



# FFTs in Graphics and Vision

Homogenous Polynomials  
and  
Irreducible Representations



# Outline

Homogenous Polynomials

Representations of Functions on the Unit-Circle

- Sub-Representations for the Circle
- Sub-Representations for the Sphere



# Monomials

## Definition:

A monomial in variables  $\{x_1, \dots, x_n\}$  is a product of non-negative integer powers of the variables.

The degree of a monomial is the sum of the powers.



# Monomials

## Examples:

- Degree 0: 1
- Degree 1:  $x, y, z$
- Degree 2:  $x^2, y^2, z^2, xy, xz, yz$
- Degree 3:  $x^3, x^2y, x^2z, xy^2, xz^2, xyz, y^3, y^2z, yz^2, z^3$



# Polynomials

## Definition:

A polynomial of degree  $d$  in variables  $\{x_1, \dots, x_n\}$  is a linear sum of monomials in  $\{x_1, \dots, x_n\}$ , each of whose degree is no greater than  $d$ .

## Notation:

Denote by  $P^d(x_1, \dots, x_n)$  the set of polynomials in  $\{x_1, \dots, x_n\}$  of degree  $d$ .



# Polynomials

## Examples:

- $d = 0$ :
  - $P^0(x) = P^0(x, y) = P^0(x, y, z) = a$
- $d = 1$ :
  - $P^1(x) = ax + c$
  - $P^1(x, y) = ax + by + c$
  - $P^1(x, y, z) = ax + by + cz + d$
- $d = 2$ :
  - $P^2(x) = ax^2 + bx + c$
  - $P^2(x, y) = ax^2 + by^2 + cxy + dx + ey + f$
  - $P^2(x, y, z) = ax^2 + by^2 + cz^2 + dxy + exz + gyz + hx + iy + jz + k$
- ...



# Polynomials

## Properties:

- The linear sum of polynomials  $p, q \in P^d(x_1, \dots, x_n)$  is a polynomial:

$$a \cdot p(x_1, \dots, x_n) + b \cdot q(x_1, \dots, x_n) \in P^d(x_1, \dots, x_n)$$

- The product of polynomials  $p \in P^{d_1}(x_1, \dots, x_n)$  and  $q \in P^{d_2}(x_1, \dots, x_n)$  is a polynomial:

$$p(x_1, \dots, x_n) \cdot q(x_1, \dots, x_n) \in P^{d_1+d_2}(x_1, \dots, x_n)$$

- The  $k$ -th power of a polynomial  $p \in P^d(x_1, \dots, x_n)$  is a polynomial:

$$p^k(x_1, \dots, x_n) \in P^{d \cdot k}(x_1, \dots, x_n)$$



# Homogenous Polynomials

## Definition:

A degree  $d$  polynomial is said to be homogenous if the individual monomials all have degree  $d$ .

## Notation:

Denote by  $HP^d(x_1, \dots, x_n)$  the set of homogenous polynomials in  $\{x_1, \dots, x_n\}$  of degree  $d$ .





# Homogenous Polynomials

## Examples:

- $d = 0$ :
  - $HP^0(x) = HP^0(x, y) = HP^0(x, y, z) = a$
- $d = 1$ :
  - $HP^1(x) = ax$
  - $HP^1(x, y) = ax + by$
  - $HP^1(x, y, z) = ax + by + cz$
- $d = 2$ :
  - $HP^2(x) = ax^2$
  - $HP^2(x, y) = ax^2 + by^2 + cxy$
  - $HP^2(x, y, z) = ax^2 + by^2 + cz^2 + dxy + exz + gyz$
- ...



# Homogenous Polynomials

## Properties:

- The linear sum of homogenous polynomials  $p, q \in HP^d(x_1, \dots, x_n)$  is a homogenous polynomial:  
$$a \cdot p(x_1, \dots, x_n) + b \cdot p(x_1, \dots, x_n) \in HP^d(x_1, \dots, x_n)$$
- The product of homogenous polynomials  $p \in HP^{d_1}(x_1, \dots, x_n)$  and  $q \in HP^{d_2}(x_1, \dots, x_n)$  is a homogenous polynomial:  
$$p(x_1, \dots, x_n) \cdot q(x_1, \dots, x_n) \in HP^{d_1+d_2}(x_1, \dots, x_n)$$
- The  $k$ -th power of a homogenous polynomial  $p \in HP^d(x_1, \dots, x_n)$  is a homogenous polynomial:  
$$p^k(x_1, \dots, x_n) \in HP^{d \cdot k}(x_1, \dots, x_n)$$



# Homogenous Polynomials

## Note 1:

Any degree  $d$  polynomial in  $\{x_1, \dots, x_n\}$  can be uniquely expressed as the sum of homogenous polynomials in  $\{x_1, \dots, x_n\}$  of degrees 0 through  $d$ :

$$P^d(x_1, \dots, x_n) = HP^0(x_1, \dots, x_n) \oplus \dots \oplus HP^d(x_1, \dots, x_n)$$



# Homogenous Polynomials

Note 1:

$$P^d(x_1, \dots, x_n) = HP^0(x_1, \dots, x_n) \oplus \dots \oplus HP^d(x_1, \dots, x_n)$$

