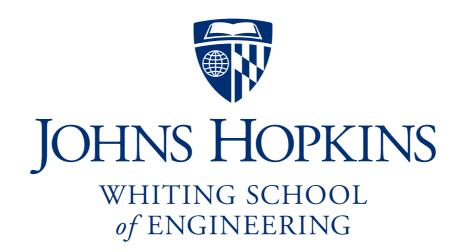
Sequencing error correction

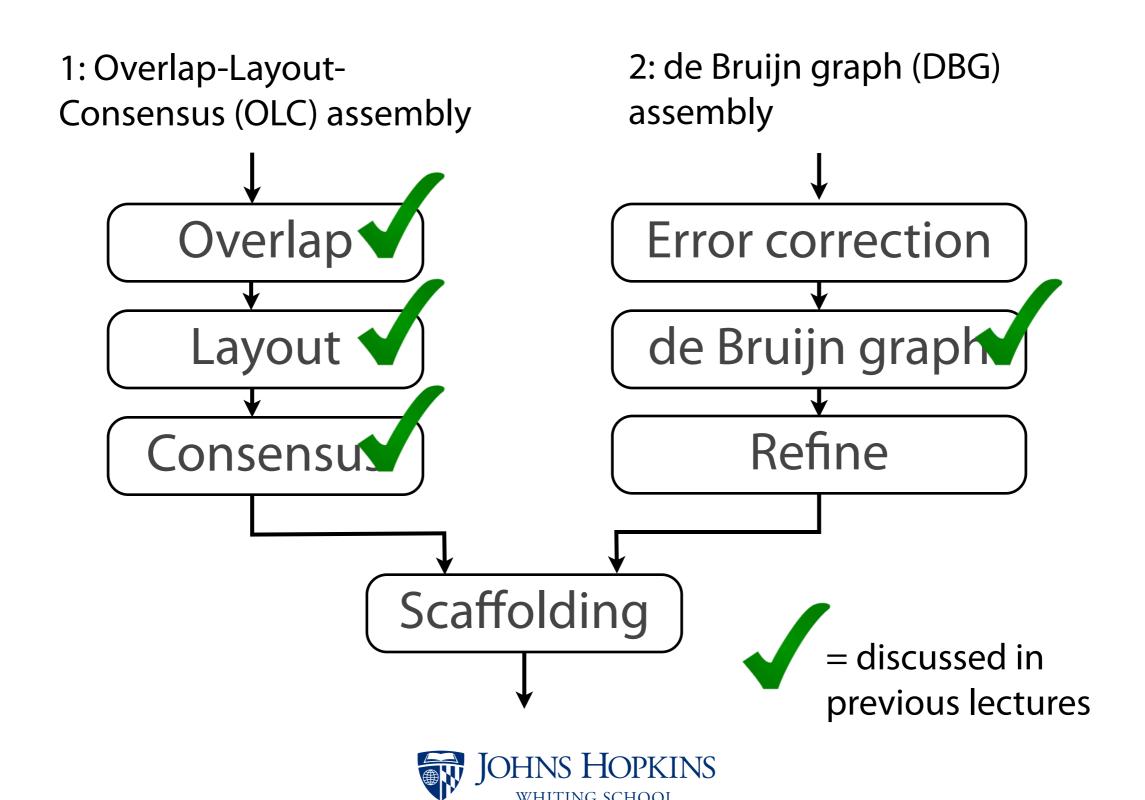
Ben Langmead



Department of Computer Science

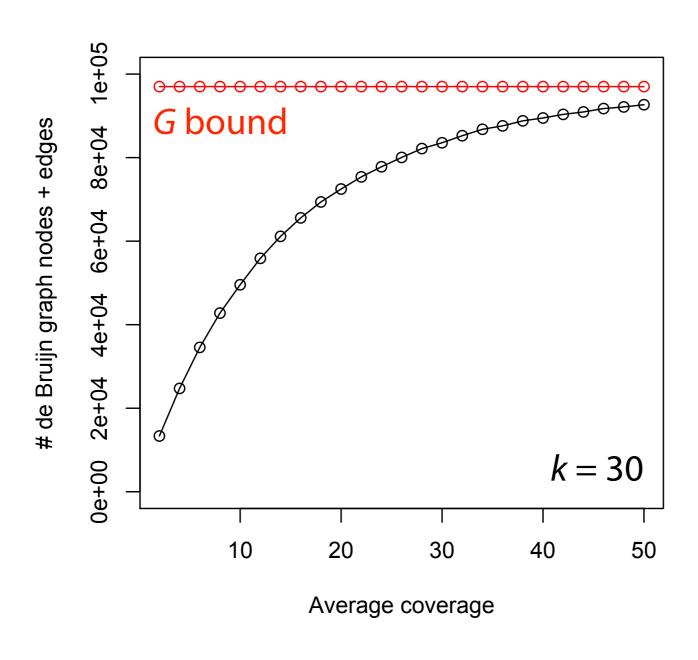
You are free to use these slides. If you do, please sign the guestbook (www.langmead-lab.org/teaching-materials), or email me (ben.langmead@gmail.com) and tell me briefly how you're using them. For original Keynote files, email me.

