

# FFTs in Graphics and Vision

More Math Review

### **Outline**



### Inner Product Spaces

- Real Inner Products
- Hermitian Inner Products
- Orthogonal Transforms
- Unitary Transforms
- Function Spaces



Given a real vector space V, a real inner product is a function  $\langle \cdot, \cdot \rangle$ :  $V \times V \to \mathbb{R}$  that takes a pair of vectors and returns a real value.



An inner product is a map from  $V \times V$  into the real numbers that is:

- 1. Linear: For all  $u, v, w \in V$  and  $\lambda \in \mathbb{R}$ :  $\langle u + v, w \rangle = \langle u, w \rangle + \langle v, w \rangle$   $\langle \lambda v, w \rangle = \lambda \langle v, w, \rangle$
- 2. Symmetric: For all  $v, w \in V$ :  $\langle v, w \rangle = \langle w, v \rangle$
- 3. Positive Definite: For all  $v \in V$ :  $\langle v, v \rangle \ge 0$   $\langle v, v \rangle = 0 \Leftrightarrow v = 0$



An inner product defines a notion of distance on a vector space by setting:

$$D(v, w) = \sqrt{\langle v - w, v - w \rangle} = ||v - w||$$



### Examples:

1. On the space of n-dimensional arrays, the standard inner product is:

$$\langle (a_1, \cdots, a_n), (b_1, \cdots, b_n) \rangle = a_1 \cdot b_1 + \cdots + a_n \cdot b_n$$
$$= (a_1, \cdots, a_n) \cdot (b_1, \cdots b_n)^t$$



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$$= (a_1, \cdots, a_n) \cdot (b_1, \cdots b_n)^t$$

On the space of continuous, real-valued functions, defined on a circle, the standard inner product is:

$$\langle f, g \rangle = \int_0^{2\pi} f(\theta) \cdot g(\theta) d\theta$$



#### **Examples**:

3. Suppose we have the space of n-dimensional arrays, and suppose we have a matrix:

$$M = \begin{pmatrix} M_{11} & \cdots & M_{1n} \\ \vdots & \ddots & \vdots \\ M_{n1} & \cdots & M_{nn} \end{pmatrix}$$

Does the map:

$$\langle v, w \rangle_M = v^t M w$$

define an inner product?



### **Examples**:

3. Does the map:

$$\langle v, w \rangle_M = v^t M w$$

define an inner product?

- Is it linear?
- Is it symmetric?
- Is it positive definite?



#### **Examples**:

$$\langle v, w \rangle_M = v^t M w$$

Is it linear?

$$\langle u + v, w \rangle_{M} = (u + v)^{t} M w$$

$$= (u^{t} + v^{t}) M w$$

$$= u^{t} M w + v^{t} M w$$

$$= \langle u, w \rangle_{M} + \langle v, w \rangle_{M}$$



#### **Examples**:

$$\langle v, w \rangle_M = v^t M w$$

Is it linear?

$$\langle u + v, w \rangle_M = \langle u, w \rangle_M + \langle v, w \rangle_M$$

$$\langle \lambda v, w \rangle_{M} = (\lambda v)^{t} M w$$
$$= \lambda v^{t} M w$$
$$= \lambda \langle v, w \rangle_{M}$$



#### **Examples**:

$$\langle v, w \rangle_M = v^t M w$$

Is it linear? Yes

$$\langle u + v, w \rangle_M = \langle u, w \rangle_M + \langle v, w \rangle_M$$

$$\langle \lambda v, w \rangle_M = \lambda \langle v, w \rangle_M$$



#### **Examples**:

$$\langle v, w \rangle_M = v^t M w$$

Is it symmetric?

$$\langle w, v \rangle_{M} = w^{t} M v$$

$$= (w^{t} M v)^{t}$$

$$= v^{t} M^{t} w$$

$$= \langle v, w \rangle_{M^{t}}$$



### **Examples**:

$$\langle v, w \rangle_M = v^t M w$$

• Is it symmetric? Only if M is  $(M = M^t)$  $\langle w, v \rangle_M = \langle v, w \rangle_{M^t}$ 



### **Examples**:

$$\langle v, w \rangle_M = v^t M w$$

Is it positive definite?