Example:

$$\circ \underbrace{p(x, y)}_{\in P^2(x, y)} = \underbrace{2x^2 + 3y^2 - xy}_{\in HP^2(x, y)} + \underbrace{5x - 7y}_{\in HP^1(x, y)} + \underbrace{2}_{\in HP^0(x, y)}$$



# Homogenous Polynomials

## Note 2:

Any homogenous polynomial in  $\{x_1, \dots, x_n\}$  of degree  $d$  can be uniquely expressed as:

- $x_1$  times a degree  $d - 1$  homogenous polynomial in  $\{x_1, \dots, x_n\}$ , plus
- a degree  $d$  homogenous polynomial in  $\{x_2, \dots, x_n\}$ .

$$HP^d(x_1, \dots, x_n) = x_1 \cdot HP^{d-1}(x_1, \dots, x_n) \oplus HP^d(x_2, \dots, x_n)$$



# Homogenous Polynomials

Note 2:

$$HP^d(x_1, \dots, x_n) = x_1 \cdot HP^{d-1}(x_1, \dots, x_n) \oplus HP^d(x_2, \dots, x_n)$$

Example:

$$\begin{aligned} \circ \quad \underbrace{p(x, y)}_{\in HP^2(x, y)} &= 2x^2 + 3y^2 - xy \\ &= x \cdot \underbrace{(2x - y)}_{\in HP^1(x, y)} + \underbrace{3y^2}_{\in HP^2(y)} \end{aligned}$$



# Dimensions

What is the dimension of  $P^d(x_1, \dots, x_n)$ ?

Since every polynomial of degree  $d$  can be uniquely expressed as the sum of homogenous polynomials of degrees 0 through  $d$ :

$$\dim\left(P^d(x_1, \dots, x_n)\right) = \dim\left(HP^0(x_1, \dots, x_n)\right) + \dots + \dim\left(HP^d(x_1, \dots, x_n)\right)$$



# Dimensions

What is the dimension of  $HP^d(x_1, \dots, x_n)$ ?





# Dimensions

Three properties give us a recursive definition:

1. A homogenous polynomial of degree  $d$  factors as:

$$HP^d(x_1, \dots, x_n) = x_1 \cdot HP^{d-1}(x_1, \dots, x_n) \oplus HP^d(x_2, \dots, x_n)$$

2. The space of homogenous polynomials in  $\{x_1, \dots, x_n\}$  of degree 0 is one-dimensional:

$$HP^0(x_1, \dots, x_n) = a$$

3. The space of homogenous polynomials in  $\{x\}$  of degree  $d$  is one-dimensional:

$$HP^d(x) = ax^d$$



# Dimensions

## Homogenous Polynomials of Degree Zero:

The dimension of the space of homogenous polynomials of degree 0 in any number of variables is one:

$$\dim[HP^0(x_1, \dots, x_n)] = 1$$



# Dimensions

## Homogenous Polynomials in One Variable:

The dimension of the space of homogenous polynomials of degree  $d$  in one variable is one, for all degrees  $d$ :

$$\dim[HP^d(x)] = 1$$



# Dimensions

## Homogenous Polynomials in $n$ Variables:

The dimension of the space of homogenous polynomials of degree  $d$  in  $n$  variables is:

$$\dim[HP^d(x_1, \dots, x_n)] = \dim[HP^d(x_2, \dots, x_n)] \\ + \dim[HP^{d-1}(x_1, \dots, x_n)]$$



# Dimensions

## Homogenous Polynomials in $n$ Variables:

The dimension of the space of homogenous polynomials of degree  $d$  in  $n$  variables is:

$$\begin{aligned}\dim[HP^d(x_1, \dots, x_n)] &= \dim[HP^d(x_2, \dots, x_n)] \\ &\quad + \dim[HP^{d-1}(x_2, \dots, x_n)] \\ &\quad + \dim[HP^{d-2}(x_1, \dots, x_n)]\end{aligned}$$



# Dimensions

## Homogenous Polynomials in $n$ Variables:

The dimension of the space of homogenous polynomials of degree  $d$  in  $n$  variables is:

$$\dim[HP^d(x_1, \dots, x_n)] = \sum_{i=1}^d \dim[HP^i(x_2, \dots, x_n)] + \dim[HP^0(x_1, \dots, x_n)]$$



# Dimensions

## Homogenous Polynomials in $n$ Variables:

The dimension of the space of homogenous polynomials of degree  $d$  in  $n$  variables is:

$$\dim[HP^d(x_1, \dots, x_n)] = \sum_{i=0}^d \dim[HP^i(x_2, \dots, x_n)]$$



# Dimensions

$$\dim[HP^d(x_1, \dots, x_n)] = \sum_{i=0}^d \dim[HP^i(x_2, \dots, x_n)]$$

Homogenous Polynomials in  $n$  Variables:

One Variable:

$$\dim[HP^d(x)] = 1$$





# Dimensions

$$\dim[HP^d(x_1, \dots, x_n)] = \sum_{i=0}^d \dim[HP^i(x_2, \dots, x_n)]$$
$$\dim[HP^d(x)] = 1$$

