



Trees



What is a Tree?

Non-linear data structure

- Hierarchical arrangement of data

Has components named after natural trees

- root
- branches
- leaves

Drawn with root at the top



Components of a Tree

Node: stores a data element

Parent: single node that directly precedes a node

- all nodes have 1 parent except root (has 0)

Child: one or more nodes that directly follow a node

Ancessor: any node which precedes a node

- itself, its parent, or an ancestor of its parent

Descendent: any node which follows a node

- itself, its child, or a descendent of its child



More Tree Terminology

Leaf (external) node: node with no children

Internal node: non-leaf node

Siblings: nodes which share same parent

Subtree: a node and all its descendants

- Ignoring the node's parent, this is itself a tree

Ordered tree: tree with defined order of children

- enables ordered *traversal*

Binary tree: ordered tree with up to two children per node



Examples of Trees

Directory tree

- Organizes directories and files hierarchically
- Directories are internal nodes, files are leaf nodes (usually)

Class hierarchy

- Object is root, other classes are descendants

Decision tree

- Binary tree
- Path taken determined by boolean expression

Expression tree

- Operators are internal nodes, variables and constants are leaf nodes



Comparison of Tree and List

	List	Tree
Start	head	root
# before	1 (prev)	1 (parent)
# after	1 (next)	≥ 1 (children)



Tree methods

`root()`: returns root
`parent(v)`: returns parent of `v`
`children(v)`: returns iterator of children of `v`
`size()`: returns number of nodes
`elements()`: returns iterator of all elements
`positions()`: returns iterator of all positions/nodes
`swapElements(v,w)`: swaps elements at two nodes
`replaceElement(v,e)`: replaces element of a node

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Tree query utility methods

`isInternal(v)`: test if node is internal
`isExternal(v)`: test if node is external
`isRoot(v)`: test if node is root

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Depth

Depth of `v` is numbers of ancestors (excluding `v`)

- depth of root is 0
- depth of node is depth of parent plus 1

```

public static int depth (Tree T, Node v) {
  if (T.isRoot(v)) return 0;
  else return 1 + depth(T, T.parent(v));
} // running time?  $O(d_v)$ 
  
```

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Height

Height of `v` is maximum path length of subtree

- height of leaf node is 0
- height of internal node is maximum height of children + 1

—height of a tree is height of root or maximum depth of a leaf

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Naïve height algorithm

```

public static int height1(Tree T) {
  int h=0;
  PositionIterator it = T.positions();
  while (it.hasNext()) {
    Position v = it.nextPosition();
    if (T.isExternal(v))
      h = Math.max(h, depth(T,v));
  }
  return h; } // running time?  $O(n^2)$ 
  
```

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Efficient height algorithm

```

public static int height2(Tree T, Position v) {
  if (T.isExternal(v)) return 0;
  else {
    int h=0;
    PositionIterator children = T.children(v);
    while (children.hasNext())
      h = Math.max(h, height2(T, children.nextPosition()));
    return 1 + h; }
} // running time?
  
```

$O(n)$: each node visited once

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Traversal

Ordered way of *visiting* all nodes of tree
Converts hierarchy into a linear sequence



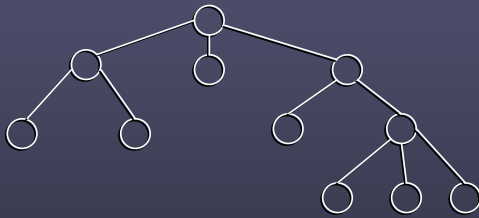
Preorder Traversal

Visit node, then visit children

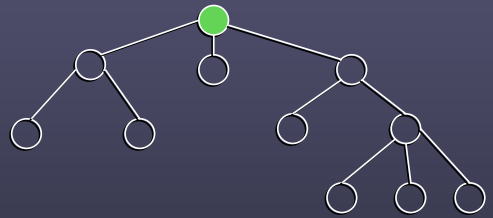
```
public void preorder(Tree T, Position v)
{
    visit(v);
    PositionIterator children = T.children(v);
    while (children.hasNext())
        preorder(children.nextPosition());
}
```



