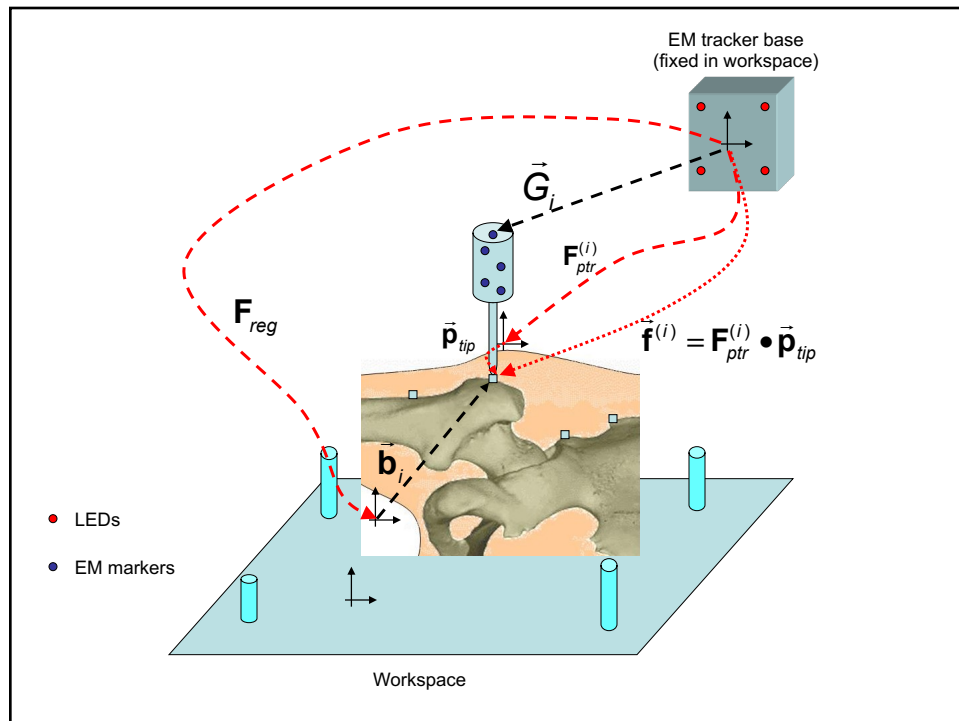
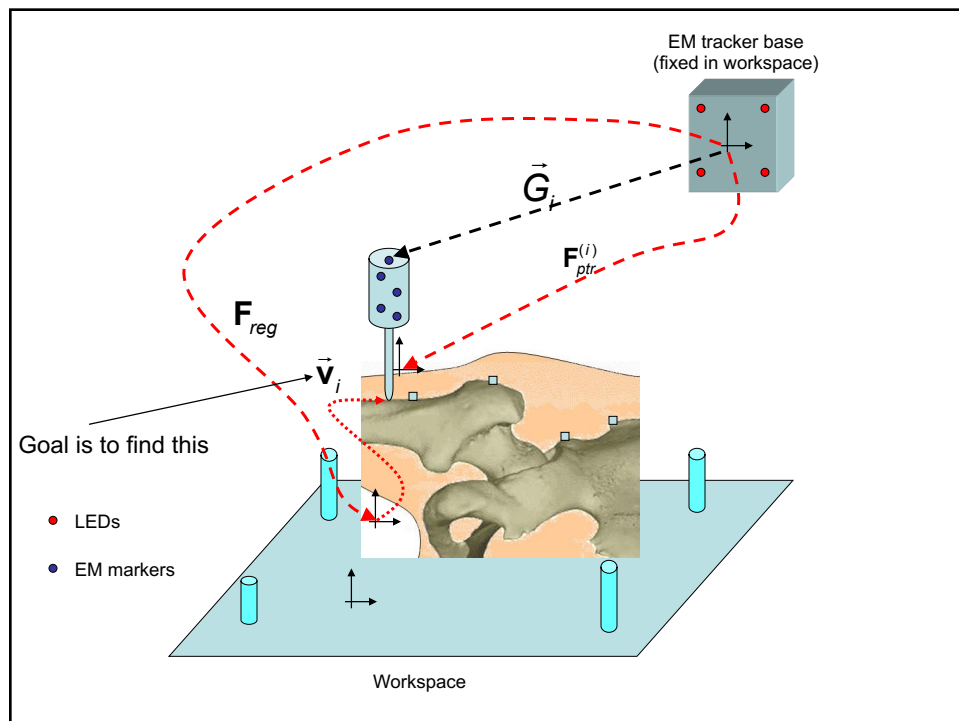
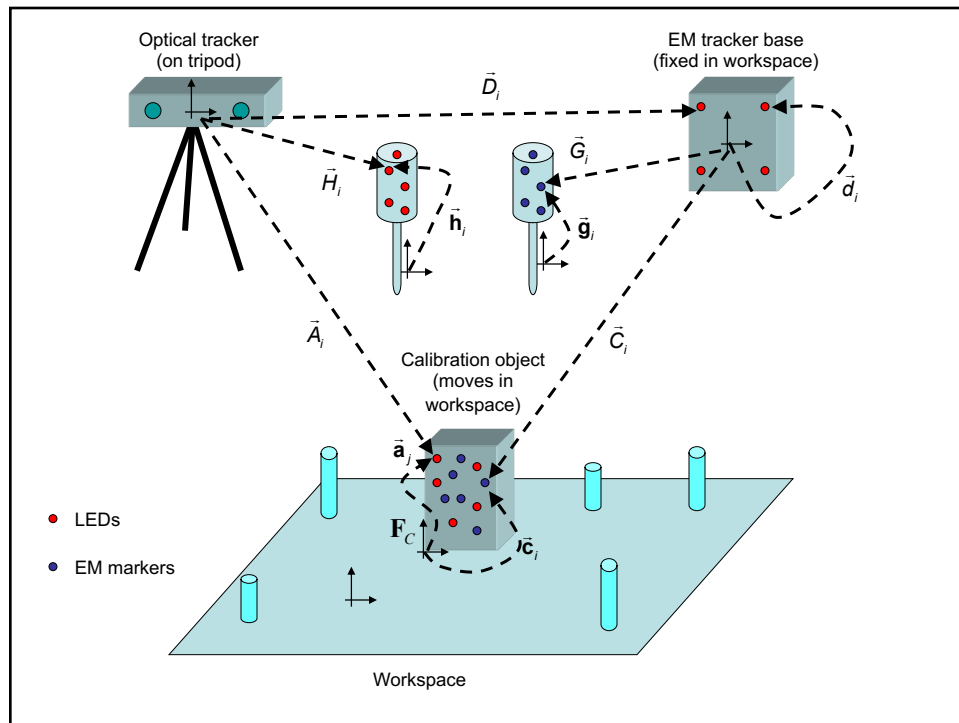




