

Lecture 12: Dynamic Programming II

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October 7, 2021

601.433/633 Introduction to Algorithms

Introduction

Today: two more examples of dynamic programming

- ▶ *Longest Common Subsequence* (strings)
- ▶ *Optimal Binary Search Tree* (trees)

Important problems, but really: more examples of dynamic programming

Both in CLRS (unlike Weighted Interval Scheduling)

Longest Common Subsequence

Definitions

String: Sequence of elements of some *alphabet* ($\{0, 1\}$, or $\{A - Z\} \cup \{a - z\}$, etc.)

Definition: A sequence $Z = (z_1, \dots, z_k)$ is a *subsequence* of $X = (x_1, \dots, x_m)$ if there exists a strictly increasing sequence (i_1, i_2, \dots, i_k) such that $x_{i_j} = z_j$ for all $j \in \{1, 2, \dots, k\}$.

Example: (B, C, D, B) is a subsequence of (A, B, C, B, D, A, B)

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Definition: In *Longest Common Subsequence* problem (LCS) we are given two strings $\mathbf{X} = (x_1, \dots, x_m)$ and $\mathbf{Y} = (y_1, \dots, y_n)$. Need to find the longest \mathbf{Z} which is a subsequence of both \mathbf{X} and \mathbf{Y} .

Subproblems

First and most important step of dynamic programming: define subproblems!

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Prefixes of strings

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- ▶ $\mathbf{Y}_j = (y_1, y_2, \dots, y_j)$ (so $\mathbf{Y} = \mathbf{Y}_n$)

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Two-dimensional table!

Optimal Substructure

Second step of dynamic programming: prove optimal substructure

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Optimal Substructure: Proof (I)

Case 1: If $x_i = y_j$, then $z_k = x_i = y_j$ and $Z_{k-1} = \text{OPT}(i-1, j-i)$

Proof Sketch.

Contradiction.

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Part 2: Suppose $Z_{k-1} \neq \text{OPT}(i-1, j-1)$.

$\implies \exists W$ LCS of X_{i-1}, Y_{j-1} of length $> k-1 \implies \geq k$

$\implies (W, a)$ common subsequence of X_i, Y_j of length $> k$

▶ Contradiction to Z being LCS of X_i and Y_j



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Case 2: If $x_i \neq y_j$ and $z_k \neq x_i$ then $Z = \text{OPT}(i - 1, j)$

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Case 2: If $x_i \neq y_j$ and $z_k \neq x_i$ then $\mathbf{Z} = \mathbf{OPT}(i-1, j)$

Proof.

Since $z_k \neq x_i$, \mathbf{Z} a common subsequence of $\mathbf{X}_{i-1}, \mathbf{Y}_j$

$\mathbf{OPT}(i-1, j)$ a common subsequence of $\mathbf{X}_i, \mathbf{Y}_j$

$\Rightarrow |\mathbf{OPT}(i-1, j)| \leq |\mathbf{OPT}(i, j)| = |\mathbf{Z}|$ (def of $\mathbf{OPT}(i, j)$ and \mathbf{Z})

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$\Rightarrow |\text{OPT}(i-1, j)| \leq |\text{OPT}(i, j)| = |Z|$ (def of $\text{OPT}(i, j)$ and Z)

$\Rightarrow Z = \text{OPT}(i-1, j)$



Optimal Substructure: Proof (III)

Case 3: If $x_i \neq y_j$ and $z_k \neq y_j$ then $Z = \text{OPT}(i, j - 1)$

Proof.

Symmetric to Case 2. □

Structure Corollary

Corollary

$$\text{OPT}(i,j) = \begin{cases} \emptyset & \text{if } i = 0 \text{ or } j = 0, \\ \text{OPT}(i-1, j-1) \circ x_i & \text{if } i, j > 0 \text{ and } x_i = y_j \\ \max(\text{OPT}(i, j-1), \text{OPT}(i-1, j)) & \text{if } i, j > 0 \text{ and } x_i \neq y_j \end{cases}$$

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Gives obvious recursive algorithm

- ▶ Can take exponential time (good exercise at home!)

Dynamic Programming!

- ▶ Top-Down: are problems getting “smaller”? What does “smaller” mean?
- ▶ Bottom-Up: two-dimensional table! What order to fill it in?

