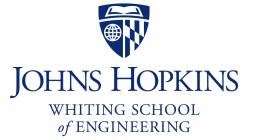
### CS 318 Principles of Operating Systems

### Fall 2017

### **Lecture 13: Dynamic Memory Allocation**

Ryan Huang



# Administrivia

### Lab 2 due Friday midnight

### Guoye will be traveling 10/21 to 10/30

- Lab 3 overview session will be livestreamed or recorded
- His office hours will be canceled, but please ask questions on Piazza, via emails, or request remote meeting

### Midterm grading

# Memory Allocation

### Static Allocation (fixed in size)

- want to create data structures that are fixed and don't need to grow or shrink
- global variables, e.g., char name[16];
- done at compile time

### Dynamic Allocation (change in size)

- want to increase or decrease the size of a data structure according to different demands
- done at run time

# **Dynamic Memory Allocation**

### Almost every useful program uses it

- Gives wonderful functionality benefits
- Don't have to statically specify complex data structures
- Can have data grow as a function of input size
- Allows recursive procedures (stack growth)
- But, can have a huge impact on performance

### Two types of dynamic memory allocation

- Stack allocation: restricted, but simple and efficient
- Heap allocation (focus today): general, but difficult to implement.

# **Dynamic Memory Allocation**

### Today: how to implement dynamic heap allocation

- Lecture based on [Wilson] (good survey from 1995)

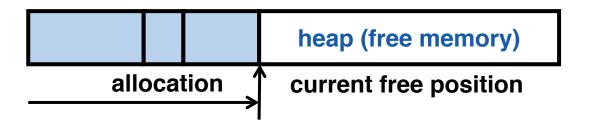
#### • Some interesting facts:

- Two or three line code change can have huge, non-obvious impact on how well allocator works (examples to come)
- Proven: impossible to construct an "always good" allocator
- Surprising result: after 35 years, memory management still poorly understood
  - Mallacc: Accelerating Memory Allocation: ASPLOS 2017 Highlights
- Big companies may write their own "malloc"
  - Google: TCMalloc
  - Facebook: jemalloc

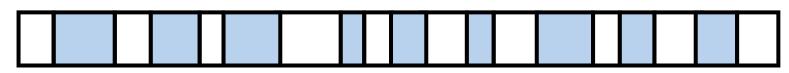
# Why Is It Hard?

Satisfy arbitrary set of allocation and frees.

 Easy without free: set a pointer to the beginning of some big chunk of memory ("heap") and increment on each allocation:

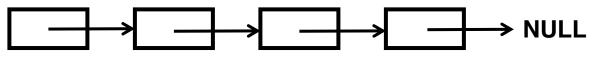


 Problem: free creates holes ("fragmentation") Result? Lots of free space but cannot satisfy request!



# More Abstractly

#### What an allocator must do?



- Track which parts of memory in use, which parts are free freelist
- Ideal: no wasted space, no time overhead

#### What the allocator cannot do?

- Control order of the number and size of requested blocks
- Know the number, size, & lifetime of future allocations
- Move allocated regions (bad placement decisions permanent)

#### malloc(20)?



#### The core fight: minimize fragmentation

- App frees blocks in any order, creating holes in "heap"
- Holes too small? cannot satisfy future requests

# What Is Fragmentation Really?

- Inability to use memory that is free
- Two factors required for fragmentation
  - 1. Different lifetimes—if adjacent objects die at different times, then fragmentation:



• If all objects die at the same time, then no fragmentation:

2. Different sizes: If all requests the same size, then no fragmentation (that's why no external fragmentation with paging):

# **Important Decisions**

#### Placement choice: where in free memory to put a requested block?

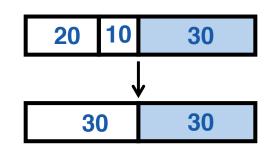
- Freedom: can select any memory in the heap
- Ideal: put block where it won't cause fragmentation later (impossible in general: requires future knowledge)

#### Split free blocks to satisfy smaller requests?

- Fights internal fragmentation
- Freedom: can choose any larger block to split
- One way: choose block with smallest remainder (best fit)

#### Coalescing free blocks to yield larger blocks

- Freedom: when to coalesce (deferring can save work)
- Fights external fragmentation



# Impossible to "Solve" Fragmentation

#### If you read allocation papers to find the best allocator

- All discussions revolve around tradeoffs
- The reason? There cannot be a best allocator

#### Theoretical result:

 For any possible allocation algorithm, there exist streams of allocation and deallocation requests that defeat the allocator and force it into severe fragmentation.

