

VC Dimension

Note Title

4/5/2010

Additional notes on VC dimension (from Stat 232)

Some changes in notation

VC-dim h

Risk - Error

These notes contain:

- The VC bound theorem.
- Discussion of the capacity term $\phi(h, n, \delta)$
- VC's for margins and kernels
(too advanced, kernels haven't been mentioned yet.)
- The 'trends' of VC bounds.
- Structural risk minimization

VC-Dimension

Note Title

11/19/2006

$$\underline{\text{Risk}}: R(\alpha) = \sum_{x,y} L(\alpha(x), y) P(x, y)$$

$$\underline{\text{Empirical Risk}} \quad R_{\text{emp}}(\alpha) = \frac{1}{N} \sum_{i=1}^N L(\alpha(x_i), y_i)$$

Minimize the empirical risk by constraining the set $\mathcal{H}$ of classifiers.

Vapnik-Chervonenkis (VC) dimension of a set $\mathcal{H}$ of classifiers.

VC = largest number of datapoints which can be shattered by the classifier set.

Shattered means that all possible dichotomies of the dataset can be expressed by a classifier in the set.

E.g. Hyperplanes can Shatter any set provided $n \leq d+1$, $d = \text{dim space}$

Hence, VC-dimension of hyperplanes is $d+1$.

(2) Probably Approximately Correct (PAC)

Let h be the VC dimension of a set Γ of classifiers.

If number of data samples $n \leq h$, then learning (i.e. generalization) is impossible — you can only memorize.

VC Bound Theorem: Suppose $n > h$

then, with probability at least $1 - \delta$:

$$R[\alpha] \leq R_{\text{emp}}[\alpha] + \phi(h, n, \delta), \quad \forall \alpha \in \Gamma$$

$$\text{where } \phi(h, n, \delta) = \sqrt{\left(\frac{8}{n}\right) \left\{ h \log\left(\frac{n}{h}\right) + h + \log \frac{4}{\delta} \right\}}$$

(Several different ϕ 's appear in different proofs)

Comment: require $\phi(h, n, \delta)$ to be small to ensure generalization.

$$\begin{array}{l} \text{requires: } n \gg h \\ n \gg |\log \delta| \end{array} \quad \left\| \begin{array}{l} \text{small } h/n \\ \text{small } |\log \delta|/n \end{array} \right.$$

note: to require certainty, $\delta \rightarrow 0 \Rightarrow n \rightarrow \infty$.

(3) Comment: the derivation of VC bounds is complicated. The bounds require many approximations — so they are not tight.

Also, the proofs require ruling out all other possible interpretations of the data
→ this is too conservative.

VC Margins for Hyperplanes.

Consider hyperplanes, $\underline{a} \cdot \underline{x} = 0$,
normalised wrt. data $\{\underline{x}_\mu : \mu = 1 \text{ to } n\}$
s.t. $\min_{\mu \in \{1, \dots, n\}} |\underline{a} \cdot \underline{x}_\mu| = 1$.

Then, the set of hyperplane classifiers
of form $\text{sign}(\underline{x} \cdot \underline{a})$, with $|\underline{a}| \leq \Lambda$

has VC dimension $h < R^2 \Lambda^2$ $\overset{\text{margin}}{\text{inverse margin}}$

where R^2 is radius of smallest sphere containing data points.

Intuition: low VC, if we require large margin region & data lies in small region

(4) The same result also applies to kernels, because the kernel trick can be used.

The margin Δ , depends only on the kernel.
The radius of the minimum sphere R depends only on the kernel.

Proof, the minimum sphere can be found by a quadratic optimization problem.

$$L_p(R, \underline{x}^*) = R^2 - \sum_{\mu=1}^n \lambda_{\mu} (R^2 - |\underline{x}_{\mu} - \underline{x}^*|$$

$$\lambda_{\mu} \geq 0.$$

λ Lagrange term enforces

$$R^2 \geq |\underline{x}_{\mu} - \underline{x}^*| \quad \forall \mu$$

$$\frac{\partial L_p}{\partial \underline{x}^*} = 0 \Rightarrow \sum_{\mu} \lambda_{\mu} (\underline{x}_{\mu} - \underline{x}^*) = 0$$

$$\frac{\partial L_p}{\partial R} = 0 \Rightarrow$$

$$1 = \sum_{\mu=1}^n \lambda_{\mu}.$$

$$\Rightarrow \sum_{\mu} \lambda_{\mu} \underline{x}_{\mu} \cdot \underline{x}^* = \sum_{\mu} \lambda_{\mu} \underline{x}^* \cdot \underline{x}^*.$$

Hence:
$$L_d = \sum_{\mu=1}^n \lambda_{\mu} (\underline{x}_{\mu} - \underline{x}^*)^2$$

$$L_d = \sum_{\mu=1}^n \lambda_{\mu} \underline{x}_{\mu} \cdot \underline{x}_{\mu} - 2 \sum_{\mu=1}^n \lambda_{\mu} \underline{x}_{\mu} \cdot \underline{x}^* + \sum_{\mu=1}^n \lambda_{\mu} (\underline{x}^*)^2$$

$$= \sum_{\mu=1}^n \lambda_{\mu} \underline{x}_{\mu} \cdot \underline{x}_{\mu} - \sum_{\mu, \nu=1}^n \lambda_{\mu} \lambda_{\nu} \underline{x}_{\mu} \cdot \underline{x}_{\nu}$$

