

# Approximation-aware Dependency Parsing by Belief Propagation

Matt Gormley Mark Dredze Jason Eisner

September 19, 2015 TACL at EMNLP

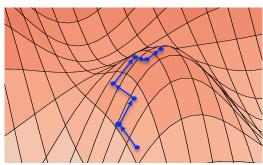


## Motivation #1:

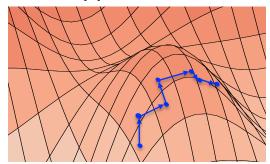
## Approximation-unaware Learning

**Problem:** Approximate inference causes standard learning algorithms to go awry (Kulesza & Pereira, 2008)





with approx. inference:



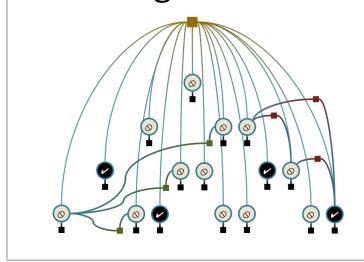
Can we take our approximations into account?



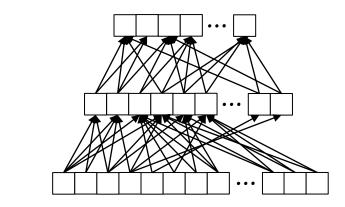
## Motivation #2:

## Hybrid Models

**Graphical models** let you encode domain knowledge



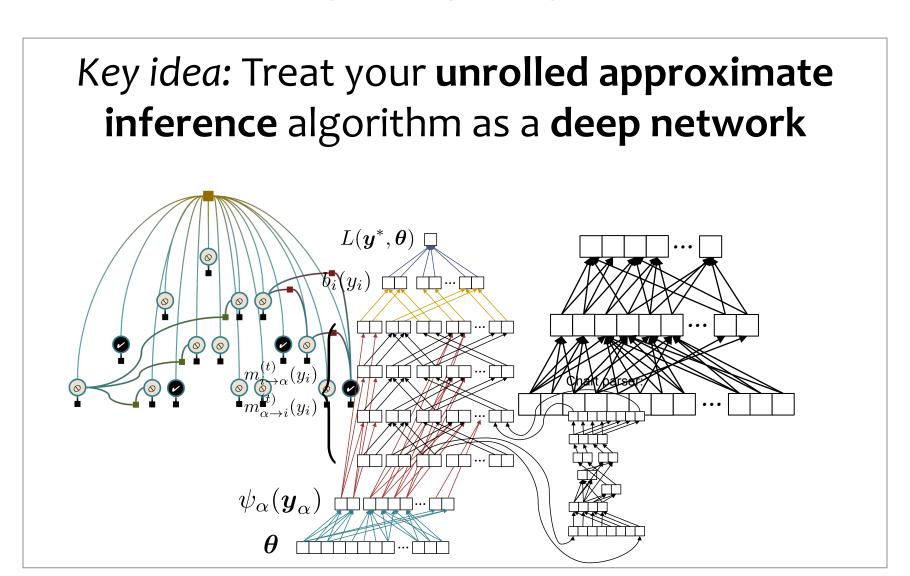
Neural nets are really good at fitting the data discriminatively to make good predictions



Could we define a neural net that incorporates domain knowledge?



## Our Solution





## Talk Summary



















= This Talk





Loopy BP + Dynamic Prog.



Backprop.



= This Talk



Graphical + Hypergraphs Models

Neural Networks = The models that interest me

- If you're thinking, "This sounds like a great direction!"
- Then you're in good company
- And have been since before 1995

LeRec: A NN/HMM Hybrid for On-Line Handwriting Recognition



Yoshua Bengio\* bengioy@iro.umontreal.ca yann@research.att.com

Yann LeCun



Craig Nohl nohl@research.att.com

Chris Burges burges@research.att.com



AT&T Bell Laboratories Rm 4G332, 101 Crawfords Corner Road Holmdel, NJ 07733

To appear in Neural Computation, Volume 7, Number 5, 1995



Loopy BP + Dynamic Prog. + Backprop.







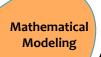




Graphical + Hypergraphs Models

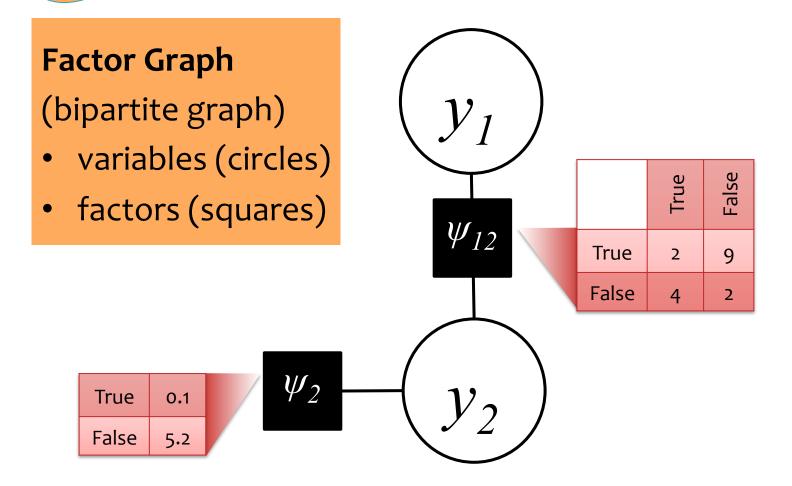
+ Neural Networks = The models that interest me

- So what's new since 1995?
- Two new emphases:
  - 1. Learning under approximate inference
  - 2. Structural constraints