Homogenous Polynomials in  $n$  Variables:

Two Variables:

$$\begin{aligned} \dim[HP^d(x, y)] &= \sum_{i=0}^d \dim[HP^i(x)] \\ &= \sum_{i=0}^d 1 \\ &= d + 1 \end{aligned}$$



# Dimensions

$$\dim[HP^d(x_1, \dots, x_n)] = \sum_{i=0}^d \dim[HP^i(x_2, \dots, x_n)]$$
$$\dim[HP^d(x, y)] = d + 1$$

Homogenous Polynomials in  $n$  Variables:

Three Variables:

$$\begin{aligned} \dim[HP^d(x, y, z)] &= \sum_{i=0}^d \dim[HP^i(x, y)] \\ &= \sum_{i=0}^d (i + 1) \\ &= \frac{(d + 2) \cdot (d + 1)}{2} \end{aligned}$$



# Dimensions

## Homogenous Polynomials in $n$ Variables:

One Variable:  $\dim[HP^d(x)] = 1$

Two Variables:  $\dim[HP^d(x, y)] = d + 1$

Three Variables:  $\dim[HP^d(x, y, z)] = \frac{(d+2) \cdot (d+1)}{2}$



# Outline

Homogenous Polynomials

Representations of Functions on the Unit-Circle

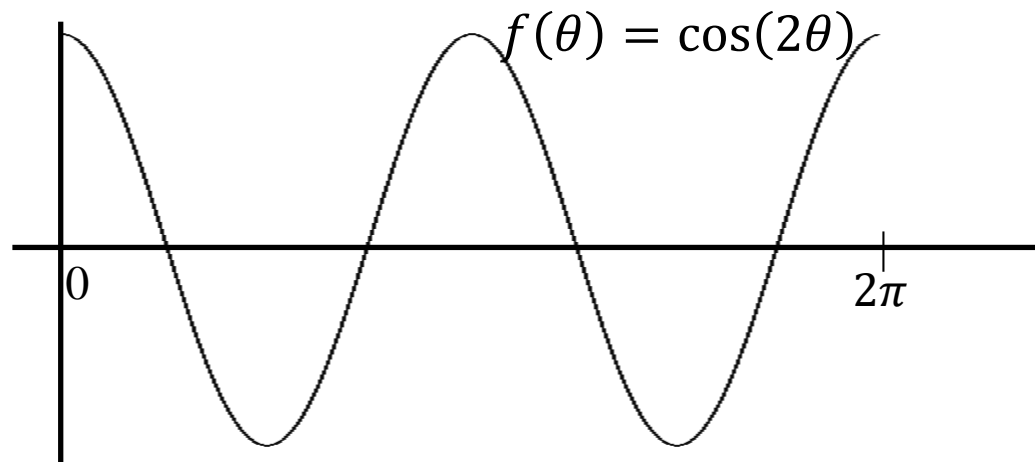
- Sub-Representations for the Circle
- Sub-Representations for the Sphere



# Representing Functions on the Unit-Circle

There are two ways we can represent a function on the unit-circle:

1. By Parameter: Every point on the circle can be represented by an angle in the range  $[0, 2\pi)$ .  
 $\Rightarrow$  We can represent circular functions as 1D functions on the domain  $[0, 2\pi)$ .





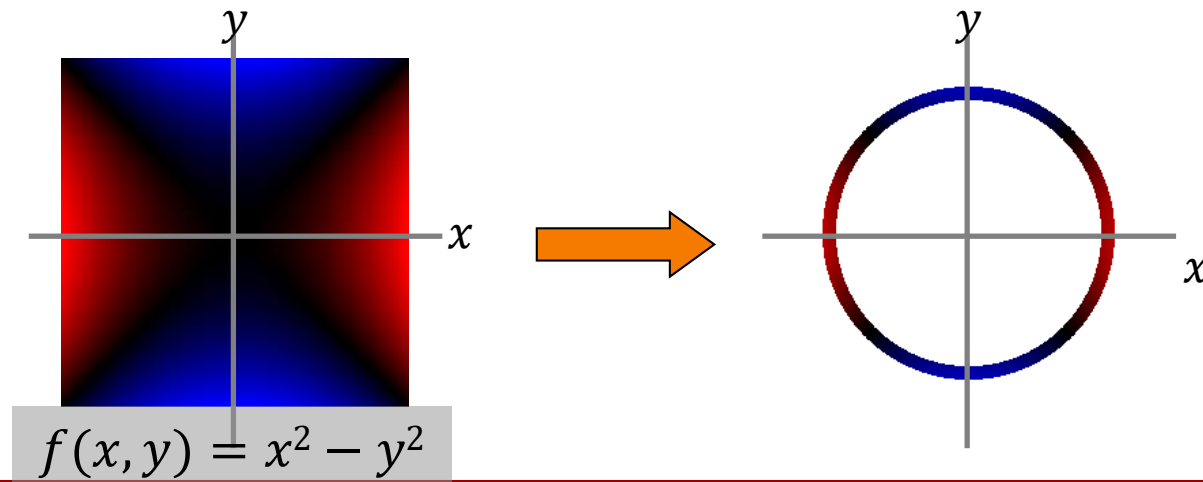
# Representing Functions on the Unit-Circle

There are two ways we can represent a function on the unit-circle:

2. By Restriction: We know that the unit-circle “lives” in 2D, i.e. it is the set of points  $(x, y)$  satisfying:

$$x^2 + y^2 = 1$$

⇒ We can represent circular functions by looking at the restriction of 2D functions to the unit-circle.