Assembly paradigms



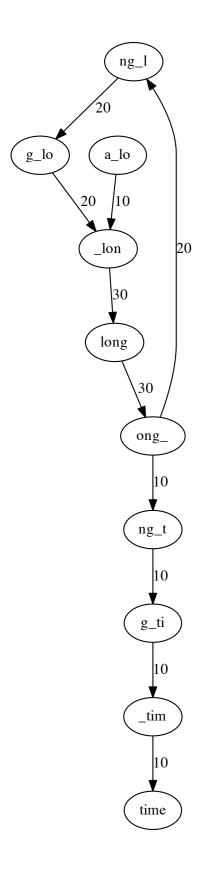
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When data is error-free, # nodes, edges in de Bruijn graph is O(min(G, N))



What about data with sequencing errors?

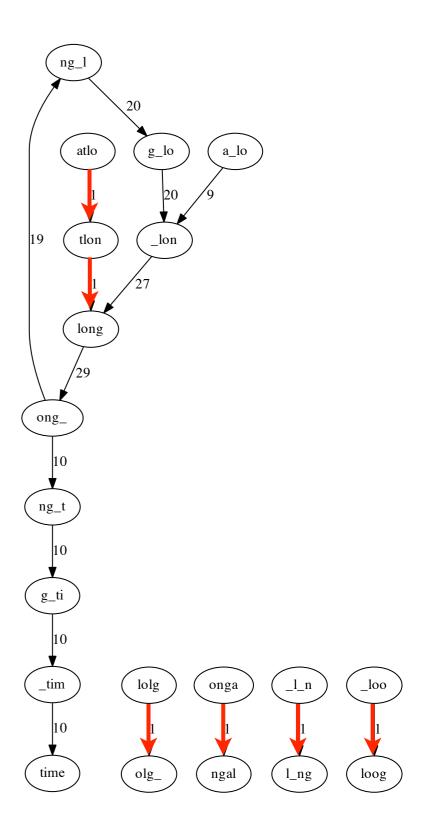




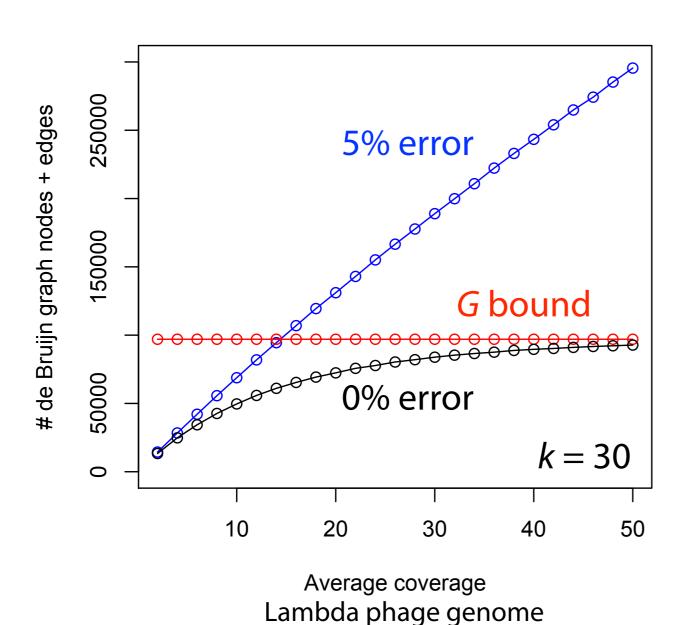
Take an example we saw (left) and mutate a *k*-mer character to a random other character with probability 1% (right)

