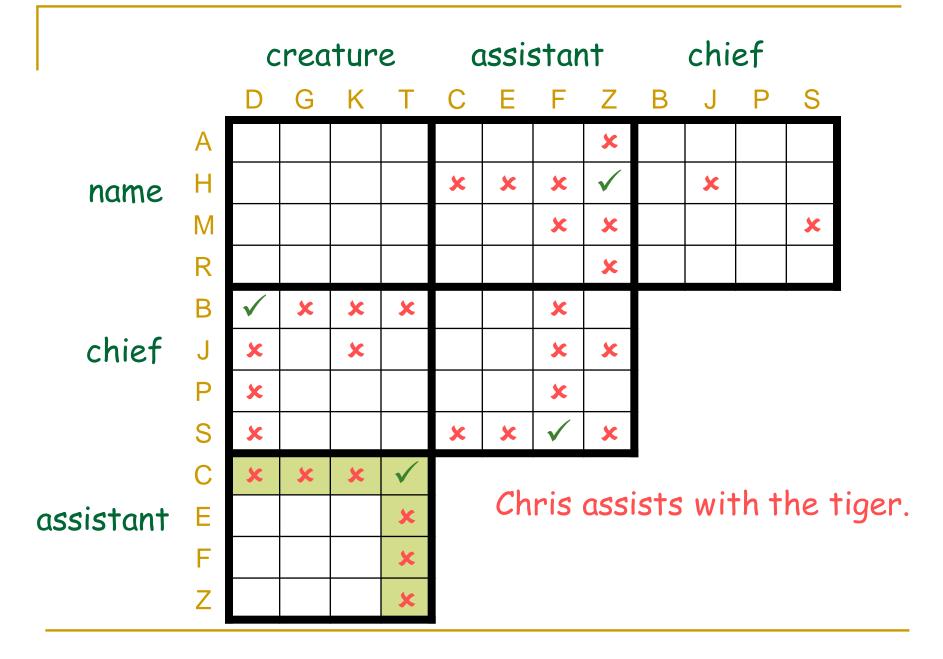


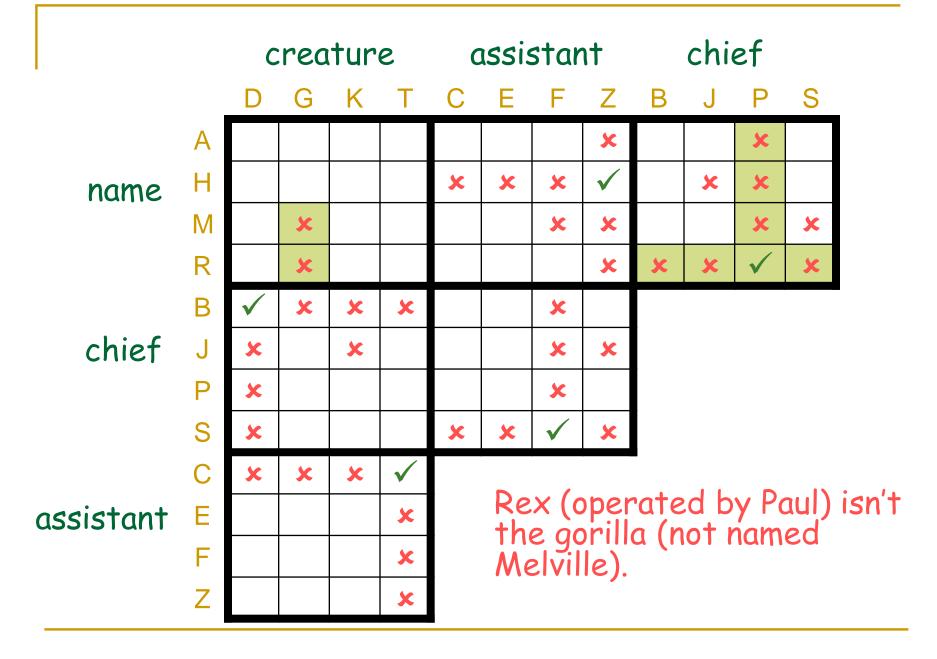


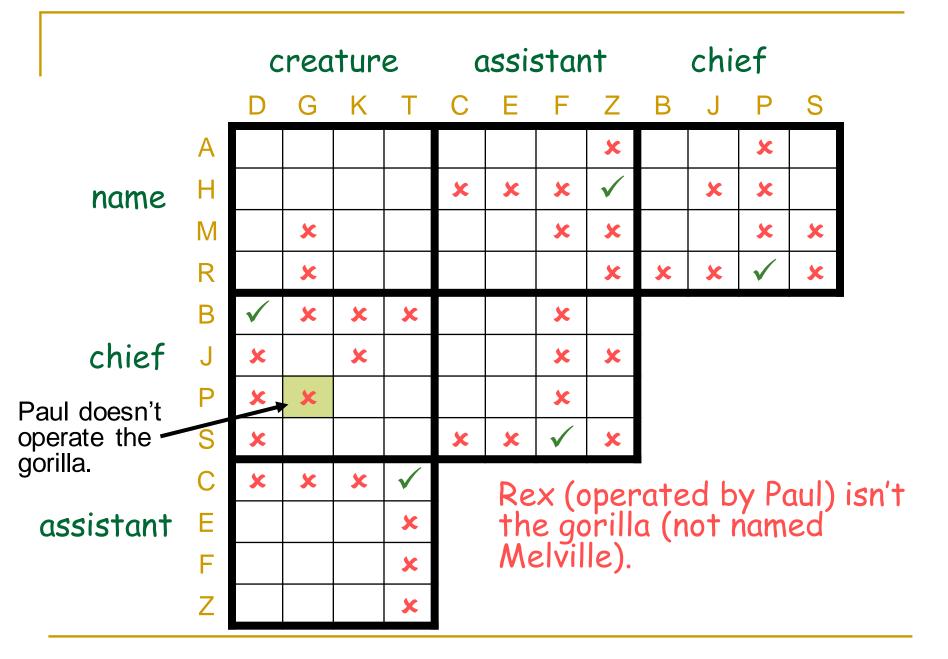












Grid method

(for puzzles that match people with roles, etc.)

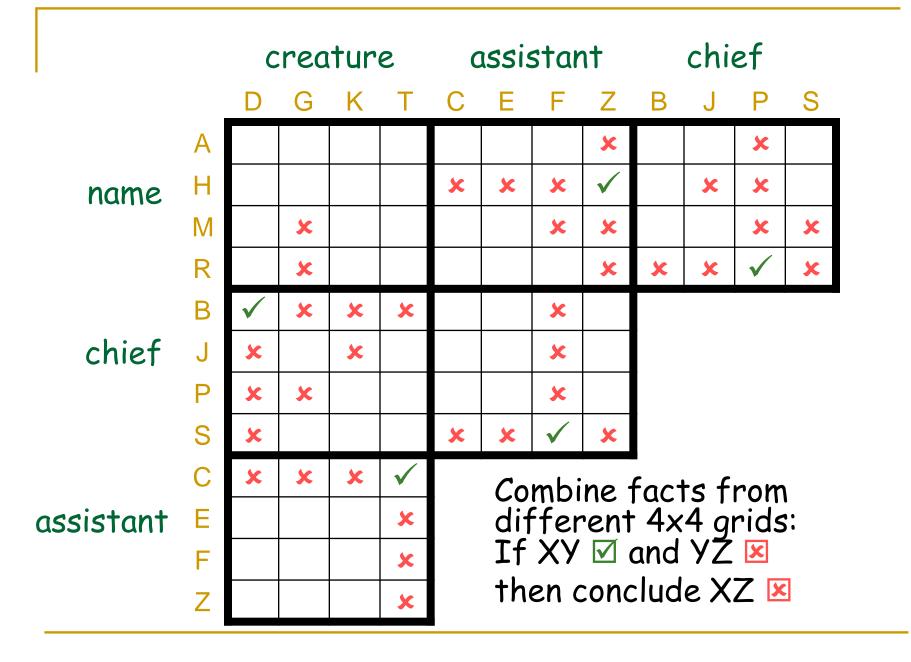
- Each statement simply tells you to fill a particular cell with ☑ or 区
- If you fill a cell with ☑, then fill the rest of its row and column with 区
- If a row or column has one blank and the rest are ⋈, then fill the blank with ⋈

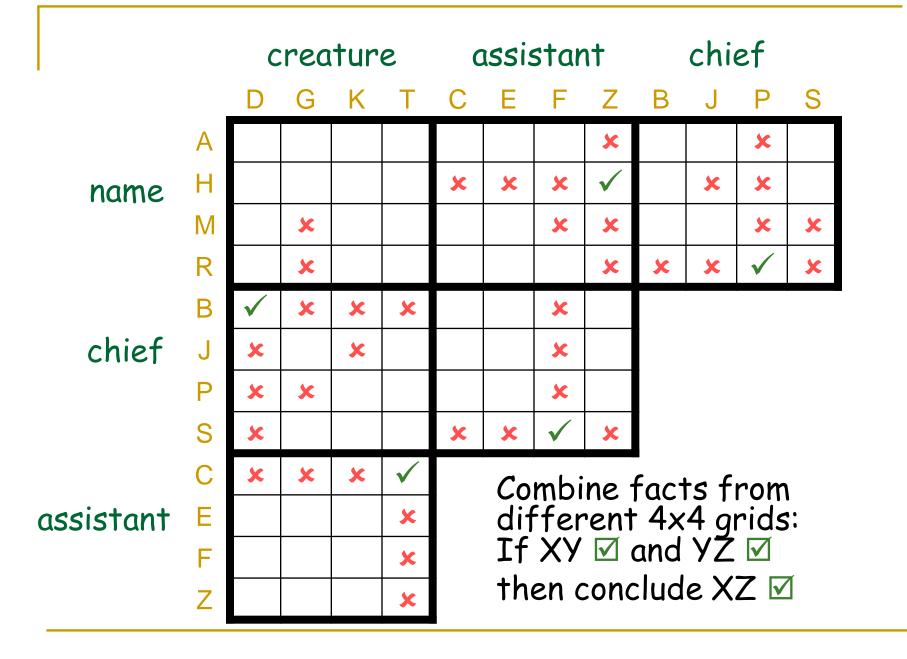
Is that enough?