If M is symmetric, there exists an orthogonal basis  $\{v_1, ..., v_n\}$  w.r.t which M is diagonal:

$$M = B^{t} \begin{pmatrix} \lambda_{1} & 0 & \dots & 0 & 0 \\ 0 & \lambda_{2} & \dots & 0 & 0 \\ \vdots & \ddots & & \vdots & \\ 0 & 0 & \dots & \lambda_{n-1} & 0 \\ 0 & 0 & \dots & 0 & \lambda_{n} \end{pmatrix} B$$



### **Examples**:

$$\langle v, w \rangle_M = v^t M w$$

Is it positive definite?

If we express v in terms of this basis:

$$v = a_1 v_1 + \dots + a_n v_n$$

then:

$$\langle v, v \rangle_M = \lambda_1 a_1^2 + \dots + \lambda_n a_n^2$$



### **Examples**:

$$\langle v, w \rangle_M = v^t M w$$

• Is it positive definite? Only if  $\lambda_i > 0$  for all i.

If we express v in terms of this basis:

$$v = a_1 v_1 + \dots + a_n v_n$$

then:

$$\langle v, v \rangle_M = \lambda_1 a_1^2 + \dots + \lambda_n a_n^2$$



### **Examples**:

4. On the space of continuous, real-valued functions, defined on a circle, does the map:

$$\langle f, g \rangle = \int_0^{2\pi} f(\theta) \cdot g(\theta) \cdot \omega(\theta) d\theta$$

define an inner product?



#### **Examples**:

4. On the space of continuous, real-valued functions, defined on a circle, does the map:

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define an inner product? No



### **Examples**:

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define an inner product? No What if  $\omega(\theta) > 0$ ? Yes

## **Hermitian Inner Product Spaces**



Given a complex vector space V, a Hermitian inner product is a function  $\langle \cdot, \cdot \rangle$ :  $V \times V \to \mathbb{C}$  that takes a pair of vectors and returns a complex value.

# **Hermitian Inner Product Spaces**



A Hermitian inner product is a map from  $V \times V$  into  $\mathbb{C}$  that is:

- 1. Linear: For all  $u, v, w \in V$  and any  $\lambda \in \mathbb{C}$ :  $\langle u + v, w \rangle = \langle u, w \rangle + \langle v, w \rangle$   $\langle \lambda v, w \rangle = \lambda \langle v, w \rangle$
- 2. Conjugate Symmetric: For all  $u, v \in V$ :  $\langle v, w \rangle = \overline{\langle w, v \rangle}$
- 3. Positive Definite: For all  $v \in V$ :  $\langle v, v \rangle \ge 0$   $\langle v, v \rangle = 0 \Leftrightarrow v = 0$



As in the real case, a Hermitian inner product defines a notion of distance on a complex vector space by setting:

$$D(v, w) = \sqrt{\langle v - w, v - w \rangle} = ||v - w||$$

# **Hermitian Inner Product Spaces**



#### **Examples**:

1. On complex-valued, *n*-dimensional arrays, the standard Hermitian inner product is:

$$\langle (a_1, \cdots, a_n), (b_1, \cdots, b_n) \rangle = a_1 \cdot \overline{b_1} + \cdots + a_n \cdot \overline{b_n}$$
$$= (a_1, \cdots, a_n) \cdot (\overline{b_1}, \cdots, \overline{b_n})^t$$

# **Hermitian Inner Product Spaces**



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$$= (a_1, \cdots, a_n) \cdot (\overline{b_1}, \cdots, \overline{b_n})^t$$

On the space of continuous, complex-valued functions, defined on a circle, the standard Hermitian inner product is:

$$\langle f, g \rangle = \int_0^{2\pi} f(\theta) \cdot \overline{g(\theta)} \, d\theta$$



#### Recall:

If we have an n-dimensional vector space V then a linear map L is a function from V to V that preserves the linear structure:

 $L(a \cdot v_1 + b \cdot v_2) = a \cdot L(v_1) + b \cdot L(v_2)$  for all  $v, w \in V$  and all scalars a and b.