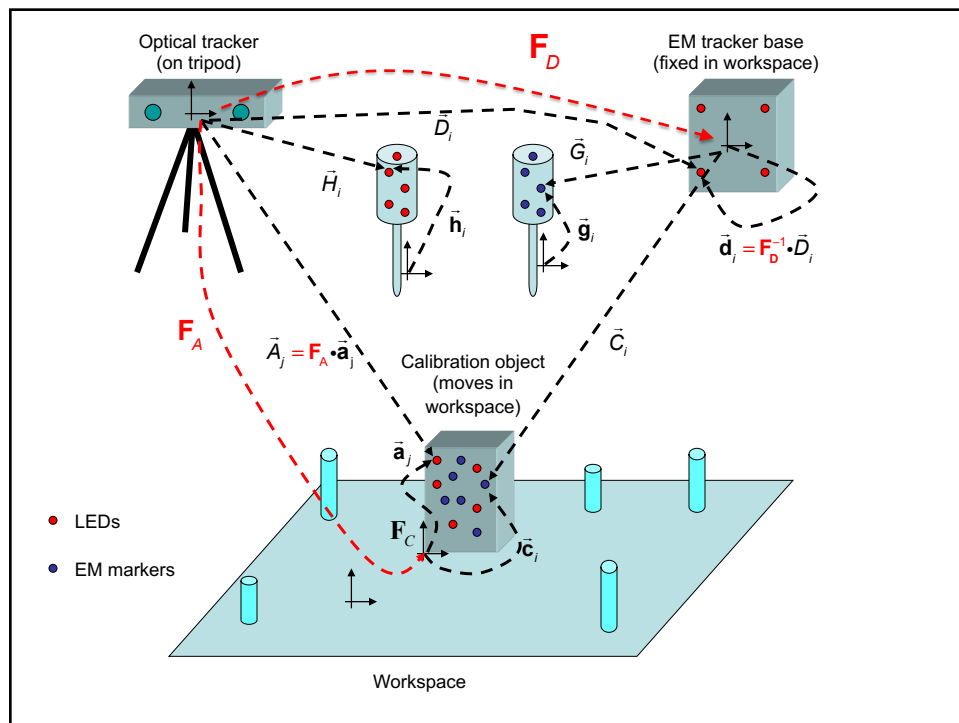
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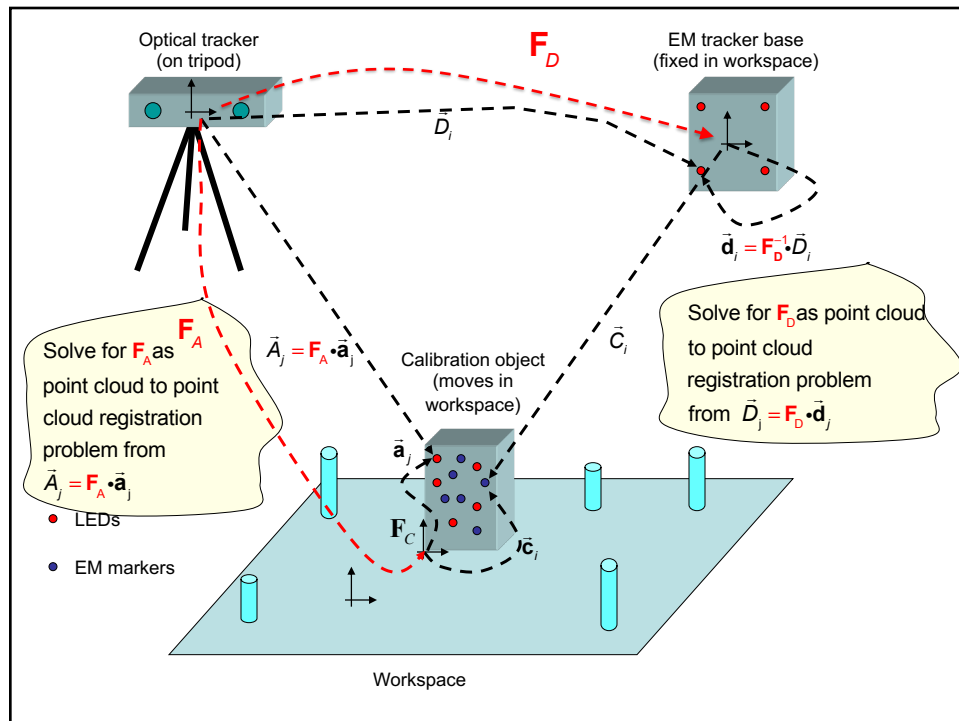