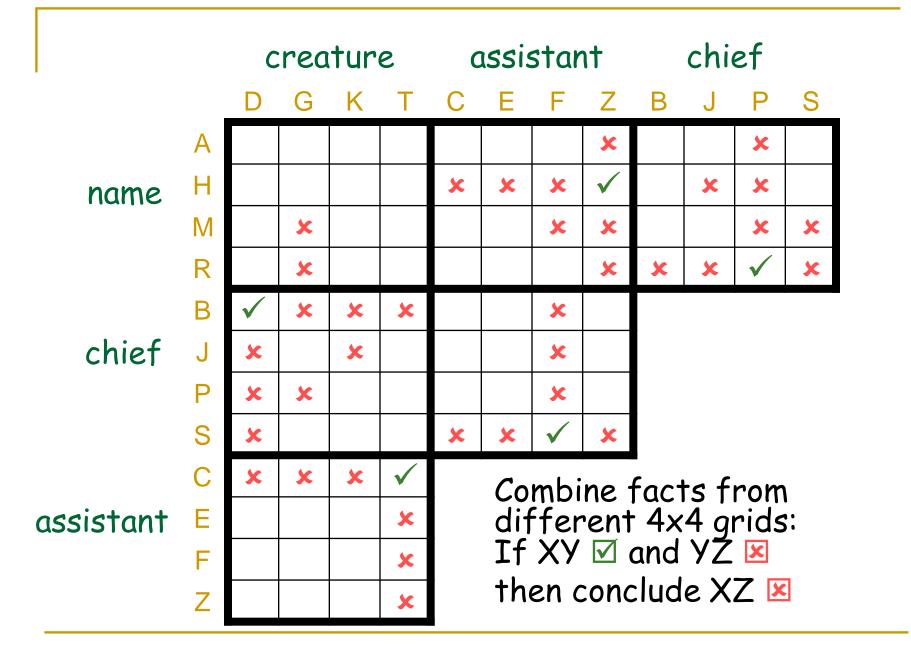
No! It didn't even solve the puzzle before.

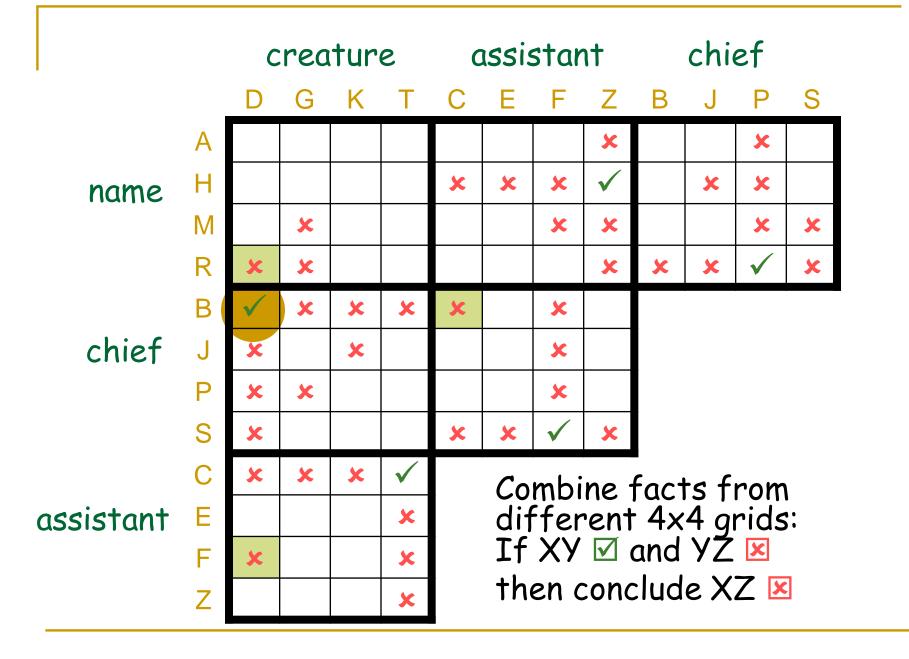
We need more powerful reasoning patterns ("propagators"):

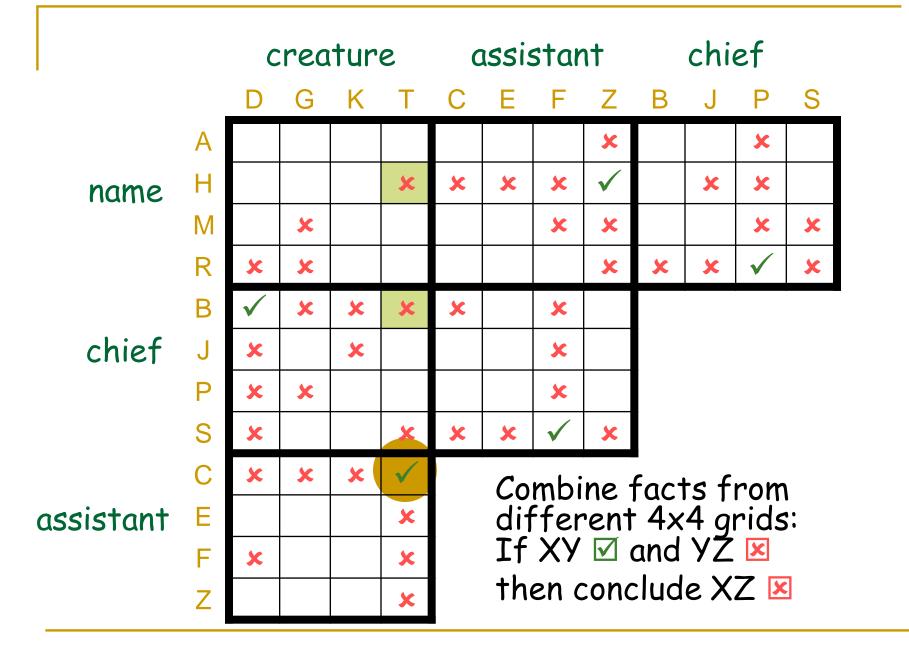
- We were told that Ben operates the dragon.
- We already deduced that Ben doesn't work with Faye.
- What should we conclude?