#### Recall:

If we have an n-dimensional vector space V then a linear map L is a function from V to V that preserves the linear structure:

$$L(a \cdot v_1 + b \cdot v_2) = a \cdot L(v_1) + b \cdot L(v_2)$$
 for all  $v, w \in V$  and all scalars  $a$  and  $b$ .

If L is invertible, then we can think of L as a function that "renames" all the elements in V while preserving the underlying vector space structure.



### Orthogonal Transformations:

For a real vector space *V* that has an inner product, we would also like to consider those functions that "rename" the elements of *V* while preserving the underlying structure.



### **Orthogonal Transformations:**

For a real vector space *V* that has an inner product, we would also like to consider those functions that "rename" the elements of *V* while preserving the underlying structure.

#### If *R* is such a function, then:

- R must be an invertible linear operator, in order to preserve the underlying vector space structure.
- R must also preserve the underlying inner product.



### **Orthogonal Transformations:**

For a real inner-product space V, a linear operator R is called <u>orthogonal</u> if it preserves the inner product:

$$\langle R(v), R(w) \rangle = \langle v, w \rangle$$

for all  $v, w \in V$ .



### Example:

On the space of real-valued, n-dimensional arrays, a matrix is orthogonal if:

$$\langle R(v), R(w) \rangle = \langle v, w \rangle$$

$$\updownarrow$$

$$(Rv)^{t}(Rw) = v^{t}w$$

$$\updownarrow$$

$$v^{t}R^{t}Rw = v^{t}w$$

$$\updownarrow$$

$$R^{t} = R^{-1}$$



#### Example:

On the space of real-valued, n-dimensional arrays, a matrix is orthogonal if:

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### Example:

On the space of real-valued, n-dimensional arrays, a matrix is orthogonal if:

$$R^t = R^{-1}$$

Note: The determinant of an orthogonal matrix always has absolute value 1:

```
[\det(R)]^2 = \det(R) \cdot \det(R^t)
= \det(R) \cdot \det(R^{-1})
= \det(RR^{-1})
= 1
```



### Example:

On the space of real-valued, n-dimensional arrays, a matrix is orthogonal if:

$$R^t = R^{-1}$$

Note: The determinant of an orthogonal matrix always has absolute value 1.

If the determinant of an orthogonal matrix is equal to 1, the matrix is called a <u>rotation</u>.

# Orthogonal Matrices and Eigenvalues

If R is an orthogonal transformation and R has an eigenvalue  $\lambda$ , then  $|\lambda| = 1$ .

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If R is an orthogonal transformation and R has an eigenvalue  $\lambda$ , then  $|\lambda| = 1$ .

To see this, let v be the e.vector corresponding to the e.value  $\lambda$ . Since R is orthogonal, we have:

$$\langle v, v \rangle = \langle Rv, Rv \rangle$$
  
=  $\langle \lambda v, \lambda v \rangle$   
=  $\lambda^2 \langle v, v \rangle$ 

so  $\lambda^2 = 1$ .



#### **Unitary Transformations:**

For a complex vector space V, an invertible linear operator R is called <u>unitary</u> if it preserves the hermitian inner product:

$$\langle Rv, Rw \rangle = \langle v, w \rangle$$

for all  $v, w \in V$ .



#### Example:

On the space of complex-valued, n-dimensional arrays, a matrix is unitary if:

$$\langle Rv, Rw \rangle = \langle v, w \rangle$$

$$\downarrow \\ (Rv)^t \overline{(Rw)} = v^t \overline{w}$$

$$\downarrow \\ v^t R^t \overline{R} \overline{w} = v^t \overline{w}$$

$$\downarrow \\ \overline{R}^t = R^{-1}$$



#### Example:

On the space of complex-valued, n-dimensional arrays, a matrix is unitary if:

$$\bar{R}^t = R^{-1}$$



#### Example:

On the space of complex-valued, n-dimensional arrays, a matrix is unitary if:

$$\bar{R}^t = R^{-1}$$

Note: The determinant of a unitary matrix always has norm 1:

$$\|\det(R)\|^2 = \det(R) \cdot \det(\overline{R}^t)$$

$$= \det(R) \cdot \det(R^{-1})$$

$$= \det(RR^{-1})$$

$$= 1$$

# **Unitary Matrices and Eigenvalues**



If R is a unitary transformation and R has an eigenvalue  $\lambda$ , then  $||\lambda|| = 1$ .