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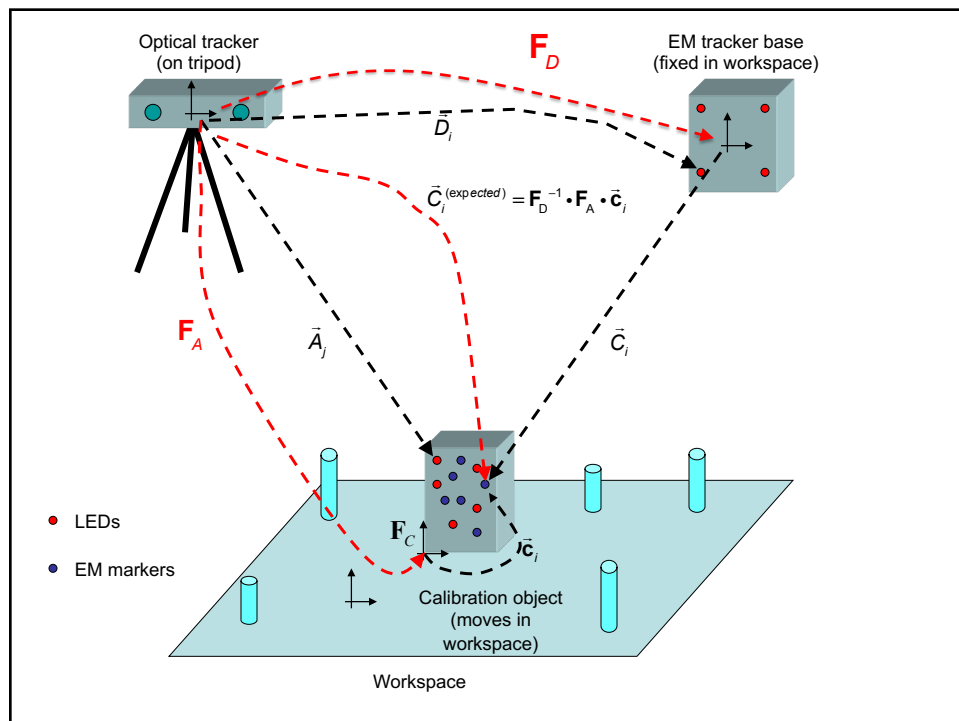
3