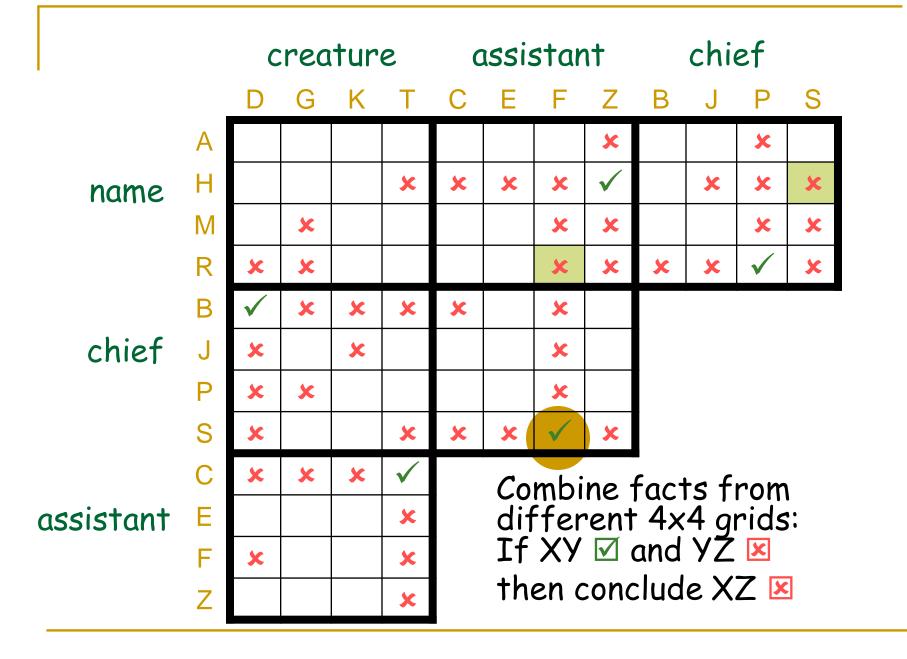


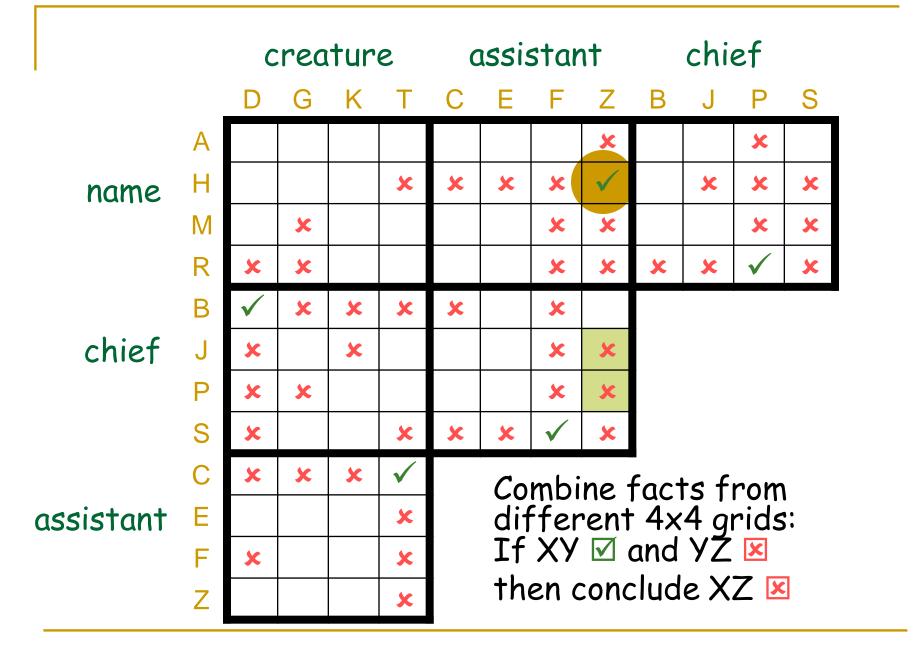


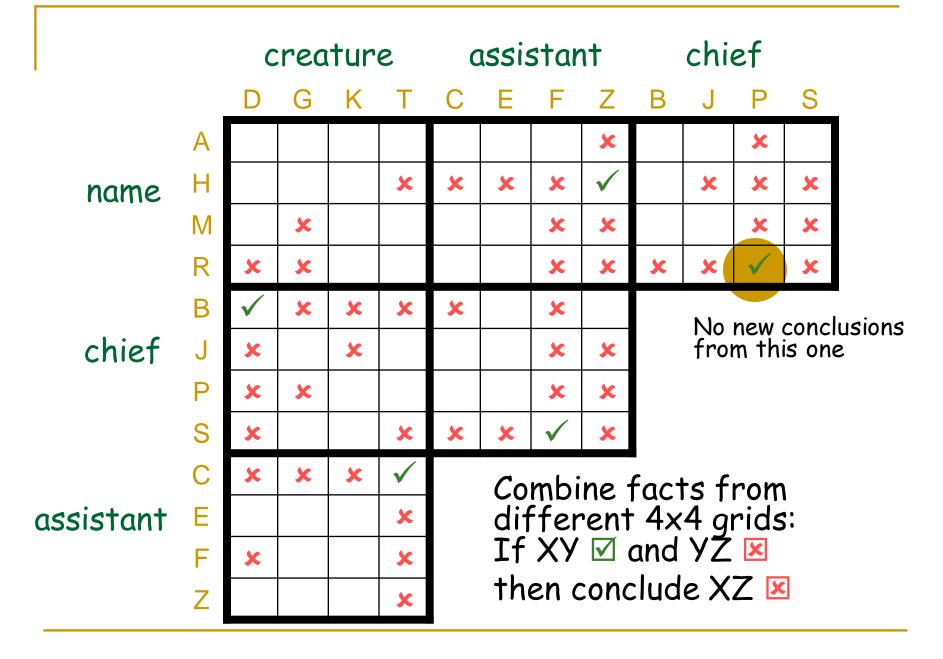


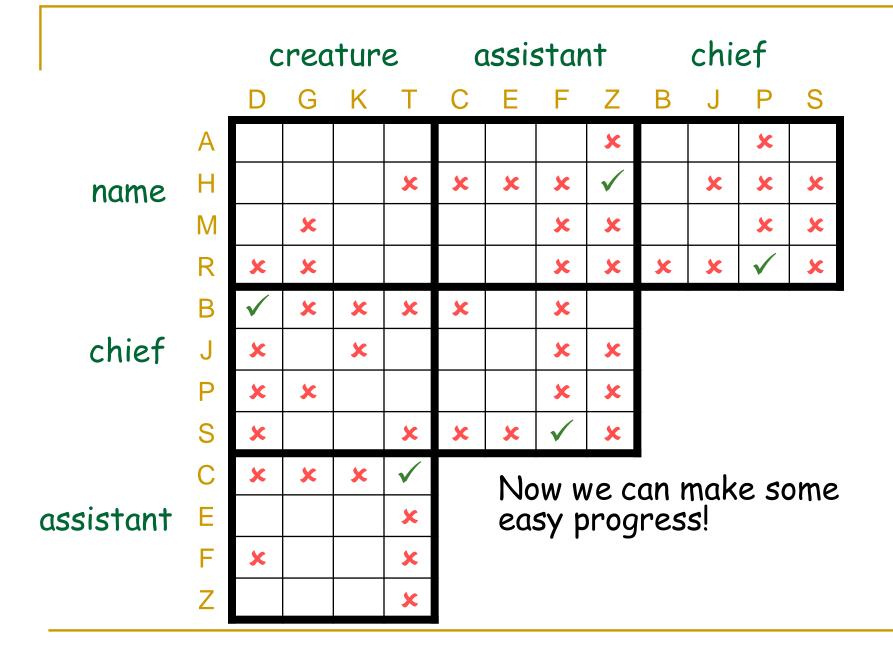


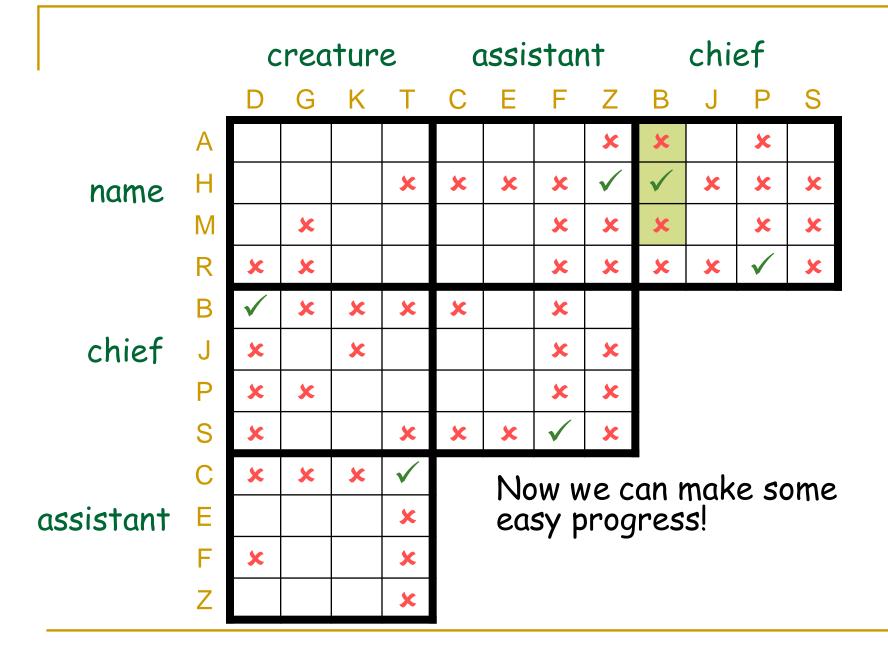


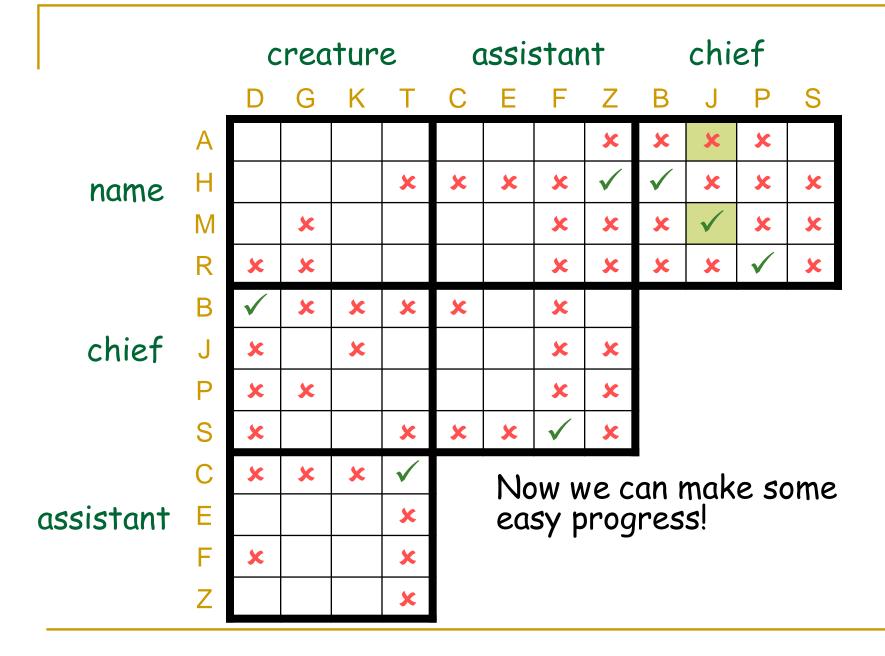


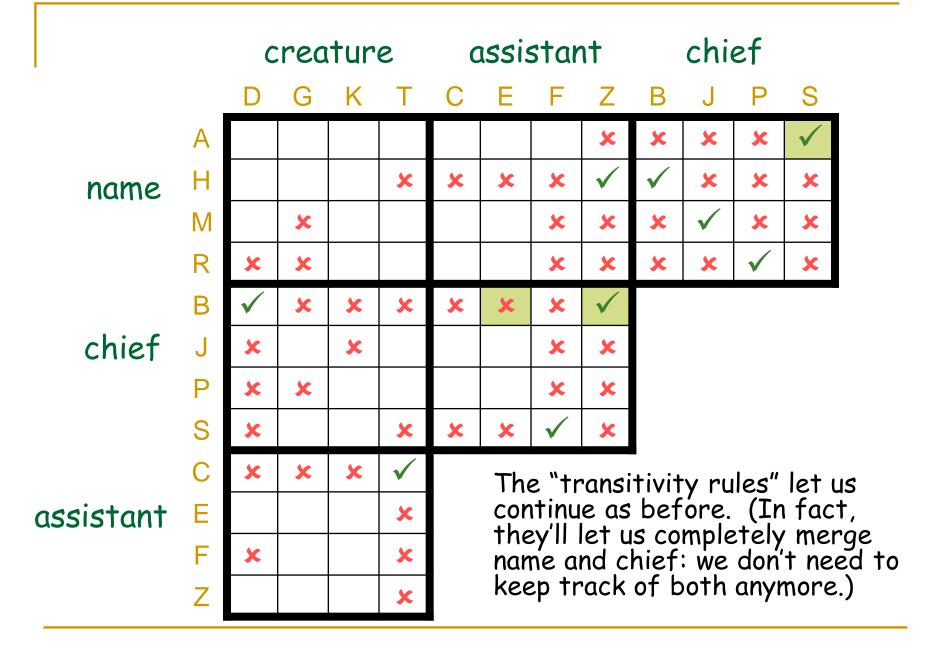












But does the grid method always apply?

(assuming the statements given are enough to solve the problem)

"Each statement simply tells you to fill a particular cell with ▶ or ☑" – always true?

People: Alice, Bob, Cindy

Roles: Hero, Villain, Jester

- Alice is not the Jester.
- The Villain and the Hero got legally married in Nigeria.

Let's try it on the board and see what happens ...

But does the grid method always apply?

(assuming the statements given are enough to solve the problem)

- Alice is not the Jester.
- The Villain and the Hero got legally married in Nigeria.

The problem is that the second statement didn't tell us exactly which cells to fill in. It gave us choices.

If these English statements aren't just telling us about cells to fill in, what <u>kinds</u> of things are they telling us?

Can we encode them formally using some little language?

Then the computer can solve them ...

- If A is a [boolean] variable, then A and ~A are "literal" formulas.
- If F is a formula, then so is ~F ("not F").

"not F"

F	~F			
0	1			
0	1			
1	0			
1	0			

- If A is a [boolean] variable, then A and ~A are "literal" formulas.
- If F is a formula, then so is ~F ("not F").
- If F and G are formulas, then so are F ^ G, F v G, etc.
- "Truth tables" like the multiplication table, but for booleans

"not F"

F	G	~F			
0	0	1			
0	1	1			
1	0	0			
1	1	0			

- If A is a [boolean] variable, then A and ~A are "literal" formulas.
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"not F" "F and G"

F	G	~F	F^G		
0	0	1	0		
0	1	1	0		
1	0	0	0		
1	1	0	1		

- If A is a [boolean] variable, then A and ~A are "literal" formulas.
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"not F" "F and G" "F or G"

F	G	F _~	F^G	FvG		
0	0	1	0	0		
0	1	1	0	1		
1	0	0	0	1		
1	1	0	1	1		

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"not F" "F and G" "F or G" "F xor G"

F	G	~F	F^G	FvG	F \oplus G	
0	0	1	0	0	0	
0	1	1	0	1	1	
1	0	0	0	1	1	
1	1	0	1	1	0	

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"not F" "F and G" "F or G" "F xor G" "F iff G"

F	G	~F	F^G	FvG	F⊕G	$F \leftrightarrow G$	
0	0	1	0	0	0	1	
0	1	1	0	1	1	0	
1	0	0	0	1	1	0	
1	1	0	1	1	0	1	

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- "Truth tables" like the multiplication table, but for booleans

"not F" "F and G" "F or G" "F \times or G" "F iff G" "F implies G"

F	G	FF-	F&G F^G	F V G	F≠G F⊕G	$F \leftrightarrow G$	if F then G $F \rightarrow G$
0	0	1	0	0	0	1	1
0	1	1	0	1	1	0	1
1	0	0	0	1	1	0	0
1	1	0	1	1	0	1	1

- If A is a [boolean] variable, then A and ~A are "literal" formulas.
- If F is a formula, then so is ~F ("not F").

Base case

If F and G are formulas, then so are F ^ G, F v G, etc.

