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chp 4.

Parametric Methods

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How to estimate the probabilities to make decisions (previous lecture).

Abstract: estimate the sufficient statistics which are functions of the data samples. These are sufficient to determine the parameters of the distribution.

Density estimator $p(x)$
Use this to estimate $p(x|\theta)$ & $p(\theta)$

Maximum Likelihood Estimation (MLE)

Sample $X = \{x^t\}_{t=1}^N$
i.i.d. from some distribution $p(x|\theta)$
parameter.

likelihood $l(\theta) \equiv p(X|\theta) = \prod_{t=1}^N p(x^t|\theta)$

MLE: Find $\hat{\theta}$ to maximize $l(\theta)$

or, equivalently maximize the log likelihood
 $J(\theta|X) \equiv \log l(\theta|X) = \sum_{t=1}^N \log p(x^t|\theta)$

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Bernoulli Density

two outcomes,

random variable X

$X=1$, with prob p

$X=0$, with prob $1-p$.

$$p(x) = p^x (1-p)^{1-x}, \quad x \in \{0, 1\}.$$

p is the only parameter.

Log-likelihood

$$\mathcal{L}(p|X) = \log \prod_{t=1}^N p^{x^t} (1-p)^{1-x^t}$$

$$= \sum_t x^t \log p + (N - \sum_t x^t) \log(1-p).$$

Solve $\frac{\partial \mathcal{L}(p|X)}{\partial p} = 0$

gives $\hat{p} = \frac{\sum_t x^t}{N}.$

Intuition, no. of positive outcomes
divided by number of samples.

Multinomial Density

generalization of Bernoulli

K classes, probability p_i , $\sum_{i=1}^K p_i = 1$

$$p(x_1, x_2, \dots, x_K) = \prod_{i=1}^K p_i^{x_i}$$

x_i 's indicator variables

$x_i = 1$, if outcome is i
 0 , otherwise.

(3) N experiments with outcomes $X = \{x^t\}_{t=1}^N$
 $x^t_i = \begin{cases} 1, & \text{if experiment } t \text{ chose state } i \\ 0, & \text{otherwise} \end{cases}$

MLE of p_i is $\hat{p}_i = \frac{\sum_t x^t_i}{N}$
 proportion of sample which lie in class i .

Gaussian (Normal) Density

$$p(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \quad -\infty < x < \infty$$

$\mathcal{N}(\mu, \sigma^2)$

Sample $X = \{x^t\}_{t=1}^N$, with $x^t \sim \mathcal{N}(\mu, \sigma^2)$

log likelihood $\mathcal{L}(\mu, \sigma | X) = -\frac{N}{2} \log 2\pi - N \log \sigma - \sum_t \frac{(x^t - \mu)^2}{2\sigma^2}$

MLE

$$\mu = \frac{\sum_t x^t}{N}$$

$$s^2 = \frac{\sum_t (x^t - \mu)^2}{N}$$

Convention: Greek for the parameters.
 Roman for their estimates.

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Exponential Distributions and Maximum Likelihood

$$P(x|\lambda) = \frac{e^{\lambda \cdot \phi(x)}}{Z[\lambda]}$$

exponential distribution
statistics $\phi(\cdot)$

parameter λ

$$Z[\lambda] = \sum_x e^{\lambda \cdot \phi(x)}, \text{ if } x \text{ is discrete-valued}$$

normalization
term.

$$= \int dx e^{\lambda \cdot \phi(x)}, \text{ if } x \text{ is continuous-valued}$$

Ensures $\sum_x P(x|\lambda) = 1$, or $\int dx P(x|\lambda) = 1$.

Note: (1) most "named" distributions can be expressed as exponential distribution $\rightarrow$ e.g. Gaussian, Poisson, Bernoulli, ...

(2) any distribution can be approximated arbitrarily accurately by an exponential distribution.

(3) mixture models can be expressed as exponential distributions by introducing hidden variables

Example: Gaussian in 1-D $P(x;\mu,\sigma) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2\sigma^2}(x-\mu)^2}$

$$\log P(x;\mu,\sigma) = \frac{-1}{2\sigma^2} x^2 + \frac{x\mu}{\sigma^2} - \frac{1}{2\sigma^2} \mu^2 - \log \sqrt{2\pi}\sigma$$

$$\log P(x;\lambda) = \lambda \cdot \phi(x) - \log Z[\lambda] \quad \text{set } \phi(x) = (x, x^2)$$

$$\lambda = \left(-\frac{1}{2\sigma^2}, \frac{\mu}{\sigma^2}\right)$$

$$\log Z[\lambda] = -\frac{1}{2\sigma^2} \mu^2 - \log \sqrt{2\pi}\sigma$$

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Note: the sufficient statistics $\phi(x)$ are the properties of the data x that we need to store (we can throw out the rest of the data).