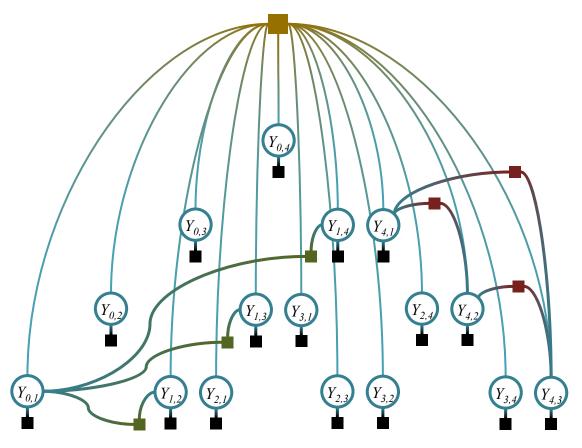




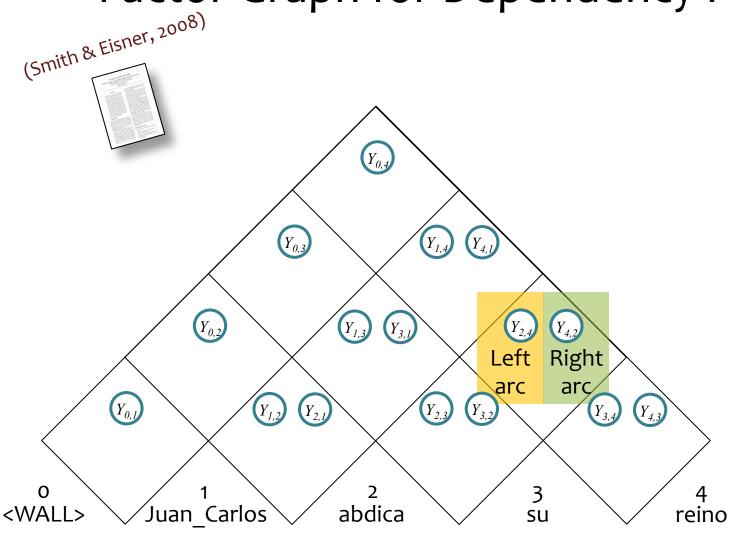
## An Abstraction for Modeling



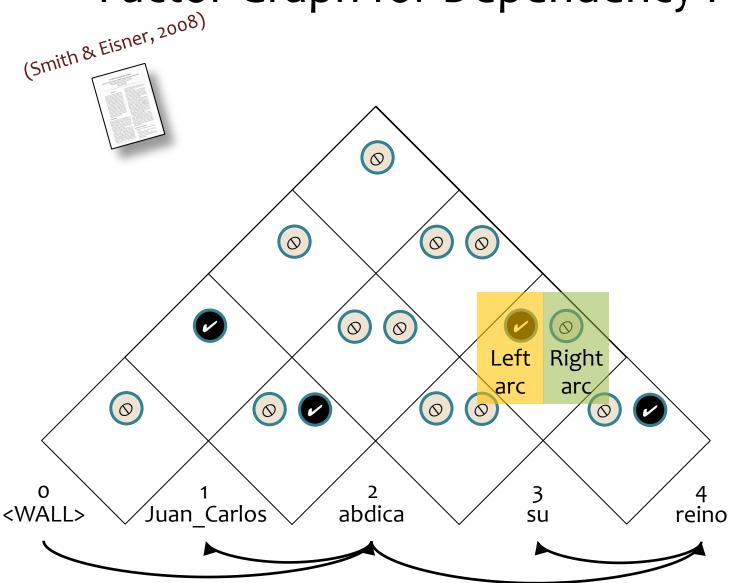




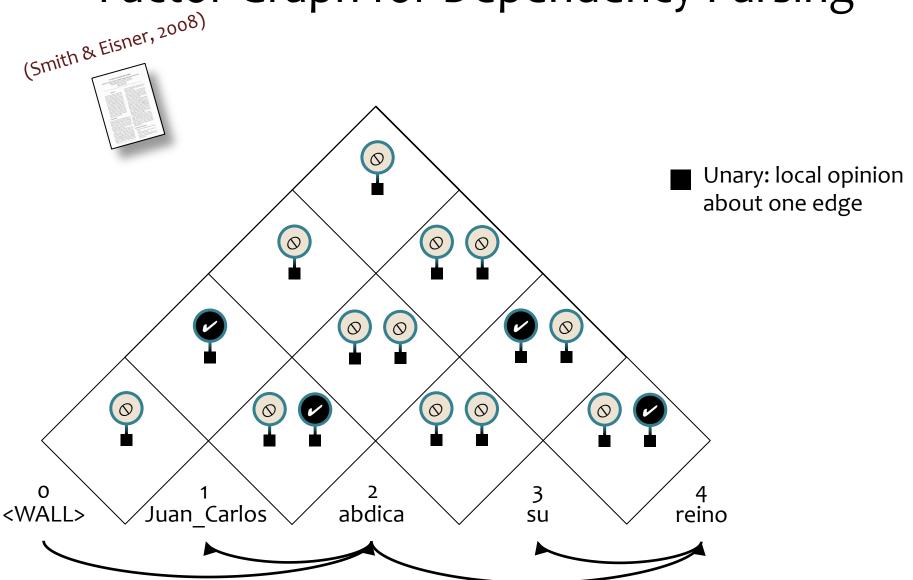




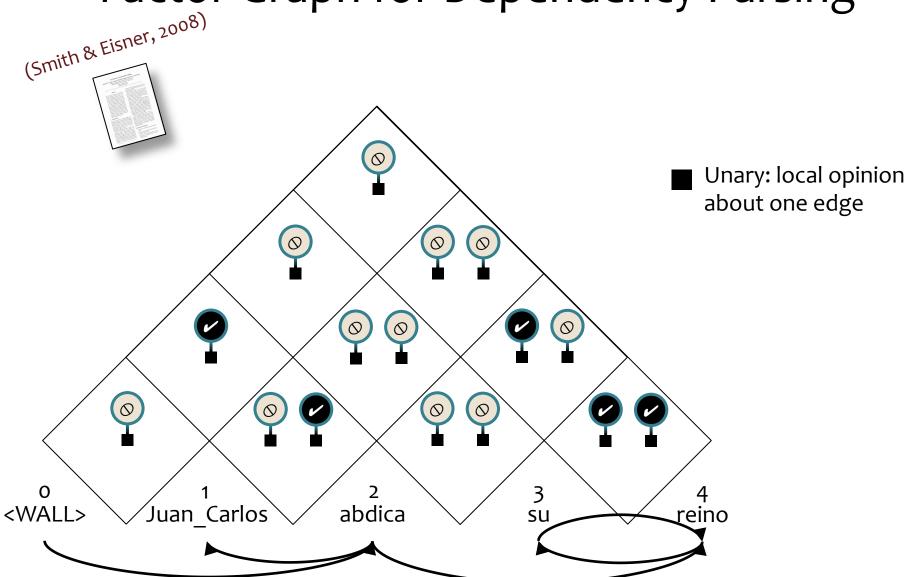