Build bigger formulas out of littler ones

- So this is a formula: (~F → G) ^ ~(G v H)
- Given an assignment of values to the variables F, G, H,
 - We can compute the value of the whole formula, bottom-up
 - □ Just like evaluating arithmetic expressions: $(-F/G) \times -(F \times H)$

	^_0
$\rightarrow 0$	~ 1
$^{\prime}_{1}$ G	V ₀
F 0	Ġ H

F	G	Н	$(\sim F \rightarrow G) \land \sim (G \lor H)$
0	0	0	0

- If A is a [boolean] variable, then A and ~A are "literal" formulas.
- If F is a formula, then so is ~F ("not F").
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- So this is a formula: $(\sim F \rightarrow G) \land \sim (G \lor H)$
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	^ 0	
$\rightarrow 0$		· 0
~1 G	,	Ι V, 1
F 0	G	Н
0	Ō	1

F	G	Н	$(\sim F \rightarrow G) ^ \sim (G \vee H)$
0	0	0	0
0	0	1	0

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		^	
_ _ _ F	G	`\ G	' ' H
•		J	

F	G	Н	$(\sim F \rightarrow G) ^ \sim (G \vee H)$
0	0	0	0
0	0	1	0
0	1	0	0
0	1	1	0
1	0	0	1

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This particular formula is satisfied (has value 1) for only one assignment: F=1, G=0, H=0

So	it's	equ	ıival	lent	to
	F ^	~G	^ ~	-	

F	G	Н	$(\sim F \rightarrow G) ^ \sim (G \vee H)$
0	0	0	0
0	0	1	0
0	1	0	0
0	1	1	0
1	0	0	1

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F	G	Н	(~F → G) ^ ~(G v H)
1	0	0	1
o t	<mark>h e r w i s</mark>	е	0

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 - □ Just like evaluating arithmetic expressions: $(-F/G) \times -(F \times H)$

This particular formula is satisfied (has value 1) for only one assignment: F=1, G=0, H=0

So it's equivalent to F^~G^~H

F	G	Н	(~F → G) ^ ~(G v H)
0	*	*	0
1	0	0	1
1	0	1	0
1	1	*	0

Compressed version with "don't care" values

Satisfying assignments

- An "assignment" of values to boolean variables is a choice of 0 (false) or 1 (true) for each variable
 - Given an assignment, can compute whether formula is satisfied (true)
- Satisfiability problem:
 - Input: a formula
 - Output: a satisfying assignment to its variables, if one exists. Otherwise return "UNSAT".

Asking for a satisfying assignment

Let's try encoding the hero-villain problem on the board:

People: Alice, Bob, Cindy

Roles: Hero, Villain, Jester

- Alice is not the Jester.
- The Villain and the Hero got legally married in Nigeria.

		nort				FC	if Ethan C
F	G	~F	F&G F^G	F v G	F#6 F⊕G	$F \leftrightarrow G$	$F \rightarrow G$
0	0	1	0	0	0	1	1
0	1	1	0	1	1	0	1
1	0	0	0	1	1	0	0
1	1	0	1	1	0	1	1

"not F" "F and G" "F or G" "F yor G" "F iff G" "F implies G"

Satisfying assignments

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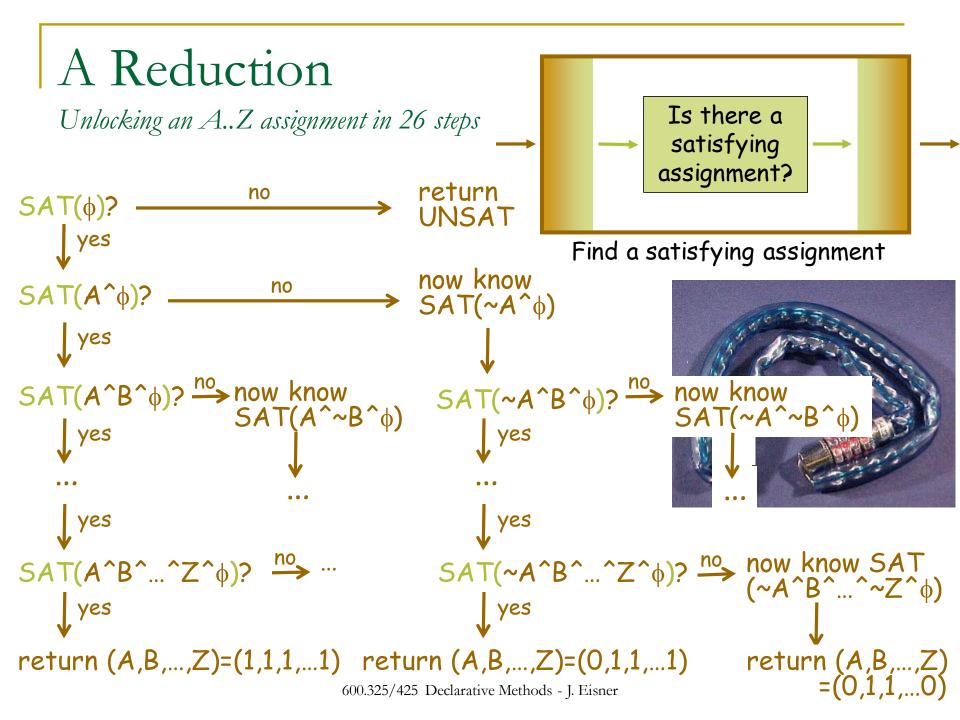
Satisfiability problem:

- Input: a formula
- Output: a satisfying assignment to its variables, if one exists. Otherwise return "UNSAT".



Traditional version:

- Input: a formula
- Output: "true" if there exists a satisfying assignment, else "false."
- Why isn't this useless in practice??



Another LSAT Practice Problem

- When the goalie has been chosen, the Smalltown Bluebirds hockey team has a starting lineup that is selected from two groups:
- 1st Group: John, Dexter, Bart, Erwin
- 2nd Group: Leanne, Roger, George, Marlene, Patricia
- Certain requirements are always observed (for the sake of balance, cooperation, and fairness).

Another LSAT Practice Problem

1st Group: John, Dexter, Bart, Erwin

2nd Group: Leanne, Roger, George, Marlene, Patricia

- Two players are always chosen from the 1st group.
 Three players are always chosen from the 2nd group.
- George will only start if Bart also starts.
 "3 of 5" here. Could
- Dexter and Bart will not start together. you efficiently encode
- If George starts, Marlene won't start.
 "13 of 26"?
- The 4 fastest players are: John, Bart, George and Patricia.
 3 of the 4 fastest players will always be chosen.
- 1. Who always starts?

- These questions are different: ∀ not ∃
- If Marlene starts, what subset of first-group players starts with her?
- If George starts, who must also start? (M or J, D or L, D or J, J or P, M or R)
- Which of these pairs cannot start together? (ED, GJ, RJ, JB, PM)

Encoding "at least 13 of 26"

(without listing all 38,754,732 subsets!)

A	В	C		L	M		Υ	Z
A≥1	A-B≥1	A-C≥1		A-L≥1	A-M≥1		A-Y≥1	A-Z≥1
	A-B≥2	A-C≥2		A-L≥2	A-M≥2		A-Y≥2	A-Z≥2
		A-C≥3		A-L≥3	A-M≥3		A-Y≥3	A-Z≥3
26 original variables $A \dots Z$, plus < 26^2 new variables such as $A-L\geq 3$			•••					
			A-L≥12	A-M≥12		A-Y≥12	A-Z≥12	
				A-M≥13	*	- A-Y≥13 <	–A-Z≥13	

- SAT formula should require that A-Z≥13 is true ... and what else?
- yadayada ^ A-Z≥13 ^ (A-Z≥13 → (A-Y≥13 v (A-Y≥12 ^ Z)))
 ^ (A-Y≥13 → (A-X≥13 v (A-X≥12 ^ Y))) ^ ...

Encoding "at least 13 of 26"

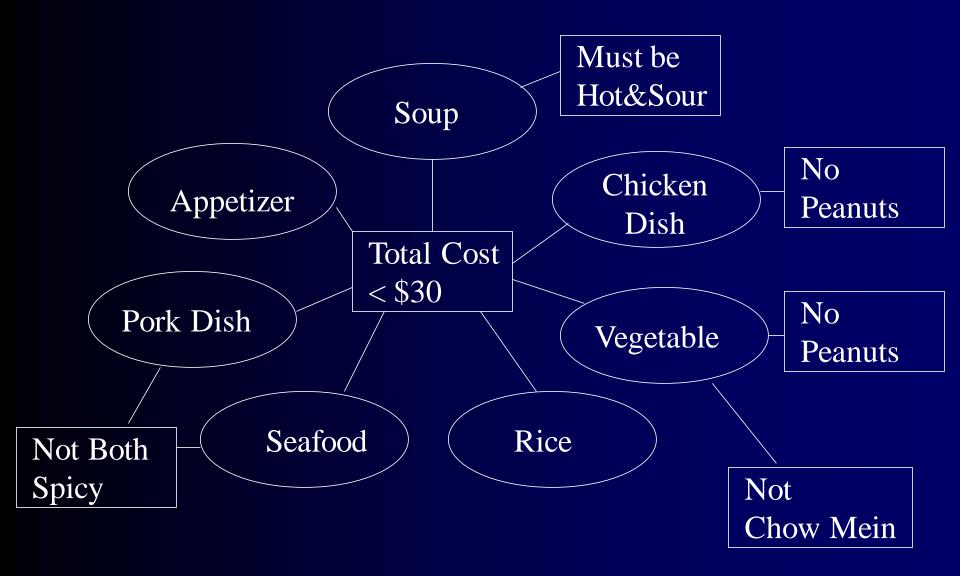
(without listing all 38,754,732 subsets!)

A	В	С		L	M		Y	Z
A≥1 ←	A-B≥1	A-C≥1	<	A-L≥1	A-M≥1	<	A-Y≥1	A-Z≥1
	A-B≥2	A-C≥2	←	A-L≥2	A-M≥2	«	A-Y≥2	A-Z≥2
		A-C≥3	←	- A-L≥3 <	A-M≥3	←	- A-Y≥3 <	A-Z≥3
26 orig	jinal var	iables A	Z,					•••
plus < 2	26 ² new	variable		A-L≥12	A-M≥12	*	A-Y≥12	-A-Z≥12
such as	s A-L≥3				A-M≥13	*	- A-Y≥13	-A-Z≥13

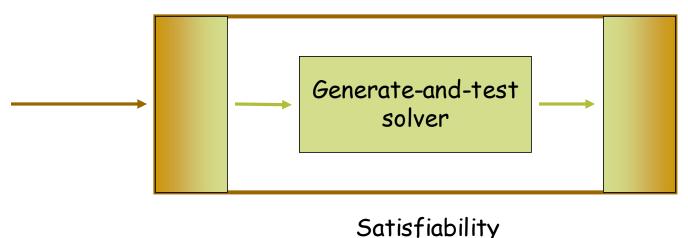
SAT formula should require that A-Z≥13 is true ... and what else?

one "only if" definitional constraint for each new variable

Chinese Dinner After the LSAT



Relation to generate-and-test



How does this reduction work?

A generalpurpose
"generate-andtest solver" is
really called a
Nondeterministic
Turing Machine.