6 errors result in 10 new nodes and 6 new weighted edges, all with weight 1





As more k-mers overlap errors, # nodes, edges approach N

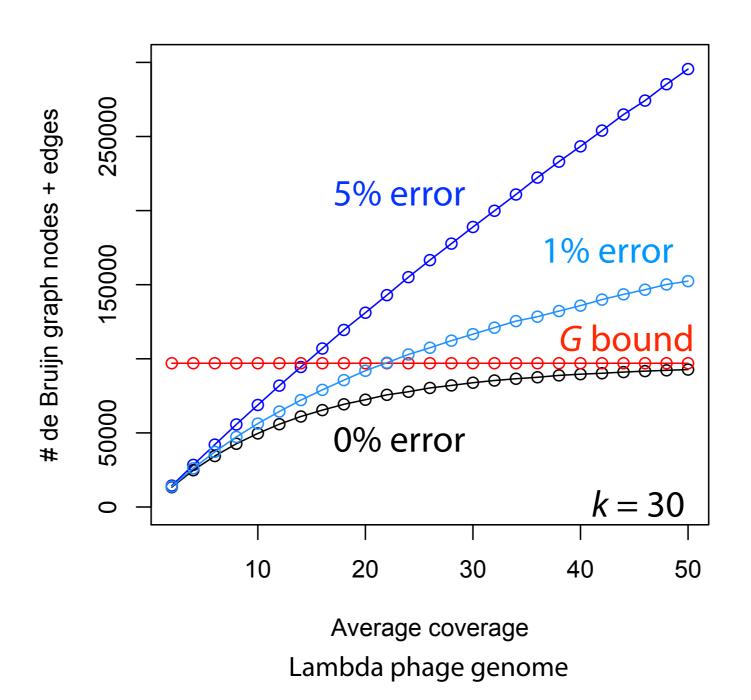


Same experiment as before but with 5% error added

Errors wipe out much of the benefit of the *G* bound

Instead of $O(\min(G, N))$, we have something more like O(N)







If we can correct sequencing errors up-front, we can prevent De Bruijn graph from growing much beyond the *G* bound

How do we correct errors?

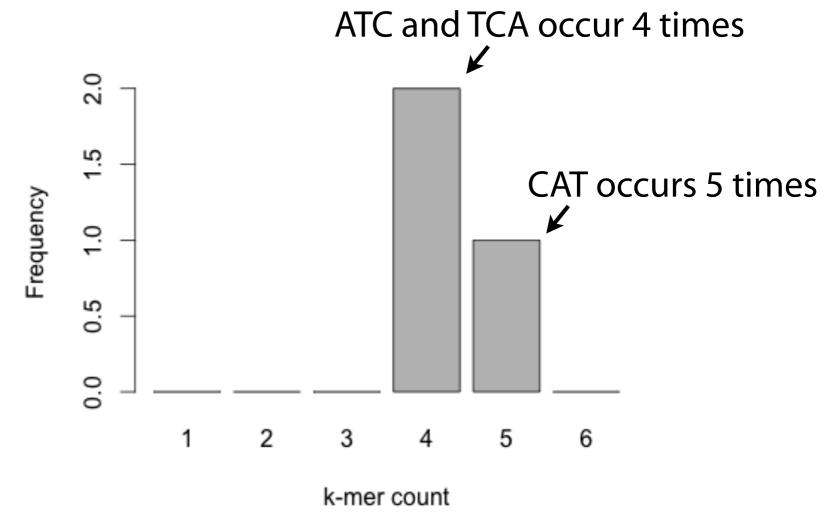
Analogy: design a spell checker for a language you've never seen before. How do you come up with suggestions?