4

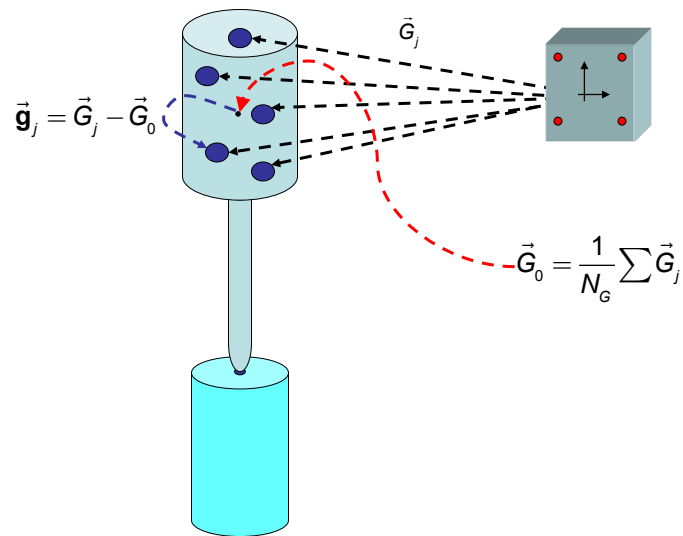


5



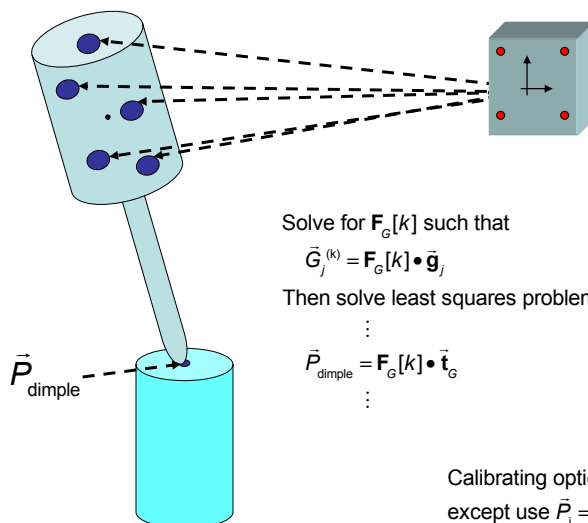
6

Defining the EM rigid body



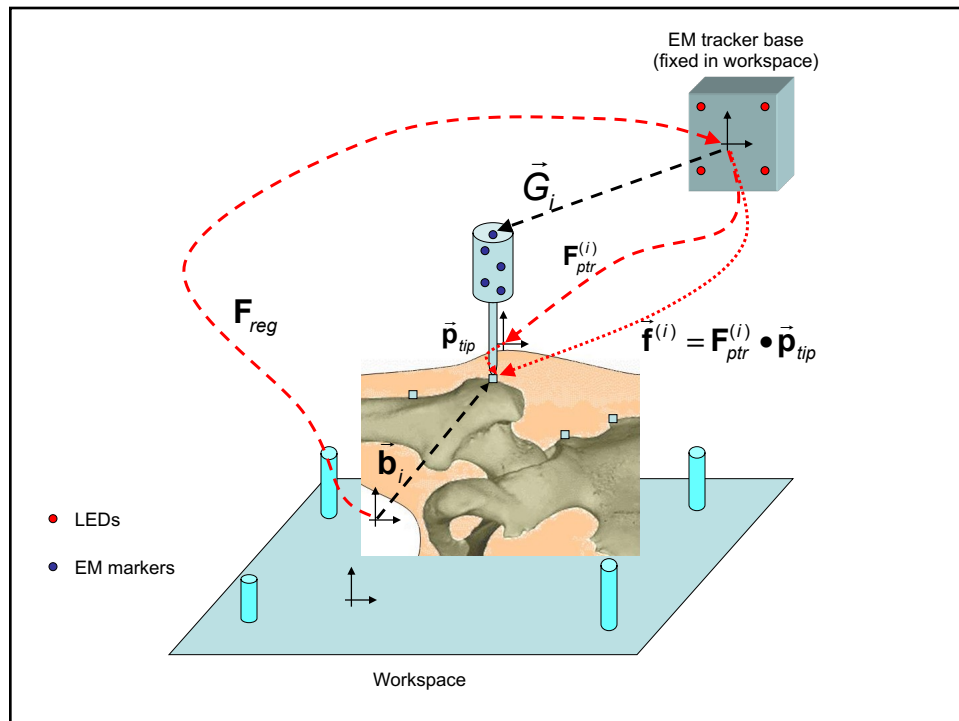
7

Calibrating the EM Pointer (pivot calibration)