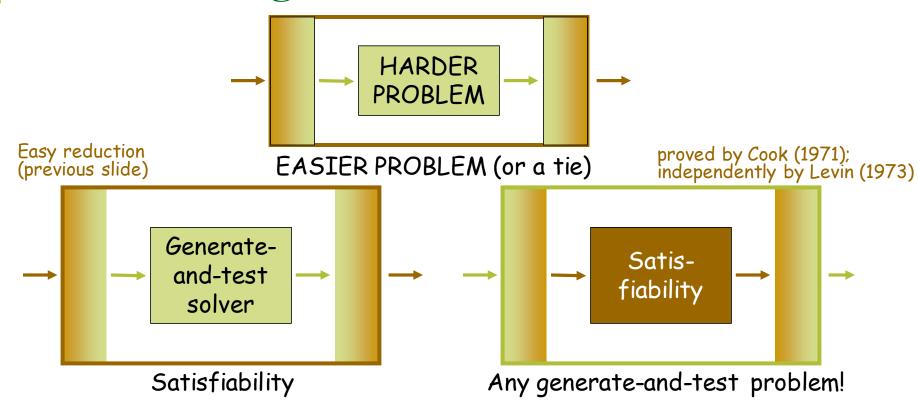
Inner solver is general-purpose and can be given any checking function f as part of its input.

Recall the inner solver's input and output;

Input: string x; checking function f(x,y)

Output: Some string y such that f(x,y) = true

Relation to generate-and-test

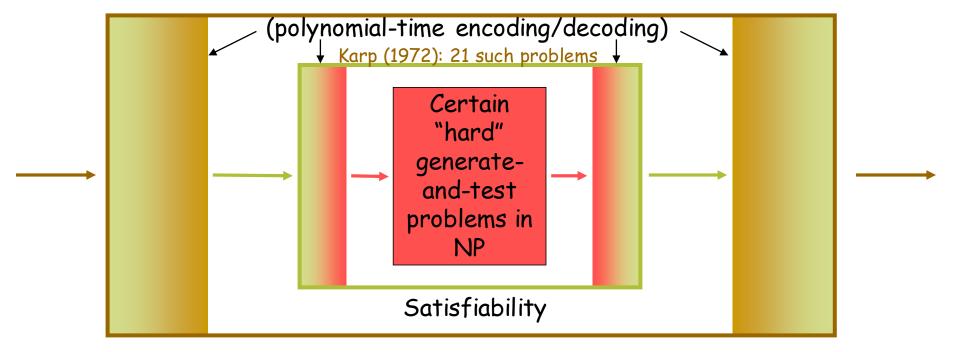


Interreducible problems! (under polynomial encoding/decoding)

So if we could find a fast solver for SAT, we'd solve half the world's problems (but create new problems, e.g., cryptography wouldn't work anymore) (neither would some theoretical computer scientists)

So probably impossible. But a "pretty good" SAT solver would help the world.

NP-completeness



Any generate-and-test problem in NP

These innermost problems are called NP-complete
They are all interreducible with SAT
A "pretty good" solver for **any** of them would help the world equally

<u>Many</u> practically important examples: see course homepage for pointers

You may well discover some yourself – most things you want are NP-complete

Local register allocation

(an NP-complete planning problem from systems)

- Computer has N fast registers, and unlimited slow memory
- Given a straight sequence of computations using M > N vars:

```
\Box ... x = y * z; w = x + y; ...
                                      Do we need these? Not if y, z i
Generate assembly-language code:
                                      are already in registers
\Box ##### x = y*z #####
-LOAD R2, - (address -of -y)-
```

- □ -LOAD R3, (address -of -z)-
- □ MUL (R1) R2 R3
- □ -STORE--(address-of-x)-,-R1-

w = x+y

- -! until we need it again
- \square LOAD R1, (address of x) x is already in a register (R1)
- LOAD R2, (address of y) y is already in a register (R2)
- ADD (R3) R1 R2 Clever to pick R3? Is z the best thing to overwrite?

Do we need this? Not if we

 $\frac{1}{2}$ can arrange to keep x in R1

- □ -STORE -(address-of-w), -R3
- Can we eliminate or minimize loads/stores? Reorder code?

Register allocation as a SAT problem

- Tempting to state everything a reasonable person would know:
 - Don't have the same variable in two registers
 - Don't store something unless you'll need it again ("liveness")
 - Don't store something that's already in memory
 - Only ever store the result of the computation you just did
 - **...**
- Yes, looks like an optimal solution will observe these constraints
- But you don't have to state them!
- They are part of the solution, not part of the problem
 - (violating them is allowed, merely dumb)
- Stating these extra constraints might speed up the SAT solver
 - Helps the solver prune away stupid possibilities
 - But that's just an optimization you can add later
 - Might slow things down if the overhead exceeds the benefit
 - A great SAT solver might discover these constraints for itself

Assumptions about the input code

- Assume all statements look like x = y*z
 - Preprocess input to eliminate more complex statements:

$$a = b*c + d*e \longrightarrow \begin{cases} temp1 = b*c \\ temp2 = d*e \\ a = temp1 + temp2 \end{cases}$$

- Now all intermediate quantities are associated with variables
- So if needed, we can store them to memory and reload them later
- Assume variables are constant once computed
 - ullet Preprocess: If z takes on two different values, split it into z_1 and z_2

$$x = y*z$$

$$z = x+1 \longrightarrow \begin{cases} x = y*z_1 \\ z_2 = x+1 \\ a_2 = a_1+z_2 \end{cases}$$

 \square When z_2 is in a register or memory, we know which version we have "static single assignment (SSA) form"

How to set up SAT variables?

· Get dressed

(one possibility)

Typical when encoding · Solve Rubik's cube

a planning problem

- Time 0 config - load-compute-store

Other planning problems:

K time steps, M program vars, N registers

- Time 1 config load-compute-store

SAT variable 2y3 is true iff at time 2, y is in R3

⇒ Time 2 config –

SAT variable 2y is true iff at time 2, y is in memory

. . .

An assignment to all variables defines a "configuration" of the machine at <u>each</u> time t

- Time K-1 config load-compute-store
- Time K config -

- How many variables total?
- How will we decode the SAT solution? (which only tells us what the configs are)
 - □ For each time t, decoder will generate a load-compute-store sequence of machine code to get to t's configuration from t-1's preferred
 - 1. To put some new values in registers, generate loads

(faster than loads)

- 2. To put other new values in registers, generate computes than loads (might use newly loaded registers; order multiple computes topologically)
- 3. To put new values in memory, generate stores (might use newly computed registers)

How to set up SAT variables?

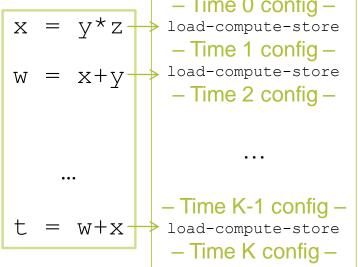
(one possibility)

K time steps

- How do we pick K?
- Large enough to compile input
- Not too large, or solver is slow
- Solution: Let K = # of input instructions;
 we know that's large enough ...
- How will we decode the SAT solution?
 - □ For each time t, will generate a load-compute-store sequence of machine code to get to t's configuration from t-1's
 - 1. To put some new values in registers, generate loads
 - 2. To put other new values in registers, generate computes (might use newly loaded registers; order multiple computes topologically)
 - 3. To put new values in memory, generate stores (might use newly computed registers)

Allows dumb solution from a few slides ago (not most efficient, but proves the formula with K steps is SAT)

— Time 0 config —



Example: How do we get from t-1 to t?

	R1	R2	R3	Mem
Time t-1	У			y,z
Time t	X		Z	x,y,z

- □ LOAD R3, (address of z)
- MUL R1 R1 R3 // compute x into R1, overwriting y
- □ STORE (address of x), R1
- For each time t, generate a load-compute-store sequence to get to t's configuration from t-1's
- 1. To put some new values in registers, generate loads
- 2. To put other new values in registers, generate computes (might use newly loaded registers; order multiple computes topologically)
- 3. To put new values in memory, generate stores (might use newly computed registers)

```
- Time 0 -
x = y*z
- Time 1 -
w = x+y
- Time 2 -
...

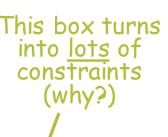
- Time K-1 -
t = w+x
- Time K -
```

What is the SAT formula? This setup may even reorder

or eliminate computations!

- Many constraint clauses combined with "and":
 - At time K, desired output vars are in mem/registers
 - At time 0, input vars are in mem/certain registers
 - ... but otherwise, no vars are held anywhere!
 - E.g., ~0y ^ 0y1 ^ ~0y2 ^ ...^ ~0x ^ ~0x1 ^ ~0x2 ...
 - No two vars can be in same register at same time
 - If w is in a register at time t but not t-1, where w=x*y, then
 - either w was in memory at time t-1 (load)
 - or (better) x, y were also in registers at time t (compute)
 - If w is in memory at time t but not t-1, then
 - w was also in a register at time t (store)
- What's missing?

If these hold, we can find an adequate load-compute-store sequence for $t-1 \rightarrow t$



Where did we say to minimize loads/stores???

- Additional constraints:
 - No loads -
 - No stores
- But what if SAT then fails?
 - Retry with a weaker constraint: "at most 1 load/store" ...
 - Continue by linear search or binary chop

```
If w is in a register at time t but not t-1, then

either w was in memory at time t-1

or (better) x, y were also in registers at time t

If w is in memory at time t but not t-1, then
```

w was also in a register at time t

Strengthen our constraints $A \rightarrow (B \lor C)$ to $A \rightarrow C$

and $D \rightarrow E$ to $\sim D$

Alternatively, use MAX-SAT

- Specify our input formula as a conjunction of several subformulas (known as "clauses" or "constraints")
- A MAX-SAT solver seeks an assignment that satisfies as many clauses as possible
- Such conjunctive formulas are very common:
 - each clause encodes a fact about the input, or a constraint
- Can specify a weight for each clause (not all equally important)
- Weighted MAX-SAT: seek an assignment that satisfies a subset of clauses with the maximum total weight possible
 - How does this relate to unweighted MAX-SAT?
 - Can you implement either version by wrapping the other?
- How do we encode our register problem?
 - □ Specifically, how do we implement "hard" vs. "soft" constraints?

Minimizing loads/stores with weighted MAX-SAT

We require certain clauses to be satisfied (e.g., so that we'll be able to decode the satisfying assignment into a load-compute-store sequence).

We give these **hard constraints** a weight of ∞. The MAX-SAT solver must respect them.

It's okay to violate "don't load" and "don't store," but each violation costs 150 cycles of runtime.

We give each of these **soft constraints** a weight of 150. The MAX-SAT solver will try to satisfy as many as it can.

Include both kinds ...

weight ∞ : $A \rightarrow (B \lor C)$ weight 150: $A \rightarrow C$ weight ∞ : $D \rightarrow E$ weight 150: $\sim D$

If w is in a register at time t but not t-1, then

either w was in memory at time t-1

or (better) x, y were also in registers at time t

If w is in memory at time t but not t-1, then

w was also in a register at time t

Strengthen our constraints $A \rightarrow (B \lor C)$ to $A \rightarrow C$ and $D \rightarrow E$ to $\sim D$

Eliminating infinite-weight clauses ...

- Can specify a weight for each clause (not all equally important)
- Weighted MAX-SAT: seek an assignment that satisfies a subset of clauses with the maximum total weight possible
- What if the solver doesn't allow ∞ as a clause weight?