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If R is a unitary transformation and R has an eigenvalue  $\lambda$ , then  $\|\lambda\| = 1$ .

To see this, let v be the e.vector corresponding to the e.value  $\lambda$ . Since R is unitary, we have:

$$\langle v, v \rangle = \langle Rv, Rv \rangle$$

$$= \langle \lambda v, \lambda v \rangle$$

$$= \lambda \overline{\lambda} \langle v, v \rangle$$

$$= ||\lambda||^2 \langle v, v \rangle$$

so  $\|\lambda\| = 1$ .



In this course, the vector spaces we will be looking at most often are the vector spaces of functions defined on some domain:

- $\circ$  Continuous functions on the unit circle ( $S^1$ )
- Continuous functions on the unit disk  $(D^2)$
- $\circ$  Continuous, periodic functions on the plane ( $\mathbb{R}^2$ )
- $\circ$  Continuous functions on the unit sphere ( $S^2$ )
- $\circ$  Continuous functions on the unit ball ( $B^3$ )



Continuous functions on the unit circle  $(S^1)$ :

This is the set of points (x, y) s.t.  $x^2 + y^2 = 1$ .

If we have functions f(x,y) and g(x,y) then:

$$\langle f, g \rangle = \int_{p \in S^1} f(p) \cdot \bar{g}(p) dp$$



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If we have functions f(x,y) and g(x,y) then:

$$\langle f, g \rangle = \int_{p \in S^1} f(p) \cdot \bar{g}(p) dp$$

Or, we can represent points on the circle in terms of angle  $\theta \in [0,2\pi)$ :

$$\theta \to (\cos \theta, \sin \theta)$$

For functions  $f(\theta)$  and  $g(\theta)$  the inner product is:

$$\langle f, g \rangle = \int_0^{2\pi} f(\theta) \cdot \bar{g}(\theta) d\theta$$



Continuous functions on the unit disk  $(D^2)$ :

This is the set of points (x, y) s.t.  $x^2 + y^2 \le 1$ .

If we have functions f(x,y) and g(x,y) then:

$$\langle f, g \rangle = \int_{p \in D^2} f(p) \cdot \bar{g}(p) dp$$



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If we have functions f(x,y) and g(x,y) then:

$$\langle f, g \rangle = \int_{p \in D^2} f(p) \cdot \bar{g}(p) dp$$

Or, we can represent points on the circle in terms of radius  $r \in [0,1]$  and angle  $\theta \in [0,2\pi)$ :

$$(r, \theta) \rightarrow (r \cdot \cos \theta, r \cdot \sin \theta)$$

For functions  $f(r, \theta)$  and  $g(r, \theta)$  the inner product is:

$$\langle f, g \rangle = \int_0^{2\pi} \int_0^1 f(r, \theta) \cdot \bar{g}(r, \theta) \cdot r \, dr \, d\theta$$



Continuous, periodic functions on the plane ( $\mathbb{R}^2$ ):

This is the set of functions f(x, y) s.t.:

$$f(x,y) = f(x + 2\pi, y) = f(x, y + 2\pi)$$

If we have functions f(x,y) and g(x,y) then:

$$\langle f, g \rangle = \int_0^{2\pi} \int_0^{2\pi} f(x, y) \cdot \bar{g}(x, y) \, dy \, dx$$



Continuous functions on the unit sphere ( $S^2$ ):

This is the set of points (x, y, z) s.t.  $x^2 + y^2 + z^2 = 1$ .