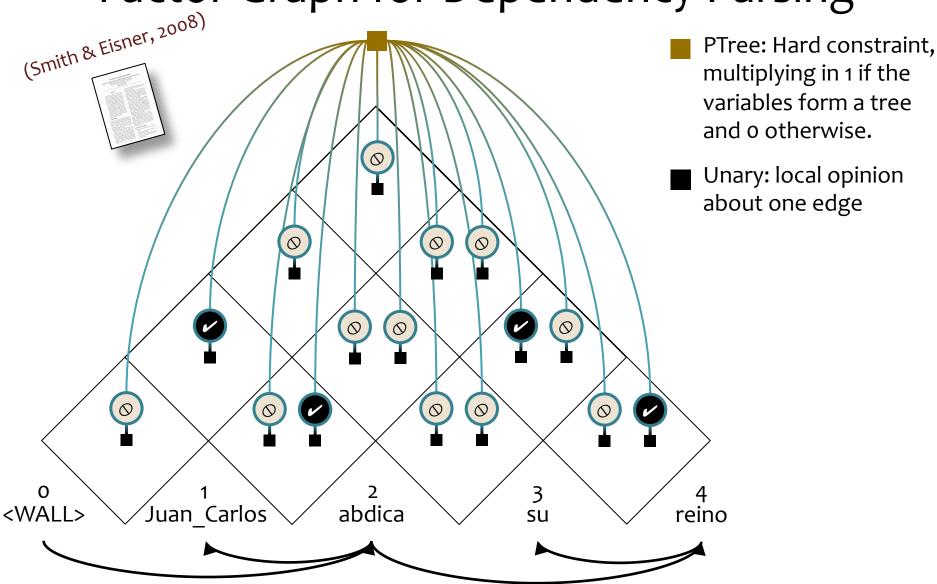




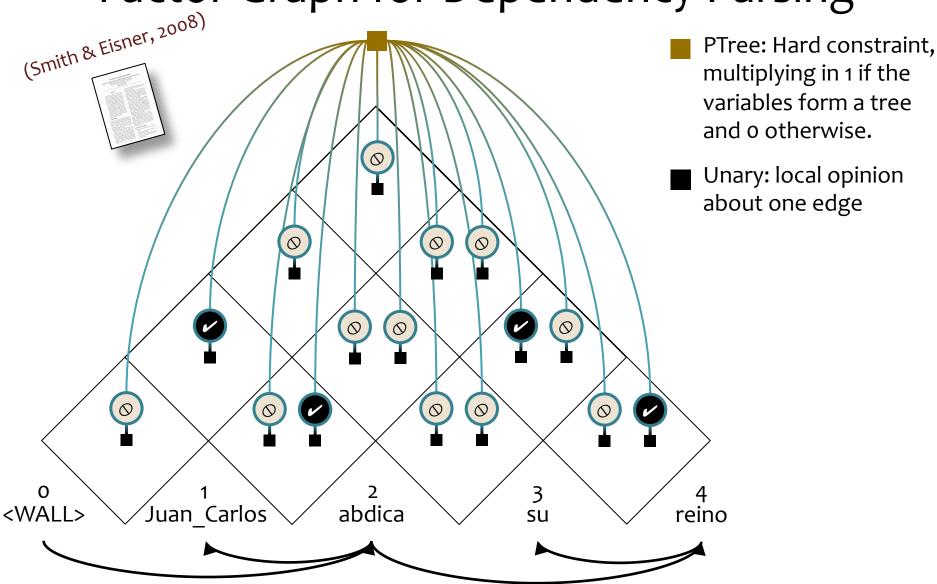




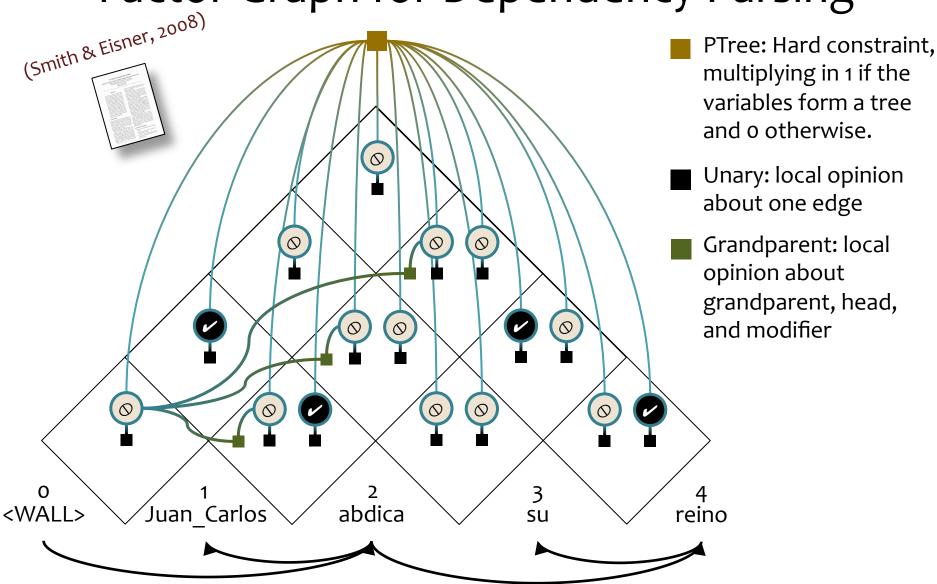




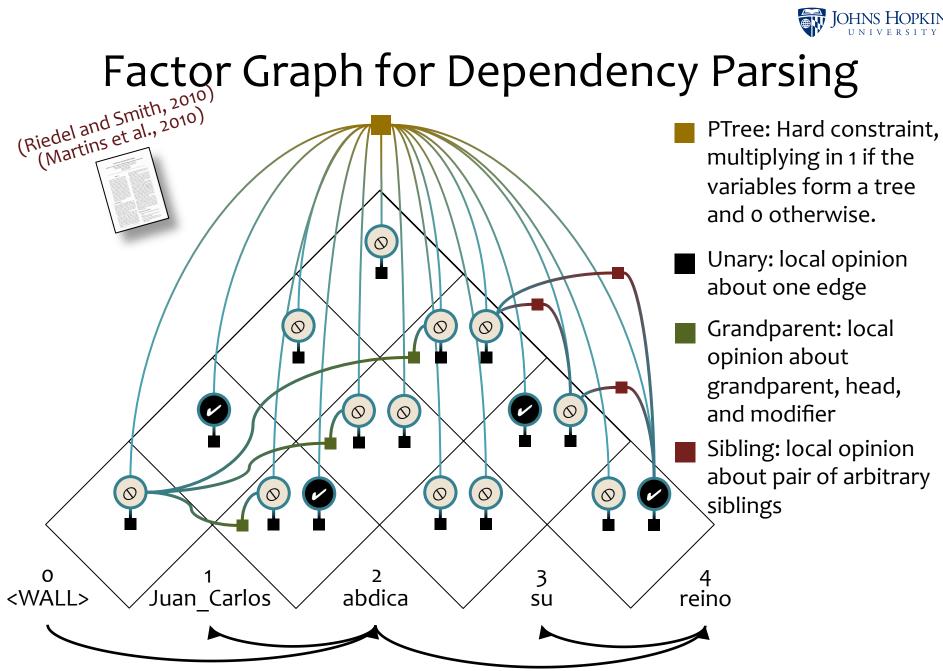




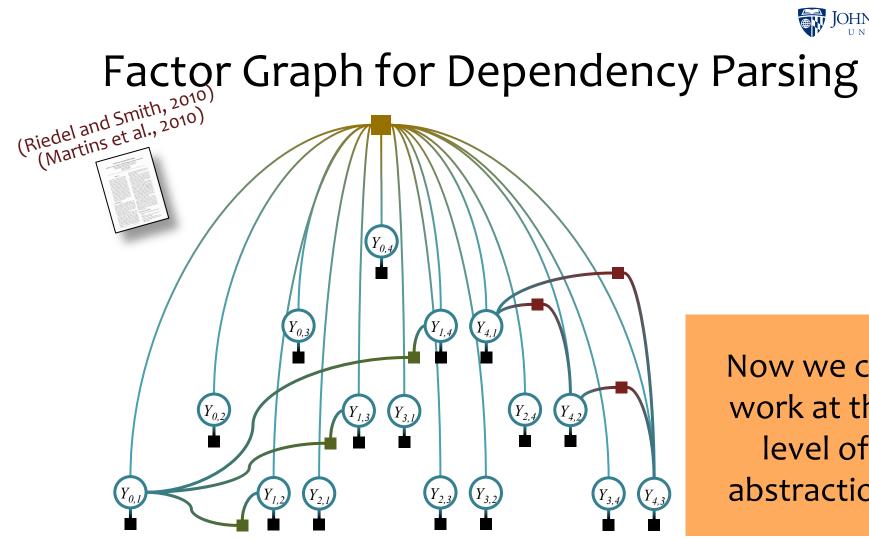












Now we can work at this level of abstraction.