Hard constraints

```
weight \infty: A \rightarrow (B \lor C) weight \infty: D \rightarrow E ...
```

Soft constraints

```
weight 20: A \rightarrow C
weight 14: ~D
```

TOTAL WEIGHT 999

- Just give weight 999+1 = 1000 to each hard constraint in this case
- This acts like weight ∞, since solver would rather violate <u>all</u> soft constraints than violate even one hard constraint!
- So solver will only violate hard constraints if it can't avoid doing so
 - Check the solution. If any hard constraints are violated, then the set of hard constraints must be UNSAT.

Simpler formulas, simpler solvers

- If A is a [boolean] variable, then A and ~A are "literal" formulas.
- If F and G are formulas, then so are

```
    F ^ G ("F and G")
    F ∨ G ("F or G")
    F → G ("If F then G"; "F implies G")
    F ↔ G ("F if and only if G"; "F is equivalent to G")
    F ⊕ G ("F or G but not both"; "F differs from G")
    ~F ("not F")
```

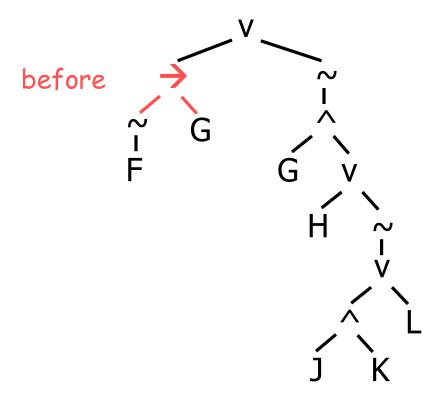
- Is all of this fancy notation really necessary?
 - Or is some of it just syntactic sugar?
 - Can we write a front-end preprocessor that reduces the user's formula to a simpler notation? That would simplify solver's job.

Simpler formulas, simpler solvers

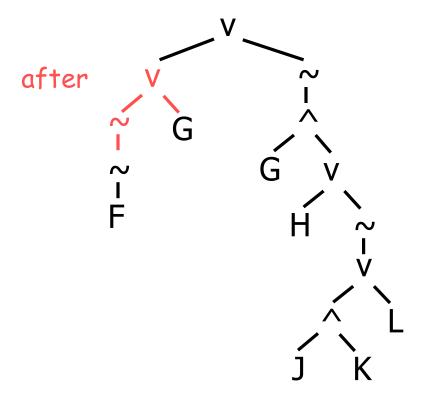
- If A is a [boolean] variable, then A and ~A are "literal" formulas.
- If F and G are formulas, then so are
 - F^G
 - F v G
 - $\Box F \rightarrow G \longrightarrow (\sim F \vee G)$
 - □ $F \leftrightarrow G^{--} \Rightarrow (F \rightarrow G) \land (G \rightarrow F)$ Alternatively: $(F \land G) \lor (\sim F \land \sim G)$

 - □ ~F

Step 1: Eliminate \leftrightarrow , xor, then \rightarrow



Step 1: Eliminate \leftrightarrow , xor, then \rightarrow

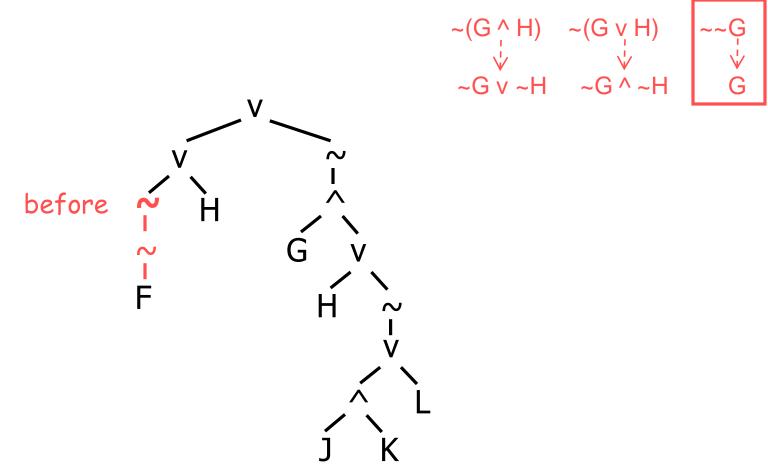


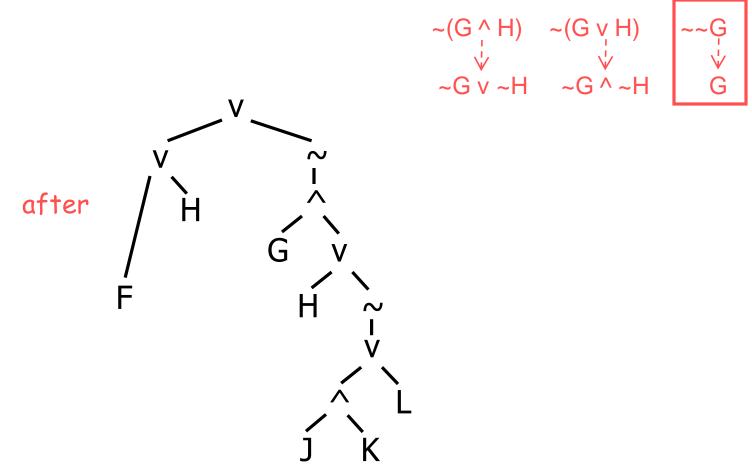
Simpler formulas, simpler solvers

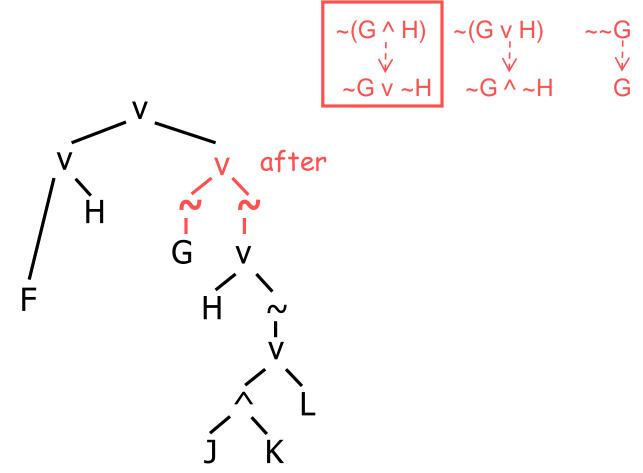
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 - □ $F \leftrightarrow G^{--} \Rightarrow (F \rightarrow G) \land (G \rightarrow F)$ Alternatively: $(F \land G) \lor (\sim F \land \sim G)$

 - If not already a literal, must have form \sim (G $^{\wedge}$ H) or \sim (G $^{\vee}$ H) or \sim \sim G $^{\vee}$ $^{\vee}$

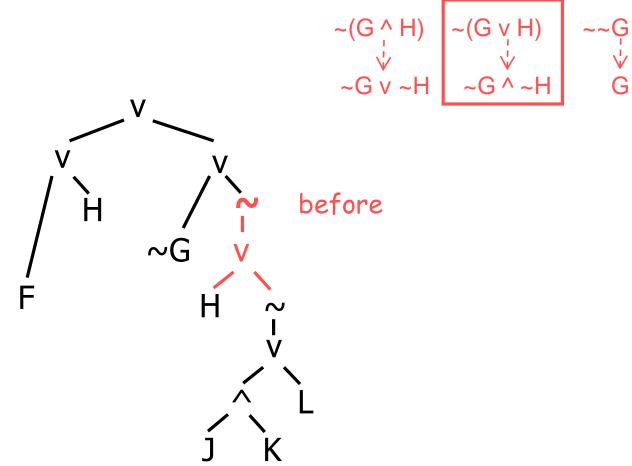
Step 2: Push ~ down to leaves

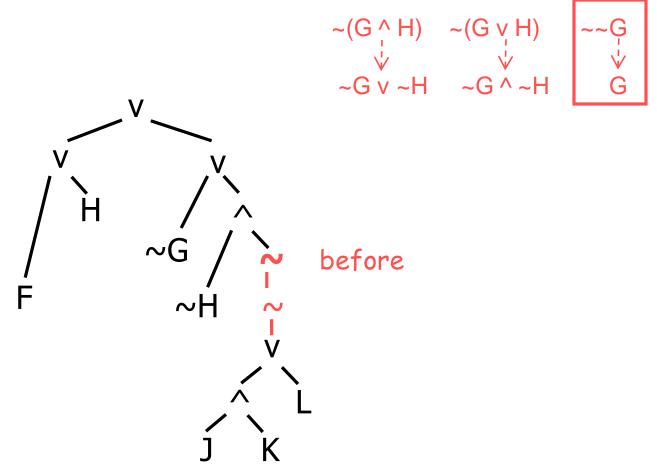


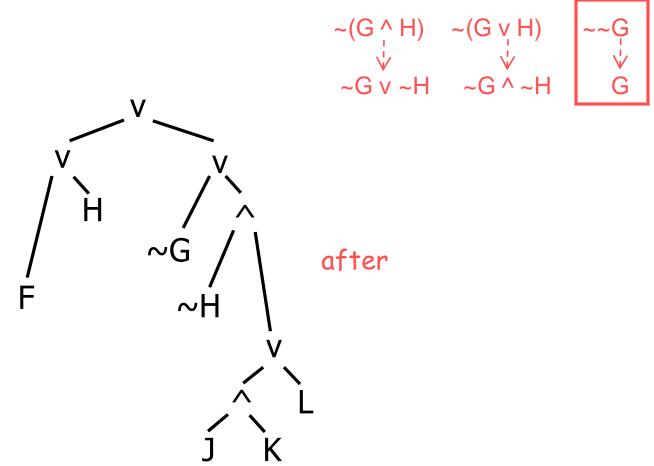




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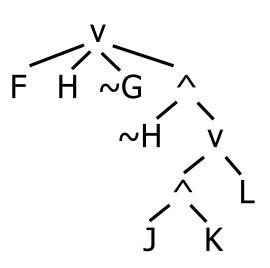






same tree redrawn

(For simplicity, we're now drawing root as v with 4 children. Used to be (F v H) v (G v ...), but F v H v G v ... is okay since v is associative.)

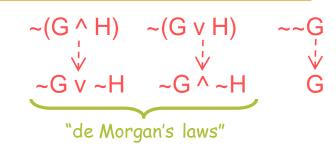


Now everything is ^ and v over literals. Yay!

Duality ...

So <u>essentially the same</u>: just swap the meanings of "true" and "false" (in both input and output)

Reduce green to brown: encode by negating inputs, decode by negating outputs



"Primal"	"Dual"	Reduction	Reverse reduction
V	^	$F \wedge G = \sim (\sim F \vee \sim G)$	$F \vee G = \sim (\sim F \wedge \sim G)$
3	\forall	$\forall x \phi(x) = \sim \exists x \sim \phi(x)$	$\exists x \phi(x) = \sim \forall x \sim \phi(x)$
SAT	TAUT	$TAUT(\phi) = \sim SAT(\sim \phi)$	$SAT(\phi) = \simTAUT(\sim\phi)$
NP	co-NP	$\forall y \ f(x,y) = \neg \exists y \sim f(x,y)$	$\exists y \ f(x,y) = \sim \forall y \sim f(x,y)$

F	G	FvG
0	0	0
0	1	1
1	0	1
1	1	1

Truth table for OR

Negate and or	inputs

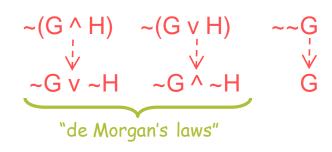
F	G	F^G
1	1	1
1	0	0
0	1	0
0	0	0

Truth table for AND 86 (listed upside-down from usual order)

Duality ...