#### How much fragmentation should we tolerate?

- Let M = bytes of live data,  $n_{min}$  = smallest allocation,  $n_{max}$  = largest allocation
- Bad allocator: M  $\cdot$   $(n_{max}/n_{min})$ 
  - E.g., make all allocations of size  $n_{\text{max}}$  regardless of requested size
- Good allocator: ~  $M \cdot \log(n_{max}/n_{min})$

# Pathological Examples

#### Suppose heap currently has 7 20-byte chunks



- What's a bad stream of frees and then allocates?

- Next: two allocators (best fit, first fit) that, in practice, work pretty well
  - "pretty well" =  $\sim$ 20% fragmentation under many workloads

# Pathological Examples

Suppose heap currently has 7 20-byte chunks

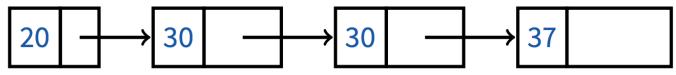
20 20 20 20 20 20 20

- What's a bad stream of frees and then allocates?
- Free every other chunk, then alloc 21 bytes
- Next: two allocators (best fit, first fit) that, in practice, work pretty well
  - "pretty well" =  $\sim$ 20% fragmentation under many workloads



 Strategy: minimize fragmentation by allocating space from block that leaves smallest fragment

- Data structure: heap is a list of free blocks, each has a header holding block size and a pointer to the next block



- Code: Search freelist for block closest in size to the request. (Exact match is ideal)
- During free return free block, and (usually) coalesce adjacent blocks

#### Potential problem: Sawdust

- Remainder so small that over time left with "sawdust" everywhere
- Fortunately not a problem in practice

# Best Fit Gone Wrong

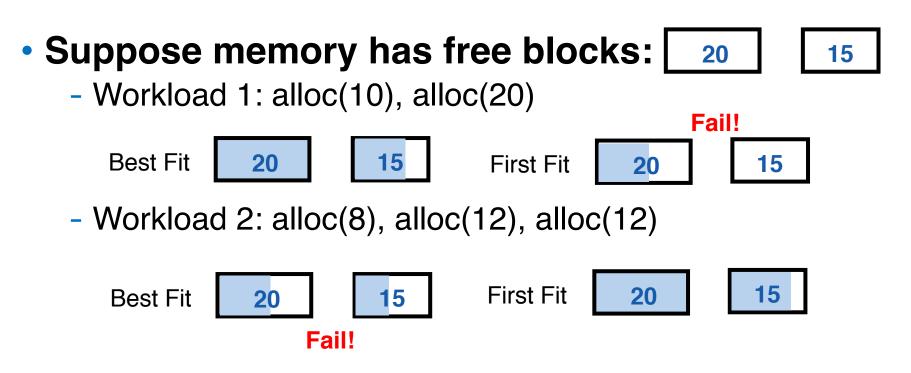
- Simple bad case: allocate n, m (n < m) in alternating orders, free all the ns, then try to allocate an n + 1
- Example: start with 99 bytes of memory
  - alloc 19, 21, 19, 21, 19
  - free 19, 19, 19:

- alloc 20? Fails! (wasted space = 57 bytes)
- However, doesn't seem to happen in practice

# First Fit

### Strategy: pick the first block that fits

- Data structure: free list, sorted LIFO, FIFO, or by address
- Code: scan list, take the first one



# First Fit

### • LIFO: put free object on front of list.

- Simple, but causes higher fragmentation
- Potentially good for cache locality

### Address sort: order free blocks by address

- Makes coalescing easy (just check if next block is free)
- Also preserves empty/idle space (locality good when paging)

### • FIFO: put free object at end of list

- Gives similar fragmentation as address sort, but unclear why

# Subtle Pathology: LIFO FF

Storage management example of subtle impact of simple decisions

### • LIFO first fit seems good:

 Put object on front of list (cheap), hope same size used again (cheap + good locality)

### • But, has big problems for simple allocation patterns:

- E.g., repeatedly intermix short-lived 2n-byte allocations, with long-lived (n + 1)-byte allocations
- Each time large object freed, a small chunk will be quickly taken, leaving useless fragment. Pathological fragmentation

# First Fit: Nuances

### First fit sorted by address order, in practice

- Blocks at front preferentially split, ones at back only split when no larger one found before them
- Result? Seems to roughly sort free list by size
- So? Makes first fit operationally similar to best fit: a first fit of a sorted list = best fit!