# Representing By Restriction

## Observation 1:

On a circle, a point with angle  $\theta$  has  $x$ - and  $y$ -coordinates given by:

$$x = \cos(\theta) \quad y = \sin(\theta)$$

This lets us transform a (circular) function represented by the restriction of a 2D function  $f(x, y)$  to a function represented by parameter:

$$f(x, y) \rightarrow g(\theta) \equiv f(\cos \theta, \sin \theta)$$



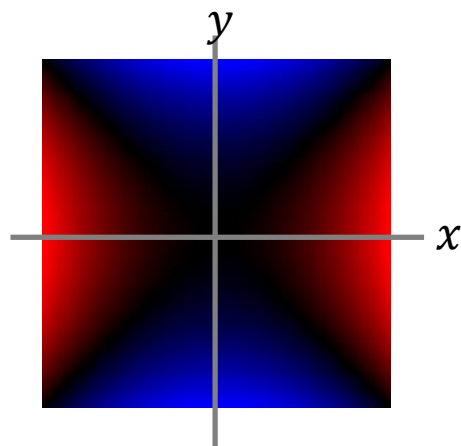
# Representing By Restriction

Example: If the circular function is defined as the restriction of the 2D function:

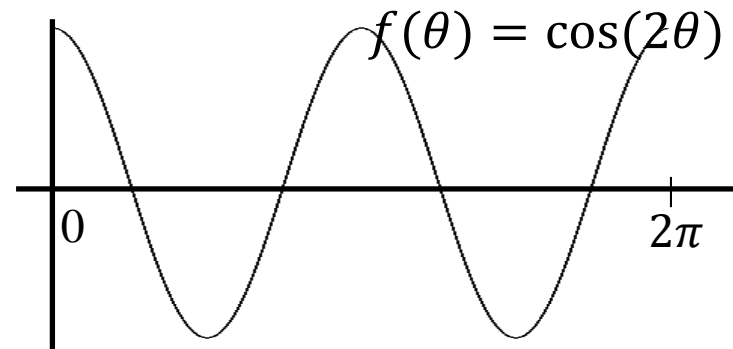
$$f(x, y) = x^2 - y^2$$

Then the representation in terms of angle is:

$$\begin{aligned} g(\theta) &= \cos^2 \theta - \sin^2 \theta \\ &= \cos 2\theta \end{aligned}$$