k-mer count histogram:

x axis is an integer k-mer count, y axis is # distinct k-mers with that count

Right: such a histogram for 3-mers of CATCATCATCATCAT:



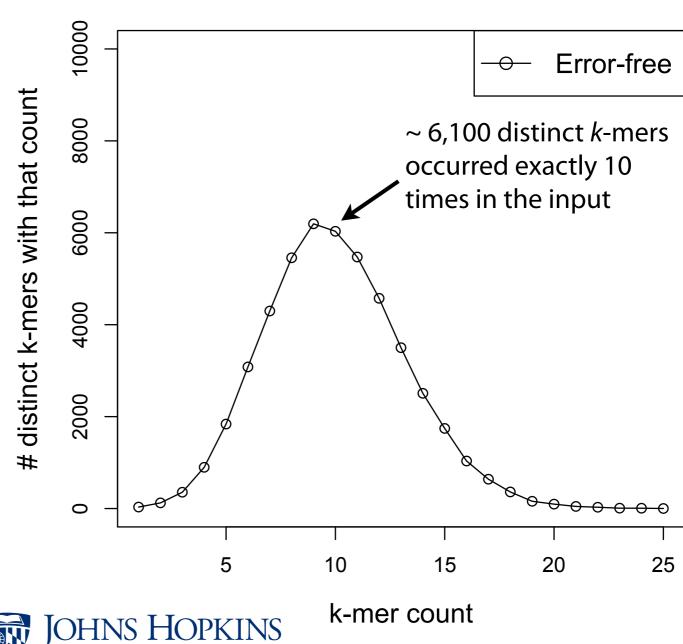


Say we have error-free sequencing reads drawn from a genome. The amount of sequencing is such that average coverage = 200.

Let *k*= 20

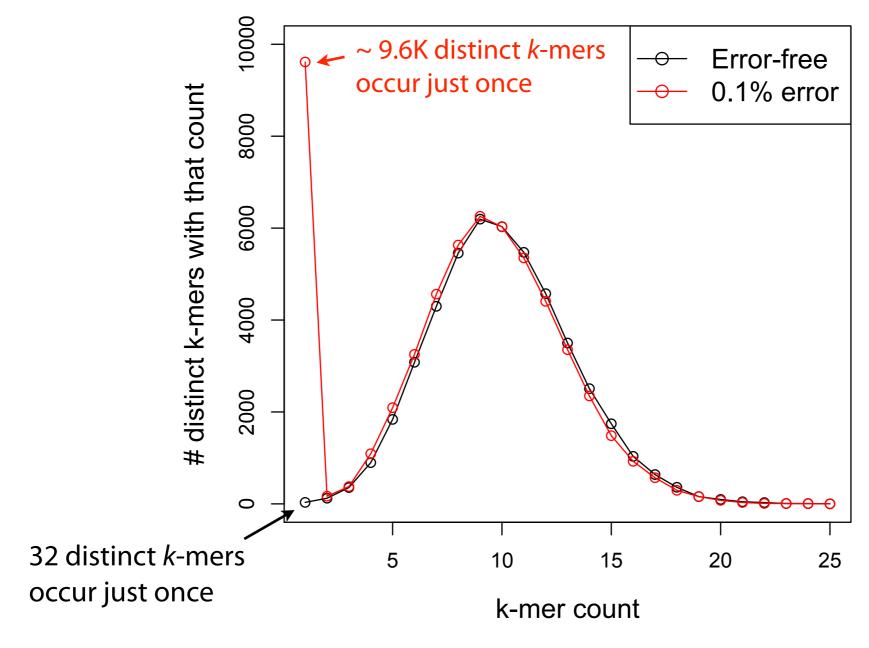
How would the picture change for data with 1% error rate?