### Problem: sawdust at beginning of the list

- Sorting of list forces a large requests to skip over many small blocks. Need to use a scalable heap organization

# Some Other Ideas

### • Worst-fit:

- Strategy: fight against sawdust by splitting blocks to maximize leftover size
- In real life seems to ensure that no large blocks around

#### • Next fit:

- Strategy: use first fit, but remember where we found the last thing and start searching from there
- Seems like a good idea, but tends to break down entire list

### Buddy systems:

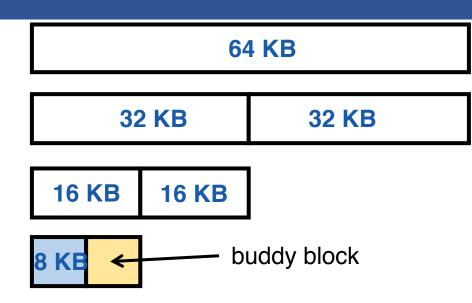
- Round up allocations to power of 2 to make management faster

# **Buddy Allocator Motivation**

### Allocation requests: frequently 2<sup>n</sup>

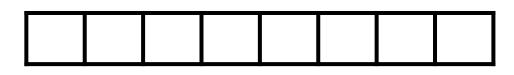
- E.g., allocation physical pages in Linux
- Generic allocation strategies: overly generic
- Fast search (allocate) and merge (free)
  - Avoid iterating through free list
- Avoid external fragmentation for req of 2<sup>n</sup>
- Keep physical pages contiguous
- Used by Linux, FreeBSD

# **Buddy Allocation**

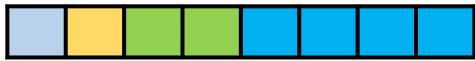


- Recursively divide larger blocks until reach suitable block
  - Big enough to fit but if further splitting would be too small
- Insert "buddy" blocks into free lists
- Upon free, recursively coalesce block with buddy if buddy free

### **Buddy Allocation Example**



 $p1 = alloc(2^0)$ 



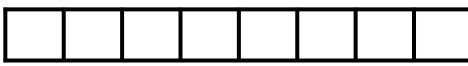
 $p2 = alloc(2^2)$ 



free(p1)



free(p2)



freelist[3] =  $\{0\}$ 

freelist[0] =  $\{1\}$ , freelist[1] =  $\{2\}$ , freelist[2] =  $\{4\}$ 

freelist[0] =  $\{1\}$ , freelist[1] =  $\{2\}$ 

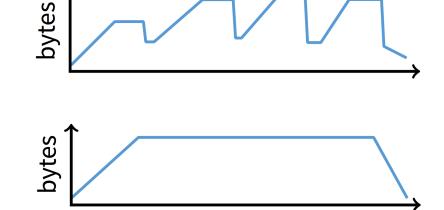
 $freelist[2] = \{0\}$ 

freelist[3] =  $\{0\}$ 

# Known Patterns of Real Programs

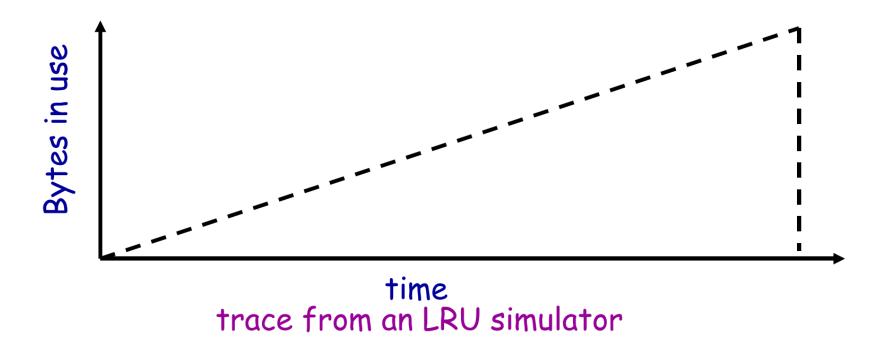
- So far we've treated programs as black boxes.
- Most real programs exhibit 1 or 2 (or all 3) of the following patterns of alloc/dealloc:
  - Ramps: accumulate data monotonically over time
  - Peaks: allocate many objects, use briefly, then free all

- Plateaus: allocate many objects, use for a long time



bytes

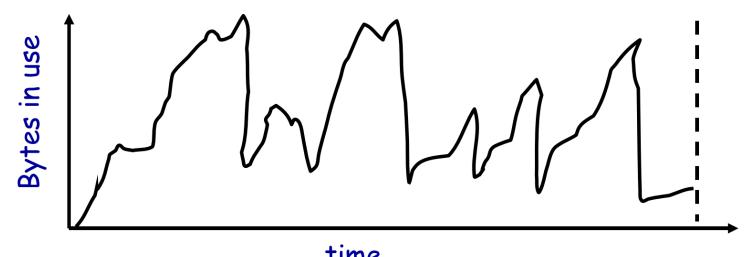
### Pattern 1: ramps



#### • In a practical sense: ramp = no free!

- Implication for fragmentation?
- What happens if you evaluate allocator with ramp programs only?