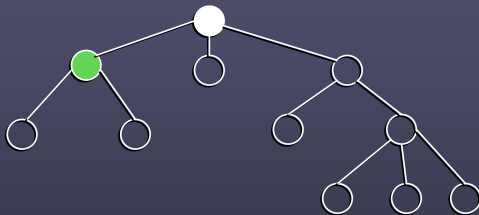
Preorder Example



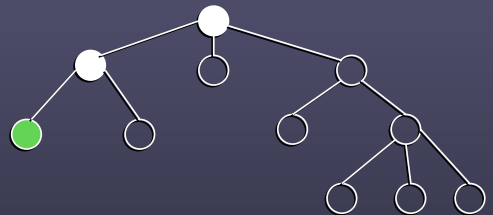
Preorder Example



Preorder Example

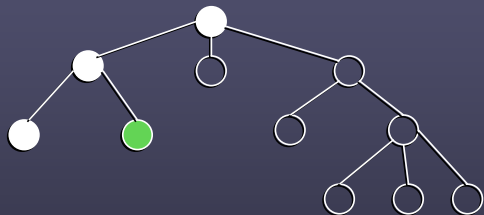


Preorder Example





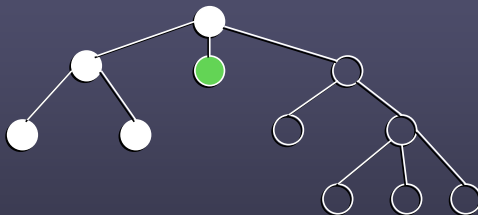
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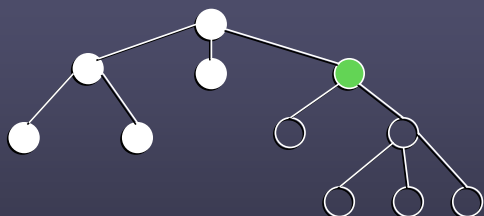
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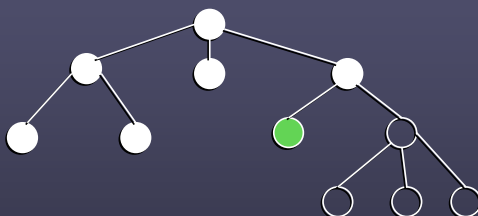
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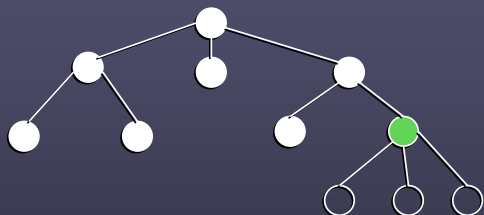
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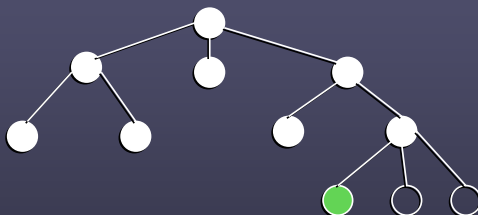
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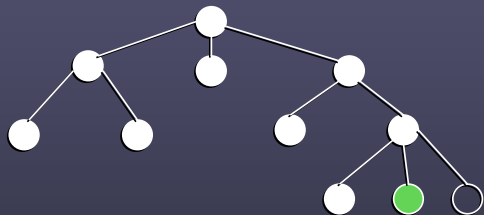
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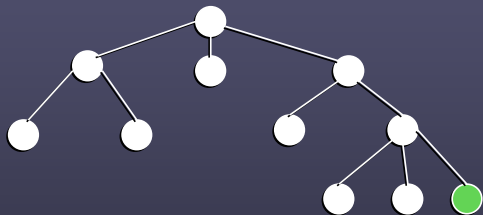
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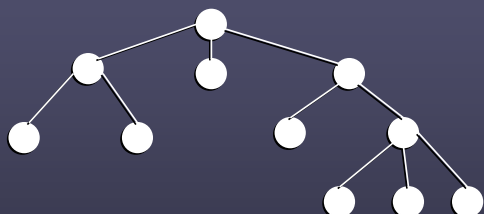
Preorder Example



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Preorder Example



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Postorder Traversal

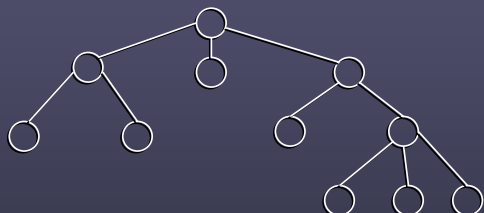
Visit children, then visit node

```
public void postorder(Tree T, Position v)
{
    PositionIterator children = T.children(v);
    while (children.hasNext())
        postorder(children.nextPosition());
    visit(v);
}
```