Hint: errors usually change high-count *k*-mer into low-count *k*-mer





k-mers with errors usually occur fewer times than error-free *k*-mers





Idea: errors tend to turn frequent k-mers to infrequent k-mers, so corrections should do the reverse

Say we have a collection of reads where each distinct 8-mer occurs an average of ~10 times, and we have the following read:

```
Read:
                                     (20 nt)
         GCGTATTACGCGTCTGGCCT
          GCGTATTA: 8
           CGTATTAC: 8
            GTATTACG: 9
             TATTACGC: 9
                                   # times each 8-mer
              ATTACGCG: 9
                                   occurs in the dataset.
                TTACGCGT: 12
                                   "k-mer count profile"
                 TACGCGTC: 9
     8-mers:
                  ACGCGTCT: 8
                   CGCGTCTG: 10
                                              All 8-mer counts are around
                    GCGTCTGG: 10
                                              the average, suggesting read
                     CGTCTGGC: 11
                      GTCTGGCC: 9
                                              is error-free
```



Suppose there's an error

```
Read:
        GCGTACTACGCGTCTGGCCT
        GCGTACTA: 1
                                            k-mer count profile has
          CGTACTAC: 3
                            Below average
                                            corresponding stretch of
           GTACTACG: 1
                                            below-average counts
            TACTACGC: 1
             ACTACGCG: 2
              CTACGCGT: 1
               TACGCGTC: 9
                ACGCGTCT: 8
                 CGCGTCTG: 10
                                     Around average
                  GCGTCTGG: 10
                    CGTCTGGC: 11
                     GTCTGGCC: 9
                      TCTGGCCT: 8
```



k-mer count profiles when errors are in different parts of the read:

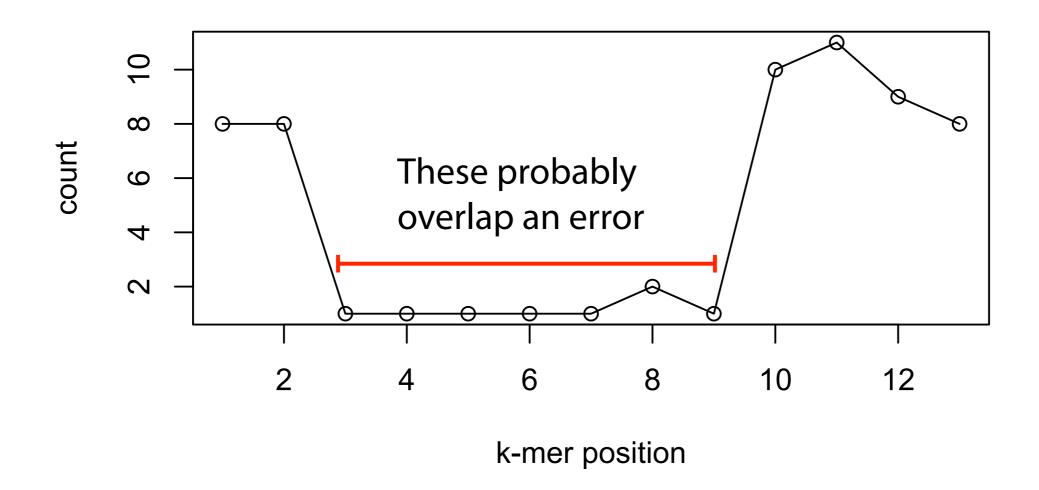
GCGTACTACGCGTCTGGCCT GCGTACTA: 1 CGTACTAC: 3 GTACTACG: 1 TACTACGC: 1 ACTACGCG: 2 CTACGCGT: 1 TACGCGTC: 9 ACGCGTCT: 8 CGCGTCTG: 10 GCGTCTGG: 10 CGTCTGGC: 11 GTCTGGCC: 9 TCTGGCCT: 8