If we have functions f(x, y, z) and g(x, y, z) then:

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Or, we can represent points on the sphere in terms of spherical angle  $\theta \in [0, \pi]$  and  $\phi \in [0, 2\pi)$ :

$$(\theta, \phi) \rightarrow (\sin \theta \cdot \cos \phi, \cos \theta, \sin \theta \cdot \sin \phi)$$

For functions  $f(\theta, \phi)$  and  $g(\theta, \phi)$  the inner product is:

$$\langle f, g \rangle = \int_0^{2\pi} \int_0^{\pi} f(\theta, \phi) \cdot \bar{g}(\theta, \phi) \cdot \sin(\theta) \ d\theta \ d\phi$$



Continuous functions on the unit ball  $(B^3)$ :

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Or, representing points in the ball in terms of radius  $r \in [0,1]$  and spherical angle  $\theta \in [0,\pi]$ ,  $\phi \in [0,2\pi)$ :  $(r,\theta,\phi) \to (r \cdot \sin\theta \cdot \cos\phi, r \cdot \cos\theta, r \cdot \sin\theta \cdot \sin\phi)$ 

For functions  $f(r, \theta, \phi)$  and  $g(r, \theta, \phi)$  then:

$$\langle f, g \rangle = \int_0^{2\pi} \int_0^{\pi} \int_0^1 f(r, \theta, \phi) \cdot \bar{g}(r, \theta, \phi) \cdot r^2 \cdot \sin(\theta) \ dr \ d\theta \ d\phi$$



#### **Examples**

If we consider the space of continuous, complexvalued functions on the unit circle:

Is the map:

$$f(p) \rightarrow f(p) + 1$$

a linear transformation?



#### **Examples**

If we consider the space of continuous, complexvalued functions on the unit circle:

Is the map:

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a linear transformation? No



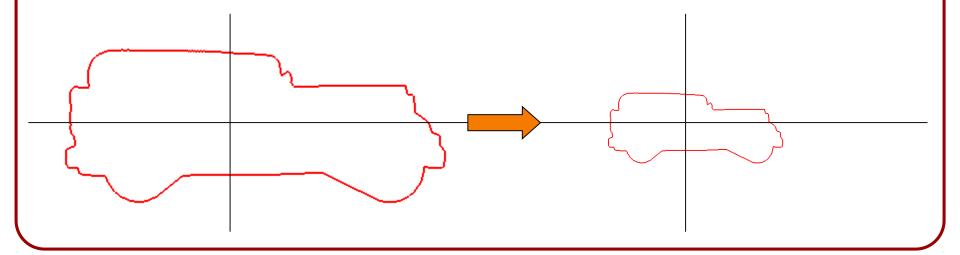
#### **Examples**

If we consider the space of continuous, complexvalued functions on the unit circle:

• For any scalar value  $\lambda$ , is:

$$f(p) \to \lambda f(p)$$

a linear transformation?





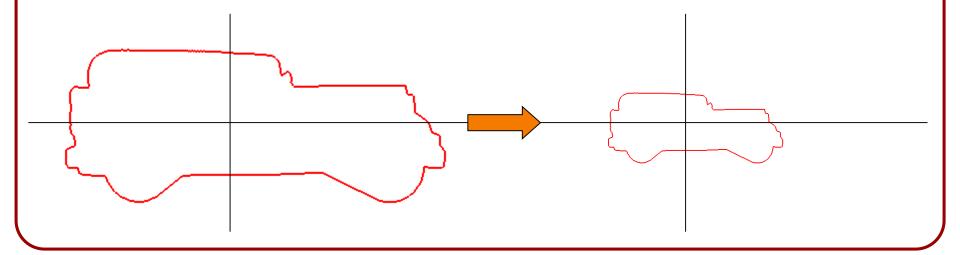
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- Is it unitary? No
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a linear transformation? Yes

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- How about if  $||\lambda|| = 1$ ? **Yes**



#### **Examples**

If we consider the space of continuous, complexvalued functions on the unit circle:

Is the differentiation operator:

$$f(p) \to f'(p)$$

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If we consider the space of continuous, complexvalued functions on the unit circle:

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 What if we only consider the functions that are infinitely differentiable?