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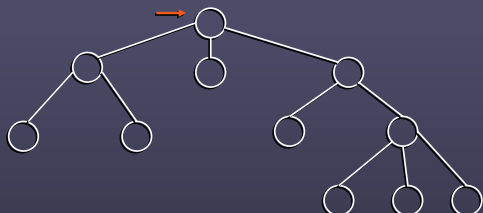
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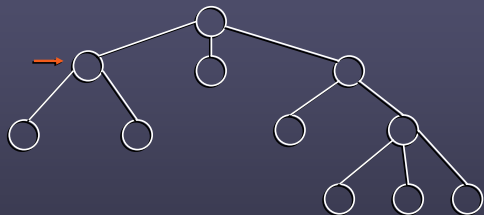
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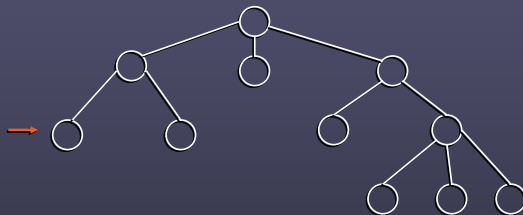
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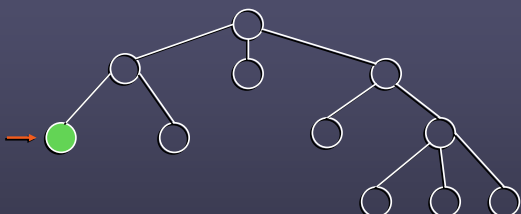
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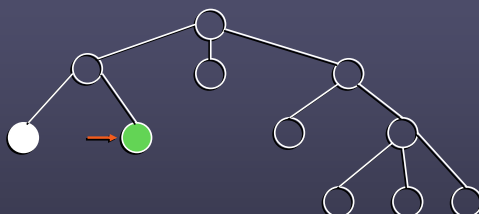
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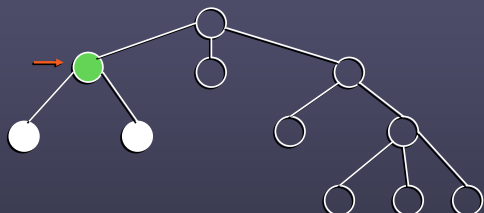
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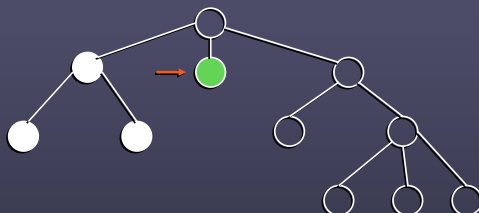
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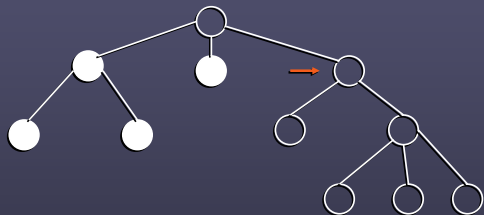
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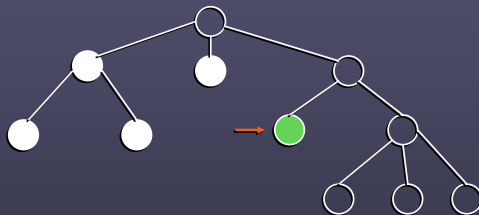
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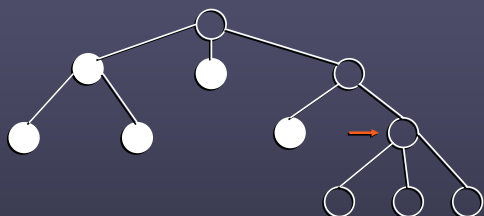
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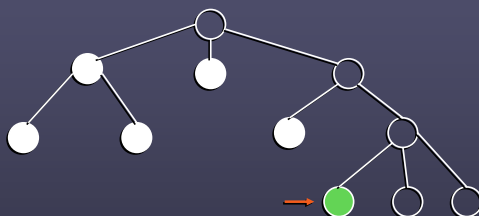
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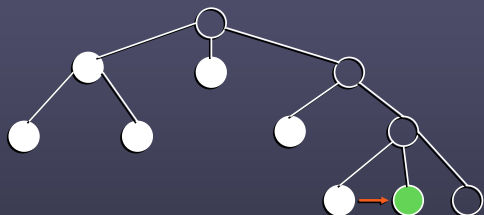
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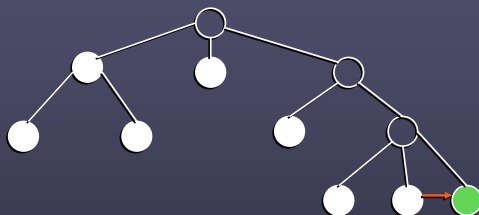
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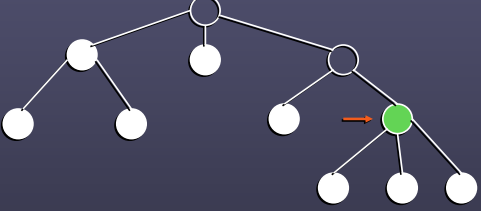