Dynamic Programming Algorithm

```
LCS(X,Y) {  
  for(i = 0 to m) M[i, 0] = 0;  
  for(j = 0 to n) M[0, j] = 0;  
  for(i = 1 to m) {  
    for(j = 1 to n) {  
      if(xi = yj)  
        M[i, j] = 1 + M[i - 1, j - 1];  
      else  
        M[i, j] = max(M[i, j - 1], M[i - 1, j]);  
    }  
  }  
  return M[m, n];  
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Running Time: $O(mn)$

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Theorem

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Induction on $\mathbf{i} + \mathbf{j}$ (or could do on iterations in the algorithm)

Base Case: $\mathbf{i} + \mathbf{j} = \mathbf{0} \implies \mathbf{i} = \mathbf{j} = \mathbf{0} \implies \mathbf{M}[i,j] = \mathbf{0} = |\mathbf{OPT}(i,j)|$

Correctness

Theorem

$$\mathbf{M}[i,j] = |\mathbf{OPT}(i,j)|$$

Proof.

Induction on $i + j$ (or could do on iterations in the algorithm)

Base Case: $i + j = 0 \implies i = j = 0 \implies \mathbf{M}[i,j] = 0 = |\mathbf{OPT}(i,j)|$

Inductive Step: Divide into three cases

1. If $i = 0$ or $j = 0$, then $\mathbf{M}[i,j] = 0 = |\mathbf{OPT}(i,j)|$

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3. If $\mathbf{x_i \neq y_j}$, then

$$\begin{aligned} \mathbf{M[i,j]} &= \max(\mathbf{M[i,j - 1]}, \mathbf{M[i - 1, j]}) && \text{(def of algorithm)} \\ &= \max(|\mathbf{OPT(i, j - 1)}|, |\mathbf{OPT(i - 1, j)}|) && \text{(induction)} \\ &= |\mathbf{OPT(i, j)}| && \text{(structure thm/corollary)} \end{aligned}$$

Computing a Solution

Like we talked about last lecture: backtrack through dynamic programming table.

Details in CLRS 15.4

Optimal Binary Search Trees

Problem Definition

Input: probability distribution / search frequency of keys

- ▶ n distinct keys $k_1 < k_2 < \dots < k_n$
- ▶ For each $i \in [n]$, probability p_i that we search for k_i (so $\sum_{i=1}^n p_i = 1$)

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Cost of searching for k_i in tree T is $\text{depth}_T(k_i) + 1$ (say depth of root = 0)

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Definition: $c(T) = \sum_{i=1}^n p_i (\text{depth}_T(k_i) + 1)$

Problem: Find search tree T minimizing cost.

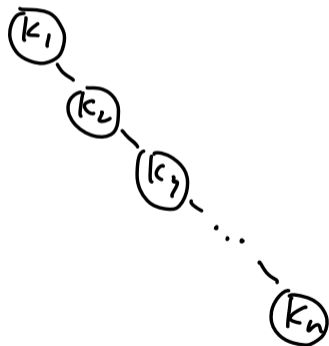
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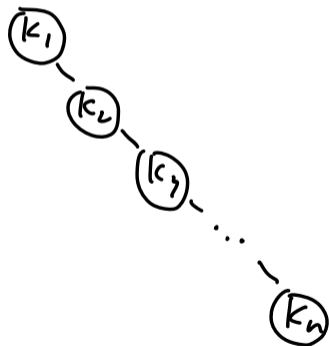
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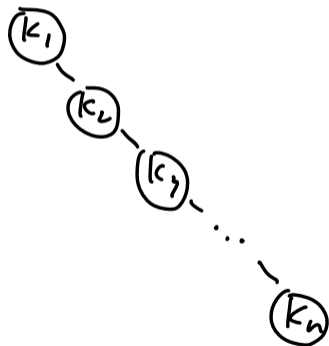


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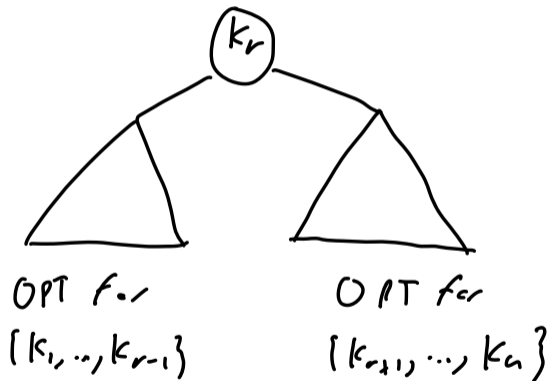
Balanced search tree: $E[\text{cost}] \leq O(\log n)$

Intuition

Suppose root is \mathbf{k}_r . What does optimal tree look like?

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Theorem (Optimal Substructure)