For a set of samples $x^1, x^2, \dots, x^M$ from a Gaussian,

we only need to store the statistics

$$\frac{1}{M} \sum_{i=1}^M (x^i) \quad \text{and} \quad \frac{1}{M} \sum_{i=1}^M (x^i)^2.$$

the parameters of the Gaussian — μ & σ^2 — estimated by ML will depend only on these statistics:

e.g. we don't need to also store

$$\frac{1}{M} \sum_{i=1}^M (x^i)^4, \quad \text{or even all the samples } x^1, x^2, \dots, x^M)$$

Another example: Bernoulli.

$$p(x) = \theta^x (1-\theta)^{1-x}$$

$$\log p(x) = x \log \theta + (1-x) \log (1-\theta)$$

$$= x \{ \log \theta - \log (1-\theta) \} + \log (1-\theta)$$

Exponential

$$\phi(x) = x$$

$$\lambda = \log \theta - \log (1-\theta)$$

$$\log \pi(\lambda) = \log (1-\theta)$$

(6) Maximum Likelihood for Exponential Distribution
 Samples $\{x^i : i=1 \dots M\}$ from $P(x|\lambda) = \frac{e^{\lambda \cdot \phi(x)}}{Z(\lambda)}$

ML say maximize $\prod_{i=1}^M P(x^i|\lambda)$
 w.r.t. λ

$$\hat{\lambda} = \text{ARG MAX}_{\lambda} \sum_{i=1}^M \log P(x^i|\lambda)$$

$$\hat{\lambda} = \text{ARG MAX}_{\lambda} \left(\lambda \cdot \sum_{i=1}^M \phi(x^i) - M \log Z(\lambda) \right)$$

Equivalently: minimize $F(\lambda) = \log Z(\lambda) - \lambda \cdot \frac{1}{M} \sum_{i=1}^M \phi(x^i)$

where $\psi = \frac{1}{M} \sum_{i=1}^M \phi(x^i)$ is the empirical statistic
 e.g. $(\frac{1}{M} \sum_{i=1}^M x^i, \frac{1}{M} \sum_{i=1}^M (x^i)^2)$ for Gaussian

Minimize: solve $\frac{\partial F(\lambda)}{\partial \lambda} = 0$, for λ :

Note $F(\lambda)$ is convex — $\frac{\partial^2 F}{\partial \lambda^2} \geq 0$ by properties of $\log Z(\lambda)$

so there is a unique solution

(property of $\log Z(\lambda)$) $\frac{\partial F}{\partial \lambda} = \frac{\partial \log Z(\lambda)}{\partial \lambda} - \psi = \sum_x P(x|\lambda) \phi(x) - \psi$

Maximum likelihood selects λ for that the expected statistic $\sum_x P(x|\lambda) \phi(x)$ equal the observed statistic ψ

— e.g. for a Gaussian the mean and variance parameters λ, μ are chosen to equal the mean and variance of the data

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Important:

how to solve

$$\sum_x P(x|\lambda) \phi(x) = \underline{\psi} \quad ?$$

(or $\int dx P(x|\lambda) \phi(x) = \underline{\psi}$) ?

For special distributions — like Gaussians, Bernoulli, Poisson — these can be solved analytically to give a closed form solution

→ e.g. $\mu = \frac{1}{N} \sum_{i=1}^N x^i$ for Gaussians

$$\sigma^2 = \frac{1}{N} \sum_{i=1}^N (x^i)^2 + \mu^2$$

But for other distributions we cannot solve analytically.

(or Generalized Iterative Scaling GIS)

In these cases we can do steepest descent on $F(\lambda)$ — which is convex, so steepest descent converges to the unique solution.

$$\underline{\lambda}^{t+1} = \underline{\lambda}^t - \epsilon \frac{\partial F(\underline{\lambda})}{\partial \underline{\lambda}} \Big|_{\underline{\lambda}^t}$$

$t=0$
 t — index of iteration.

$$\underline{\lambda}^{t+1} = \underline{\lambda}^t - \epsilon \sum_x \phi(x) P(x; \underline{\lambda}^t) + \epsilon \underline{\psi}$$

converges — when $\sum_x \phi(x) P(x; \underline{\lambda}^t) = \underline{\psi}$
model statistics = empirical statistics

Problem: each iteration

requires estimating $\sum_x \phi(x) P(x; \underline{\lambda}^t)$,

which is difficult — note, if we can compute this analytically then we can probably solve $\sum_x \phi(x) P(x; \underline{\lambda}) = \underline{\psi}$ directly (e.g. for Gaussian $\int \phi(x) P(x; \lambda) dx = (\mu, \sigma^2 | \mu^2)$)

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Alternate perspective: Maximum Entropy.