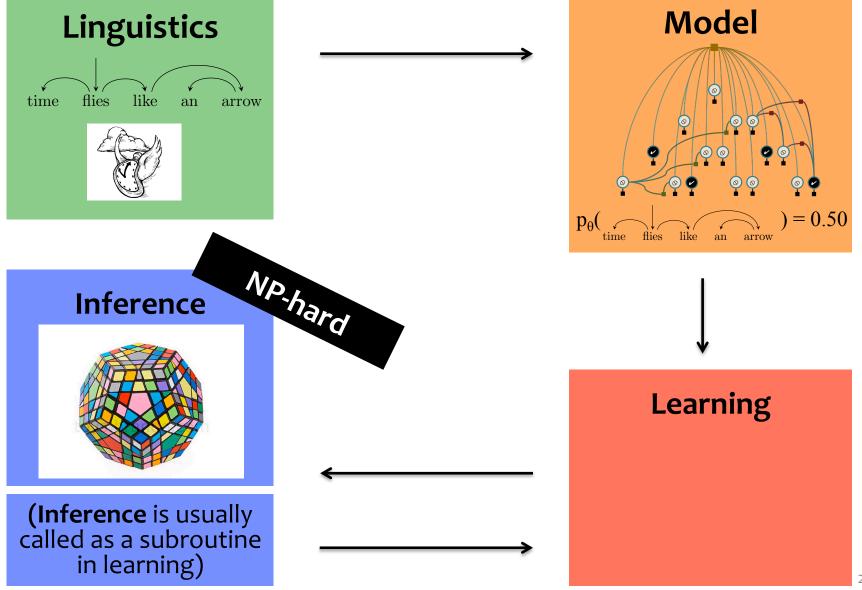
$$p_{\theta}(\boldsymbol{y}) = \frac{1}{Z} \prod_{\alpha} \psi_{\alpha}(\boldsymbol{y}_{\alpha})$$

## Why dependency parsing?

- 1. Simplest example for Structured BP
- 2. Exhibits both polytime and NP-hard problems