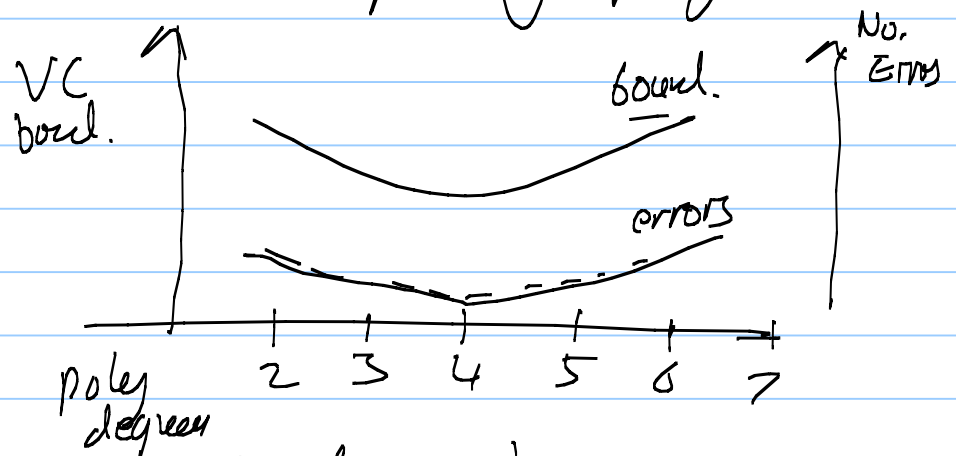
depends on dot product. Hence kernel trick applies.

(5) Applications of VC-bound.

Use the Margin VC to decide which kernels will generalize best for learning to classify handwritten digits (US Post Office dataset).

→ For each kernel, solve the dual problem to estimate R .

Schölkopf did this comparing polynomial kernels.



The VC bound predicted the form of the

errors (as a function of poly. degree).

But, the bounds very significantly worse than the errors.

(6) Structural Risk Minimization

Take the generalization into account when estimating the best classifier.

Statistics says, learn a classifier on a training dataset and use cross-validation to evaluate it.

VC theory says, evaluate the bound $\phi(h, n, S)$ and ensure there are sufficient number of samples to make $\phi(h, n, S)$ very small.

Alternative - Structural Risk Minimization.

Divide the set of classifiers into a hierarchy of sets $S_p \subset S_{p+1} \subset \dots$ with VC dimensions $h_p, h_{p+1}, \dots$

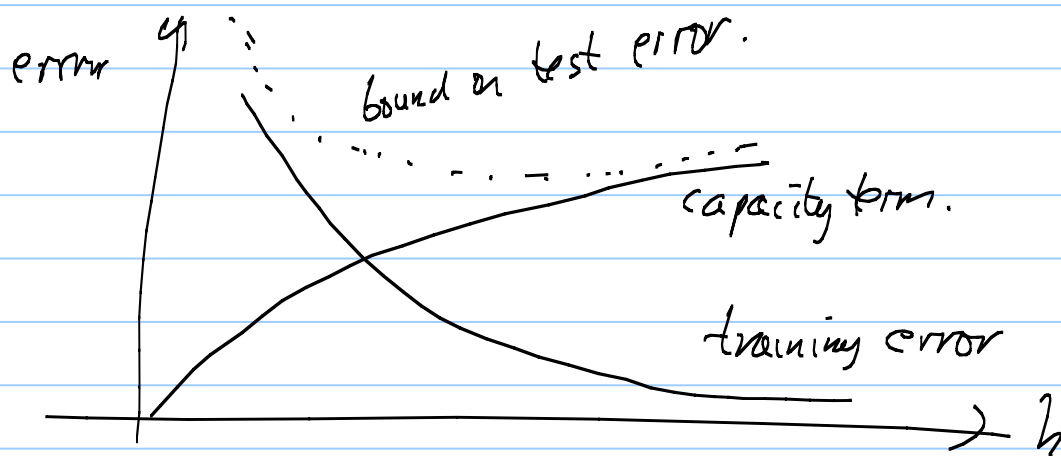
Select classifier to minimize

$$\underbrace{R_{\text{emp}}[\alpha]}_{\text{empirical risk}} + \underbrace{\left(\frac{1}{n}\right) \left(h_p (\log(2m/n) + 1) + \log(4/\delta) \right)}_{\text{capacity term}}$$

(7) A small capacity term ensures good generalization (with high probability)

Increasing the amount of data allows you to increase p

But, is the bound good enough? Does it give a fair balance between performance on the training set (R_{emp}) and generalizability (capacity term)? Does it overweight the importance of generalization?



$$C \subseteq S_{p-1} \subseteq S_p \subseteq \dots$$