

# 3D Scattered Data Approximation with Adaptive Compactly Supported Radial Basis Functions

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# Problem Statement

- Given a set of points,  $\mathcal{P} = \{\mathbf{p}_1, \dots, \mathbf{p}_N\}$ , and corresponding unit normals,  $\mathcal{N} = \{\mathbf{n}_1, \dots, \mathbf{n}_N\}$ , find a function  $f$  such that the zero set  $f(\mathbf{x}) = 0$  approximates  $\mathcal{P}$ .
- NOTE: This definition of  $f$ , given in the text, does not regard  $\mathcal{N}$  and does not address the trivial solution.

# Solution Outline

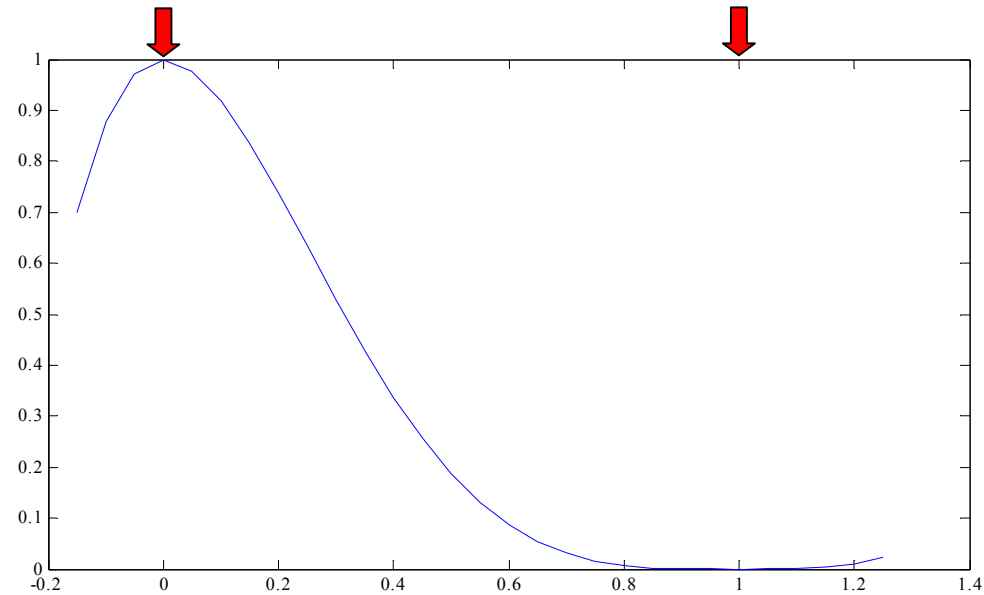
- Use a set of *approximation centers*  $C = \{\mathbf{c}_1, \dots, \mathbf{c}_M\}$
- Approximate  $\mathcal{P}$  by  $f$  as follows:

$$f(\mathbf{x}) = \sum_{\mathbf{c}_i \in C} [g_i(\mathbf{x}) + \lambda_i] \phi_{\sigma_i}(\|\mathbf{x} - \mathbf{c}_i\|)$$

- $\sigma$ 's are influence radii for the centers
- $g$ 's are unknown functions,  $\lambda$ 's are unknown coefficients
- $\phi$ 's are *radial basis functions*.

$$\phi(r) = (1 - r)_+^4 (4r + 1)$$

# Radial Basis Function



$$\phi(r) = (1 - r)_+^4 (4r + 1)$$

# Solution Outline

- Construct  $g_i$  as a local quadratic approximation of  $\mathcal{P}$  in  $\{\|\mathbf{x} - \mathbf{c}_i\| < \sigma_i\}$
- Find  $\lambda$ 's through solving a linear equation:  
 $f(\mathbf{c}_j) = 0$
- Normalize the basis functions and decompose  $f$

$$\underbrace{\sum_{\mathbf{c}_i \in \mathcal{C}} g_i(\mathbf{x}) \Phi_{\sigma_i}(\|\mathbf{x} - \mathbf{c}_i\|)}_{\text{adaptive PU}} + \underbrace{\sum_{\mathbf{c}_i \in \mathcal{C}} \lambda_i \Phi_{\sigma_i}(\|\mathbf{x} - \mathbf{c}_i\|)}_{\text{normalized RBF}} = 0$$