### Pattern 2: Peaks



time trace of gcc compiling with full optimization

#### Peaks: allocate many objects, use briefly, then free all

- Fragmentation a real danger
- What happens if peak allocated from contiguous memory?
- Interleave peak & ramp? Interleave two different peaks?

# **Exploiting Peaks**

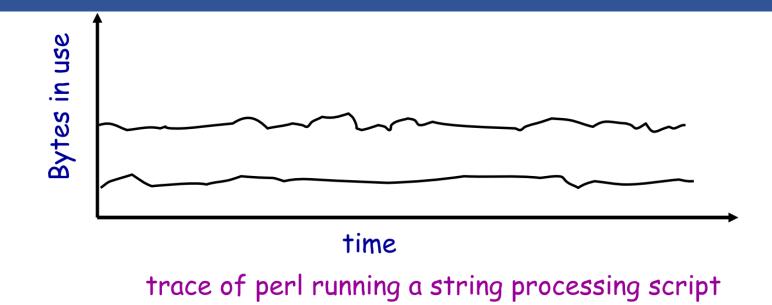
#### Peak phases: allocate a lot, then free everything

- Change allocation interface: allocate as before, but only support free of everything all at once
- Called "arena allocation", "obstack" (object stack), or alloca/procedure call (by compiler people)

### Arena = a linked list of large chunks of memory

- Advantages: alloc is a pointer increment, free is "free"
- No wasted space for tags or list pointers

### Pattern 3: Plateaus



#### Plateaus: allocate many objects, use for a long time

- What happens if overlap with peak or different plateau?

### **Slab Allocation**

- Kernel allocates many instances of same structures
  - E.g., a 1.7 KB task\_struct for every process on system
- Often want contiguous physical memory (for DMA)
- Slab allocation optimizes for this case:
  - A slab is multiple pages of contiguous physical memory
  - A cache contains one or more slabs
  - Each cache stores only one kind of object (fixed size)
- Each slab is full, empty, or partial

## **Slab Allocation**

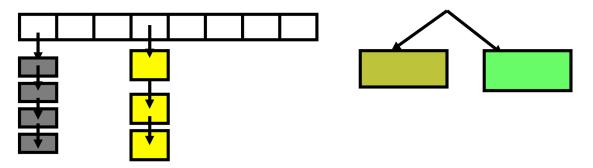
#### • E.g., need new task\_struct?

- Look in the task\_struct cache
- If there is a partial slab, pick free task\_struct in that
- Else, use empty, or may need to allocate new slab for cache

### • Free memory management: bitmap

- Allocate: set bit and return slot, Free: clear bit
- Advantages: speed, and no internal fragmentation
- Used in FreeBSD and Linux, implemented on top of buddy page allocator

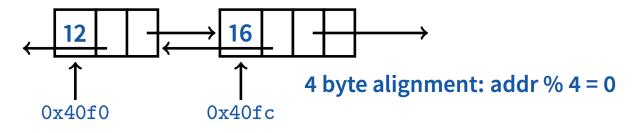
# Simple, Fast Segregated Free Lists



- Array of free lists for small sizes, tree for larger
  - Place blocks of same size on same page
  - Have count of allocated blocks: if goes to zero, can return page
- Pro: segregate sizes, no size tag, fast small alloc
- Con: worst case waste: 1 page per size even w/o free, After pessimal free: waste 1 page per object
- TCMalloc [Ghemawat] is a well-documented malloc like this

# **Typical Space Overheads**

- Free list bookkeeping and alignment determine minimum allocatable size:
- If not implicit in page, must store size of block
- Must store pointers to next and previous freelist element



#### Allocator doesn't know types

- Must align memory to conservative boundary

# Getting More Space from OS

#### • On Unix, can use sbrk

- E.g., to activate a new zero-filled page:

| stack              | <pre>/* add nbytes of valid virtual address space */</pre> |
|--------------------|--|
|                    | <pre>void *get_free_space(size_t nbytes) {</pre>           |
| sbrk               | <pre>void *p = sbrk(nbytes);</pre>                         |
| heap               | if (!p)  |
| r/w data           | <pre>error("virtual memory exhausted"); return p;</pre>    |
| r/o data<br>+ code | }  |

#### For large allocations, sbrk a bad idea

- May want to give memory back to OS
- Can't with sbrk unless big chunk last thing allocated
- So allocate large chunk using mmap's MAP\_ANON



• Read Chapter 36, 37