Let k_r be the root of $\mathbf{OPT}(i, j)$. Then the left subtree of $\mathbf{OPT}(i, j)$ is $\mathbf{OPT}(i, r - 1)$, and the right subtree of $\mathbf{OPT}(i, j)$ is $\mathbf{OPT}(r + 1, j)$.

Proof Sketch of Optimal Substructure

Definitions:

- ▶ Let $\mathbf{T} = \mathbf{OPT}(i, j)$, \mathbf{T}_L its left subtree, \mathbf{T}_R its right subtree.
- ▶ Suppose for contradiction $\mathbf{T}_L \neq \mathbf{OPT}(i, r - 1)$, let $\mathbf{T}' = \mathbf{OPT}(i, r - 1)$
 $\implies c(\mathbf{T}') < c(\mathbf{T}_L)$ (def of $\mathbf{OPT}(i, r - 1)$)
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Symmetric argument works for $\mathbf{T}_R = \mathbf{OPT}(r + 1, j)$

Cost Corollary

Corollary

$$c(\text{OPT}(i, j)) = \sum_{a=i}^j p_a + \min_{i \leq r \leq j} (c(\text{OPT}(i, r-1)) + c(\text{OPT}(r+1, j)))$$

Let k_r be root of $\text{OPT}(i, j)$

$$\begin{aligned} c(\text{OPT}(i, j)) &= \sum_{a=i}^j p_a (\text{depth}_{\text{OPT}(i, j)}(k_a) + 1) \\ &= \sum_{a=i}^{r-1} (p_a (\text{depth}_{\text{OPT}(i, r-1)}(k_a) + 2)) + p_r + \sum_{a=r+1}^j p_a (\text{depth}_{\text{OPT}(r+1, j)}(k_a) + 2) \\ &= \sum_{a=i}^j p_a + \sum_{a=i}^{r-1} (p_a (\text{depth}_{\text{OPT}(i, r-1)}(k_a) + 1)) + \sum_{a=r+1}^j p_a (\text{depth}_{\text{OPT}(r+1, j)}(k_a) + 1) \\ &= \sum_{a=i}^j p_a + c(\text{OPT}(i, r-1)) + c(\text{OPT}(r+1, j)). \end{aligned}$$

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Same logic holds for any possible root \implies take min

Algorithm

Fill in table **M**:

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- ▶ Base case: if $j - i < 0$ then $M[i, j] = \text{OPT}(i, j) = 0$
- ▶ Inductive step:

$$M[i, j] = \min_{i \leq r \leq j} \left(\sum_{a=i}^j p_a + M[i, r-1] + M[r+1, j] \right) \quad (\text{alg def})$$

$$= \min_{i \leq r \leq j} \left(\sum_{a=i}^j p_a + c(\text{OPT}(i, r-1)) + c(\text{OPT}(r+1, j)) \right) \quad (\text{induction})$$

$$= c(\text{OPT}(i, j)) \quad (\text{cost corollary})$$

Algorithm: Bottom-up

What order to fill the table in?

- ▶ Obvious approach: for($i = 1$ to $n - 1$) for($j = i + 1$ to n) Doesn't work!

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- ▶ Take hint from induction: $j - i$

```
OBST {  
  Set  $M[i, j] = 0$  for all  $j > i$ ;  
  Set  $M[i, i] = p_i$  for all  $i$   
  for( $\ell = 1$  to  $n - 1$ ) {  
    for( $i = 1$  to  $n - \ell$ ) {  
       $j = i + \ell$   
       $M[i, j] = \min_{i \leq r \leq j} \left( \sum_{a=i}^j p_a + M[i, r - 1] + M[r + 1, j] \right)$ ;  
    }  
  }  
  return  $M[1, n]$ ;  
}
```

Analysis

Correctness: same as top-down

Running Time:

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- ▶ # table entries:

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Total running time: $O(n^3)$