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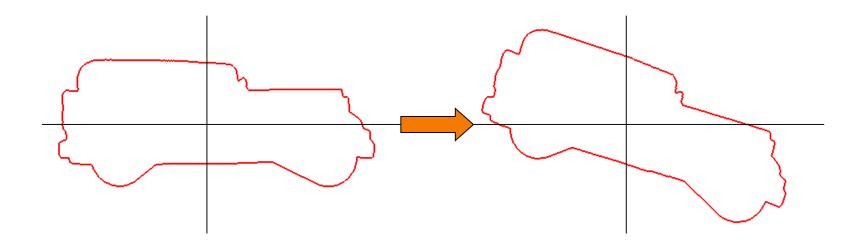
#### **Examples**

If we consider the space of continuous, complexvalued functions on the unit circle:

• For any 2D rotation *R* is the transformation:

$$f(p) \to f(R^{-1}p)$$

a linear transformation?





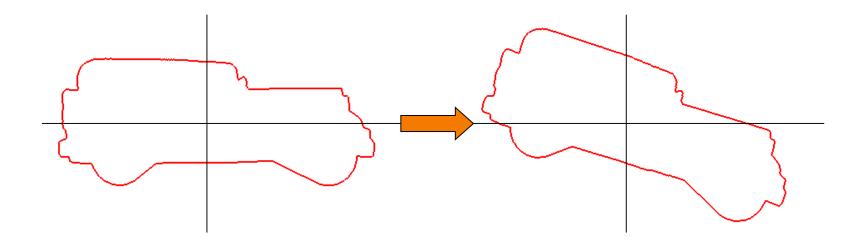
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a linear transformation? Yes

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#### **Examples**

If we consider the space of continuous, periodic, complex-valued functions on the plane:

• For any 2D point  $(x_0, y_0)$ , is the transformation:

$$f(x,y) \to f(x-x_0,y-y_0)$$

a linear transformation?



#### **Examples**

If we consider the space of continuous, periodic, complex-valued functions on the plane:

• For any 2D point  $(x_0, y_0)$ , is the transformation:

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#### **Examples**

If we consider the space of continuous, periodic, complex-valued functions on the plane:

- For any 2D point  $(x_0, y_0)$ , is the transformation:  $f(x,y) \rightarrow f(x-x_0, y-y_0)$ a linear transformation? **Yes**
- Is it unitary?



#### **Examples**

If we consider the space of continuous, periodic, complex-valued functions on the plane:

- For any 2D point  $(x_0, y_0)$ , is the transformation:  $f(x,y) \rightarrow f(x-x_0, y-y_0)$ a linear transformation? **Yes**
- Is it unitary? Yes



#### **Examples**

If we consider the space of continuous, infinitelydifferentiable, periodic, complex-valued functions on the plane:

 $\circ$  Is differentiation with respect to x:

$$f(x,y) \to \frac{\partial}{\partial x} f(x,y)$$

a linear transformation?



#### **Examples**

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a linear transformation? Yes

Is it unitary? No



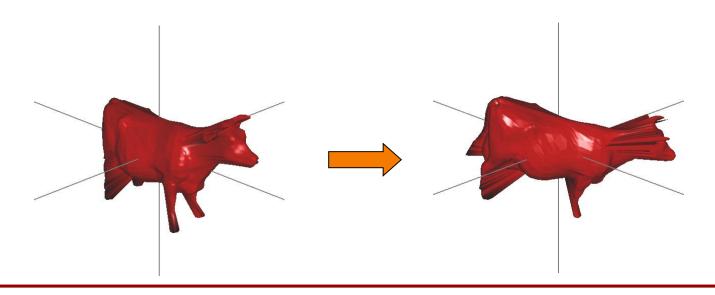
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If we consider the space of continuous, complexvalued functions on the sphere:

 $\circ$  For any rotation R, is the transformation:

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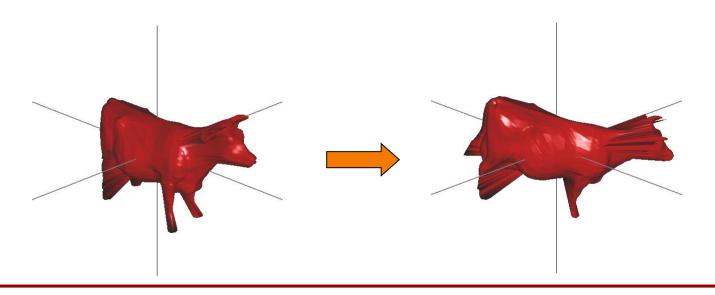
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