x86 Introduction

Philipp Koehn

25 October 2019



x86



- Yet another processor architecture...
- Why do we care?
- x86 is the dominant chip in today's computers (Mac, Windows, Linux)
 - 100 million chips sold per year
 - \$5 billion annual development budget
- We will focus on C programs get compiled into x86 machine code



history





- 16-bit processer released in 1978 by Intel
- 8 16-bit internal registers, 20-bit address bus
- Ahead of its time, too expensive, slow sales
- 8-bit processors dominated the market



- Scaled down version of 8068
- 8-bit data bus instead of 16-bit
- But looked the same from programmer's perspective
- Clock speed 4.77 MHz
- Chosen by IBM for its PC, released 1981
 - IBM PC for sale for \$1,265 (\$3,360 in 2016 dollars)
 - Apple][for sale for \$1,355 (\$3,599 in 2016 dollars)





- Released by intel in 1981, used in IBM AT in 1984
- More instructions, e.g., support for multi-tasking
- Faster
 - clock speed 4.77 MHz ightarrow 6 MHz
 - average number of cycles per instructions 12 ightarrow 4.5
- Downward compatible: "real" mode vs. "protected" mode





- Released in 1985, in computers late 1986, popular until early 1990s
- 32-bit processor, but downward compatible to 286, 8086
- Virtual real mode
 - allows different processes use different parts of memory
 - crashes do not affect whole systems
 - \rightarrow true multi-tasking

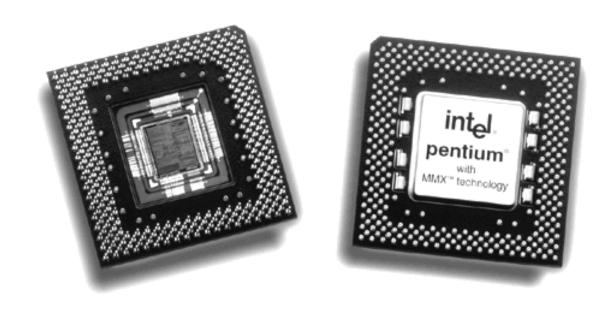




- Up to 120 MHz
- ullet Average number of cycles per instructions 4 ightarrow 2
- Internal L1 cache (hit ratio 90-95%)
- Burst memory (after initial load, 12 bytes transfered in 1 cycle)
- Internal math co-processor
- Enabled graphical user interfaces ("Windows")

586 (Pentium)





- 75-266 MHz
- 2 data paths: can execute 2 instructions in parallel
- 2 internal caches: instruction and data

And so on...



- 1995 Pentium Pro: Conditional move instruction
- 1997 Pentium MMX: Instructions for 64 bit vectors of integers
- 1999 Pentium III: Instructions for 128 bit vectors of floats
- 2000 Pentium 4: Double precision floating point
- 2004 Pentium 4E: 64 bit, hyper-threading of 2 processes in parallel
- 2006 Core 2: Multiple cores on chip
- ullet 2008 Core i7: 4 cores imes 2 hyperthreading
- 2011 Core i7: 256 bit vector instructions

Today: Intel Xeon Platinum 8180M



- 28 cores, 56 threads
- 2.5-3.8 GHz
- 38.5 MB Cache (L1, L2, L3)
- Can address 1.5 TB RAM
- Uses 205 Watt
- List price \$8399





architecture

RISC vs. CISC



- RISC = Reduced Instruction Set Computer, e.g., MIPS
 - instructions follow simple pattern
 - for instance: no memory lookup and ALU operation in same instruction
 - allows for compact design and pipelining
- CISC = Complex Instruction Set Computer, e.g., x86
 - instructions of different complexity and length (1-15 bytes)
 - some very complex: vector operations on floats
 - complexities, but were increasingly addressed with more hardware
 (Intel Xeon Platinum 8180M processors have 8 billion transistors)

8 Registers



• 4 general purpose registers: AX, BX, CX, DX (16 bit)

• Stack pointer: SP

• Base pointer: BP

• Address registers: SI, DI

• 8 bit registers: AH/AL, BH/BL, CH/CL, DH/DL

• 32 bit registers: prefix with "E", e.g., EAX

• 64 bit registers: prefix with "R", e.g., RAX 8 additional registers added (R8-R15)■

• Additional floating point registers: ST(0)-ST(7)

Operands



• As in 6502, operands can be registers and memory locations

For instance addition

```
- add EAX, EBX    ; add two registers
```

- add EAX, [ff02]; add value from memory location ff02 to register

- add [ff02], EAX; as above, store result in memory

- add [ff02], 20 ; add 20 to value stored in memory location ff02

Addressing Modes



Addressing modes similar to 6502

```
- mov [ff02], EAX ; load from address ff02
```

- mov [ESP], EAX ; load from address specified in register ESP

```
- mov [ESP+40], EAX ; address is register value + 40
```

- mov [ESP+EBX], EAX; address is sum of register values

• To deal with different data sizes: scaled index

```
- mov [60+EDI*4], EAX ; scale index register value
```

- mov [60+EDI*4+EBX], EAX ; scale index register, add base

Data Sizes



• Operations work on 8, 16, 32, or 64 bit data sizes

• Examples

```
- add AH, BL ; 8 bit
```

- add AX, BX ; 16 bit

- add AX, -1 ; 16 bit (-1 = ffff)

- add EAX, EBX ; 32 bit

- add EAX, -1 ; 16 bit (-1 = fffffff)

- add RAX, RBX ; 64 bit

Data Types



C	Intel type	Assembly suffix	Bytes
char	byte	b	1
short	word	W	2
int	double word	1	4
long	quad word	q	8
float	single precision	S	4
double	double precision	d	8

Status Flags



• Same kind of status flags as 6502

- CF: carry flag

- ZF: zero flag

- SF: sign flag

- OF: overflow flag

• Used in conditional branches

- jz: jump if zero

- jc: jump if carry



instructions

Data Movement



• Just one command: mov

- Used for
 - load
 - store
 - transfer between registers
 - copy from memory to memory

Stack Operations



• Basic stack operations

- push: place value on stack

- pop: retrieve value from stack

Jumps

- call: call a subroutine (store return address on stack)

- ret: return from sub routine

Arithmetic and Logic



• Basic math: add, sub, mul, div, neg

• Counter: inc, dec

• Boolean: and, or, xor, not

• Shift: shl, shr

Control



- Compare two values: cmp
- Test (Boolean and): test
- Map flags to register: setz, setnz, ...
- Jump: jmp
- Branch: jz, jnz, ...
- Conditional move: cmovz, cmovnz, ...

Code Example: Fibonacci



```
• Note: 32 bit indicated by
- l (long int) in instructions: movl
- extended register names: %eax, %ebx, %ecx, %edx
          movl $0, %ebx
                                       : ebx = secondlast = 1
          movl $1, %eax
                                       : eax = last = 0
      loop:
          cmp $0, %ecx
                                       ; %ecx is input value n
          jne end
                                       ; if n != 0 loop
          movl %eax, %edx
                                       ; tmp = last
          add %edx, %ebx
                                       ; tmp += secondlast
                                       : shift last -> secondlast
          movl %ebx, %eax
          movl %edx. %ebx
                                       ; shift tmp -> last
          dec %ecx
                                       : n = n - 1
          jmp loop
      end:
```

Vector Operations



- 128 bit allows encoding of 4 single precision floats (32 bit each)
- Instructions that
 - load vector of 4 floats into memory
 - multiply each element of a vector
 - store vector of 4 floats

• Example