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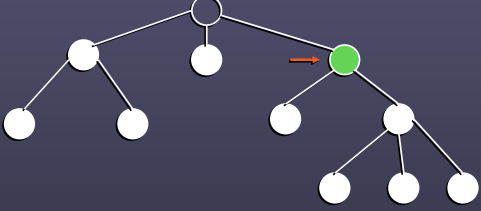
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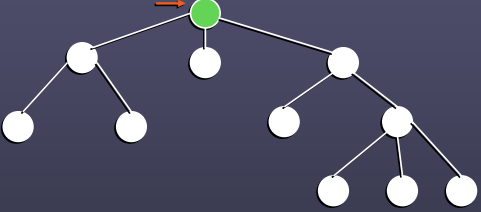
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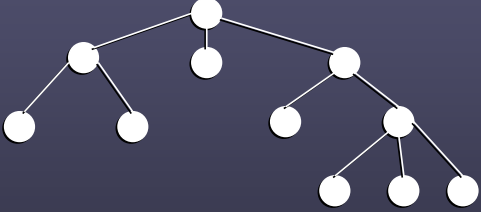
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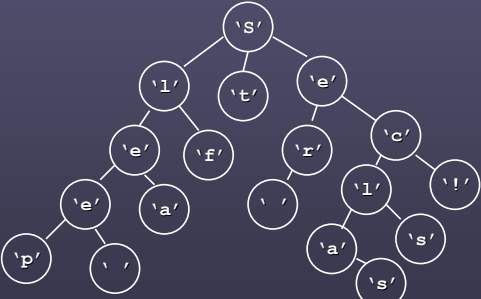
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 **In-class Exercises...**

(Paper and pencil recommended)

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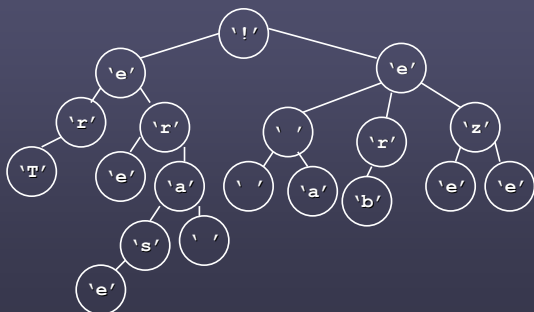
 **Preorder Letter Scramble**



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Postorder Letter Scramble



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Binary Tree

Each node has no more than 2 children

- *Proper* binary tree: each node has either 0 or 2 children

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Binary Tree ADT

`leftChild(v)`: returns left child of `v`

`rightChild(v)`: returns right child of `v`

`sibling(v)`: returns sibling of `v`

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Binary Tree Traversal

Preorder: node, left, right

Postorder: left, right, node

Inorder: left, node, right

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Euler Tour Traversal

Generalizes preorder, inorder, and postorder

Visit each internal node 3 times

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Euler Tour

```
public void eulerTour(Tree T,
                    position v) {
    visitPre(T,v);
    if (T.hasLeft(v))
        eulerTour(T, T.leftChild(v));
    visitIn(T,v);
    if (T.hasRight(v))
        eulerTour(T, T.rightChild(v));
    visitPost(T,v); return; }

```

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Template Method Pattern

Implement template or skeleton method for high-level algorithm

Extend the template's class to override lower-level methods

EulerTour example

- Override methods for visitPre, visitIn, and visitPost



Useful Binary Tree Definitions

Level d : All nodes in a binary tree at depth d

- Maximum of 2^d nodes in level d

Complete binary tree: tree of height h with 2^h leaf nodes

- $2^h - 1$ internal nodes
- $2^{h+1} - 1$ total nodes



Binary Tree Properties

(proper) Binary tree T of height h

- $h+1 \leq \text{external nodes} \leq 2^h$
- $h \leq \text{internal nodes} \leq 2^h - 1$
- $2h+1 \leq \text{total nodes} \leq 2^{h+1} - 1$
- $\log(n+1) - 1 \leq h \leq (n-1)/2$
- $\text{external nodes} = \text{internal nodes} + 1$



Implementing Binary Tree

Linked

- Each node references left, right, and parent as well as element

Vector-based

- Number nodes in level order
- Store nodes at rank according to number
 - Storage allocated for entire complete tree