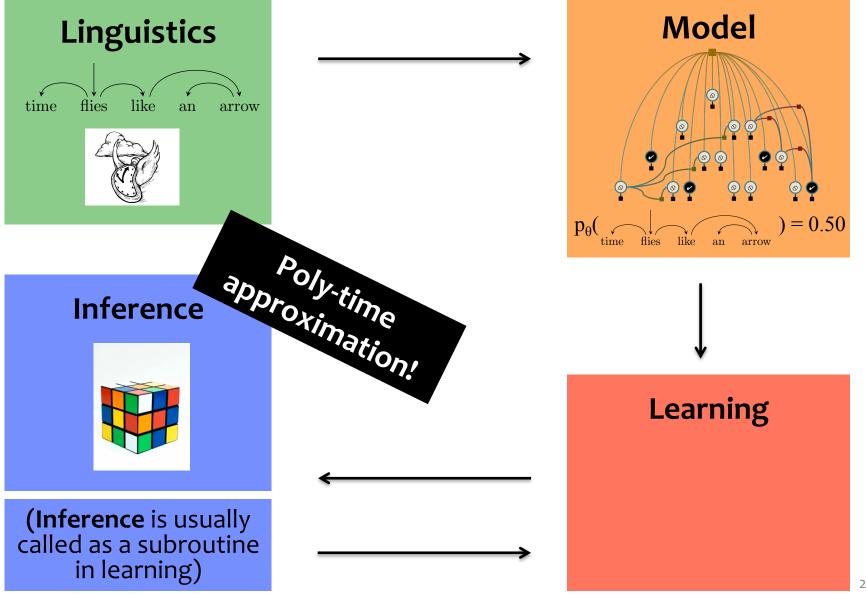


## The Impact of Approximations



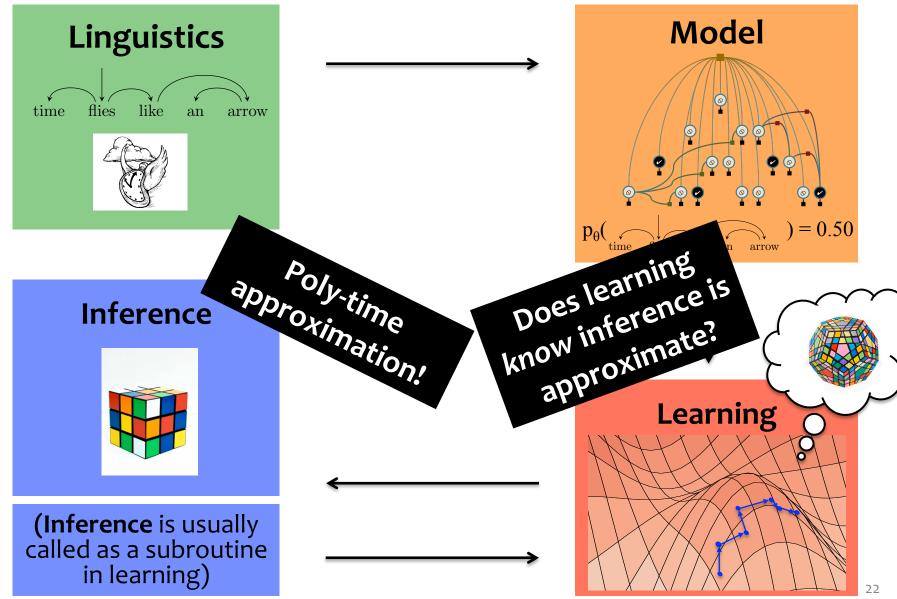


## The Impact of Approximations





## The Impact of Approximations







## Conditional Log-likelihood Training

### Choose **model**

Choose **objective**: Assign high probability to the things we observe and low probability to everything else

$$p_{\theta}(\boldsymbol{y}) = \frac{1}{Z} \prod_{\alpha} \psi_{\alpha}(\boldsymbol{y}_{\alpha})$$

$$L(\theta) = \sum_{\boldsymbol{v} \in \mathcal{D}} \log p_{\theta}(\boldsymbol{y})$$



Compute 3. derivative **by** 

derivative by hand using the chain rule 
$$\frac{dL(\theta)}{d\theta_j} = \sum_{\boldsymbol{y} \in \mathcal{D}} \left( \sum_{\alpha} \left[ f_{\alpha,j}(\boldsymbol{y}_{\alpha}) - \sum_{\boldsymbol{y}'} p_{\theta}(\boldsymbol{y}_{\alpha}') f_{\alpha,j}(\boldsymbol{y}_{\alpha}') \right] \right)$$



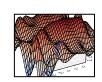
Machine Learning

## Conditional Log-likelihood Training

- Choose model

   (3. comes from log-linear factors)
- $p_{\theta}(\boldsymbol{y}) = \frac{1}{Z} \prod_{\alpha} \exp(\theta \cdot \boldsymbol{f}_{\alpha}(\boldsymbol{y}_{\alpha}))$
- 2. Choose **objective:**Assign high probability to the things we observe and low probability to everything else

$$L(\theta) = \sum_{\boldsymbol{v} \in \mathcal{D}} \log p_{\theta}(\boldsymbol{y})$$



- 3. Compute derivative by hand using the chain rule
- $egin{equation} rac{dL( heta)}{d heta_j} = \sum_{oldsymbol{y} \in \mathcal{D}} \left( \sum_{lpha} \left[ f_{lpha,j}(oldsymbol{y}_lpha) \sum_{oldsymbol{y}'} p_{ heta}(oldsymbol{y}'_lpha) f_{lpha,j}(oldsymbol{y}'_lpha) 
  ight] 
  ight) \end{aligned}$
- 4. Replace exact inference by approximate inference

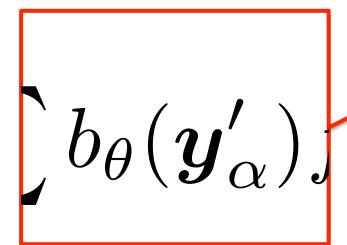
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Machine Learning

## What's wrong with CLL?

How did we compute these **approximate** marginal probabilities anyway?