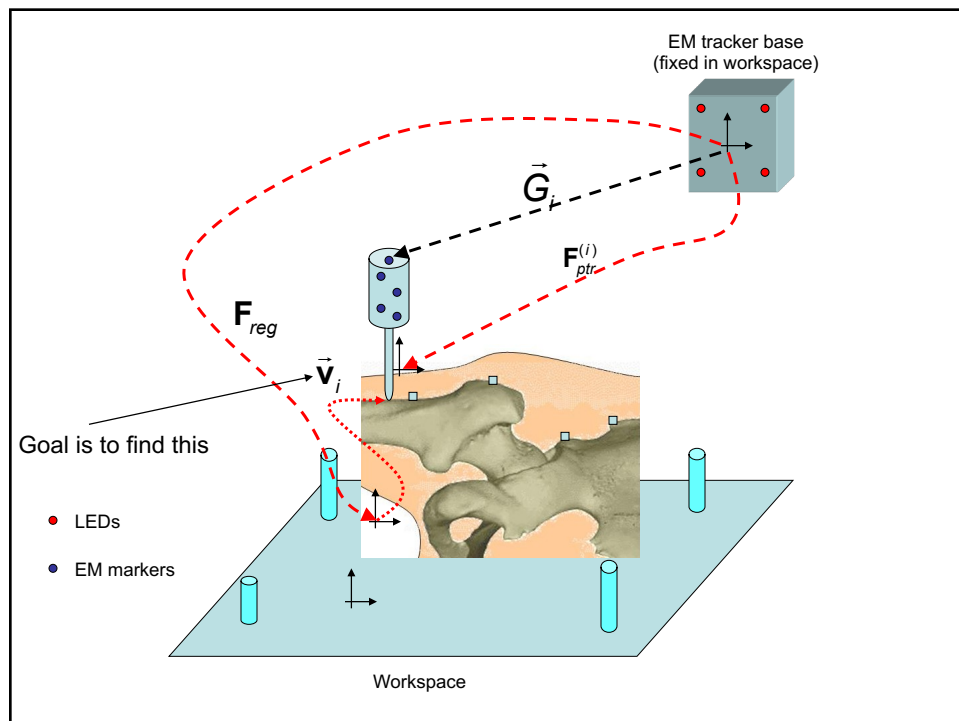


Calibrating optical pointer is similar
except use $\vec{P}_j = \mathbf{F}_D \bullet \vec{H}_j$ instead of $\vec{G}_j$

8



9



10