

Reducing Bandit problems to expert problems

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In this note, we consider the multi-armed bandit problem of [1] with K options for duration T . We provide a simple modular reduction to the best experts problem [3, 4, 2].

Notations. Let $0 \leq \gamma(t, j) \leq 1$ be the cost of j 's option at time t . Let us divide the time into T/τ phases \mathcal{T}_i of length $\tau = K/\delta$. Consider the average cost of j 's option in phase i

$$\beta(j, \mathcal{T}_i) = \text{Exp}_{t \in \mathcal{T}_i} \gamma(t, j)$$

The average grade of each option is

$$\beta(j) = \text{Exp}_{1 \leq i \leq T/\tau} \beta(j, \mathcal{T}_i)$$

and let the best option be $i^* = \arg\min_i \beta(i)$.

The solution. With probability δ we sample one of the options at random, and with probability $1 - \delta$, we exploit a “black box” experts algorithm, which picks at each phase i option j with probability $\pi_i(j)$. The experts's distribution is fixed in each phase, and it is based on the feedback from *previous* phases. Note that we sample each option at least constant number of times in a phase i ; one of these samples, selected at random, will be the feedback for the experts algorithm for this option in phase i . The expectation of this feedback is exactly $\beta(j, \mathcal{T}_i)$. The total expected cost experienced in phase i is

$$\gamma_i = \sum_j \pi_i(j) \cdot \beta(j, \mathcal{T}_i)$$

Note that the experts algorithm runs for $\tilde{T} = T/\tau$ steps, and thus per [3, 4, 2] has an error of

$$\tilde{\epsilon} = \frac{\log K}{\epsilon \cdot \tilde{T}} + \epsilon = \frac{\log K}{\epsilon \cdot T/\tau} + \epsilon = \frac{\log K \cdot K}{\epsilon \cdot T \cdot \delta} + \epsilon$$

The error experience by this algorithm consists of the experts errors, and a per-step error of δ that is attributed to sampling. The total error is

$$\tilde{\epsilon} + \delta = \frac{\log K \cdot K}{\epsilon \cdot T \cdot \delta} + \epsilon + \delta$$

This is optimized by choosing $\epsilon = \delta$ in which case we have error of $\frac{\log K \cdot K}{T \cdot \delta^2} + 2\delta$ which is minimized by selecting $\delta^3 = \frac{\log K \cdot K}{T}$ yielding

$$\text{average error of } \delta = \sqrt[3]{\frac{\log K \cdot K}{T}}$$

Note that [1] accomplishes smaller error, namely $\sqrt[2]{\frac{\log K \cdot K}{T}}$.

References

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- [3] Adam Kalai and Santosh Vempala. Geometric algorithms for online optimization, 2003. unpublished manuscript.
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