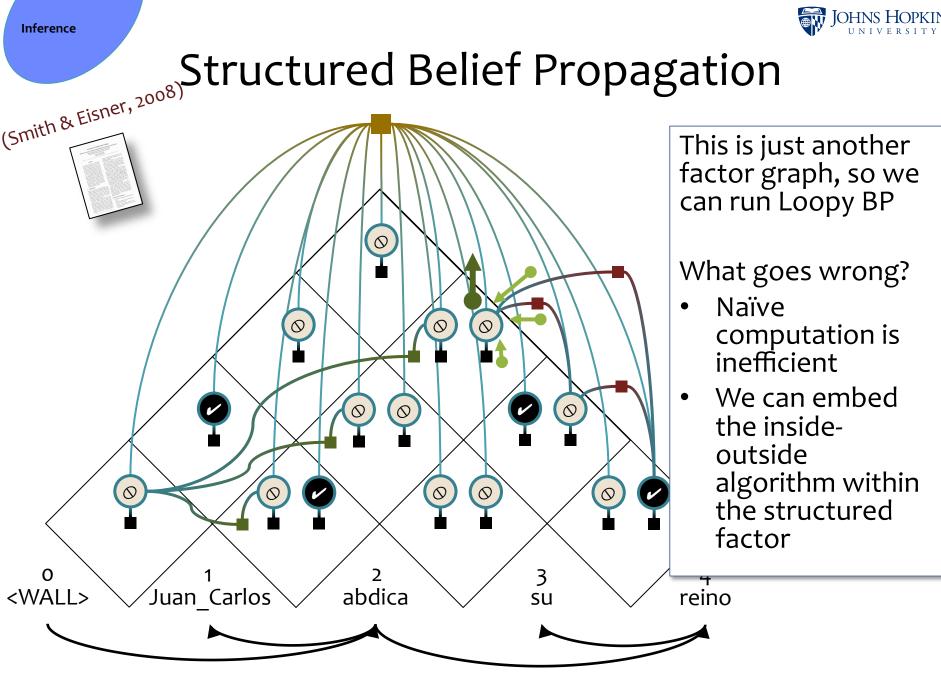


By Structured Belief Propagation of course!

## Everything you need to know about: Structured BP

- It's a message passing algorithm
- 2. The message computations are just multiplication, addition, and division
- 3. Those computations are differentiable







## Algorithmic Differentiation

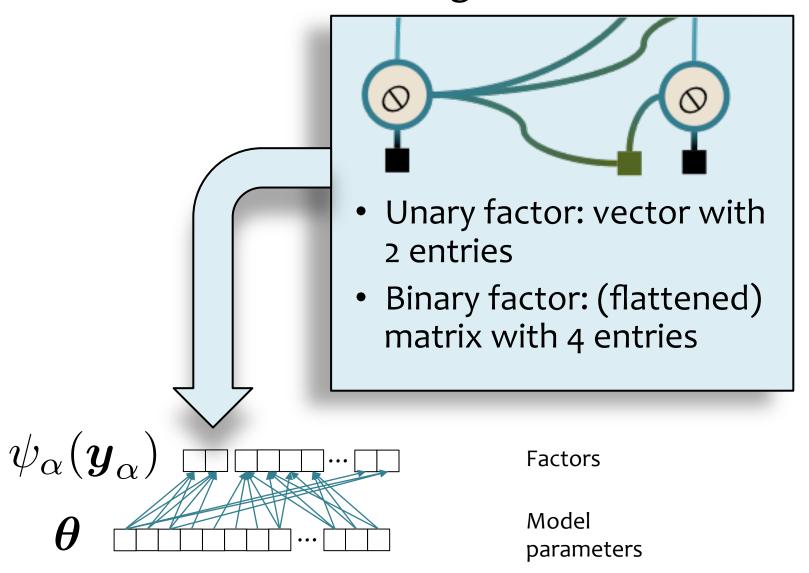
- Backprop works on more than just neural networks
- You can apply the chain rule to any arbitrary differentiable algorithm

## That's the key (old) idea behind this talk.

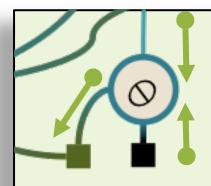
 Alternatively: could estimate a gradient by finite-difference approximations – but algorithmic differentiation is much more efficient!



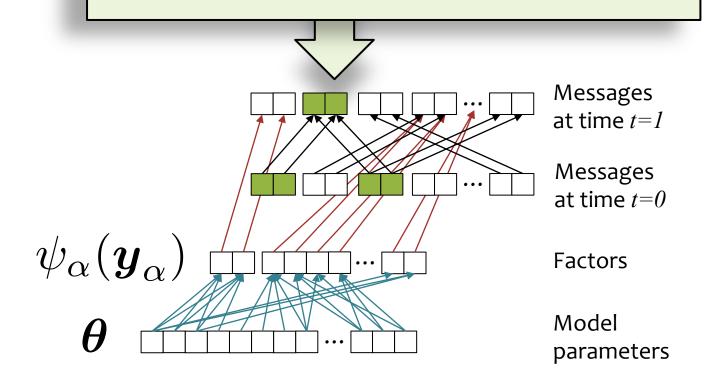
## Feed-forward Topology of Inference, Decoding and Loss







- Messages from neighbors used to compute next message
- Leads to sparsity in layerwise connections



### **Arrows in Neural Net:**

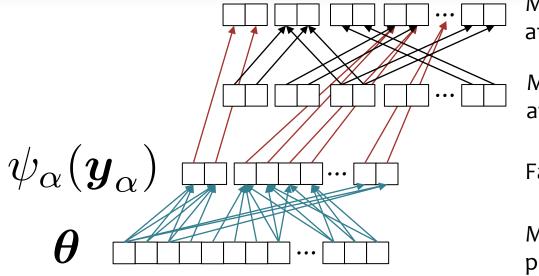
Linear combination, then a sigmoid

$$a_i = \sigma \left( \sum_j \theta_j b_j \right)$$

## **Arrows in This Diagram:**

A different semantics given by the algorithm

$$\psi_{\alpha}(\boldsymbol{y}_{\alpha}) = \exp(\boldsymbol{\theta} \cdot \boldsymbol{f}_{\alpha}(\boldsymbol{y}_{\alpha}, \boldsymbol{x}))$$