So <u>essentially the same</u>: just swap the meanings of "true" and "false" (in both input and output)

Reduce green to brown: encode by negating inputs, decode by negating outputs



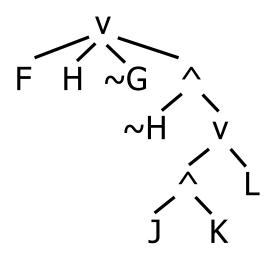
"Primal"	"Dual"	Reduction	Reverse reduction
V	^	$F \wedge G = \sim (\sim F \vee \sim G)$	$F \vee G = \sim (\sim F \wedge \sim G)$
3	\forall	$\forall x \phi(x) = \neg \exists x \neg \phi(x)$	$\exists x \phi(x) = \neg \forall x \neg \phi(x)$
SAT	TAUT	$TAUT(\phi) = \sim SAT(\sim \phi)$	$SAT(\phi) = \sim TAUT(\sim \phi)$
NP	co-NP	$\forall y \ f(x,y) = \sim \exists y \sim f(x,y)$	$\exists y \ f(x,y) = \sim \forall y \sim f(x,y)$

At least one (not empty): like v

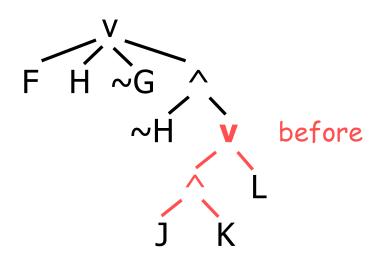
- ∃x = "there exists x such that"
- SAT = is the formula satisfiable? (there exists a satisfying assignment)
- NP = generalization of SAT (problems that return **true** iff ∃y f(x,y), where f can be computed in polynomial time O(|x|^k))

All (complement is not empty): like ^

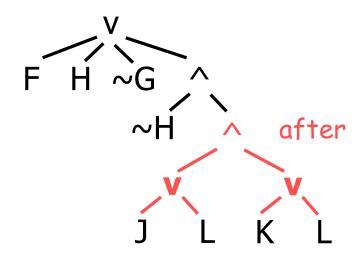
- $\forall x = \text{``all } x \text{ are such that''}$
- TAUT = is the formula a tautology? (all assignments are satisfying)
- co-NP = generalization of TAUT (problems that return **true** iff ∀y f(x,y), where f can be computed in polynomial time O(|x|^k))



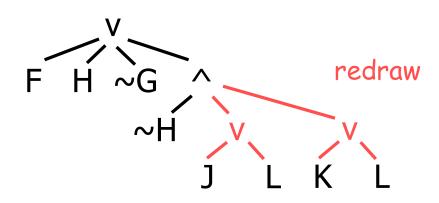
- Now everything is ^ and v over literals. Yay!
- Can we make it even simpler??
 - Yes. We can also push v down, to just above the leaves.
 - Then the whole tree will be ^ at the root, over v, over ~ at the leaves.
 - That's called "conjunctive normal form" (CNF).



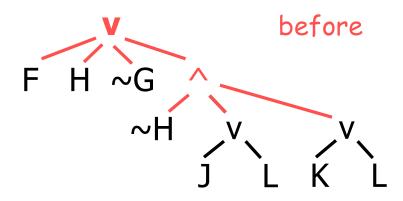
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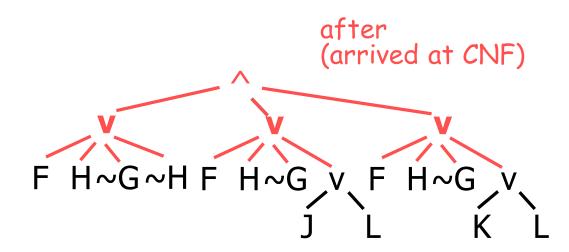
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 - That's called "conjunctive normal form" (CNF).

Simpler formulas, simpler solvers

- Conjunctive normal form (CNF):
 - Conjunction of disjunctions of literals
 - (A v B v ~C) ^ (~B v D v E) ^ (~A v ~D) ^ ~F ...
 - Can turn any formula into CNF
 - □ So all we need is a CNF solver (still NP-complete: no free lunch)
- Disjunctive normal form (DNF):
 - Disjunction of conjunctions of literals
 - □ (A ^ B ^ ~C) v (~B ^ D ^ E) v (~A ^ ~D) v ~F ...
 - Can turn any formula into DNF
 - □ So all we need is a DNF solver (still NP-complete: no free lunch)

Wait a minute! Something wrong. Can you see a fast algorithm?

What goes wrong with DNF

- Satisfiability on a DNF formula takes only linear time:
 - (A ^ B ^ ~C) v (~B ^ D ^ E) v (~A ^ ~D) v ~F ...
- Proof that we can convert any formula to DNF
 - □ First convert to v/^ form, then do it recursively:
 - Base case: Literals don't need to be converted

 Because ^ distributes
 - □ To convert A v B, first convert A and B individually distributes over +:

 $(a_1+a_2+...+a_n)*(b_1+b_2+...+b_m)$

 $= a_1b_1+a_1b_2+...+a_nb_m$

- $(A_1 \lor A_2 \lor ...A_n) \lor (B_1 \lor B_2 \lor ...B_m)$
- $= A_1 \vee A_2 \vee ... \vee A_n \vee B_1 \vee B_2 \vee ... \vee B_m$
- □ **To convert A ^ B,** first convert A and B individually
 - $(A_1 \lor A_2 \lor ... \lor A_n) \land (B_1 \lor B_2 \lor ... \lor B_m)$
 - $= (A_1 ^B_1) V (A_1 ^B_2) V ... V (A_2 ^B_1) V (A_2 ^B_2) V ... (A_n ^B_m)$
 - Hmm, this is quadratic blowup. What happens to A ^ B ^ C ... ?
 - $(A_1 \vee A_2) \wedge (B_1 \vee B_2) \wedge (C_1 \vee C_2) \wedge ... = what?$
 - Exponential blowup really just generate and test of all combinations
 - So it doesn't help that we have a linear DNF solver
 - □ It's like having a "linear-time" factoring algorithm where the input has to be in unary notation: 2010 encoded as "111111111111111..."
 - □ Or more precisely, a SAT algorithm where input is a truth table! (* allowed)

Just the same thing goes wrong with CNF

- DNF and CNF seem totally symmetric: just swap v, ^
 - You can convert to CNF or DNF by essentially same algorithm
 - DNF blows up when you try to convert A ^ B ^ C ...
 - CNF blows up when you try to convert A v B v C ...
- But there is another way to convert to CNF! (Tseitin 1970)
 - □ Only quadratic blowup after we've reduced to v, ^, ~
 - Idea: introduce a new "switching variable" for each v
 - □ $(B_1 \land B_2 \land B_3) \lor (C_1 \land C_2 \land C_3)$ this is satisfiable iff ... = $(Z \rightarrow (B_1 \land B_2 \land B_3)) \land (\sim Z \rightarrow (C_1 \land C_2 \land C_3))$... this is satisfiable = $(\sim Z \lor (B_1 \land B_2 \land B_3)) \land (Z \lor (C_1 \land C_2 \land C_3))$ (solver picks Z) distribute \lor over \land as before, but gives 3+3 clauses, not 3*3 = $(\sim Z \lor B_1) \land (\sim Z \lor B_2) \land (\sim Z \lor B_3) \land (Z \lor C_1) \land (Z \lor C_2) \land (Z \lor C_3)$

Efficiently encode any formula as CNF

- We rewrote $(B_1 \land B_2 \land B_3) \lor (C_1 \land C_2 \land C_3)$ = $(\sim Z \lor B_1) \land (\sim Z \lor B_2) \land (\sim Z \lor B_3) \land (Z \lor C_1) \land (Z \lor C_2) \land (Z \lor C_3)$
- Recursively eliminate \mathbf{v} from $(A_1 \land A_2) \mathbf{v} \left((B_1 \land B_2) \mathbf{v} (C_1 \land C_2) \right)$: $= (A_1 \land A_2) \mathbf{v} \left((\sim Z \lor B_1) \land (\sim Z \lor B_2) \land (Z \lor C_1) \land (Z \lor C_2) \right)$ as before

switching variable
$$Y_1$$

=(\sim Y v A₁) ^ (\sim Y v A₂) ^ (Y v \sim Z v B₁) ^ (Y v \sim Z v B₂) ^ (Y v Z v C₁) ^ (Y v Z v C₂)

- Input formula suffers at worst quadratic blowup. Why? Each of its literals simply becomes a clause with the switching variables that affect it:
- For example, we start with a copy of B1 that falls in the 2nd arg of the Y v and the 1st arg of the Z v. So it turns into a clause (Y v ~Z v B₁).

Efficiently encode any formula as CNF

- We rewrote $(B_1 ^B_2 ^B_3) ^V (C_1 ^C_2 ^C_3)$ = $(~Z \lor B_1) ^(~Z \lor B_2) ^(~Z \lor B_3) ^(Z \lor C_1) ^(Z \lor C_2) ^(Z \lor C_3)$
- Recursively eliminate \mathbf{v} from $(A_1 \land A_2) \mathbf{v}$ $((B_1 \land B_2) \mathbf{v} (C_1 \land C_2)) \land D)$:

 switching variable \mathbf{Z} = $(A_1 \land A_2) \mathbf{v}$ $((\sim \mathbf{Z} \lor B_1) \land (\sim \mathbf{Z} \lor B_2) \land (\mathbf{Z} \lor C_1) \land (\mathbf{Z} \lor C_2) \land D)$ switching variable \mathbf{Y} = $(\sim \mathbf{Y} \lor A_1) \land (\sim \mathbf{Y} \lor A_2) \land (\mathbf{Y} \lor \sim \mathbf{Z} \lor B_1) \land (\mathbf{Y} \lor \sim \mathbf{Z} \lor B_2) \land (\mathbf{Y} \lor \mathbf{Z} \lor C_1) \land (\mathbf{Y} \lor \mathbf{Z} \lor C_2)$ $\land (\mathbf{Y} \lor \mathbf{D})$
- Input formula suffers at worst quadratic blowup. Why? Each of its literals simply becomes a clause with the switching variables that affect it:
- For example, we start with a copy of B₁ that falls in the 2nd arg of the Y v and the 1st arg of the Z v. So it turns into a clause (Y v ~Z v B₁).