GCGTATTACACGTCTGGCCT GCGTATTA: 8 CGTATTAC: 8 GTATTACA: 1 TATTACAC: 1 ATTACACG: 1 TTACACGT: 1 TACACGTC: 1 ACACGTCT: 2 CACGTCTG: 1 GCGTCTGG: 10 CGTCTGGC: 11 GTCTGGCC: 9 TCTGGCCT: 8

GCGTATTACGCGTCTGGTCT GCGTATTA: 8 CGTATTAC: 8 GTATTACG: 9 TATTACGC: 9 ATTACGCG: 9 TTACGCGT: 12 TACGCGTC: 9 ACGCGTCT: 8 CGCGTCTG: 10 GCGTCTGG: 10 CGTCTGGT: 1 GTCTGGTC: 2 TCTGGTCT: 1



k-mer count profile indicates where errors are





Simple algorithm: given a count threshold *t*:

For each read:

For each k-mer:

If *k*-mer count < *t*:

Examine k-mer's neighbors within certain Hamming/edit distance. If neighbor has count $\geq t$, replace old k-mer with neighbor.

Pick a t that lies in the trough (the dip) between the peaks

Pick a t that lies in the trough (the mer distribution of the dip) between the peaks



Error correction: implementation excerpt

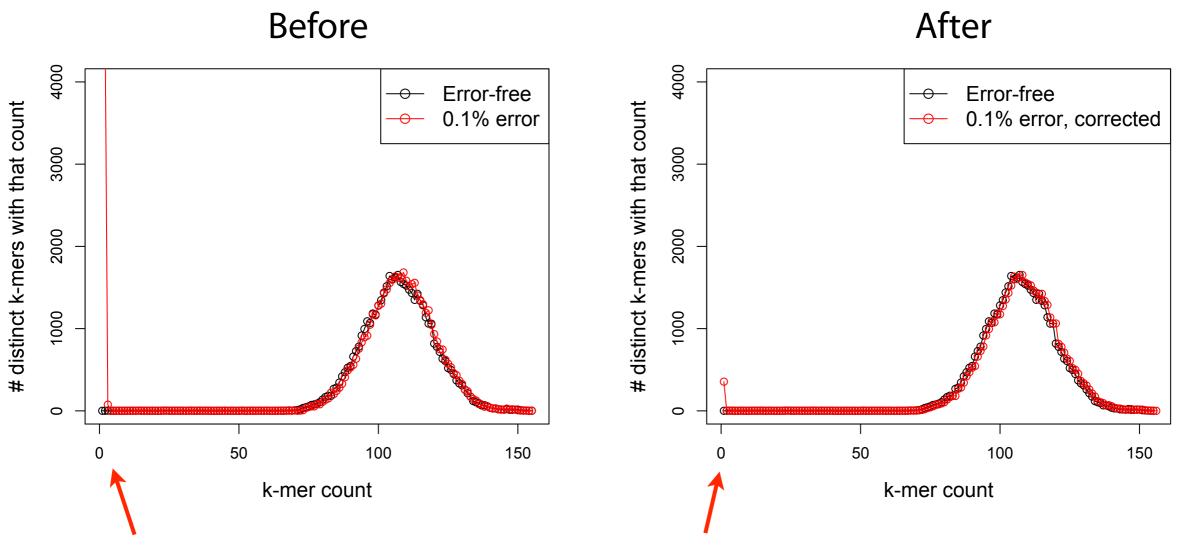
```
def correct1mm(read, k, kmerhist, alpha, thresh):
    ''' Return an error-corrected version of read. k = k-mer length.
        kmerhist is kmer count map. alpha is alphabet. thresh is
        count threshold above which k-mer is considered correct. '''
    # Iterate over k-mers in read
    for i in xrange(0, len(read)-(k-1)):
        kmer = read[i:i+k]
        # If k-mer is infrequent...
        if kmerhist.get(kmer, 0) <= thresh:</pre>
            # Look for a frequent neighbor
            for newkmer in neighbors1mm(kmer, alpha):
                if kmerhist.get(newkmer, 0) > thresh:
                    # Found a frequent neighbor; replace old kmer
                    # with neighbor
                    read = read[:i] + newkmer + read[i+k:]
                    break
    # Return possibly-corrected read
    return read
```