# Main Properties

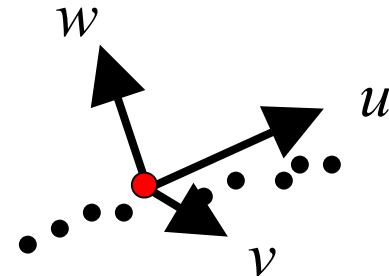
- Reduction of problem size by using a small number of approximation centers.
- RBF's on a limited domain → focus on local features
- Different influence radii for different approximation centers

# Explaining Equation 7.5

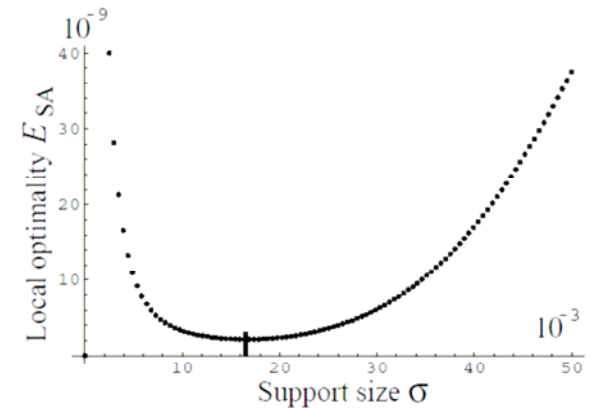
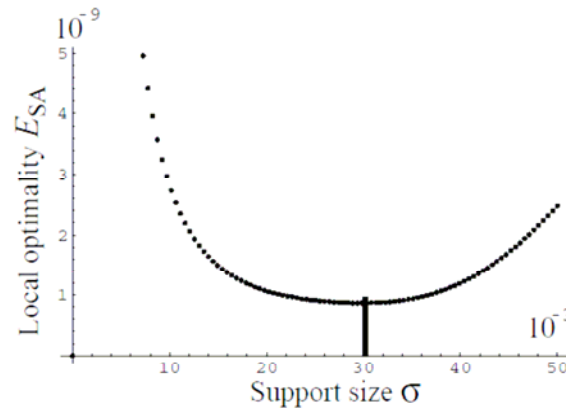
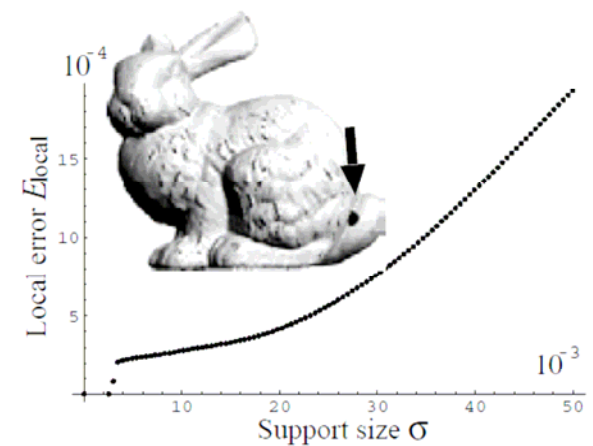
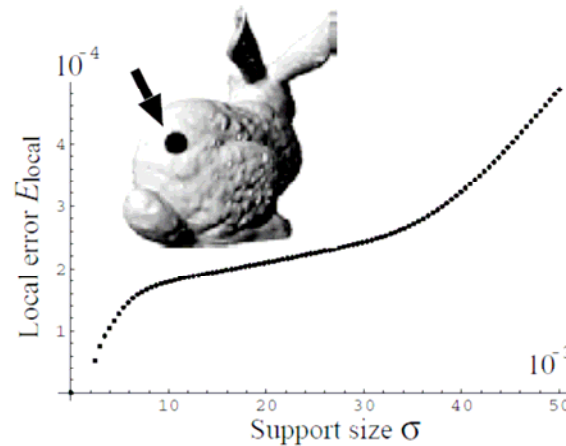
- $h$  is a local approximation of the surface as a bivariate quadratic function on the tangent plane at  $\mathbf{p}_i$ .
  - $g_i(\mathbf{x}) = w - h(u, v)$
- $w$  is measured for each neighbor of  $\mathbf{p}_i$  as the distance from the tangent plane.

$$w = h(u, v) \equiv Au^2 + 2Buv + Cv^2 + Du + Ev + F$$

- The coefficients are computed by solving linear equations.



# Finding Local Influence Radius



$$E_{\text{SA}}(\sigma) = E_{\text{local}}(\sigma)^2 + \frac{C}{\sigma^2},$$