Messages at time t=1

Messages at time t=0

**Factors** 

Model parameters

### **Arrows in Neural Net:**

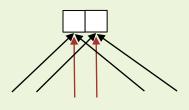
Linear combination, then a sigmoid

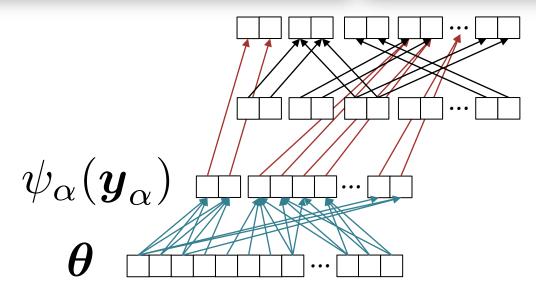
$$a_i = \sigma \left( \sum_j \theta_j b_j \right)$$

## **Arrows in This Diagram:**

A different semantics given by the algorithm

$$m_{\alpha \to i}(y_i) = \frac{1}{\kappa_{\alpha \to i}} \sum_{\boldsymbol{y}_{\alpha} \sim y_i} \psi_{\alpha}(\boldsymbol{y}_{\alpha}) \prod_{j \in \mathcal{N}(\alpha) \setminus i} m_{j \to \alpha}(y_i)$$





Messages at time t=1

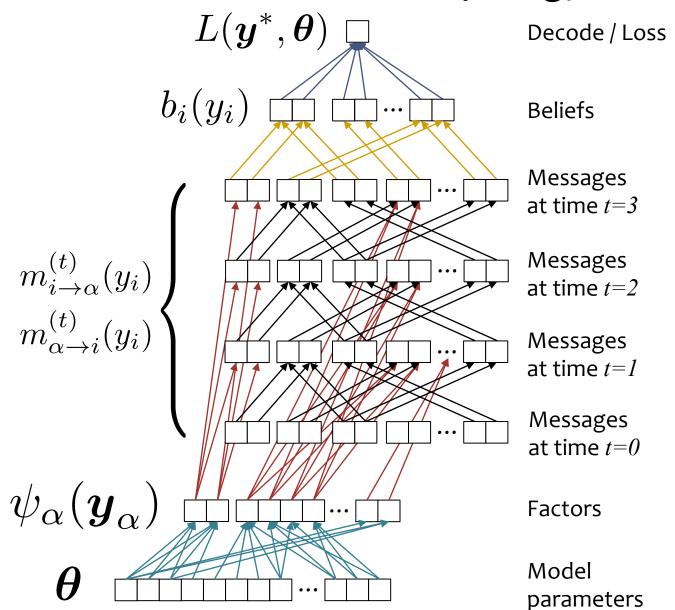
Messages at time t=0

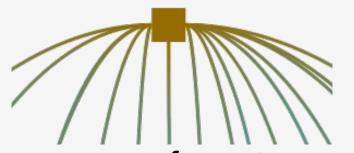
**Factors** 

Model parameters



## Feed-forward Topology



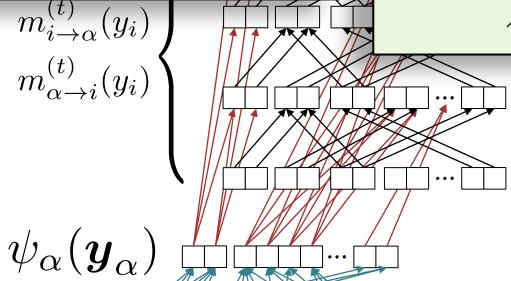


Messages from PTree factor rely on a variant of **inside-outside** 

## **Arrows in This Diagram:**

A different semantics given by the algorithm

$$m_{\alpha \to i}(y_i) = \frac{1}{\kappa_{\alpha \to i}} \sum_{\boldsymbol{y}_{\alpha} \sim y_i} \psi_{\alpha}(\boldsymbol{y}_{\alpha}) \prod_{j \in \mathcal{N}(\alpha) \setminus i} m_{j \to \alpha}(y_i)$$



a

Messages at time t=1

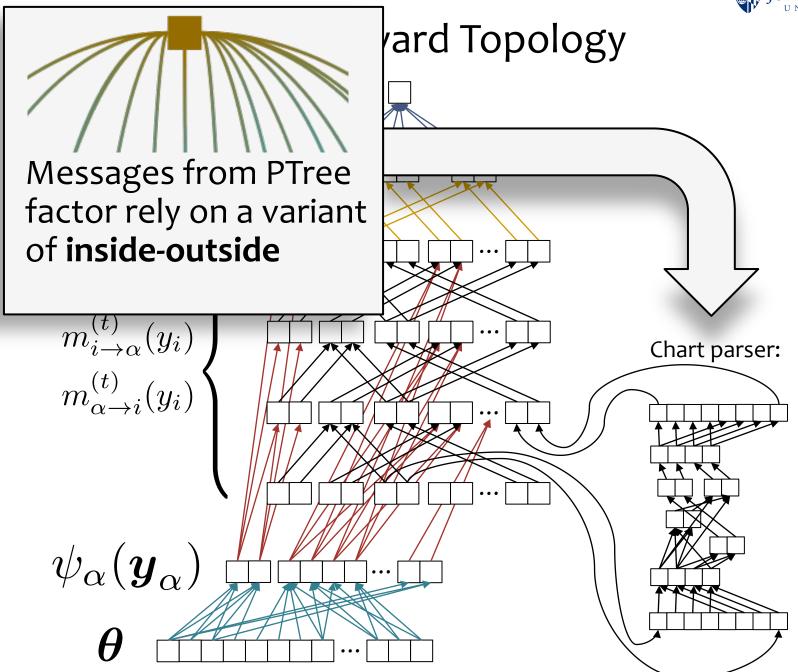
Messages at time t=0

**Factors** 

 $\boldsymbol{\theta}$ 

Model parameters





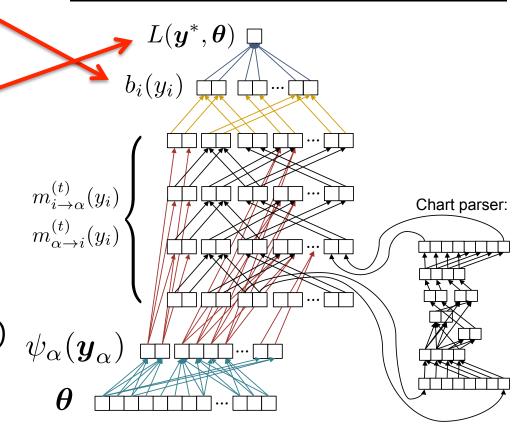


Machine Learning

## Approximation-aware Learning

- Choose model to be the computation with all its approximations
- Choose objective
   to likewise include the
   approximations
- Compute derivative by backpropagation (treating the entire computation as if it were a neural network)
- 4. Make no approximations!(Our gradient is exact)