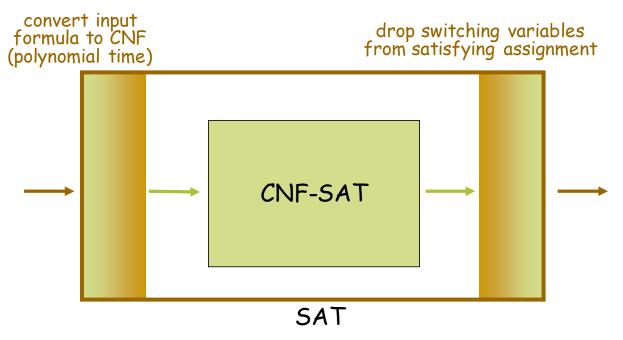
So why can't we use this trick for DNF?

- We rewrote $(B_1 \land B_2 \land B_3) \lor (C_1 \land C_2 \land C_3)$ as a "short" CNF formula: = $(\sim Z \lor B_1) \land (\sim Z \lor B_2) \land (\sim Z \lor B_3) \land (Z \lor C_1) \land (Z \lor C_2) \land (Z \lor C_3)$
- But we can just switch v and ^ they're symmetric!
- So why not rewrite $(B_1 \vee B_2 \vee B_3) \wedge (C_1 \vee C_2 \vee C_3)$ as this "short" DNF? = $(\sim Z \wedge B_1) \vee (\sim Z \wedge B_2) \vee (\sim Z \wedge B_3) \vee (Z \wedge C_1) \vee (Z \wedge C_2) \vee (Z \wedge C_3)$
 - Because we'd get a polytime SAT solver and win the Turing Award.
 - And because the rewrite is clearly wrong. It yields something easy to satisfy.
- The CNF/DNF difference is because we introduced extra variables.
- In CNF, original formula was satisfiable if new formula is satisfiable for either Z=true or Z=false. But wait! We're trying to switch or and and:
- In DNF, original formula is satisfiable if new formula is satisfiable for both Z=true and Z=false. Look at the formulas above and see it's so!
 - Alas, that's not what a SAT checker checks. We'd have to call it many times (once per assignment to the switching variables Y, Z, ...).

CNF and DNF are duals ...

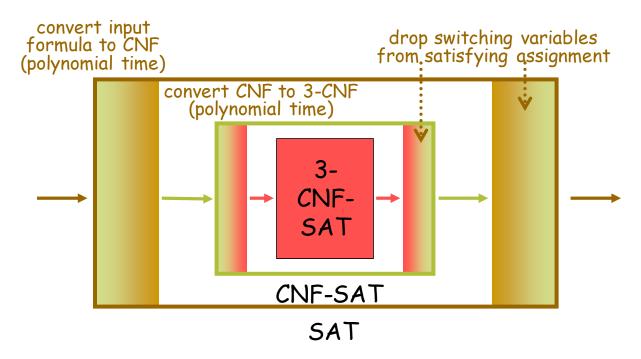
"Primal"	"Dual"	Reduction	Reverse reduction
V	^	$F \wedge G = \sim (\sim F \vee \sim G)$	$F \vee G = \sim (\sim F \wedge \sim G)$
3	\forall	$\forall x \ \phi(x) = \neg \exists x \ \neg \phi(x)$	$\exists x \phi(x) = \sim \forall x \sim \phi(x)$
SAT	TAUT	$TAUT(\phi) = \sim SAT(\sim \phi)$	$SAT(\phi) = \sim TAUT(\sim \phi)$
NP	co-NP	$\forall y \ f(x,y) = \sim \exists y \sim f(x,y)$	$\exists y \ f(x,y) = \sim \forall y \sim f(x,y)$
CNF-SAT	DNF-TAUT	can reduce problem efficiently to this form, using switching vars, but of course it's still hard to solve	
DNF-SAT	CNF-TAUT	problem in this form can be solved in linear time, but reducing to this form can blow up the size exponentially since switching variable trick can no longer be used	

So we've reduced SAT to CNF-SAT



- Most SAT solvers are actually CNF-SAT solvers.
 - They make you enter a CNF formula.
 - To use an arbitrary formula, you have to convert it to CNF yourself.
 - Fortunately, many practical problems like the LSAT puzzles are naturally expressed as something close to CNF. (Convert each fact or constraint to CNF and conjoin them all: the result is still in CNF.)

From CNF-SAT to 3-CNF-SAT



- SAT solvers could be even more annoyingly restrictive:
 - They could require each CNF clause to have at most 3 literals.
 - □ When converting your input formula to CNF,
 you'd have to get rid of "long" clauses like (A₁ v A₂ v A₃ v A₄).
 - This conversion is easy, so 3-CNF-SAT is still hard (NP-complete).

From CNF-SAT to 3-CNF-SAT

- How do we convert CNF to 3-CNF?
- Again replace "v" with a switching variable.
 - □ Formerly did that to fix non-CNF: $(A_1 \land A_2) \lor (B_1 \land B_2)$
 - Now do it to fix long clause: A₁ v A₂ v A₃ v A₄

$$A_1 \vee A_2 \vee \dots A_{n-2} \vee A_{n-1} \vee A_n$$

$$(Z \rightarrow A_1 \vee A_2 \vee \dots A_{n-2}) \wedge (\sim Z \rightarrow A_{n-1} \vee A_n)$$

$$(A_1 \vee A_2 \vee \dots A_{n-2} \vee \sim Z) \wedge (A_{n-1} \vee A_n \vee Z)$$

$$(A_{n-1} \vee A_n \vee Z)$$

From CNF-SAT to 3-CNF-SAT

- Why can't we get down to 2-CNF-SAT?
 - Actually 2-CNF-SAT can be solved in polynomial time.
 - So if we could convert any formula to 2-CNF-SAT in polynomial time, we'd have a proof that P = NP.

So it would be surprising if we could use switching variables to get to 2-CNF-SAT:

$$A_{1} \vee A_{2} \vee A_{3}$$

$$(Z \rightarrow A_{1}) \wedge (\sim Z \rightarrow A_{2} \vee A_{3})$$

$$(A_{1} \vee \sim Z) \wedge (A_{2} \vee A_{3} \vee Z)$$

$$(A_{3} \vee A_{3} \vee Z) \wedge (A_{2} \vee A_{3} \vee Z)$$

$$(A_{3} \vee A_{3} \vee Z) \wedge (A_{2} \vee A_{3} \vee Z)$$

$$(A_{3} \vee A_{3} \vee Z) \wedge (A_{3} \vee A_{3} \vee Z)$$

$$(A_{1} \vee A_{2} \vee A_{3} \vee Z)$$

$$(A_{2} \vee A_{3} \vee Z) \wedge (A_{3} \vee Z)$$

$$(A_{3} \vee A_{3} \vee Z)$$

$$(A_{3} \vee$$

The Tseitin Transformation (1968)

- Alternative way to convert any formula directly to 3-CNF.
- Disadvantages:
 - Introduces even more extra variables, and sometimes more clauses.
 - If the original formula is already in 3-CNF, will make it bigger.

Advantages:

- Simple, general, elegant.
- Gets only linear blowup.
 - That is, the CNF formula has length O(k) where k is the length of the original formula.
- \Box Linear even if the original formula contains \leftrightarrow , xor.
 - Our old method of eliminating those could get exponential blowup.
 - Why? Converted $F \leftrightarrow G$ to $(F \rightarrow G) \land (G \rightarrow F)$, doubling the length.
 - And F, G could contain ↔ themselves, hence repeated doubling.

The Tseitin Transformation (1968)

Associate a new variable with each internal node (operator) in the formula tree

Constrain each new variable to have the appropriate value given its children

$$(X_{1} \leftrightarrow (X_{2} \vee X_{4}))$$

$$^{\wedge}(X_{2} \leftrightarrow (X_{3} \rightarrow G)) \quad ^{\wedge}(X_{4} \leftrightarrow (^{\sim}X_{5}))$$

$$^{\wedge}(X_{3} \leftrightarrow (^{\sim}F)) \qquad ^{\wedge}(X_{5} \leftrightarrow (G \wedge X_{6}))$$

$$^{\wedge}(X_{6} \leftrightarrow (H \vee X_{7}))$$

$$^{\wedge}(X_{7} \leftrightarrow (^{\sim}X_{8}))$$

$$^{\wedge}(X_{8} \leftrightarrow (X_{9} \vee L))$$

$$^{\wedge}(X_{9} \leftrightarrow (J \wedge K))$$

$$^{\wedge}(X_{9} \leftrightarrow (J \wedge K))$$

$$^{\wedge}(X_{1} \leftrightarrow (X_{2} \vee X_{4}))$$

$$^{\wedge}(X_{2} \leftrightarrow (X_{3} \rightarrow G)) \quad ^{\wedge}(X_{4} \leftrightarrow (^{\sim}X_{5}))$$

$$^{\wedge}(X_{5} \leftrightarrow (G \wedge X_{6}))$$

$$^{\wedge}(X_{7} \leftrightarrow (^{\sim}X_{8}))$$

$$^{\wedge}(X_{9} \leftrightarrow (J \wedge K))$$

$$^{\wedge}(X_{9} \leftrightarrow (J \wedge K))$$

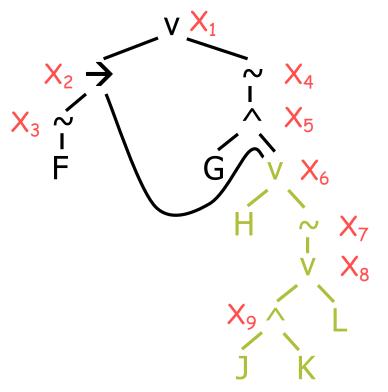
$$^{\wedge}(X_{1} \leftrightarrow (X_{2} \vee X_{4}))$$

Now separately convert each of these <u>short</u> clauses to 3-CNF. E.g., $(X_1 \leftrightarrow (X_2 \lor X_4))$ becomes $(\sim X_1 \lor X_2 \lor X_4) \land (X_1 \lor X_2) \land (X_1 \lor X_4)$

The Tseitin Transformation (1968)

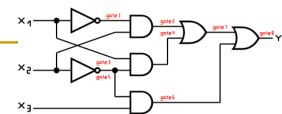
Associate a new variable with each internal node (operator) in the formula tree

DAG



You can build such a DAG out of logic gates. So it's called a "Boolean circuit":

- The circuit allows shared subformulas, so can be much smaller than the formula written out without sharing.
- Tseitin transformation will <u>reuse</u> the work on each subformula!
- Each node in the DAG gives rise to at most four 3-clauses.
- So the final 3-CNF formula has size that's linear in the size of the input DAG.



Quantified Satisfiability (QSAT)

- SAT asks whether (∃a) F(a) a is an assignment to all vars
- TAUT asks whether $(\forall a)$ F(a) a is an assignment to all vars
- They're the standard NP-complete and co-NP-complete problems.
- QSAT lets you ask, for example, whether
 (∃a) (∀b) (∃c) (∀d) F(a,b,c,d) a,b,c,d are assignments
 to non-overlapping subsets
 of the vars
- Harder! Worse than NP-complete (outside both NP and co-NP).
- QSAT problems are the standard complete problems for the problem classes higher up in the polynomial hierarchy.
- Example: Can White force a win in 4 moves? That is: Is there an opening move for you (∃a) such that for whatever response Kasparov makes (∀b), you will have some reply (∃c) so that however Kasparov moves next (∀d), you've checkmated him in a legal game (F(a,b,c,d))?