Entropy of a distribution

$$-\sum_x p(x) \log p(x), \text{ or } -\int dx p(x) \log p(x)$$

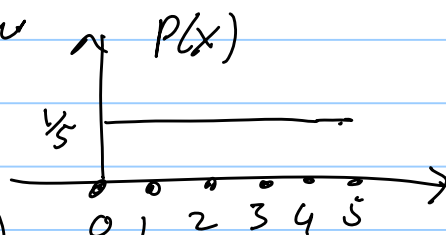
expected information from a sample x of a distribution

Shannon's Theory of Information

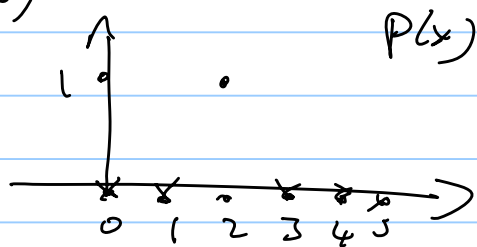
uniform distribution

entropy $-5 \left(\frac{1}{5}\right) \log\left(\frac{1}{5}\right) = \log 5$

generally $\log N$ (if N no. of states)



entropy $-4(0 \log 0) - (1 \log 1)$
 $= 0$



$$\begin{pmatrix} 0 \log 0 = 0 \\ 1 \log 1 = 0 \end{pmatrix}$$

no information is transmitted if we get a sample from this distribution, since we know what the value will be before we see it (it has to be 2)

But we do get information from a sample from the uniform distribution

Shannon; says we should encode a sample x from $p(x)$ by $-\log p(x)$ bits — so samples with high probability have low number of bits — then the expected coding cost (in bits) is just the entropy

$$\sum_x p(x) [-\log p(x)] = -\sum_x p(x) \log p(x)$$

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Maximum entropy principle:

suppose that we observe some statistics $\phi(x)$ and they take a value $\underline{\psi}$

(e.g. the mean of the data takes a value).

What distribution describes the data?

Maximum Entropy Principle (see Jaynes)

Suppose we select the distribution $P(x)$ that maximizes the entropy (i.e. is as uniform as possible) but is consistent with the data

$$L(P; \lambda, \mu) = - \sum_x P(x) \log P(x) + \mu \left(\sum_x P(x) - 1 \right) + \lambda \left(\sum_x P(x) \phi(x) - \psi \right)$$

Lagrange multipliers
imposed on the constraint

$$\frac{\partial L}{\partial P} = 0 \Rightarrow -\log P(x) + 1 + \mu + \lambda \cdot \phi(x) = 0$$
$$\Rightarrow P(x) = e^{\lambda \cdot \phi(x)} e^{1+\mu} \quad (*)$$

$$\frac{\partial L}{\partial \mu} = 0 \Rightarrow \sum_x P(x) = 1, \text{ normalization}$$

$$\frac{\partial L}{\partial \lambda} = 0 \Rightarrow \sum_x P(x) \phi(x) = \psi, \text{ consistency with the data}$$

Imposing normalization on (*) gives

$$P(x; \lambda) = \frac{1}{Z(\lambda)} e^{\lambda \cdot \phi(x)} \rightarrow \text{exponential distribution!}$$

$$\text{s.t. } \sum_x P(x; \lambda) \phi(x) = \psi$$

So Maximum Likelihood with Exponential Distribution is the same as doing Maximum Entropy with the statistics

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Maximum Entropy suggests a solution to the problem - how do we know what distribution to use?

Maximum Entropy strategy is to search over the statistics - instead of searching over distributions

i.e. statistic $\phi_1(\cdot)$ gives distribution $P(x) = \frac{1}{Z(\lambda_1)} e^{\lambda_1 \cdot \phi_1(x)}$

" " $\phi_2(\cdot)$ " " $P(x) = \frac{1}{Z(\lambda_2)} e^{\lambda_2 \cdot \phi_2(x)}$

" $\phi_1(x) \& \phi_2(x)$ " " $P(x) = \frac{1}{Z(\lambda_1, \lambda_2)} e^{\lambda_1 \cdot \phi_1(x) + \lambda_2 \cdot \phi_2(x)}$

" " "Searching over Statistics" is complicated and difficult

- see papers by Della Pietra, Della Pietra, Elftadey
Zhu, Wu, Mumford.

Beyond scope of this course.