Key idea: Open up the black box!





## **Experimental Setup**

Goal: Compare two training approaches

- Standard approach (CLL)
- 2. New approach (Backprop)

## **Data:** English PTB

- Converted to dependencies using Yamada & Matsumoto (2003) head rules
- Standard train (02-21), dev (22), test (23) split
- TurboTagger predicted POS tags

**Metric:** Unlabeled Attachment Score (higher is better)

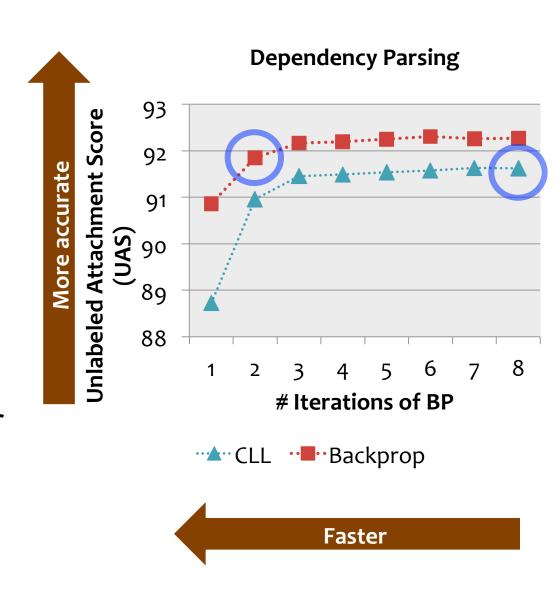


## Results

## Speed-Accuracy Tradeoff

New training approach yields models which are:

- Faster for a given level of accuracy
- More accurate for a given level of speed

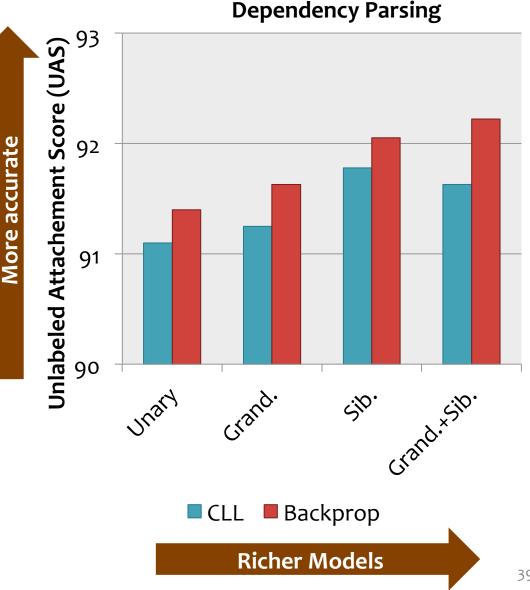




## Results

## Increasingly **Cyclic Models**

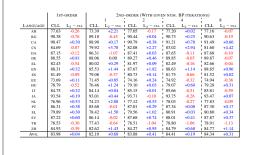
- As we add more factors to the model, our model becomes loopier
- Yet, our training by Backprop consistently improves as models get richer



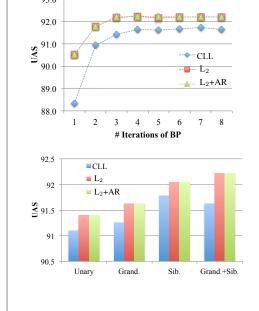


## See our TACL paper for...

1) Results on 19 languages from CoNLL 2006 / 2007



2) Results with alternatetrainingobjectives



3) Empirical comparison of **exact** and **approximate** inference

TRAIN	Inference	DEV UAS	TEST UAS
CLL	Exact	91.99	91.62
CLL	BP 4 iters	91.37	91.25
$L_2$	Exact	91.91	91.66
$L_2$	BP 4 iters	91.83	91.63





## Comparison of Two Approaches

- 1. CLL with approximate inference
  - A totally ridiculous thing to do!
  - But it's been done for years because it often works well
  - (Also named "surrogate likelihood training" by Wainright (2006))



Machine Learning

## Comparison of Two Approaches

Key idea: Open up the black box!

- 2. Approximation-aware Learning for NLP
  - In hindsight, treating the approximations as part of the model is the obvious thing to do (Domke, 2010; Domke, 2011; Stoyanov et al., 2011; Ross et al., 2011; Stoyanov & Eisner, 2012; Hershey et al., 2014)
  - Our contribution: Approximation-aware learning with structured factors
  - But there's some challenges to get it right (numerical stability, efficiency, backprop through structured factors, annealing a decoder's argmin)
  - Sum-Product Networks are similar in spirit
     (Poon & Domingos, 2011; Gen & Domingos, 2012)



## Takeaways

 New learning approach for Structured BP maintains high accuracy with fewer iterations of BP, even with cycles

 Need a neural network? Treat your unrolled approximate inference algorithm as a deep network



## Questions?

## Pacaya - Open source framework for hybrid graphical models, hypergraphs, and neural networks

### **Features:**

- Structured BP
- Coming Soon: Approximation-aware training

Language: Java

URL: <a href="https://github.com/mgormley/pacaya">https://github.com/mgormley/pacaya</a>