$$f(x, y) = x^2 - y^2$$



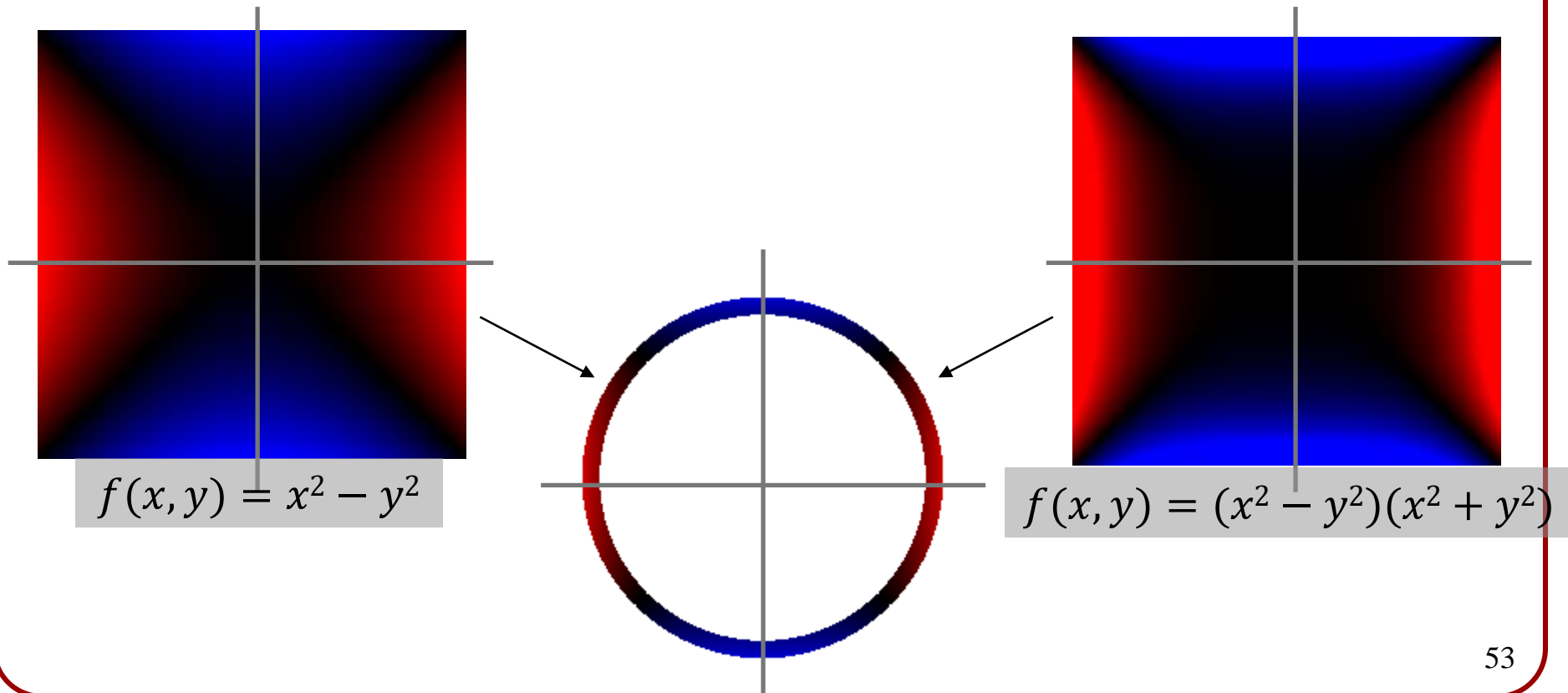




# Representing By Restriction

## Observation 2:

Two different functions in 2D, can have the same restriction to the unit-circle.





# Outline

Homogenous Polynomials

Representations of Functions on the Unit-Circle

- Sub-Representations for the Circle
- Sub-Representations for the Sphere



# Irreducible Representations

Recall:

In shape/image analysis tasks:

- Rotation invariant representation
- Image filtering
- Symmetry detection
- (2D) Rotational alignment

we needed to consider the representation of the group of 2D rotations on the space of circular functions.



# Irreducible Representations

Recall:

To perform these tasks efficiently and/or effectively, we depended on Schur's Lemma.

⇒ Since the group was commutative, the irreducible representations were all one (complex) dimensional



# Irreducible Representations

Challenge:

We know that the irreducible representations exist. How do we find them?



# Sub-Representations

How do we find a sub-space of functions that is also a sub-representation?

$\Leftrightarrow$  How do we find a space of functions such that a rotation of a function from this space gives some other function in the space?



# Fourier Basis

For the circles, we know that these spaces are one-dimensional, spanned by:

$$f_k(\theta) = e^{ik\theta}$$

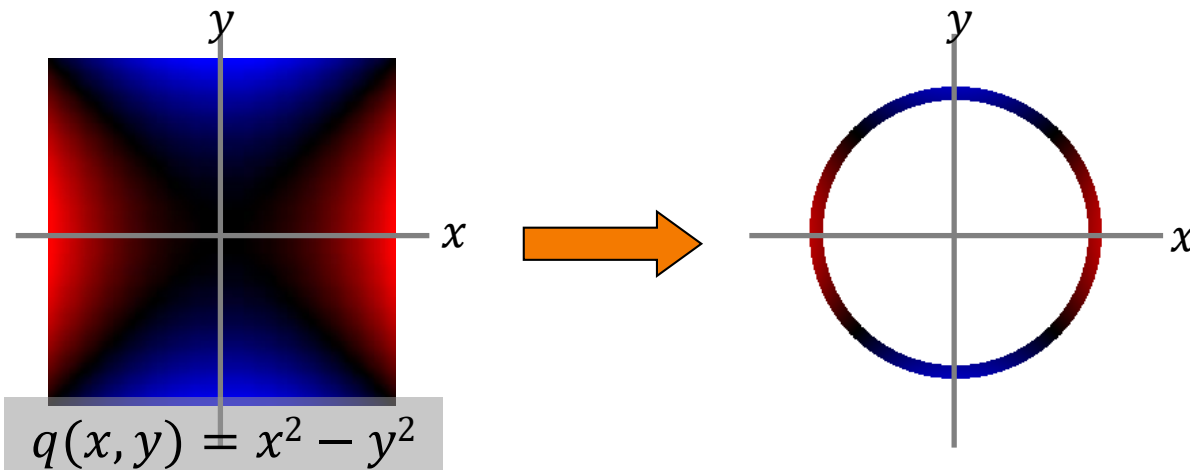
But how would we go about finding them if we didn't know?



# Polynomials

Consider the circular functions that are obtained by restricting degree  $d$  polynomials to the circle:

$$q(x, y) = \sum_{j+k \leq d} a_{jk} \cdot x^j \cdot y^k$$







# Polynomials

Consider the circular functions that are obtained by restricting degree  $d$  polynomials to the circle:

$$q(x, y) = \sum_{j+k \leq d} a_{jk} \cdot x^j \cdot y^k$$

How does a rotation act on this function?

$$R = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$



# Polynomials

Rotations act on the space of functions by rotating the domain of evaluation:

$$(\rho_R(q))(x, y) = q(R^{-1}(x, y))$$

Since the inverse of a rotation is its transpose, the rotation  $R^{-1}$ , acts on the 2D space by:

$$R^{-1}(x, y) = (ax + cy, bx + dy)$$



# Polynomials

$$(\rho_R(q))(x, y) = q(ax + cy, bx + dy)$$

⇒ The rotation acts on the polynomial:

$$q(x, y) = \sum_{j+k \leq d} a_{jk} \cdot x^j \cdot y^k$$

by sending it to:

$$(\rho_R(q))(x, y) = \sum_{j+k \leq d} a_{jk} \cdot \underbrace{(ax + cy)^j}_{\text{Degree 1}} \cdot \underbrace{(bx + dy)^k}_{\text{Degree 1}}$$