Full Python example: http://nbviewer.ipython.org/7339417



Error correction: results

Corrects 99.2% of the errors in the example 0.1% error dataset



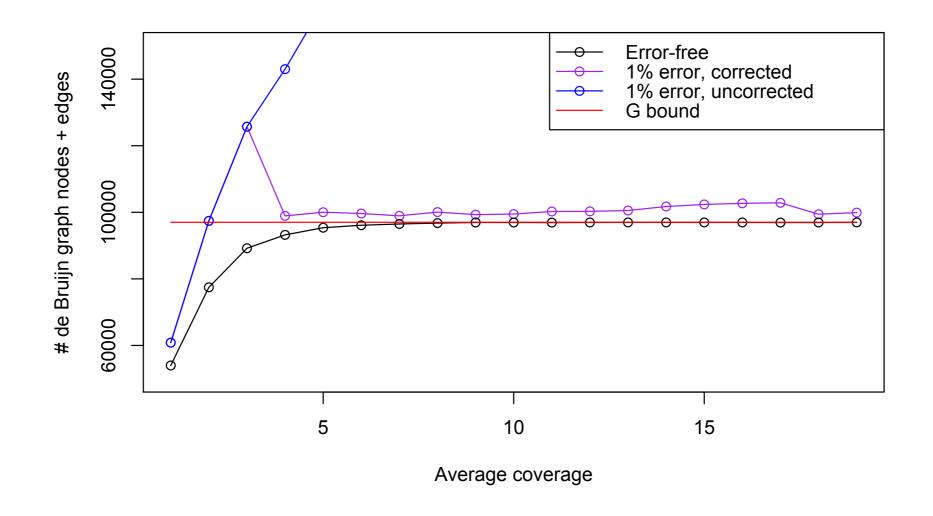
From 194K k-mers occurring exactly once to just 355



Error correction: results

For uncorrected reads, De Bruijn graph size is off the chart

For corrected reads, De Bruijn graph size is near G bound





For error correction to work well:

Average coverage should be high enough and *k* should be set so we can distinguish infrequent from frequent *k*-mers

k-mer neighborhood we explore must be broad enough to find frequent neighbors. Depends on error rate and *k*.

Data structure for storing k-mer counts should be substantially smaller than the De Bruijn graph

Otherwise there's no point doing error correction separately

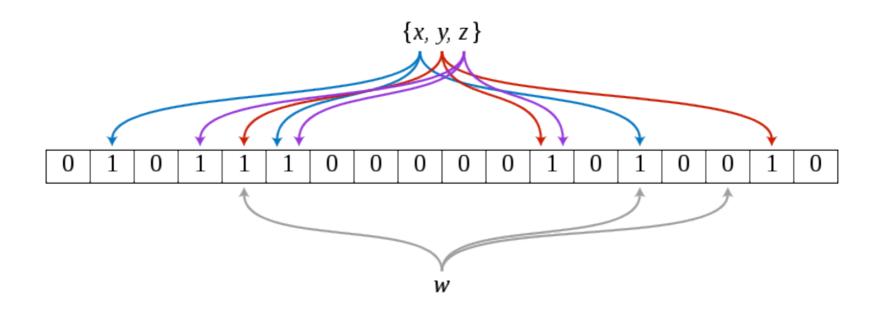
Counts don't have to be 100% accurate; just have to distinguish frequent and infrequent



Error correction: sketches

Sketch data structures are extremely compact, but fail sometimes

E.g. a Bloom Filter is like a hash set, but far smaller, and will sometimes say an object is in the set when it's not



CountMin sketches generalize Bloom Filters for histograms (sets where elements have associated counts); reported counts might be too high

These are candidates for compactly storing *k*-mer counts

http://en.wikipedia.org/wiki/Bloom_filter

http://en.wikipedia.org/wiki/Count-Min_sketch