# Polynomials

$$(\rho_R(q))(x, y) = q(ax + cy, bx + dy)$$

⇒ The rotation acts on the polynomial:

$$q(x, y) = \sum_{j+k \leq d} a_{jk} \cdot x^j \cdot y^k$$

by sending it to:

$$(\rho_R(q))(x, y) = \sum_{j+k \leq d} a_{jk} \cdot \underbrace{(ax + cy)^j}_{\text{Degree } j} \cdot \underbrace{(bx + dy)^k}_{\text{Degree } k}$$



# Polynomials

$$(\rho_R(q))(x, y) = q(ax + cy, bx + dy)$$

⇒ The rotation acts on the polynomial:

$$q(x, y) = \sum_{j+k \leq d} a_{jk} \cdot x^j \cdot y^k$$

by sending it to:

$$(\rho_R(q))(x, y) = \sum_{j+k \leq d} a_{jk} \cdot \underbrace{(ax + cy)^j \cdot (bx + dy)^k}_{\text{Degree } j + k}$$

⇒ Since  $j + k \leq d$ , the rotation of  $q(x, y)$  by  $R$  is also a polynomial of degree  $d$ .



# Polynomials

If we start with a polynomial of degree  $d$ :

$$q(x, y) \in P^d(x, y)$$

and we apply any rotation  $R$  to it, the rotated polynomial will also be a polynomial of degree  $d$ :

$$\rho_R(q) \in P^d(x, y)$$

$\Rightarrow$  The space of functions obtained by restricting polynomials of degree  $d$  to the unit circle is a sub-representation.



# Polynomials

We can repeat the argument for restrictions of homogenous polynomials:

$$q(x, y) = \sum_{j+k=d} a_{jk} \cdot x^j \cdot y^k$$
$$\Updownarrow$$

$$(\rho_R(q))(x, y) = \sum_{j+k=d} a_{jk} \cdot (ax + cy)^j \cdot (bx + dy)^k$$



# Polynomials

We can repeat the argument for restrictions of homogenous polynomials:

$$q(x, y) = \sum_{j+k=d} a_{jk} \cdot x^j \cdot y^k$$

$\Updownarrow$

$$(\rho_R(q))(x, y) = \sum_{j+k=d} a_{jk} \cdot \underbrace{(ax + cy)^j}_{\text{Degree 1}} \cdot \underbrace{(bx + dy)^k}_{\text{Degree 1}}$$





# Polynomials

We can repeat the argument for restrictions of homogenous polynomials:

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# Polynomials

We can repeat the argument for restrictions of homogenous polynomials:

$$q(x, y) = \sum_{j+k=d} a_{jk} \cdot x^j \cdot y^k$$
$$\Updownarrow$$

$$(\rho_R(q))(x, y) = \sum_{j+k=d} a_{jk} \cdot \underbrace{(ax + cy)^j \cdot (bx + dy)^k}_{\text{Degree } j + k}$$

⇒ The space of functions obtained by restricting homogenous polynomials of degree  $d$  to the unit circle is a sub-representation.



# Homogenous Polynomials

How small are these sub-representations?

The space of homogenous polynomials of degree  $d$  in two variables is  $(d + 1)$ -dimensional.

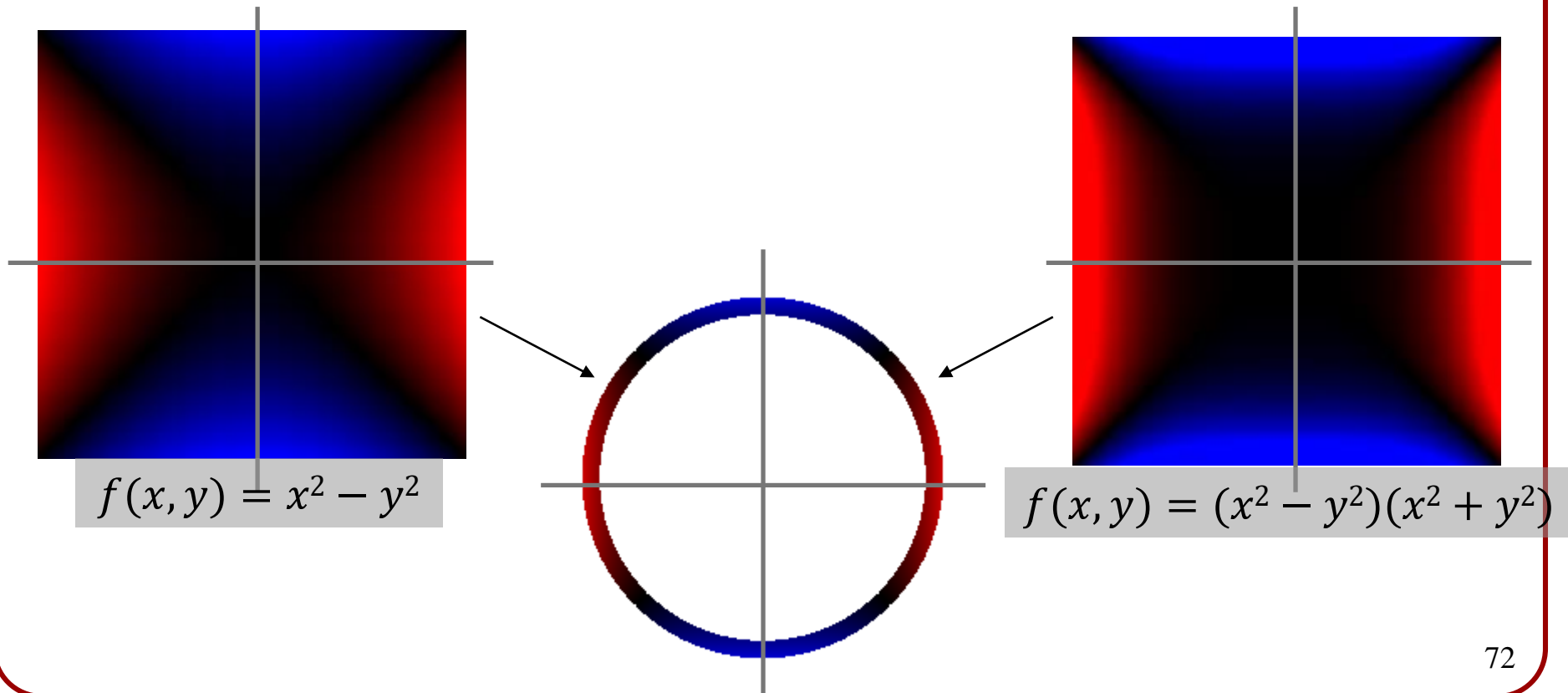
We know that the irreducible representations all have to be one-dimensional – what's going on?



# Homogenous Polynomials

Recall:

Two different functions in 2D, can have the same restriction to the unit-circle.





# Homogenous Polynomials

Note that every point  $(x, y)$  on the circle satisfies:

$$x^2 + y^2 = 1$$

$\Rightarrow$  For any  $q(x, y) \in HP^d(x, y)$ , the homogenous polynomial  $q(x, y) \cdot (x^2 + y^2) \in HP^{d+2}(x, y)$  will have the same restriction to the unit circle.



# Homogenous Polynomials

When considering the restriction of homogenous polynomials to the circle, degree  $d$  polynomials are “contained” in the restriction of the degree  $(d + 2)$  polynomials.

Since the restrictions of degree  $d$  polynomials to the circle form a sub-representation, we want the polynomials of degree  $(d + 2)$  whose restrictions are orthogonal to those of degree  $d$  polynomials.



# Homogenous Polynomials

## Example:

- $d = 0$ :

$HP^d(x, y)$  is spanned by  $\{1\}$  so the restriction is the space of constant functions.



# Homogenous Polynomials

## Example:

- $d = 1$ :

$HP^d(x, y)$  is spanned by  $\{x, y\}$  so the restriction is the space of functions  $ax + by$ .

Since we can write out the  $x$  and  $y$  coordinates in terms of the angle  $\theta$ :

$$x = \cos \theta \quad y = \sin \theta$$

this gives the space of functions of the form:

$$f(\theta) = a \cdot \cos \theta + b \cdot \sin \theta$$





# Homogenous Polynomials

## Example:

- $d = 2$ :

$HP^d(x, y)$  is spanned by  $\{x^2, xy, y^2\}$  so the restriction is the space of functions of the form  $ax^2 + bxy + cy^2$ . In terms of the angle, this gives the space of functions of the form:

$$f(\theta) = a \cdot \cos^2 \theta + b \cdot \cos \theta \cdot \sin \theta + c \cdot \sin^2 \theta$$



# Homogenous Polynomials

## Example:

- $d = 2$ :

$$f(\theta) = a \cdot \cos^2 \theta + b \cdot \cos \theta \cdot \sin \theta + c \cdot \sin^2 \theta$$

Since we know that:

$$\cos^2 \theta + \sin^2 \theta = 1$$

is a constant function accounted for by the  $d = 0$  case, we want the space of homogenous polynomial restrictions that are perpendicular to those accounted for by the  $d = 0$  case.



# Homogenous Polynomials

## Example:

- $d = 2$ :

A function of the form:

$$f(\theta) = a \cdot \cos^2 \theta + b \cdot \cos \theta \cdot \sin \theta + c \cdot \sin^2 \theta$$

is perpendicular to the function:

$$\cos^2 \theta + \sin^2 \theta = 1$$

if and only if:

$$0 = \langle 1, a \cdot \cos^2 \theta + b \cdot \cos \theta \cdot \sin \theta + c \cdot \sin^2 \theta \rangle$$



# Homogenous Polynomials

Example:

- $d = 2$ :

$$0 = \langle 1, a \cdot \cos^2 \theta + b \cdot \cos \theta \cdot \sin \theta + c \cdot \sin^2 \theta \rangle$$

$$\Downarrow$$

$$0 = \int_0^{2\pi} (a \cdot \cos^2 \theta + b \cdot \cos \theta \cdot \sin \theta + c \cdot \sin^2 \theta) d\theta$$

$$\Downarrow$$

$$0 = a \cdot \pi + c \cdot \pi$$

$$\Downarrow$$

$$a = -c$$



# Homogenous Polynomials

## Example:

- $d = 2$ :

Homogenous polynomials of degree two can be expressed as:

$$f(\theta) = a \cdot \cos^2 \theta + b \cdot \cos \theta \cdot \sin \theta + c \cdot \sin^2 \theta$$

and orthogonality implies that:

$$c = -a$$

$\Rightarrow$  A basis for the sub-representation is:

$$\{\cos^2 \theta - \sin^2 \theta, \cos \theta \cdot \sin \theta\}$$



$$\{\cos 2\theta, \sin 2\theta\}$$



# Homogenous Polynomials

## Example:

- $d \geq 2$ :

As in the  $d = 2$  case, we start with the space of homogenous polynomials of degree  $d$ .

Since the space of homogenous polynomials of degree  $d - 2$  is contained in this space, we “remove” the degree  $d - 2$  polynomials.

Thus, the final dimension of the sub-representation is:

$$\dim[HP^d(x, y)] - \dim[HP^{d-2}(x, y)] = (d + 1) - (d - 1) = 2$$



# Homogenous Polynomials

## Example:

- $d \geq 2$ :

As in the  $d = 2$  case, that the two functions:  
 $\{\cos d\theta, \sin d\theta\}$   
are a basis for the sub-representation.



# Homogenous Polynomials

Note:

These sub-representations are not irreducible.

By Schur's lemma, the irreducible representations are all one-dimensional and for  $d > 0$ , we are getting two-dimensional sub-representations.

To get the irreducible representations, we need to further break apart these sub-representations.

$$\{\cos d\theta, \sin d\theta\} = \begin{Bmatrix} \cos d\theta + i \sin d\theta \\ \cos d\theta - i \sin d\theta \end{Bmatrix} = \begin{Bmatrix} e^{id\theta} \\ e^{-id\theta} \end{Bmatrix}$$

These two-dimensional representations are irreducible representations for the group of orthogonal transformations (i.e. rotations and reflections).





# Outline

Homogenous Polynomials

Representations of Functions on the Unit-Circle

- Sub-Representations for the Circle
- Sub-Representations for the Sphere



# Spherical Functions

As in the case of circular functions, we would like to find the sub-representations of the spherical functions – sub-spaces of spherical functions which get rotated back into themselves.



# Spherical Functions

As in the case of circular functions, we would like to find the sub-representations of the spherical functions – sub-spaces of spherical functions which get rotated back into themselves.

In this case, the group does not commute, so we do not expect the sub-representations to be one-dimensional.



# Homogenous Polynomials

As with circular functions, we consider spherical functions obtained by restricting homogenous polynomials of degree  $d$  to the unit sphere:

$$q(x, y, z) = \sum_{j+k+l=d} a_{jkl} \cdot x^j \cdot y^k \cdot z^l$$



# Homogenous Polynomials

If  $R$  is a rotation:

$$R = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$$

then  $R$  will rotate the polynomial  $q$  by:

$$\begin{aligned} (\rho_R(q))(x, y, z) &= \\ &= \sum_{j+k+l=d} a_{jkl} \cdot (ax + dy + gz)^j \cdot (bx + ey + hz)^k \cdot (cx + fy + iz)^l \end{aligned}$$

Again, rotations fix the space of homogenous polynomials – mapping homogenous polynomials of degree  $d$  back into homogenous polynomials of degree  $d$ .



# Homogenous Polynomials

As in the 2D case, we know that the restrictions of homogenous polynomials of degree  $d$  to the unit sphere contain the restrictions of homogenous polynomials of degree  $d - 2$  to the unit sphere.

So for any  $q(x, y, z) \in HP^d(x, y, z)$ , the polynomial  $q(x, y, z) \cdot (x^2 + y^2 + z^2) \in HP^{d+2}(x, y, z)$  will have the same restriction to the unit sphere.



# Homogenous Polynomials

⇒ Sub-representations can be obtained by considering the restrictions of homogenous polynomials of degree  $d$  to the unit sphere, and removing those that were already accounted for at degree  $d - 2$ .

⇒ The dimension of the space obtained from the degree  $d$  homogenous polynomials will be:

$$\begin{aligned} & \dim[HP^d(x, y, z)] - \dim[HP^{d-2}(x, y, z)] \\ &= \frac{(d+2) \cdot (d+1)}{2} - \frac{d \cdot (d-1)}{2} \\ &= 2d + 1 \end{aligned}$$



# Homogenous Polynomials

⇒ Sub-representations can be obtained by considering the restrictions of homogenous polynomials of degree  $d$  to the unit sphere, and removing those that were already accounted for at degree  $d - 2$ .

⇒ The dimension of the space obtained from the degree  $d$  homogenous polynomials will be:

$$\dim[HP^d(x, y, z)] - \dim[HP^{d-2}(x, y, z)] =$$

It turns out that for spherical functions, these are the irreducible representations for the group of rotations.